





# **SINAMICS** Drives

# **SINAMICS S120**

Chassis Format Converter Units Cabinet Modules

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SINAMICS S150

**Converter Cabinet Units** 

Catalog D 21.3 Edition 2017

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# **Related catalogs**

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SIMOTICS FDD 81.8Low-Voltage MotorsD 81.8Frame sizes 315 to 450Power range 200 to 1800 kWPDF (E86060-K5581-A181-A5-7600)		This manual offers users comprehensive sup configuring of drives and associated system The first three chapters are devoted primaril physical principles of variable-speed electri EMC Installation Guidelines as well as gener and planning information which relate to all SINAMICS range.	o components. y to the fundamental c drives and include al system descriptions
LOHER Low-Voltage Motors D 83.1 Type series 1MD5, 1PS0, 1PS1, 1PS4 and 1PS5 Frame sizes 71 to 500 Power range 0.12 to 1400 kW E86060-K5583-A111-A3-7600	The second	The other chapters then discuss in detail qu dimensioning of drives with converters of sp the selection of suitable motors. Note: The manual is not available in hard copy f electronic file in PDF format.	ecific types as well as



Dear Customer,

We are pleased to present you with the new Catalog D 21.3 · 2017. This catalog provides a comprehensive overview of the powerful drive systems SINAMICS S120 chassis format converter units, SINAMICS S120 Cabinet Modules and SINAMICS S150 with the associated system components.

Siemens AC

We would like to draw your attention to the following product innovations:

- SINAMICS S120 chassis format converter units in water-cooled version
- These built-in units are specially designed for the operation of shared cooling circuits for the plant, motor and converter.

The products listed in this Catalog are also included in the new edition of the Interactive Catalog CA 01 on DVD-ROM and in the Industry Mall. Please contact your local Siemens office for additional information.

Up-to-date information about SINAMICS S120 and SINAMICS S150 is available on the Internet at:

www.siemens.com/sinamics-s120

**SIEMENS** 

CAC

www.siemens.com/sinamics-s150

You can access our Interactive Catalog and our Industry Mall on the Internet at: www.siemens.com/industrymall

We are keen to receive your suggestions and recommendations for improvement (please make reference to Catalog D 21.3  $\cdot$  2017) at catalogs.industry@siemens.com

We hope that you will often enjoy using Catalog D 21.3 · 2017 as a selection and ordering reference document and wish you every success with our products and solutions.

With kind regards,

Franz-Peter Petz Vice President Sales Siemens AG, Process Industries and Drives, Large Drives

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# SINAMICS S120 Chassis Format Converter Units SINAMICS S120 Cabinet Modules SINAMICS S150 Converter Cabinet Units

# **SINAMICS Drives**



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# Catalog D 21.3 · 2017

Supersedes: Catalog D 21.3 · 2015 (PDF)

Refer to the Industry Mall for current updates of this catalog: www.siemens.com/industrymall

The products contained in this catalog can also be found in the Interactive Catalog CA 01. Article No.: E86060-D4001-A510-D8-7600

Please contact your local Siemens branch.

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The products and systems described in this catalog are manufactured/distributed under application of a certified quality management system in accordance with EN ISO 9001 (Certified Registration No. 002241 QM UM). The certificate is recognized by all IQNet countries.

# **Integrated Drive Systems**

Faster on the market and in the black with Integrated Drive Systems

SINAMICS is an important element of a Siemens Integrated Drive System, contributing significantly to increased efficiency, productivity, and availability in industrial production processes.

Integrated Drive Systems are Siemens' trendsetting answer to the high degree of complexity that characterizes drive and automation technology today. The world's only true one-stop solution for entire drive systems is characterized in particular by its threefold integration: Horizontal, vertical, and lifecycle integration ensure that every drive system component fits seamlessly into the whole system, into any automation environment, and even into the entire lifecycle of a plant.

The outcome is an optimal workflow – from engineering all the way to service that entails more productivity, increased efficiency, and better availability. That's how Integrated Drive Systems reduce time to market and time to profit.

# Horizontal integration

Integrated drive portfolio: The core elements of a fully integrated drive portfolio are frequency converters, motors, couplings, and gear units. At Siemens, they're all available from a single source. Perfectly integrated, perfectly interacting. For all power and performance classes. As standard solutions or fully customized. No other player in the market can offer a comparable portfolio. Moreover, all Siemens drive components are perfectly matched, so they are optimally interacting.



You can boost the availability of your application or plant to up to



# **Vertical integration**

Thanks to **vertical integration**, the complete drive train is seamlessly integrated in the entire automation environment – an important prerequisite for production with maximum value added. Integrated Drive Systems are part of Totally Integrated Automation (TIA), which means that they are perfectly embedded into the system architecture of the entire industrial production process. This enables optimal processes through maximum communication and control.

With TIA Portal you can cut your engineering time by up to

30%

# Lifecycle integration

Lifecycle integration adds the factor of time: Software and service are available for the entire lifecycle of an Integrated Drive System. That way, important optimization potential for maximum productivity, increased efficiency, and highest availability can be leveraged throughout the system's lifecycle – from planning, design, and engineering to operation, maintenance, and all the way even to modernization.

With Integrated Drive Systems, assets become important success factors. They ensure shorter time to market, maximum productivity and efficiency in operation, and shorter time to profit. With Integrated Drive Systems you can reduce your maintenance costs by up to

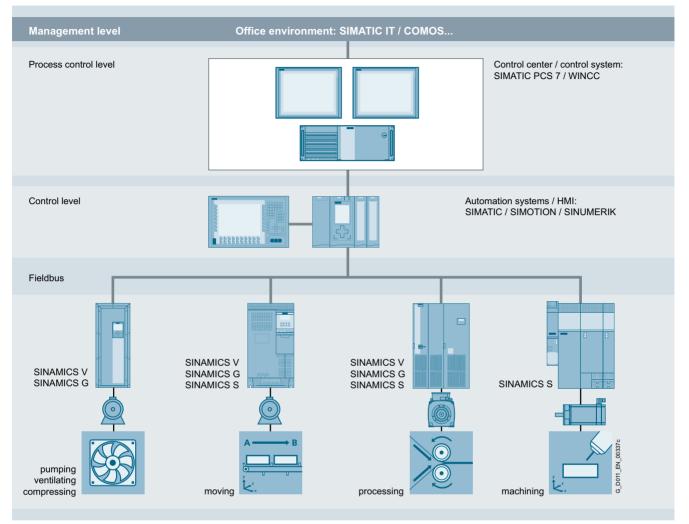


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#### The SINAMICS drive family

# Overview

#### Integration in automation



SINAMICS in the automation environment

#### Totally Integrated Automation and communication

SINAMICS is an integral component of Siemens Totally Integrated Automation. The integrated and seamless SINAMICS system covering engineering, data management, and communication at the automation level ensures solutions with low associated costs in conjunction with the SIMATIC, SIMOTION, and SINUMERIK control systems.

Depending on the application, the appropriate converter can be selected and incorporated in the automation concept. With this in mind, the converters are clearly subdivided into their different applications. A wide range of communication options (depending on the drive type) are available for establishing a communication link to the automation system:

- PROFINET
- PROFIBUS
- EtherNet/IP
- Modbus TCP
- Modbus RTU
- AS-Interface
- CANopen

1/2

- BACnet MS/TP
- Web server

#### Applications

SINAMICS is the comprehensive family of drives from Siemens designed for machine and plant engineering applications. SINAMICS offers solutions for all drive tasks:

- Simple pump and fan applications in the process industry
- Demanding single drives in centrifuges, presses, extruders, elevators, as well as conveyor and transport systems
- Drive line-ups in textile, plastic film, and paper machines as well as in rolling mill plants
- High-precision servo drives for the manufacture of wind turbines
- Highly dynamic servo drives for machine tools, as well as packaging and printing machines

# The SINAMICS drive family **Overview** (continued) SIMOTION SINUMERIK SIMATIC -SINAMICS SIMOTICS D211 XX 00335 SIEMEN Ċ

SINAMICS as part of the Siemens modular automation system

# Innovative, energy-efficient and reliable drive systems and applications as well as services for the entire drive train

The solutions for drive technology place great emphasis on the highest productivity, energy efficiency and reliability for all torque ranges, performance and voltage classes.

Siemens offers not only the right innovative variable frequency drive for every drive application, but also a wide range of energy-efficient low voltage motors, geared motors, explosionprotected motors and high-voltage motors for combination with SINAMICS.

Furthermore, Siemens supports its customers with global pre-sales and after-sales services, with over 295 service points in 130 countries – and with special services e.g. application consulting or motion control solutions.

#### Energy efficiency

#### Energy management process

Efficient energy management consultancy identifies the energy flows, determines the potential for making savings and implements them with focused activities.

Almost two thirds of the industrial power requirement is from electric motors. This makes it all the more important to use drive technology permitting energy consumption to be reduced effectively even in the configuration phase, and consequently to optimize plant availability and process stability. With SINAMICS, Siemens offers powerful energy efficient solutions which, depending on the application, enable a significant reduction in electricity costs.

#### Up to 70 % potential for savings using variable speed operation

SINAMICS enables great potential for savings to be realized by controlling the motor speed. In particular, huge potential savings can be recovered from pumps, fans and compressors which are operated with mechanical throttle and valves. Here, changing to variable-speed drives brings enormous economic advantages. In contrast to mechanical control systems, the power consumption at partial load operation is always immediately adjusted to the demand at that time. So energy is no longer wasted, permitting savings of up to 60 % - in exceptional cases even up to 70 %. Variable-speed drives also offer clear advantages over mechanical control systems when it comes to maintenance and repair. Current spikes when powering up the motor and strong torque surges become things of the past - and the same goes for pressure waves in pipelines, cavitation or vibrations which cause sustainable damage to the plant. Smooth starting and ramp-down relieve the load on the mechanical system, ensuring a significantly longer service life of the entire drive train.

# Overview (continued)

#### Regenerative feedback of braking energy

In conventional drive systems, the energy produced during braking is converted to heat using braking resistors. Energy produced during braking is efficiently recovered to the supply system by versions of SINAMICS G and SINAMICS S drives with regenerative feedback capability and these devices do not therefore need a braking resistor. This permits up to 60 % of the energy requirement to be saved, e.g. in lifting applications. Energy which can be reused at other locations on a machine. Furthermore, this reduced power loss simplifies the cooling of the system, enabling a more compact design.

#### Variants

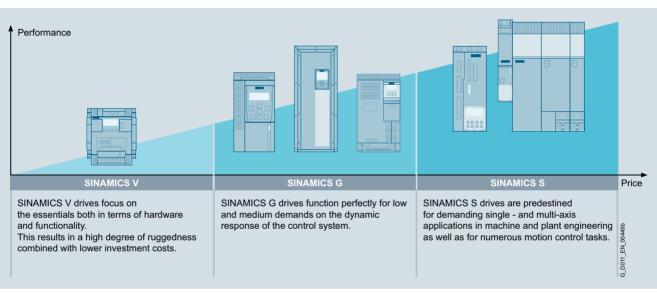
Depending on the application, the SINAMICS range offers the ideal variant for any drive task.

#### Energy transparency in all configuration phases

Early on, in the configuration phase, the SIZER for Siemens Drives engineering tool provides information on the specific energy requirement. The energy consumption across the entire drive train is visualized and compared with different plant concepts.

#### SINAMICS in combination with energy-saving motors

Engineering integration stretches beyond the SINAMICS drive family to higher-level automation systems, and to a broad spectrum of energy-efficient motors with a wide range of performance classes, which, compared to previous motors, are able to demonstrate up to 10 % greater efficiency.



#### Platform concept

All SINAMICS variants are based on a platform concept. Joint hardware and software components, as well as standardized tools for dimensioning, configuration, and commissioning tasks ensure high-level integration across all components. SINAMICS handles a wide variety of drive tasks with no system gaps. The different SINAMICS variants can be easily combined with each other.

#### Quality management according to EN ISO 9001

SINAMICS conforms to the most exacting quality requirements. Comprehensive quality assurance measures in all development and production processes ensure a consistently high level of quality.

Of course, our quality management system is certified by an independent authority in accordance with EN ISO 9001.

The SINAMICS drive family

# Overview (continued)

The SINAMICS drive family

Low voltage					DC voltage	Medium voltage					
Basic per	formance	General performance			High performance			DC applications	Applications with high outputs		
SINAMICS	SINAMICS	SINAMICS				SINAMICS	SINAMICS			SINAMICS	SINAMICS
V20	V90	G120C G120 G120P G120P G120P Cabinet	G110D G120D G110M SIMATIC ET 200pro FC-2	G130 G150	G180	SINAMICS S110	SINAMICS S210	SINAMICS S120 S120M	SINAMICS S150	DCM	GH150 GH180 GM150 SM150 GL150 SL150 SM120CM
0.12 kW to 30 kW	0.05 kW to 7 kW	0.37 kW to 630 kW	0.37 kW to 7.5 kW	75 kW to 2700 kW	2.2 kW to 6600 kW	0.55 kW to 132 kW	0.05 kW to 0.75 kW	0.55 kW to 5700 kW	75 kW to 1200 kW	6 kW to 30 MW	0.15 MW to 85 MW
Pumps, fans, compressors, conveyor belts, mixers, mills, spinning machines, textile machines, refrigerated display counters, fitness equipment, ventilation systems	Handling machines, packaging machines, automatic assembly machines, metal forming machines, printing machines, winding and unwinding units	Pumps, fans, compressors, conveyor belts, mixers, mills, extruders, building management systems, process industry, HVAC, single-axis positioning applications in machine and plant engineering	Conveyor technology, single-axis positioning applications (G120D)	Pumps, fans, compressors, conveyor belts, mixers, mills, extruders	Sector- specific for pumps, fans, compressors, conveyor belts, extruders, mixers, mills, kneaders, centrifuges, separators	Single-axis positioning applications in machine and plant engineering	Packaging machines, handling equipment, feed and withdrawal devices, stacking units, automatic assembly machines, laboratory automation, wood, glass and ceramics industry, digital printing machines	Production machines (packaging, textile and printing machines, paper machines, plastic processing machines, processing machines, process lines and rolling mills, marine drives, test bays	Test bays, cross cutters, centrifuges	Rolling mill drives, wire-drawing machines, extruders and kneaders, cableways and lifts, test bay drives	technology,
Catalog D 31.1	Brochure V90	Catalogs D 31.1, D 35	Catalog D 31.2	Catalog D 11	Catalog D 18.1	Catalog D 31.1	Brochure S210	Catalogs D 21.3, D 21.4 NC 62	Catalog D 21.3	Catalog D 23.1	Catalogs D 15.1, D 12
	Engineering tools (e.g. Drive Technology Configurator, SIZER for Siemens Drives, STARTER and SINAMICS Startdrive)										
	G_D011_EN_0						G_D011_EN_00450i				

### The SINAMICS drive family

# System properties

The SINAMICS range is characterized by the following system properties:

- Standard and seamless functionality based on a platform concept
- Standardized engineering
- High degree of flexibility and combination capability
- Wide range of power ratings
- Designed for global use
- SINAMICS Safety Integrated
- Increased economic efficiency and effectiveness
- High energy efficiency
- Wide range of options when interfacing to higher-level control systems
- Totally Integrated Automation

#### Application areas

Tailored to suit different application areas, the SINAMICS range encompasses the following products:

#### AC low-voltage converters (line supply voltage < 1000 V)

- SINAMICS G110
- The versatile drive for low power ratings
- SINAMICS G110D
  - The distributed, compact single-motor drive in a high degree of protection for basic applications
- SINAMICS G120
- The modular single drive for low up to medium power ratingsSINAMICS G120C
- The compact drive with high power density
- SINAMICS G120D
- The distributed, modular single-motor drive in a high degree of protection for sophisticated applications
- SINAMICS G120P
- The specialist for pumps, fans, and compressors
- SINAMICS G130 and SINAMICS G150
- The universal drive solution for high-performance singlemotor drives
- SINAMICS G180
- The specific drive solution for the oil & gas, chemical and process industries
- SINAMICS S110
- The basic positioning drive for single-axis applications
- SINAMICS S120
- The flexible, modular drive system for demanding drive tasks
   SINAMICS S150
- The drive solution for demanding single-motor drives with energy recovery

### DC converter (line supply voltage < 1000 V)

- SINAMICS DCM
  - The scalable drive system for both basic and demanding applications

AC medium-voltage converters (line supply voltage > 1000 V)

- SINAMICS GM150
- The universal drive solution for single-motor drivesSINAMICS SM150
- The drive solution for demanding single-motor and multi-motor drives
- SINAMICS GL150
- The drive solution for synchronous motors up to 120 MW
- SINAMICS SL150
   The drive solution for rotors with a high number of poles (slow speed) for the highest torques and overloads
- SINAMICS PERFECT HARMONY GH150
   Excellent versatility for cell-based medium-voltage converters
- SINAMICS PERFECT HARMONY GH180
   Striking harmony between performance, process and technology.

More information about SINAMICS is available online at www.siemens.com/sinamics

# 1

**Drive selection** 

# Overview

SINAMICS selection quide – typical applications

Use	Requirements for to	orque accuracy/speed ac	curacy/position accur	acy/coordination of axes/functionality			
	Continuous motion			Non-continuous mot			
	Basic	Medium	High			High	
Pumping, ventilating, compressing	Centrifugal pumps Radial / axial fans Compressors	Centrifugal pumps Radial / axial fans Compressors	Eccentric screw pumps	Hydraulic pumps Metering pumps	Hydraulic pumps Metering pumps	Descaling pumps Hydraulic pumps	
	V20 G120C G120P	G120P G130/G150 G180 <sup>-1)</sup>	S120	G120	S110	S120	
Moving $A \longrightarrow B$ $A \longrightarrow C$ $A \longrightarrow C$ A	Conveyor belts Roller conveyors Chain conveyors	Conveyor belts Roller conveyors Chain conveyors Lifting/lowering devices Elevators Escalators/moving walkways Indoor cranes Marine drives Cable railways	Elevators Container cranes Mining hoists Excavators for open-cast mining Test bays	Acceleration conveyors Storage and retrieval machines	Acceleration conveyors Storage and retrieval machines Cross cutters Reel changers	Storage and retrieva machines Robotics Pick & place Rotary indexing tables Cross cutters Roll feeds Engagers/ disengagers	
	V20 G110D G110M G120C ET 200pro FC-2 <sup>2)</sup>	G120 G120D G130/G150 G180 <sup>1)</sup>	S120 S150 DCM	V90 G120 G120D	S110 DCM	S120 DCM	
Processing	Mills Mixers Kneaders Crushers Agitators Centrifuges	Mills Mixers Kneaders Crushers Agitators Centrifuges Extruders Rotary furnaces	Extruders Winders/unwinders Lead/follower drives Calenders Main press drives Printing machines	Tubular bagging machines Single-axis motion control such as • Position profiles • Path profiles	Tubular bagging machines Single-axis motion control such as • Position profiles • Path profiles	Servo presses Rolling mill drives Multi-axis motion control such as • Multi-axis positioning • Cams • Interpolations	
	V20 G120C	G120 G130/G150 G180 <sup>1)</sup>	S120 S150 DCM	V90 G120	S110	S120 DCM	
	Main drives for • Turning • Milling • Drilling	Main drives for • Drilling • Sawing	Main drives for • Turning • Milling • Drilling • Gear cutting • Grinding	Axis drives for • Turning • Milling • Drilling	Axis drives for • Drilling • Sawing	Axis drives for • Turning • Milling • Drilling • Lasering • Gear cutting • Grinding • Nibbling and punching	
	S110	S110	S120	S110	S110	S120	

### Using the SINAMICS selection guide

The varying range of demands on modern variable frequency drives requires a large number of different types. Selecting the optimum drive has become a significantly more complex process. The application matrix shown simplifies this selection process considerably, by suggesting the ideal SINAMICS drive for examples of typical applications and requirements.

• The application type is selected from the vertical column - Pumping, ventilating, compressing

- Processing
- Machining
- The quality of the motion type is selected from the horizontal row - Basic
  - Medium
  - High

#### More information

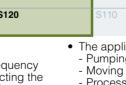
Further information about SINAMICS is available on the Internet at www.siemens.com/sinamics

Practical application examples and descriptions are available on the Internet at www.siemens.com/sinamics-applications

1) Industry-specific drives.

2) Information on the SIMATIC ET 200pro FC-2 frequency converter is available at www.siemens.com/et200pro-fc

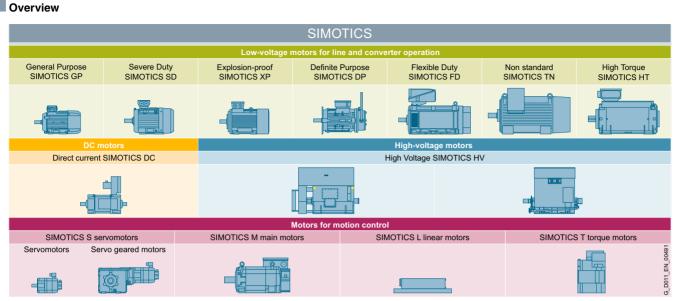
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# **System Overview**

SIMOTICS motors



#### SIMOTICS stands for

- 150 years of experience in building electric motors
- The most comprehensive range of motors worldwide
- Optimum solutions in all industries, regions and power/performance classes
- Innovative motor technologies of the highest quality and reliability
- Highest dynamic performance, precision and efficiency together with the optimum degree of compactness
- Our motors can be integrated into the drive train as part of the overall system
- A global network of skill sets and worldwide service around the clock

#### A clearly structured portfolio

The entire SIMOTICS product portfolio is transparently organized according to application-specific criteria in order to help users select the optimum motor for their application.

The product range extends from standard motors for pumps, fans and compressors to highly dynamic, precise motion control motors for positioning tasks and motion control in handling applications, as well as production machinery and machine tools, to DC motors and powerful high-voltage motors. Whatever it is that you want to move – we can supply the right motor for the task.

#### An outstanding performance for any job

A key characteristic of all SIMOTICS motors is their quality. They are robust, reliable, dynamic and precise to assure the requisite performance level for any process and deliver exactly the capabilities demanded by the application in hand. Thanks to their compact design, they can be integrated as space-saving units into installations. Furthermore, their impressive energy efficiency makes them effective as a means of reducing operating costs and protecting the environment.

# A dense network of skill sets and servicing expertise around the world

SIMOTICS offers not only a wealth of sound experience gleaned from a development history which stretches back over around 150 years, but also the know-how of hundreds of engineers. This knowledge and our worldwide presence form the basis for a unique proximity to industries which feeds through in tangible terms to the specific motor configuration which is tailored to suit your application.

Our specialists are available to answer all your queries regarding any aspect of motor technology. At any time - wherever you are in the world. When you choose SIMOTICS, therefore, you reap the benefits of a global service network which is continuously accessible, thereby helping to optimize response times and minimize downtimes.

#### Perfection of the complete drive train

SIMOTICS is perfectly coordinated with other Siemens product families. In combination with the SINAMICS integrated drives family and the SIRIUS complete portfolio of industrial controls, SIMOTICS fits seamlessly as part of the complete drive train into automation solutions which are based on the SIMATIC, SIMOTION and SINUMERIK control systems.

**SINAMICS S120** 

# Overview

# The flexible, modular drive system for demanding drive tasks

SINAMICS S120 is the modular drive system with vector and servo control that is ideal for sophisticated drive tasks in plant and machine construction.

Multi-axis drive solutions with higher-level motion control can be implemented with the modular SINAMICS S120 system just the same as solutions for single-axis drives.

Covering a power range from 0.12 kW to 5700 kW and various control modules with a graduated range of functions, the modular SINAMICS S120 system can be used to simply and quickly create a precisely tailored drive configuration – for almost any sophisticated drive application.

On the SINAMICS S120, the drive intelligence is combined with closed-loop control functions into Control Units.

These units are capable of controlling drives in the vector, servo and V/f modes. They also perform the speed and torque control functions plus other intelligent drive functions for all axes on the drive.

Using the available closed-loop control techniques, both synchronous as well as induction motors can be operated, and therefore the complete range of low-voltage motors from Siemens.

Integrated PROFINET or PROFIBUS DP interfaces ensure easy integration into complete automation solutions. SINAMICS S120 also supports many other fieldbus interfaces.

SINAMICS S120 Cabinet Modules are available as a cabinet system specifically for use in plant construction. These can be combined to form drive cabinet line-ups with a total power rating of up to 5700 kW. Standardized interfaces enable the modules to be linked quickly to create a ready-to-connect drive solution for multi-motor applications.

# Benefits

SINAMICS S120 is characterized by the following properties:

- Can be universally used in high-performance single and multi-axis applications
- Can be freely combined to create customized solutions
- Wide range of power ratings
- Wide range of functions
- SINAMICS Safety Integrated functions
- Supports various cooling types (air/liquid-cooled)
- Supports various infeed concepts
- Can be simply integrated into higher-level automation and IT environments
- User-friendly engineering
- · Ease of handling
- Simple installation
- Practical connection system
- · Auto-configuration with electronic type plates

#### Application

SINAMICS S120 vector control is recommended for drive solutions with continuous material webs, for example, wire-drawing machines, film and paper machines, as well as for hoisting gear, centrifuges and marine drives with harmonic, circular motion.

SINAMICS S120 with servo control and servo motors is employed for cyclic processes with both precise and highly dynamic closed-loop position control.

With SINAMICS S120, more performance is integrated into machines that are used in many industries, for instance in:

- Packaging machines
- Plastics processing machines
- Textile machines
- Presses and punches
- Printing and paper machines
- Machines used in the woodworking, glass and ceramics industries
- · Hoisting gear
- · Handling and assembly systems
- Machine tools
- Rolling mill drives
- Vehicle and gearbox test bays
- Text bay applications
- Marine applications

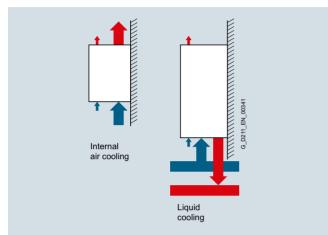
#### SINAMICS S120

### Design

SINAMICS S120 built-in units are available as Power Modules, Line Modules and Motor Modules with the appropriate line-side and motor-side components.

#### **Cooling types**

There are various cooling options available depending on the type of construction:



#### Internal air cooling

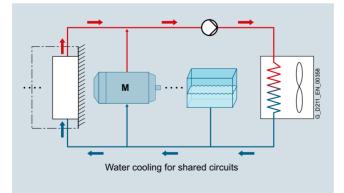
In this standard solution, the power loss from the electronics and power units of the drive components is removed by natural cooling or by a forced-ventilation system and routed to the interior of the control cabinet.

#### Liquid cooling

On liquid-cooled units, the power semiconductors are mounted on a heat sink through which the cooling medium flows. Most of the heat produced by the unit is absorbed by the cooling medium and can be dissipated outside the control cabinet.

#### Water cooling for shared circuits

With water cooling for shared circuits, the water that is available at the plant can be used. This results in a shared cooling circuit for the plant, motor, and converter. The requirements for the water quality are low in this case. Additives are not needed in the water circuit which simplifies environmentally friendly commissioning and maintenance. Furthermore, the converter is resistant to the addition of oxygen to the cooling water. The advantages of liquid cooling, such as high energy savings and efficient heat recovery, are also available with water cooling.



#### Types of construction

Power Modules are available in blocksize and chassis formats. Motor Modules and Line Modules are available in booksize, booksize compact and chassis formats.

Precise details and ordering data on the booksize, booksize compact and blocksize formats are found in Catalog D 21.4.

#### Booksize format

Booksize format units are optimized for multi-axis applications and are mounted adjacent to one another. The connection for the common DC link is an integral feature.

The units are cooled by an internal air cooling circuit.



#### Booksize compact format

Derived from the booksize format we developed the booksize compact format for machines with particularly high requirements for the compactness of their drives.

The booksize compact format combines all benefits of the booksize format and provides the same performance with an even smaller overall height and an extended overload capability.

The booksize compact format is thus particularly suitable for integration into machines requiring a high dynamic performance and where installation space is restricted.

The units are cooled by an internal air cooling circuit.



1

### Design (continued)

#### **Blocksize format**

Blocksize format units are optimized for single-axis applications and are supplied only as Power Modules. The CU310-2 can be directly snap-mounted. The units are cooled by an internal air cooling circuit.



#### Chassis format

Higher-output units (approximately 100 kW and above) are constructed in chassis format. These drive units are available as:

- Power Modules
- Basic Line Modules
- Smart Line Modules (air-cooled only)
- Active Line Modules
- Active Interface Modules
- Motor Modules

Chassis format units are cooled by an internal air cooling circuit, liquid cooling, or water cooling for shared circuits. The CU310-2 Control Unit can be integrated in the Power Modules.



Liquid-cooled units and water-cooled units for shared circuits are used primarily for applications where installation space is restricted (up to a 60 % smaller footprint when compared to air cooling) or where low noise emissions are important. They are also suitable for applications in tough ambient conditions.

#### Cabinet Modules

SINAMICS S120 Cabinet Modules are a modular cabinet system for multi-motor drives with a central supply infeed and a common DC busbar, for example, as used in paper machines, rolling mills, test bays, and hoisting gear. Cabinet Modules are available with a total power rating of up to 4500 kW in the air-cooled version and up to 5700 kW in the liquid-cooled version. The main components of the system are as follows:

- Line Connection Modules
- Basic Line Modules
- Smart Line Modules
- Active Line Modules including Active Interface Modules
- Central Braking Modules
- Motor Modules
- Auxiliary Power Supply Modules



# Overview

**SINAMICS S150** 

The drive solution for demanding single-motor drives



SINAMICS S150 cabinet units are designed for variable-speed drives in plant and machinery construction.

They are especially suitable where high demands are placed on dynamic performance and speed precision, as well as for frequent braking cycles with high braking energies and fourquadrant operation. The drive converter cabinet units provide high performance speed control with a high precision and dynamic performance, and are available for a power range extending from 75 kW up to 1200 kW.

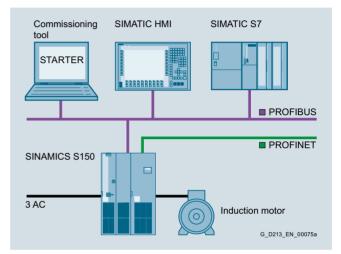
# Design

SINAMICS S150 systems are ready-to-connect converters accommodated in a standard control cabinet.

They can be optimally adapted to specific requirements as a result of a wide range of options.

Different variants allow the line and the motor connection to be made at the top or bottom. This ensures a high degree of flexibility regarding how the drive is installed.

The drive units are available with cabinet widths starting from 1400 mm in grid dimension increments of 200 mm. As standard, the cabinets have degree of protection IP20, and can be optionally increased up to IP54. The AOP30 Advanced Operator Panel is fitted as standard in the cabinet door.





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#### Safety Integrated

### Overview



#### Legal framework

Machine manufacturers and manufacturing plants must ensure that their machines or plants cannot cause danger due to malfunctions in addition to the general risks of electric shock, heat or radiation.

In Europe, for example, compliance with the Machinery Directive 2006/42/EC is legally stipulated by the EU work safety directive. In order to ensure compliance with this directive, it is recommended that the corresponding harmonized European standards are applied. This triggers the "assumption of conformity" and gives manufacturers and operators the legal security in terms of compliance with both national regulations and EU directives. The machine manufacturer uses the CE marking to document the compliance with all relevant directives and regulations in the free movement of goods.

#### Safety-related standards

Functional safety is specified in various standards. For example, EN ISO 12100 specifies standards pertaining to machine safety (risk assessment and risk reduction). IEC 61508 specifies basic requirements for electronic and programmable safety-related systems. EN 62061 (only applicable for electrical and electronic control systems) and EN ISO 13849-1, which has replaced EN 954-1, define the functional and safety-related requirements of safety-oriented control systems.

The above-mentioned standards define different safety requirements that the machine has to satisfy in accordance with the risk, frequency of a dangerous situation, probability of occurrence and the opportunities for recognizing impending danger.

- EN ISO 13849-1: Performance Level PL a ... e; Category B, 1 ... 4
- EN 62061: Safety Integrity Level SIL 1 ... 3

#### Trend toward integrated safety systems

The trend toward greater complexity and higher modularity of machines has seen a shift in safety functions away from the classical central safety functions (for example, shutdown of the complete machine using a main switch) and into the machine control system and the drives. This is often accompanied by a significant increase in productivity because the equipping times are shortened. Depending on the type of machine, it may even be possible to continue manufacturing other parts while equipping is in progress.

Integrated safety functions act much faster than those of a conventional design. The safety of a machine is increased further with Safety Integrated. Furthermore, thanks to the faster method of operation, safety measures controlled by integrated safety systems are perceived as less of a hindrance by the machine operator, therefore significantly reducing the motivation to consciously bypass safety functions.

#### Function

#### Safety functions integral to the SINAMICS drives

SINAMICS drives are characterized by a large number of integrated safety functions. In combination with the sensors and safety control required for the safety functionality, they ensure that highly-effective protection for persons and machines is implemented in a practice-oriented manner.

They comply with the requirements of the following safety categories:

- PL d and Category 3 according to EN ISO 13849-1
- SIL 2 according to IEC 61508 and IEC 61800-5-2

#### Note:

The Safe Brake Test (SBT) diagnostic function meets the requirements for Category 2 according to EN ISO 13849-1.

The Safety Integrated functions of the SINAMICS drives are generally certified by independent institutes. You can obtain the corresponding test certificates and manufacturer's declarations from your Siemens contacts.

The integrated safety functions that are currently available in the SINAMICS drive system are described below. Their functional safety satisfies the requirements defined in the international standard IEC 61800-5-2 for variable-speed drive systems.

The safety functions integrated into the SINAMICS drive system can be roughly divided into four categories:

# • Functions for safely stopping a drive

- Safe Torque Off (STO)
- Safe Stop 1 (SS1)
- Safe Stop 2 (SS2)
- Safe Operating Stop (SOS)
- · Functions for safe brake management
- Safe Brake Control (SBC)
- Safe Brake Test (SBT) (this diagnostic function exceeds the scope of IEC 61800-5-2)
- · Functions for safely monitoring the motion of a drive
  - Safely-Limited Speed (SLS)
  - Safe Speed Monitor (SSM)
  - Safe Direction (SDI)
- · Functions for safely monitoring the position of a drive
  - Safely-Limited Position (SLP)
  - Safe Position (SP) (this function exceeds the scope of IEC 61800-5-2)

The Safety Integrated Function Manual contains detailed information about the safety functions. https://support.industry.siemens.com/cs/document/109740018

Further manuals pertaining to Safety Integrated in drive systems can be found on the Internet at

https://support.industry.siemens.com/cs/ww/en/ps/13231/man

Further information about Safety Integrated can be found on the Internet at

www.siemens.com/safety-drives

#### Safe Torque Off (STO)

The STO function is the most common and basic drive-integrated safety function. It ensures that no torque-generating energy can continue to affect a motor and prevents unintentional start-ups.

#### Effect

This function is a mechanism that prevents the drive from restarting unexpectedly, in accordance with EN 60204-1, Section 5.4. The STO function suppresses the drive pulses (corresponds to Stop Category 0 according to EN 60204-1). The drive is reliably torque-free. This state is monitored internally in the drive.

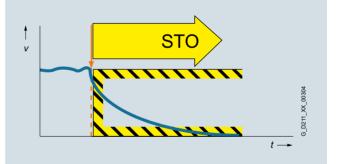
#### Application

STO has the immediate effect that the drive cannot supply any torque-generating energy. STO can be used wherever the drive will naturally reach a standstill due to load torque or friction in a sufficiently short time or when "coasting down" of the drive will not have any relevance for safety.

STO makes it possible for persons to work safely when the protective door is open (restart interlock) and is used on machines/ installations with moving axes, e.g. on handling or conveyor systems.

#### Customer benefits

Some of the advantages of the integrated STO safety function over conventional safety technology with electromechanical switchgear include the elimination of separate components as well as of the work that would be required to wire and service them, i.e. no wearing parts as a result of the electronic shutdown. Because of the fast electronic switching times, the function provides a shorter reaction time than the conventional solution comprising electromechanical components. When STO is triggered, the converter remains connected to the network and can be fully diagnosed.



#### Safety Integrated

#### Function (continued)

#### Safe Stop 1 (SS1)

The SS1 function causes a motor to stop rapidly and safely and switches the motor to torque-free mode after coming to a standstill by activating STO.

#### Effect

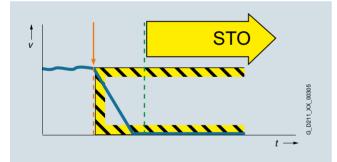
The SS1 function can safely stop the drive in accordance with EN 60204-1, Stop Category 1. When the SS1 function is selected, the drive brakes autonomously along a quick stop ramp and automatically activates the Safe Torque Off and Safe Brake Control functions (if configured) when the parameterized safety delay time expires.

#### Application

The SS1 function is used when, in the event of a safety-relevant incident, the drive must stop as quickly as possible with a subsequent transition into the STO state (e.g. EMERGENCY STOP). It is thus used to bring large centrifugal masses to a stop as quickly as possible for the safety of the operating personnel, or to brake motors at high speeds as quickly as possible. Examples of typical applications are saws, grinding machine spindles, centrifuges, winders and storage and retrieval machines.

#### Customer benefits

The targeted stopping of a drive by means of SS1 reduces the risk of danger, increases the productivity of a machine, and allows the safety clearances in a machine to be reduced. The principle is to bring the drive actively to a standstill, compared with just using the STO function. Complex mechanical brakes that are susceptible to wear are not normally required to brake the motor.



#### Safe Stop 2 (SS2)

The SS2 function brings the motor to a standstill quickly and safely and then activates the SOS function once the motor has stopped.

#### Effect

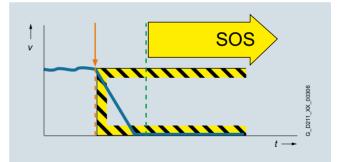
The Safe Stop 2 function can safely stop the drive in accordance with EN 60204-1, Stop Category 2. When the SS2 function is selected, the drive brakes autonomously along a quick stop ramp. In contrast to SS1, the drive control remains operational afterwards, i.e. the motor can supply the full torque required to maintain zero speed. Standstill is safely monitored (Safe Operating Stop function).

#### Application

As with SS1, the SS2 function ensures the quickest possible deceleration of the motor. However, the motor power is not switched off. Instead, a control system prevents it from leaving the standstill position - even if it is affected by external forces. Typical applications for SS2 include machine tools, for example.

#### Customer benefits

The SS2 function ensures a rapid axis stop. Because the control remains active, after the safety function is deselected, productive operation can continue without referencing. This ensures short setup and standstill times and high productivity.



### Function (continued)

#### Safe Operating Stop (SOS)

With the SOS function, the stopped motor is held in position by the drive control system and its position monitored.

#### Effect

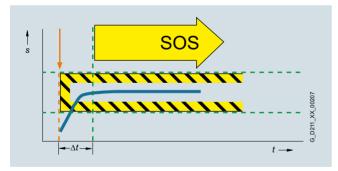
The SOS function constitutes safe standstill monitoring. The drive control remains in operation. The motor can therefore deliver the full torque to hold the current position. The actual position is reliably monitored. In contrast to safety functions SS1 and SS2, the speed setpoint is not influenced autonomously. After SOS has been activated, the higher-level control must bring the drive to a standstill within a parameterized time and then hold the position setpoint.

#### Application

SOS is an ideal solution for all those applications for which the machine or parts of the machine must be at a safe standstill for certain steps, but the drive must also supply a holding torque. It is ensured that despite counter torque the drive remains in its current position. In contrast to SS1 and SS2, the drive does not brake autonomously in this case. It expects the higher-level controller to ramp down the relevant axes as a coordinated group within an adjustable delay time. This can be used to prevent any damage to the machine or product. Typical applications for SOS include winders, converting and packaging machines and machine tools.

#### Customer benefits

No mechanical components are necessary to keep the axis in position despite any counterforce that may occur. Due to the short switching times and the fact that the drive control always remains active, setup and downtimes are reduced. Recalibration of the axis after exiting the SOS function is not necessary. The axis can immediately be moved again after deactivation of the SOS function.



#### Safe Brake Control (SBC)

The SBC function permits the safe control of a holding brake. SBC is always activated in parallel with STO.

#### Effect

A holding brake which is active in a de-energized state is controlled and monitored using safe two-channel technology. Due to the two-channel control, the brake may still be activated in the event of an insulation fault in the control cable. Errors of this kind are detected early by means of test pulses.

#### Note:

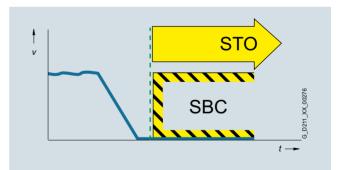
An additional Safe Brake Relay is required for power units in blocksize format. An additional Safe Brake Adapter is necessary for power units in chassis format.

#### Application

The SBC function is used in conjunction with the functions STO or SS1 to prevent the movement of an axis in the torque-free state, e.g. because of gravity.

#### Customer benefits

Again, the function saves the use of external hardware and the associated wiring.



#### Safety Integrated

# Function (continued)

### Safe Brake Test (SBT)

The SBT diagnostic function carries out a brake function test at regular intervals or before personnel enter the danger zone.

#### Effect

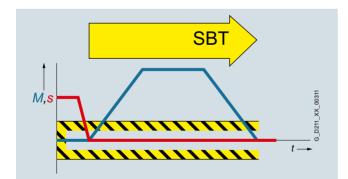
A good way to check the proper functioning of brakes that have become worn is to apply a torque to the closed brake. Drive systems that have two brakes, e.g. motor brake and external brake, can be tested with different torque values.

#### Application

The SBT diagnostic function is suitable for implementing a safe brake in combination with the SBC function.

#### Customer benefits

The function detects faults or wear in the brake mechanics. Automatically testing the effectiveness of brakes reduces maintenance costs and increases the safety and availability of the machine or plant.



#### Safely-Limited Speed (SLS)

The SLS function monitors the drive to ensure that it does not exceed a preset speed or velocity limit.

#### Effect

The SLS function monitors the drive against a parameterized speed limit. Four different limit values can be selected. As in the case of SOS, the speed setpoint is not influenced independently. After SLS has been selected, the higher-level control must bring the drive down below the selected speed limit within a parameterizable time. If the speed limit is exceeded, a customizable drive-integrated fault reaction occurs.

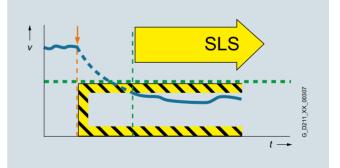
The SLS limit stage 1 can be multiplied by a factor that is transferred in 16-bit resolution via PROFIsafe. This allows an almost unlimited number of limits to be specified.

#### Application

The SLS function is used if people are in the danger zone of a machine and their safety can only be guaranteed by reduced speed. Typical application cases include those in which an operator must enter the danger zone of the machine for the purposes of maintenance or setting up, such as a winder in which the material is manually threaded by the operator. To prevent injury to the operator, the roller may only spin at a safely reduced speed. SLS is often also used as part of a two-stage safety concept. While a person is in a less critical zone, the SLS function is activated, and the drives are only stopped in a smaller area with higher potential risk. SLS can be used not only for operator protection, but also for machinery protection, e.g. if a maximum speed must not be exceeded.

#### Customer benefits

The SLS function can contribute to a significant reduction in downtime, or greatly simplify or even accelerate setup. The overall effect achieved is a higher availability of the machine. Moreover, external components such as speed monitors can be omitted.



# Function (continued)

#### Safe Speed Monitor (SSM)

The SSM function warns when a drive is working below an adjustable speed limit. As long as it remains below the threshold, the function issues a safety-related signal.

#### Effect

If a speed value drops below a parameterized limit, a safetyrelated signal is generated. This can, for example, be processed in a safety controller to respond to the event by programming, depending on the situation.

#### Safe Direction (SDI)

The SDI function ensures that the drive can only move in the selected direction.

#### Effect

Deviation from the direction of motion currently being monitored is detected reliably and the configured drive-integrated fault reaction is initiated. It is possible to select which direction of rotation is to be monitored.

#### Application

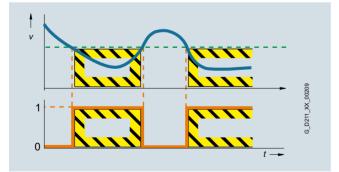
With the SSM function, in the simplest case, a safety door can be unlocked if the speed drops below a non-critical level. Another typical example is that of a centrifuge that may be filled only when it is operating below a configured speed limit.

#### Application

The SDI function is used when the drive may only move in one direction. A typical application is to permit the operator access to a danger zone, as long as the machine is rotating in the safe direction, i.e. away from the operator. In this state, the operator can feed material into the work zone / remove material from the work zone without danger.

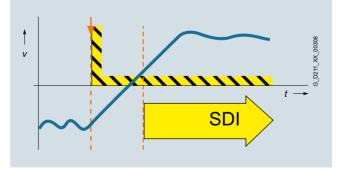
#### Customer benefits

Unlike SLS, there is no drive-integrated fault reaction when the speed limit is exceeded. The safe feedback can be evaluated in a safety control unit, allowing the user to respond appropriately to the situation.



#### Customer benefits

The function saves the use of external components such as speed monitors and the associated wiring. The release of a danger zone while the machine is moving away from the operator increases productivity. Without the SDI function, the machine must be safely stopped during material loading and removal.



### Safety Integrated

# Function (continued)

#### Safely-Limited Position (SLP)

The SLP function monitors the axis to ensure that it remains within the permissible traversing range.

#### Effect

When SLP is activated, the traversing range limited by the configured software limit switches is safely monitored. If the permitted traversing range is exited, a configurable fault reaction occurs. It is possible to toggle between two traversing ranges, even when the machine is in operation.

#### Application

SLP is used for applications in which machine operators have to enter a protection area, e.g. for feeding in and removing material. Safe monitoring of the axis position ensures that the axis cannot move into the protection area released for operators and so place them in danger, for example, on storage and retrieval machines, gantry cranes or machining centers.

#### Customer benefits

SLP can be used for highly-effective protection area monitoring. The function does away with the use of external components such as hardware limit switches and the associated wiring expense. Due to the short reaction time following a limit overshoot, safety clearances can be reduced.



#### Safe Position (SP)

The SP function transfers the actual position values determined safely in the drive over safe PROFIsafe communication to a safety control.

#### Effect

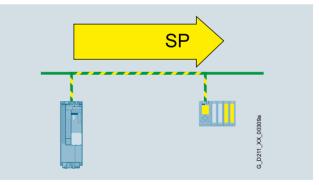
In contrast to the SLP function that monitors the current actual position value against a limit and, in the case of an overshoot, activates a drive-integrated fault reaction, SP transfers the current actual position values to the safety control. Position monitoring is implemented in the safety program of the control. Extended PROFIsafe telegrams are available for transferring the position values. The position values can be transferred in 16-bit or 32-bit resolution, as required. A time stamp is also transferred with the position values.

#### Application

Tailor-made safety concepts can be created using the SP function. It is ideal for use on machines that require flexible safety functions. It is extremely versatile and can be used, for example, to implement safe, axis-specific range detection by means of safe cams. The SP function can also be used to implement multi-axis safety concepts, multi-dimensional protection areas and zone concepts.

#### Customer benefits

Position monitoring or speed monitoring is implemented in the safety program of the control, so the user has the flexibility for implementing tailor-made safety functions. The reaction to a limit overshoot must also be specified in the safety program. This means a higher initial programming outlay, but it does offer the opportunity for initiating different fault reactions.



### **Function** (continued)

#### **Basic Functions and Extended Functions**

The Safety Integrated functions are grouped into Basic Functions and Extended Functions

- Basic Functions
- Safe Torque Off (STO)
- Safe Brake Control (SBC)
- Safe Stop 1 (SS1)
- Extended Functions
  - Safe Stop 1 (SS1) with SBR or SAM
  - Safe Stop 2 (SS2) with SAM
  - Safe Operating Stop (SOS)
  - Safely-Limited Speed (SLS)
  - Safe Speed Monitor (SSM)
  - Safe Direction (SDI)
  - Safely-Limited Position (SLP)
  - Safe Position (SP)
- Safe Brake Test (SBT) diagnostic function

For the Extended Functions SS1 and SS2 with SAM, safe acceleration monitoring (SAM) is performed during braking to identify any faults already during the braking phase.

If Safe Stop 1 is used as an encoderless function, a Safe Brake Ramp (SBR) can be configured as an alternative.

The Basic Functions – activated via on-board terminals on the device or via PROFIsafe – do not require an encoder.

#### Activation of the integrated safety functions

The safety functions for SINAMICS drives can be activated via terminals, e.g. for use of a conventional safety circuit.

For standalone safety solutions for small to medium sized applications, it is frequently sufficient that the various sensing components are directly hardwired to the drive.

For integrated safety solutions, the safety-relevant sequences are generally processed and coordinated in the fail-safe SIMATIC controller. Here, the system components communicate via the PROFINET or PROFIBUS fieldbus. The safety functions are controlled via the safe PROFIsafe communication protocol.

SINAMICS drives can be easily integrated into the plant or system topology.

#### PROFIsafe

SINAMICS drives support the PROFIsafe profile based on PROFINET as well as on PROFIBUS.

PROFIsafe is an open communications standard that supports standard and safety-related communication over the same communication path (wired or wireless). A second, separate bus system is therefore not necessary. The telegrams that are sent are continually monitored to ensure safety-relevant communication.

Possible errors such as telegrams that have been lost, repeated or received in the incorrect sequence are avoided. This is done by consecutively numbering the telegrams in a safety-relevant fashion, monitoring their reception within a defined time and transferring an ID for transmitter and receiver of a telegram. A CRC (cyclic redundancy check) data security mechanism is also used.

#### The operating principle of Safety Integrated

#### Two independent switch-off signal paths

Two independent switch-off signal paths are available. All switch-off signal paths are low active. This ensures that the system is always switched to a safe state if a component fails or in the event of cable breakage. If a fault is discovered in the switch-off signal paths, the STO or SS1 function (depending on parameter settings) is activated and a system restart inhibited.

#### Two-channel monitoring structure

All the main hardware and software functions for Safety Integrated are implemented in two independent monitoring channels (e.g. switch-off signal paths, data management, data comparison). A cyclic crosswise comparison of the safety-relevant data in the two monitoring channels is carried out.

The monitoring functions in each monitoring channel work on the principle that a defined state must prevail before each action is carried out and a specific acknowledgement must be made after each action. If these expectations of a monitoring channel are not fulfilled, the drive coasts to a standstill (two channel) and an appropriate message is output.

#### Forced dormant error detection using test stop

The functions and switch-off signal paths must be tested at least once within a defined time in order to meet requirements as per EN ISO 13849-1 and IEC 61508 in terms of timely fault detection. This must be implemented either in cyclic manual mode or the test stop must be automatically initiated as part of the process. The test stop cycle is monitored, and after a specific time has been exceeded, an alarm is output. A test stop does not require a POWER ON. The acknowledgment is set by canceling the test stop request.

Examples of when forced dormant error detection must be performed:

- When the drives are at a standstill after the system has been switched on
- Before the protective door is opened
- At defined intervals (e.g. every 8 hours)
- In automatic mode, time and event-driven

### Safety Integrated

# Function (continued)

### Safe actual value sensing with or without encoders

A drive monitor with encoder is necessary for operation of a series of safety functions.

For applications with encoderless mode or with encoders that have no safety capability, the safety functions can also be implemented without encoder. It is not possible to use all safety functions in this case.

The encoderless safety functions can be implemented on request for chassis format units (see the Function Manuals SINAMICS S120 Safety Integrated and SINAMICS G130, G150, S120 Chassis, S120 Cabinet Modules, S150; Safety Integrated).

In operation without encoder, the actual speed values are calculated from the measured electrical actual values. This means that speed monitoring is also possible during operation without an encoder. An encoder that is used for the purposes of motor control has no significance for the safety function here.

Safety Integrated Extended Functions "without encoder" must not be used if the motor, after it has been switched off, can still be accelerated by the mechanical elements of the connected machine component.

In the hoisting gear of a crane, for example, the suspended load can accelerate the motor as soon as the motor is switched off. In this case, the safety functions "without encoder" are not permitted.

A horizontal conveyor, on the other hand, is always braked to a standstill due to friction as soon as the motor is switched off. In this case, the safety functions "without encoder" can be used without any restriction.

Additional information on the encoderless safety functions is available in the Safety Integrated Function Manuals at www.siemens.com/sios (search terms 99668646 and 106254588).

The safety functions are listed below with criteria for actual value sensing:

	Functions	Abbreviation	With encoder	Without encoder	Description
<b>Basic Functions</b>	Safe Torque Off	STO	Yes	Yes	Safe Torque Off
	Safe Stop 1	SS1	Yes	Yes	Safe stopping process in accordance with stop category 1
	Safe Brake Control	SBC	Yes	Yes	Safe Brake Control
Extended Functions	Safe Torque Off	STO	Yes	Yes	Safe Torque Off
	Safe Stop 1	SS1	Yes	Yes <sup>1)</sup>	Safe stopping process in accordance with stop category 1
	Safe Brake Control	SBC	Yes	Yes	Safe Brake Control
	Safe Operating Stop	SOS	Yes	No	Safe monitoring of the standstill position
	Safe Stop 2	SS2	Yes	No	Safe stopping process in accordance with stop category 2
	Safely-Limited Speed	SLS	Yes	Yes <sup>1)</sup>	Safe monitoring of the maximum speed
	Safe Speed Monitor	SSM	Yes	Yes 1)	Safe monitoring of the minimum speed
	Safe Direction	SDI	Yes	Yes <sup>1)</sup>	Safe monitoring of the direction of motion
	Safely-Limited Position	SLP	Yes	No	Safely-limited position
	Safe Position	SP	Yes	Yes <sup>2)</sup>	Safe transfer of position values
	Safe Brake Test	SBT	Yes	No	Diagnostic function for safe testing of the required holding torque of a brake

 The use of this safety function without encoder is permitted for asynchronous (induction) motors or synchronous motors of the SIEMOSYN series.

### **Function** (continued)

#### Safe speed/position sensing with encoder

Incremental encoders or absolute encoders with photoelectric sampling are permitted for safe sensing of the position values on a drive. HTL/TTL incremental encoders may also be used.

Safe actual value sensing relies on redundant evaluation of the incremental tracks A/B that supply sin/cos signals of 1 V<sub>pp</sub>. Only encoders of the type whose A/B track signals are created and processed using purely analog techniques can be used. The encoder signals are input via the SMC20 Sensor Module Cabinet-Mounted (option **K48** for cabinets).

HTL/TTL incremental encoders may also be used. In this case, safe actual value sensing is achieved by using two independent encoders. The minimum possible speed resolution must also be taken into account. The encoder signals are input via the SMC30 Sensor Module Cabinet-Mounted (options **K50** and **K52** for cabinets).

As an alternative, motors with an integrated DRIVE-CLiQ interface can be used. The speed or position actual values are generated directly in the motor as safe values and are transferred to the Control Unit over safe communication via DRIVE-CLiQ.

Certified built-on rotary encoders with DRIVE-CLiQ interface may also be used (see

https://support.industry.siemens.com/cs/document/65402168).

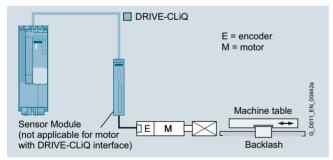
The encoder must be mechanically attached in such a manner that the encoder shaft is unable to unplug or slide off. For notes on this, see IEC 61800-5-2: 2016, Table D.16.

A list of Siemens motors that fulfill the electrical and mechanical requirements is available at:

https://support.industry.siemens.com/cs/document/33512621

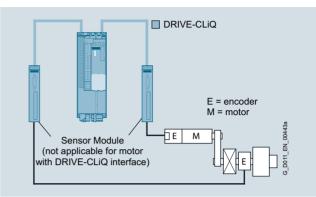
The following can be used for safe speed/position sensing:

- · Single-encoder systems or
- Dual-encoder systems



Example: Single-encoder system

In a single-encoder system, the motor encoder is used exclusively for safe actual value sensing. An incremental encoder or absolute encoder with photoelectric sampling must be used in this case.



Example: Dual-encoder system

In the case of the dual-encoder system, the safe actual values for a drive are provided by two separate encoders. HTL/TTL incremental encoders can be used as an alternative with a dualencoder system. Either two HTL/TTL encoders, one dual-HTL/ TTL encoder or one HTL/TTL encoder and one sin/cos encoder can be used.

The actual values are transferred to the Control Unit over DRIVE-CLiQ. When motors without a DRIVE-CLiQ connection are used, a Sensor Module (SMC20/30, SME20/25/120/125) must be provided. Each measuring system requires a separate DRIVE-CLiQ connection.

#### Safety Integrated for SINAMICS S120 Chassis Format Converter Units and Cabinet Modules, and for SINAMICS S150

### Overview

The safety functions integrated into the drive can greatly reduce the effort required to implement safety concepts.

The Safety Integrated functions are implemented electronically and therefore offer short response times compared to solutions with externally implemented monitoring functions.

As an alternative to controlling via terminals and/or PROFIsafe, there is also the option to parameterize several safety functions without selection. In this mode, after parameterization and a POWER ON, these functions are permanently selected.

#### Example

"SLS without selection" can be used, for example, to monitor the maximum velocity to prevent the drive from exceeding a mechanical speed limit. For this purpose, use of the "SLS without selection" function means that an F-DI is not needed.

#### Safety Integrated with and without encoder

The Safety Integrated Basic Functions STO, SBC and SS1 can be operated without an encoder. Two safety-capable incremental encoders (HTL or TTL) are required to allow use of the Safety Integrated Extended Functions SLS, SDI, SOS, SS2 and SSM. Each of these is connected to an SMC30 Sensor Module Cabinet (with SINAMICS S120 Cabinet Modules and SINAMICS S150: first SMC30 option **K50**, second SMC30 option **K52**). The minimum possible velocity resolution for an HTL/TTL encoder system must be taken into account.

# Further information can be found in the Safety Integrated Function Manual.

#### Licensing

The Safety Integrated Basic Functions do not require a license.

The Safety Integrated Extended Functions require one license for each axis with safety functions. It is of no consequence here which safety functions are used and how many.

The licenses for SINAMICS S120 chassis format units can be ordered as option **F01 to F05** for specific axes at the same time as the memory card. For SINAMICS S120 Cabinet Modules, the licenses can be ordered for specific axes with safety options **K01 to K05** for Motor Modules.

The license for SINAMICS S150 units can be ordered as option  $\pmb{K01}.$ 

#### Safe Brake Adapter

The Safe Brake Control (SBC) function requires a Safe Brake Adapter (option **K88** for SINAMICS S120 Cabinet Modules and SINAMICS S150). The Safe Brake Control is integrated in Motor Modules in booksize format.

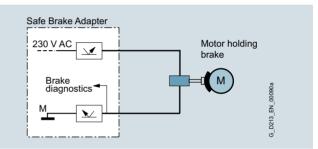
The Safe Brake Adapter and the brake control that is integrated in the booksize format allow safe control of electro-mechanical motor brakes.

The Safe Brake Adapter controls 230 VAC brakes. The SBC function monitors the control of the brake, however, not its mechanical functioning.

The converter controls the connected brake using the motor holding brake function.

External surge suppressors are not required. The cable harnesses for connection to the Power Module are included in the scope of supply.

The brake is controlled in accordance with IEC 61508 SIL 2 and EN ISO 13849-1 PL d and Category 3.



Safe Brake Control (SBC)

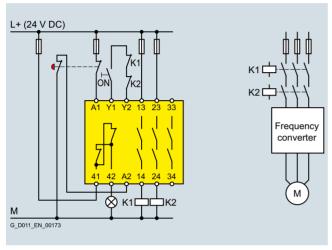
#### Safety Integrated for SINAMICS S120 Chassis Format Converter Units and Cabinet Modules, and for SINAMICS S150

# Benefits

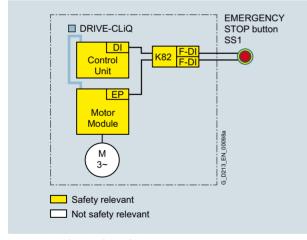
Comparison between conventional and integrated safety systems

The Safety Integrated functions are fully integrated in the drive system. They can be activated as follows:

#### Safe Torque Off (STO)



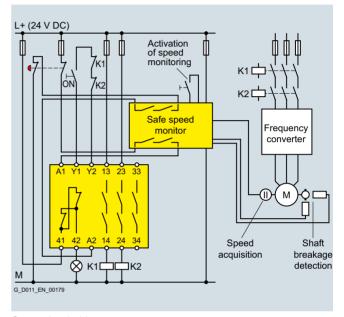
Conventional wiring



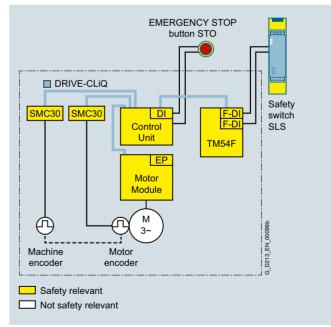
Integrated safety via fail-safe inputs

- Via safety-related inputs on the CU310-2 Control Unit or on the power unit (Basic Functions)
- Via safety-related inputs on the TM54F Terminal Module (Extended Functions)
- Via PROFIBUS or PROFINET with the PROFIsafe profile (Basic and Extended Functions)

#### Safely-Limited Speed (SLS)



Conventional wiring



Integrated safety via fail-safe inputs

The TM54F Terminal Module is not required when functions are selected via PROFIsafe.

# Safety Integrated for SINAMICS S120 Chassis Format Converter Units and Cabinet Modules, and for SINAMICS S150

# Function

# **Overview of Safety Integrated functions**

Function	Control	Underlying function	Reaction to limit overshoot	External set- point input effective	Encoder required <sup>1)</sup>	License required
Basic Fund	tions					
STO	<ul> <li>EP terminals on power unit and F-DI on CU310-2/D4xx/CX32</li> <li>Terminal module (option K82 <sup>2)</sup>)</li> <li>PROFIsafe</li> </ul>	SBC (if activated)	-	No	No	No
SBC	<ul> <li>With STO (immediately or following expiry of the delay time with SS1)</li> <li>Via Safe Brake Adapter <sup>2)</sup></li> </ul>	-	-	-	No	No
SS1	EP terminals on power unit and F-DI on CU310-2/D4xx/CX32     Terminal module (option <b>K82</b> <sup>2)</sup> )     PROFIsafe	STO, following expiry of the parameterized delay time, SBC (if activated)	STO	Can be parameter- ized	No	No
Extended F	unctions					
STO	<ul><li>F-DI on TM54F</li><li>PROFIsafe</li></ul>	SBC (if activated)	-	No	Yes	Yes
SS1 with SBR/SAM	F-DI on TM54F     F-DI on CU310-2/D4xx/CX32     PROFIsafe	Safe Acceleration Monitor (SAM) or Safe Brake Ramp (SBR) during braking. STO and SBC (if activated) following expiry of the parameterized delay time or if the speed falls below the minimum speed limit	STO	Can be parameter- ized	No	Yes
SS2	F-DI on TM54F     F-DI on CU310-2/D4xx/CX32     PROFIsafe	Safe Acceleration Monitor (SAM) during braking. Following expiry of the parame- terized delay time SOS	$SS1 \rightarrow STO$	No	Yes	Yes
SLS encoder- less	<ul> <li>F-DI on TM54F</li> <li>F-DI on CU310-2/D4xx/CX32</li> <li>PROFIsafe</li> <li>Continuously activated</li> </ul>	-	STO, SS1 (can be parameterized)	Yes	No	Yes
SLS	<ul> <li>F-DI on TM54F</li> <li>F-DI on CU310-2/D4xx/CX32</li> <li>PROFIsafe</li> <li>Continuously activated</li> </ul>	-	STO, SS1, SS2 or SOS (can be parameterized)	Yes	Yes	Yes
sos	<ul><li>F-DI on TM54F</li><li>F-DI on CU310-2/D4xx/CX32</li><li>PROFIsafe</li></ul>	-	$SS1 \rightarrow STO$	Yes	Yes	Yes
SSM	Always active, if configured	-	Signals that the speed has fallen below a specified value	Yes	No	Yes
SDI	<ul> <li>F-DI on TM54F</li> <li>F-DI on CU310-2/D4xx/CX32</li> <li>PROFIsafe</li> <li>Continuously activated</li> </ul>	-	STO, SS1, SS2 or SOS (can be parameterized)	Yes	No	Yes
SLP	F-DI on TM54F     F-DI on CU310-2/D4xx/CX32     PROFIsafe	-	STO, SS1, SS2 or SOS (can be parameterized)	Yes	Yes	Yes
SP	Always active, if configured	-	-	Yes	Yes	Yes
SBT	<ul> <li>F-DI on TM54F</li> <li>F-DI on CU310-2/D4xx/CX32</li> <li>PROFIsafe</li> </ul>	-	Signals test result. Warning if test fails	Yes	Yes	Yes

 $^{1)}\,$  The encoderless Safety Extended Functions can be implemented only on request for SINAMICS S120 chassis format units and cabinet units.

 In addition for SINAMICS S120 Cabinet Modules and SINAMICS S150 converter cabinet units (option K88).

# Overview

#### Communication overview

Digital bus systems are commonly used in industrial automation today. These handle communication between the control level, the machine control, the sensors and actuators. The SINAMICS product family offers integrated communication interfaces in all product groups – which can be used to connect the most important fieldbus systems in the simplest possible way.

The properties and special application areas of the different bus systems are described briefly below. The following table provides an overview of the protocols available for the CU310-2 and CU320-2 Control Units.

Protocol	CU310-2	CU320-2
PROFINET	✓	✓
PROFINET RT	✓	✓
<ul> <li>PROFINET IRT isochronous</li> </ul>	✓	✓
<ul> <li>PROFINET IRT not isochronous</li> </ul>	✓	✓
<ul> <li>PROFINET Shared Device</li> </ul>	✓	✓
PROFINET media redundancy MRP (non-seamless)	✓	√
<ul> <li>PROFINET media redundancy MRP (seamless)</li> </ul>	✓	√
<ul> <li>System redundancy S2</li> </ul>	✓	✓
PROFIsafe	✓	✓
PROFlenergy	✓	✓
<ul> <li>PROFIdrive application class 1</li> </ul>	✓	✓
<ul> <li>PROFIdrive application class 3</li> </ul>	✓	✓
<ul> <li>PROFIdrive application class 4</li> </ul>	$\checkmark$	✓
PROFIBUS DP	√	✓
<ul> <li>PROFIBUS DP equidistance and isochronous mode</li> </ul>	✓	√
<ul> <li>PROFIBUS DP slave-to-slave communication</li> </ul>	✓	√
EtherNet/IP	-	✓
Modbus TCP	-	✓
CANopen	-	✓
USS	✓	✓
Web server	✓	✓



#### **PROFINET** – the Ethernet standard for automation

PROFINET is the world's leading Industrial Ethernet standard for automation with more than 10 million nodes installed worldwide.

PROFINET makes companies more successful, because it speeds up processes and raises both productivity and plant availability.

#### Your advantages at a glance

Your advantages at a glance		
Flexibility	Efficiency	Performance
Tailor-made plant concepts	Optimal use of resources	Increased productivity
Industrial Wireless LAN	One cable for everything	▶ Speed
Safety	Device/network diagnostics	High precision
Flexible topologies	Energy efficiency	Large quantity structures
Open standard	Simple wiring	High transmission rate
Web tools	Fast device replacement	Redundancy
Expandability	Ruggedness/stability	Fast start-up

#### Overview (continued)

#### Flexibility

Short response times and optimized processes are the basic requirements for competitiveness in global markets because the product lifecycles are becoming shorter and shorter.

PROFINET ensures maximum flexibility in plant structures and production processes, and it enables you to implement innovative machine and plant concepts. For example, mobile devices can also be integrated at locations that are difficult to access.

#### Flexible topologies

In addition to the linear structure characterized by the established fieldbuses, PROFINET also enables the use of star, tree and ring structures. This is made possible by switching technology via active network components, such as Industrial Ethernet switches and media converters, or by integrating switch functionality into the field devices. This results in increased flexibility in the planning of machines and plants, as well as savings in cabling.

The PROFINET network can be installed without any specialist knowledge at all and meets all requirements that are relevant to the industrial environment. The "PROFINET Installations Guidelines" assist manufacturers and users with network planning, installation and commissioning. Symmetrical copper cables or RFI-resistant fiber-optic cables are used, depending on the application. Devices from different manufacturers are easily connected via standardized and rugged plug-in connectors (up to IP65/IP67 degree of protection).

By integrating switch functionality into the devices, linear topologies can be created that are directly oriented toward an existing machine or plant structure. This reduces cabling overhead and cuts down on components such as external switches.

#### IWLAN

PROFINET also supports wireless communication with Industrial Wireless LAN, thus opening up new fields of application. For example, technologies subject to wear, such as trailing cables, can be replaced and automated guided vehicle systems and mobile operator panels can be used.

#### Safety

The PROFIsafe safety profile, which has been tried and tested with PROFIBUS and which permits the transmission of standard and safety-related data on a single bus cable, can also be used with PROFINET. No special network components are necessary for fail-safe communication, which means that standard switches and standard network transitions can continue to be used without any restrictions. In addition, fail-safe communication is equally possible via Industrial Wireless LAN (IWLAN).

#### Open standard

PROFINET, the open multi-vendor standard (IEC 61158/ IEC 61784), is supported by PROFIBUS and PROFINET International (PI). It stands for maximum transparency, open IT communication, network security and simultaneous real-time communication.

Thanks to its openness, PROFINET provides the basis for a standardized automation network in the plant, to which all other machines and devices can be connected. Even the integration of existing plant components, for example using PROFIBUS, presents no problems due to the use of network transitions.

#### Use of web tools

Thanks to the unrestricted support of TCP/IP, PROFINET permits the use of standard web services in the device, such as web servers. Irrespective of the tool used, information from the automation level can be accessed from virtually any location using a commercially available Internet browser. This considerably simplifies commissioning and diagnostics. Users can then decide for themselves how much openness to the IT world they want to allow for their machine or plant. This means that PROFINET can be used simply as an isolated plant network or connected via appropriate security modules, such as the SCALANCE S modules, to the office network or the Internet. In this way, new remote maintenance concepts or the highspeed exchange of production data become possible.

#### Expandability

On the one hand, PROFINET facilitates the integration of existing systems and networks without any great effort. In this way, PROFINET safeguards investments in existing plant components that communicate via PROFIBUS and other fieldbuses such as AS-Interface. On the other hand, additional PROFINET nodes can be added at any time. By using additional network components, network infrastructures can be expanded using cabling or wireless methods – even while the plant is operating.

#### Communication > PROFINET

#### Overview (continued)

#### Efficiency

Greater global competition means that companies must use their resources economically and efficiently. This applies in particular to production. This is where PROFINET ensures greater efficiency. Simple engineering guarantees fast commissioning, while reliable devices ensure a high level of plant availability. Comprehensive diagnostic and maintenance concepts help to reduce plant downtimes and keep maintenance costs to a minimum.

#### One cable for everything

PROFINET permits simultaneous fieldbus communication with isochronous mode and standard IT communication (TCP/IP) on one cable. This real-time communication for the transmission of user/process data and diagnostic data takes place on a single cable. Specific profile communication (PROFIsafe, PROFIdrive and PROFIenergy) can be integrated without any additional cabling. This solution offers a wide scope of functions at a low level of complexity.

#### Device and network diagnostics

By retaining the tried and tested PROFIBUS device model, the same diagnostics information is available with PROFINET. In addition, module-specific and channel-specific data can also be read out from the devices during device diagnosis, enabling faults to be located quickly and easily. Apart from the availability of device information, the reliability of network operation has top priority in the network management.

In existing networks the Simple Network Management Protocol (SNMP) has established itself as the de facto standard for the maintenance and monitoring of the network components and their functions. PROFINET uses this standard and gives users the opportunity to maintain their networks with tools that are familiar to them, such as the SINEMA Server network management software.

For easier maintenance of PROFINET devices, both on-site and remotely via a secure VPN connection, application-specific websites can be set up on the integrated web server of the field devices using the familiar HTML standard.

#### Energy efficiency

Moving toward the green factory: PROFlenergy is a profile that provides functions and mechanisms for PROFINET field devices that support energy-efficient production.

The profile, which is defined by the PNO and is independent of any manufacturers or devices, enables energy demand and costs to be significantly reduced: Using PROFlenergy, any specific loads that are not currently being used can be switched off. This achieves a noticeable reduction in energy costs during breaks in production. PROFlenergy permits the simple, automated activation and deactivation of technologically related plant components. It is coordinated centrally by means of a higher-level controller and is networked via PROFINET. This ensures that as much energy as possible is saved during long breaks. Temporarily switching off plant components contributes to the even distribution and most efficient use of energy.

The use of PROFlenergy is made easy for the machine builder by its integration into familiar series of products. In addition, PROFlenergy is defined in such a way that the necessary function blocks can easily be integrated into existing automation systems at a later stage.

#### Simple wiring

Particularly stringent demands are made on the installation of cables in the industrial environment. In addition, there is a requirement to set up industry-standard networks in the shortest possible time without any special knowledge.

With FastConnect, Siemens offers a high-speed installation system that meets all of these requirements. FastConnect is the standard-compliant, industry-standard cabling system consisting of cables, connectors and assembly tools for PROFINET networks. The time required for connecting terminals is minimized by the simple installation method using just a single tool, while installation errors are prevented by the practical color-coding. Both copper cables and glass fiber optic cables can be easily assembled on site in this way.

#### Fast device replacement

PROFINET devices are identified by means of a name assigned during configuration. When replacing a defective device, a new device can be recognized from its topology information by the IO controller and a new name can be assigned to it automatically. This means that no engineering tool is necessary for the replacement of equipment.

This mechanism can even be used for the initial commissioning of a complete system. This speeds up commissioning, particularly in the case of series machines.

#### Ruggedness

An automation network must be able to withstand most external sources of interference. The use of Switched Ethernet prevents faults in one section of the network from affecting the entire plant network. For areas that are particularly prone to radio frequency interference (RFI), PROFINET allows the use of fiber optic cables.

## Overview (continued)

#### Performance

Productivity and product quality determine the level of success in the market. Precise motion control, dynamic drives, highspeed controllers and the deterministic synchronization of devices are therefore key factors in achieving superior production. They facilitate high production rates and optimum product quality at the same time.

#### Speed and precision

Fast motion control applications demand precise and deterministic exchange of data. This is implemented by means of drive controllers using isochronous real time (IRT).

With IRT and isochronous mode, PROFINET permits fast and deterministic communication. This synchronizes the various cycles of a system (input, network, CPU processing and output), even in the case of parallel TCP/IP traffic. The short cycle times of PROFINET make it possible to raise the productivity of machines and plants and to guarantee the product quality and high level of precision.

The standardized PROFIdrive profile permits vendor-independent communication between CPUs and drives.

#### Large quantity structures

The use of PROFINET makes it possible to overcome the existing restrictions regarding the scope of machines and systems that can be implemented. In one network, several different controllers can interact with their assigned field devices. The number of field devices per PROFINET network is virtually unlimited – the entire range of IP addresses is available.

#### High transmission rate

By using 100 Mbit/s in full duplex mode, PROFINET achieves a significantly higher data rate than previous fieldbuses. This means that other plant data can be transmitted over TCP/IP without any problems, in addition to the process data. PROFINET therefore meets the combined industrial demands for simultaneously transmitting high-speed IO data and large volumes of data for additional sections of the application. Even the transmission of large volumes of data, such as that from cameras, has no adverse effect on the speed and precision of the IO data transmission, thanks to PROFINET mechanisms.

#### Media redundancy

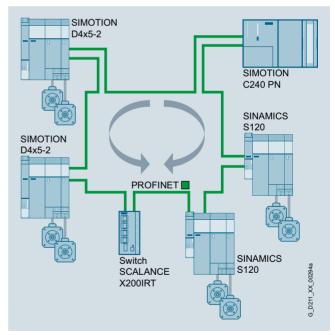
A higher plant availability can be achieved with a redundant installation (ring topology). The media redundancy can be implemented not only with the aid of external switches, but also by means of integrated PROFINET interfaces. Using the media redundancy protocol (MRP), reconfiguration times of 200 ms can be achieved. If the communication is interrupted in just one part of the ring installation this means that a plant standstill is prevented and any necessary maintenance or repair work can be performed without any time pressure.

For motion control applications, PROFINET with IRT in ring topologies offers extended media redundancy for planned duplication (MRPD) which operates in a bumpless mode without any reconfiguration time. If communication is interrupted (e.g. a cable break) the process can continue operating without interruption.

#### System redundancy

# SINAMICS S120 supports the PROFINET function "system redundancy":

SINAMICS S120 can now be connected to high-availability systems such as SIMATIC S7-400H with two controllers. No additional hardware is required to make the connection. Complex automation tasks in the process industry, in particular, where plant availability and redundancy of the control system are essential, require reliable communication with a high-availability system. Both controllers of the high-availability system always have access to the SINAMICS S120. In the event of a cable break or failure of a CPU, the other controller takes over, thus ensuring uninterrupted communication.



Seamless media redundancy illustrated by example of SINAMICS S120 with SIMOTION and SCALANCE X200IRT

## Highlights

## Communication > PROFINET

## Benefits

- PROFINET is the open Industrial Ethernet standard for automation
- PROFINET is based on Industrial Ethernet
- PROFINET uses TCP/IP and IT standards
- PROFINET is real-time Ethernet
- PROFINET enables seamless integration of fieldbus systems
- PROFINET supports fail-safe communication via PROFIsafe and also via IWLAN

### Integration

#### PROFINET – Functions of the SINAMICS S120/ SINAMICS S150 Control Units

SINAMICS S120/ SINAMICS S150	CU320-2 PN	CU320-2 DP (CBE20)	CU310-2 PN
PROFINET with IRT (isochronous mode)	✓	√	✓
Number of ports	2	4	2
Min. send clock in ms	0.25	0.5	0.25
Shared Device	√	✓	✓
Seamless media redundancy (MRPD)	✓	√	√
Non-seamless media redundancy (MRP)	✓	√	√
System redundancy S2	√	-	✓
PROFIsafe	✓	✓	✓
PROFlenergy	✓	✓	✓
PROFIdrive	√	✓	$\checkmark$

## More information

More information is available at www.siemens.com/profinet

## Highlights

# 2

## Communication > PROFIdrive

## One drive profile – different application classes

The integration of drives into automation solutions depends very strongly on the particular drive application. In order to be able to address the complete, huge bandwidth of drive applications – from basic frequency converters up to synchronized multi-axis systems with a high dynamic performance – using just one profile, PROFIdrive defines six application classes, to which most drive applications can be assigned:

- Class 1 standard drives (pumps, fans, agitators, etc.)
- Class 2 standard drives with technological functions
- Class 3 positioning drives
- Class 4 motion control drives with central, higher-level motion control intelligence and the patented "Dynamic Servo Control" positioning concept
- Class 5 motion control drives with central, higher-level motion control intelligence and position setpoint interface
- Class 6 motion control drives with distributed motion control intelligence integrated in the drives

### Design

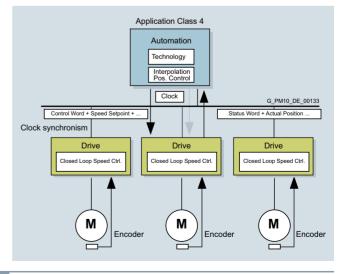
#### The device model of PROFIdrive

PROFIdrive defines a device model comprising function modules, which interoperate inside the device and which reflect the intelligence of the drive system. These modules have objects assigned to them which are described in the profile and are defined with respect to their functions. The overall functionality of a drive is therefore described through the sum of its parameters.

In contrast to other drive profiles, PROFIdrive defines only the access mechanisms to the parameters as well as a subset of profile parameters (approx. 30) such as the fault buffer, drive control and device identification.

All other parameters are vendor-specific which gives drive manufacturers great flexibility with respect to implementing control functions. The elements of a parameter are accessed acyclically over data records.

As a communication protocol, PROFIdrive uses DP-V0, DP-V1, and the DP-V2 expansions for PROFIBUS including the functions "Slave-to-Slave Communication" and "Isochronous Operation", or PROFINET IO with real-time classes RT and IRT.



#### More information

More information on PROFINET and PROFIBUS is available at www.profibus.com

See under Download / Technical description & books / PROFIdrive – Technology and Application - System Description

## Overview



# PROFIdrive – the standardized drive interface for PROFINET and PROFIBUS

PROFIdrive defines the device behavior and technique to access internal device data for electric drives connected to PROFINET and PROFIBUS – from basic frequency converters up to high-performance servo controllers.

It describes in detail the practical use of communication functions – slave-to-slave communication, equidistance and clock cycle synchronization (isochronous mode) in drive applications. In addition, it specifies all device characteristics which influence interfaces connected to a controller over PROFINET or PROFIBUS. This also includes the state machine (sequence control), the encoder interface, scaling of values, definition of standard telegrams, access to drive parameters etc.

The PROFIdrive profile supports both central as well as distributed motion control concepts.

#### What are profiles?

For devices and systems used in automation technology, profiles define properties and modes of behavior. This allows manufacturers and users to define common standards. Devices and systems that comply with such a cross-manufacturer profile, are interoperable on a fieldbus and, to a certain degree, can be interchanged.

#### Are there different types of profiles?

A distinction is made between what are known as application profiles (general or specific) and system profiles:

- Application profiles (also device profiles) predominantly refer to devices (e.g. drives) and include and agreed selection regarding bus communication as well as also specific device applications.
- System profiles describe classes of systems, including master functionality, program interfaces and integration resources.

### Is PROFIdrive fit for the future?

PROFIdrive has been specified by the PROFIBUS and PROFINET International (PI) user organization, and is specified as a standard that is fit for the future through standard IEC 61800-7.

#### The basic philosophy: Keep it simple

The PROFIdrive profile tries to keep the drive interface as simple as possible and free from technology functions. As a result of this philosophy, referencing models as well as the functionality and performance of the PROFINET/PROFIBUS master have either no influence or only a low influence on the drive interface.

#### Overview



# **PROFIBUS** – the proven, rugged bus system for automation engineering applications

The requirements of users for an open, non-proprietary communication system have resulted in the specification and standardization of the PROFIBUS protocol.

PROFIBUS defines the technical and functional features of a serial fieldbus system, with which the distributed field automation devices in the lower area (sensor/actuator level) can be networked up to the mid performance range (cell level).

Standardization according to IEC 61158/EN 50170 secures your investments for the future.

Using the conformity and interoperability test performed by the test laboratories authorized by PROFIBUS & PROFINET International (PI) and the certification of the devices by PI, users have the security of knowing that the quality and functionality is guaranteed, even in multi-vendor installations.

#### **PROFIBUS** versions

Two different PROFIBUS versions have been defined in order to comply with the widely varying requirements at field level:

- PROFIBUS PA (<u>Process Automation</u>) the version for applications in process automation. PROFIBUS PA uses the intrinsically safe transmission technology specified in IEC 61158-2.
- PROFIBUS DP (Distributed Periphery) this version, which is optimized for speed, is specifically tailored to the communication of automation systems with distributed I/O stations and drives. PROFIBUS DP sets itself apart as a result of very short response times and high noise immunity, and replaces costintensive, parallel signal transfer with 24 V and measured value transfer utilizing 0/4 ... 20 mA technology.

### Design

#### Bus participants on PROFIBUS DP

PROFIBUS DP makes a distinction between two different master classes and one slave class:

#### DP master class 1

For PROFIBUS DP, DP master class 1 is the central component. In a defined and continually repeating message cycle the central master station exchanges information with distributed stations (DP slaves).

#### DP master class 2

Devices of this type (programming, configuring or operator control devices) are used during commissioning, for configuring the DP system, for diagnostics or for operating the active plant or system. A DP master class 2 can, for example, read input, output, diagnostic and configuration data of the slaves.

### DP slave

A DP slave is an I/O device which receives output information or setpoints from the DP master, and as response, returns input information, measured values and actual values to the DP master. A DP slave never sends data automatically, but only when requested by the DP master.

The quantity of input and output information depends on the device, and for each DP slave in each send direction can be a maximum of 244 bytes.

### Function

#### Functional scope in DP masters and DP slaves

The functional scope can differ between DP masters and DP slaves. The different functional scopes are classified as DP-V0, DP-V1 and DP-V2.

#### **DP-V0** communication functions

The DP-V0 master functions consist of "Configuration", "Parameter Assignment" and "Reading Diagnostics Data", as well as cyclic reading of input data/actual values and writing output data/setpoints.

#### DP-V1 communication functions

The DP-V1 function expansions make it possible to perform acyclic read and write functions as well as processing cyclic data communication. This type of slave must be supplied with extensive parameterization data during start-up and during normal operation. These acyclically transferred parameterization data are only rarely changed in comparison to the cyclic setpoints, actual values, and measured values, and are transferred at lower priority in parallel with the cyclic high-speed user data transfer. Detailed diagnostic information can be transferred in the same way.

#### DP-V2 communication functions

The extended DP-V2 master functions mainly comprise functions for isochronous operation and slave-to-slave communication between DP slaves.

Isochronous mode:

Isochronous mode is implemented by means of an equidistant signal in the bus system. This cyclic, equidistant cycle is sent by the DP master to all bus nodes in the form of a Global Control Telegram. Master and slaves can then synchronize their applications with this signal. The signal jitter between cycles is less than 1  $\mu$ s.

• Slave-to-slave communication:

The "publisher/subscriber" model is used to implement slaveto-slave communication. Slaves declared as publishers make their input data/actual values and measured values available to other slaves, the subscribers, for reading. This is performed by sending the response frame to the master as a broadcast. Slave-to-slave communication is therefore a cyclic process.

#### **PROFIBUS** with SINAMICS

SINAMICS uses the PROFIBUS DP protocol.

SINAMICS drives can only be used as DP slaves.

## Overview



Ethernet is the basic Internet technology for worldwide networking. The many possibilities of intranet and Internet, which have been available for office applications for a long time, are now utilized for production automation with Industrial Ethernet.

Apart from the use of information technology, the deployment of distributed automation systems is also on the increase. This entails breaking up complex control tasks into smaller, manageable and drive-based control systems. This increases the demand for communication and consequently a comprehensive and powerful communication system.

Industrial Ethernet provides a powerful area and cell network for the industrial field, compliant with the IEEE 802.3 (ETHERNET) standard.

## Benefits

Ethernet enables a very fast data transfer (10/100 Mbit/s, 1/10 Gbit/s) and at the same time has full-duplex capability. It therefore provides an ideal basis for communication tasks in the industrial field. With a share of over 90 %, Ethernet is the number one network worldwide and offers important features which have essential advantages:

- · Fast commissioning thanks to the simplest connection method
- High availability since existing networks can be extended without any adverse effects
- Almost unlimited communication performance because scalable performance is available through switching technology and high data rates when required
- Networking of different application areas such as office and production areas
- Company-wide communication based on WAN (Wide Area Network) technology or the Internet
- Investment protection due to continuous compatibility with further developments
- Wireless communication using Industrial Wireless LAN

In order to make Ethernet suitable for industrial applications, considerable expansions with respect to functionality and design are required:

- Network components for use in harsh industrial environments
- Fast assembly of the RJ45 connectors
- · Fail-safety through redundancy
- Expanded diagnostics and message concept
- Use of future-oriented network components (e.g. switches)

SIMATIC NET offers corresponding network components and products.

## Integration

## Industrial Ethernet with SINAMICS

SINAMICS provides Control Units and Communication Boards with PROFINET interface based on 100 Mbit/s Ethernet. This means that process communication in real-time, as well as engineering and HMI via standard TCP/IP are simultaneously possible.

It is also possible to access the web server integrated in SINAMICS at the same time that process communication is in progress.

The CU310-2 and CU320-2 Control Units have an additional Ethernet interface at the front so that service and engineering tasks can be performed very easily.

#### Communication with SINAMICS over Industrial Ethernet

#### PG/PC/HMI communication

PG/PC/HMI communication is performed using protocols which are based on the basic TCP/IP protocol.

• Engineering and diagnostics with STARTER

#### IT communication

IT communication is performed using protocols which are based on the basic TCP/IP protocol. The most important IT protocols are:

- HTTP/HTTPS: Hypertext Transfer Protocol (Secure) Using a standard Internet browser, it is possible to retrieve predefined web pages containing diagnostic information from the device. Furthermore, user-defined web pages containing information defined by the user can be stored in the device.
- SNMP: Simple Network Management Protocol

## **Highlights**

### Overview



Ethernet Industrial Protocol (EtherNet/IP) is an open standard for industrial networks. EtherNet/IP is used to transmit cyclic I/O data and acyclic parameter data. EtherNet/IP was developed by the ODVA (Open DeviceNet Vendor Association) and belongs to the international standard series IEC 61158.

#### Communication > Modbus TCP

#### Overview



The Ethernet protocol Modbus TCP is an open standard for industrial networks. Modbus TCP is used to transmit acyclic register data. Modbus TCP has been standardized in the international series of standards IEC 61158 since 2007.

#### Communication > CANopen

### Overview



CANopen is a communication protocol based on CAN physical characteristics, which is predominantly used in the automation industry and for networking within complex devices. Originally conceived as a fieldbus for networking devices in motion control applications such as handling systems, CANopen has since established itself in the field of medical engineering, vehicle automation, rail and ship networking as well as building automation. Interoperability of CANopen is ensured through the use of application and device profiles, whereby the wide range of options offered by the bus specification enables an appropriate, precise selection to be made for the application or device in question. Furthermore, inverters with CANopen support the "CiA 402 Electrical Drives" device profile.

#### Communication > USS

#### Overview

As a simple fieldbus protocol, USS (**U**niversal **S**erial Interface protocol of Siemens AG, 1992) can be used both cyclically and acyclically. Based on RS485 physical bus characteristics, up to 32 nodes can be networked to one bus segment and connected to a higher-level controller. This protocol is generally used when there are limited demands on data throughput.





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#### System overview

#### Overview



With its separate power unit and Control Unit, the SINAMICS S120 drive system can be perfectly adapted to a wide variety of different drive tasks.

The Control Unit is selected according to the number of drives to be controlled and the required performance level, while the power unit must be rated to meet the energy requirements of the system. The connection between the Control Unit and power unit is made very simply using the DRIVE-CLiQ digital system interface.

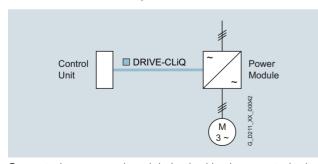
The following drive units are available in chassis format:

- Power Modules
- · Basic Line Modules
- Smart Line Modules (only available in the air-cooled version)
- Active Line Modules
- Active Interface Modules
- Motor Modules

#### **Power Modules**

The simplest version of a SINAMICS S120 drive system comprises a CU310-2 Control Unit and a Power Module.

In Power Modules specifically designed for single-motor drives without regenerative feedback into the line supply, the line-side infeed and the motor-side power unit are combined in one unit.



Generated energy produced during braking is converted to heat in braking resistors.

The Control Unit is plugged onto the Power Module; in addition to the complete control intelligence, the Control Unit also has all the drive interfaces for communication with higher-level systems and interfacing of add-on components.

#### Line Modules

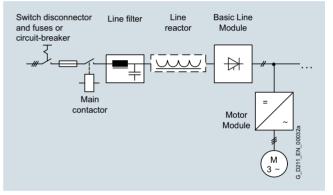
Line Modules contain the central line infeed for the DC link. Various Line Modules can be selected to address the various application profiles:

- Basic Line Modules
- Smart Line Modules
- Active Line Modules

#### **Basic Line Modules**

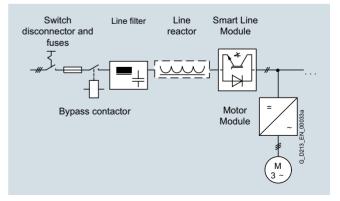
Basic Line Modules are designed only for infeed operation, i.e. they are not capable of recovering energy to the line supply. If regenerative energy is produced, e.g. when drives brake, it must be converted into heat using a Braking Module and a braking resistor.

A line filter can be optionally installed in order to ensure compliance with the limits stipulated for Category C2 in EN 61800-3.



#### Smart Line Modules

Smart Line Modules can supply energy and return regenerative energy to the supply system. A Braking Module and braking resistor are required only if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be recovered to the supply). For an infeed using a Smart Line Module, the appropriate line reactor is required. A line filter can be optionally installed in order to ensure compliance with the limits stipulated for Category C2 in EN 61800-3.



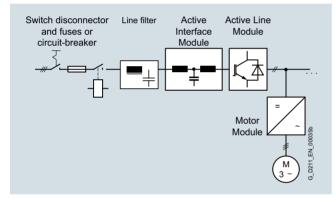
### Overview (continued)

### Active Line Modules

Active Line Modules can supply energy and return regenerative energy to the supply system. A Braking Module and braking resistor are required only if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be recovered to the supply).

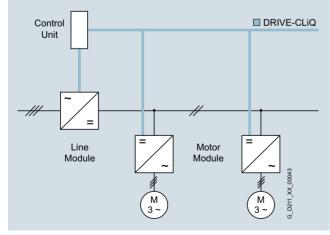
In contrast to Basic Line Modules and Smart Line Modules, Active Line Modules generate a controlled DC voltage that is kept constant despite fluctuations in the line supply voltage if the line supply voltage fluctuates within the permitted tolerance range. Active Line Modules in combination with an Active Interface Module draw a virtually sinusoidal current from the supply system. Almost no harmonics occur.

The total harmonic distortion factors of current THD(I) and voltage THD(U) are typically in the range of approx. 3 %. The stringent limit values of IEEE 519 (2014) are complied with. All of the components necessary to operate an Active Line Module are integrated in the Active Interface Module. A line filter can be optionally installed in order to ensure compliance with the limits stipulated for Category C2 in EN 61800-3.



#### Motor Modules

A voltage DC link and a converter for supplying a motor are integrated in the Motor Module.



Motor Modules are designed for multi-axis drive systems and are controlled by either a CU320-2 or a SIMOTION D Control Unit. Motor Modules are interconnected through the DC link.

One or several Motor Modules are supplied with energy for the motors via the DC link. Both synchronous and induction motors can be operated.

Since the Motor Modules share the same DC link, they can exchange energy with one another, i.e. if one Motor Module operating in generator mode produces energy, the energy can be used by another Motor Module operating in motor mode. The DC link is supplied with line supply voltage by a Line Module.

#### **Control Units**

The control intelligence for all the drive axes integrated in the multi-axis group is combined in the Control Units. They also feature drive-related inputs/outputs and interfaces for communicating with higher-level controllers. Control Units are available with different ranges of functions and with different performance levels.

#### System components

The structure of the drive system is defined by selecting the Control Unit and Power Module or Line Module and Motor Modules. The additional components provided allow optimum adaptation of the drive system to the application.

These components are subdivided into:

- Line-side components, e.g. line reactors and line filters
  DC link components e.g. Braking Modules and braking
- resistors
- Motor-side components, e.g. motor reactors and dv/dt filters plus VPL, sine-wave filters
- Supplementary system components, e.g. Terminal Modules, Operator Panels, and Communication Boards
- Encoder system interface for connecting various encoder types to SINAMICS S120

#### DRIVE-CLiQ – the digital interface between the components

SINAMICS S120 components, including motors and encoders, are equipped with the high-performance DRIVE-CLiQ system interface.

Line and Motor Modules for example are connected to the Control Unit – and Terminal Modules and Sensor Modules to the drive system via DRIVE-CLiQ – simply and efficiently. Motors that also have this interface can be directly connected to the drive system.

Converter boards (Sensor Modules) for converting standard encoder signals to DRIVE-CLiQ are available for third-party motors or retrofit applications.

#### The electronic rating plate

An important digital linkage element of the SINAMICS S120 drive system are the electronic rating plates integrated in every component. They allow all drive components to be automatically identified via the DRIVE-CLiQ link.

The electronic rating plate contains all the relevant technical data about that particular component. In addition to the technical data, the rating plate includes logistical data (manufacturer ID, article number and ID). Since this data can be called up electronically on site or remotely, all the components used in a machine can always be individually identified, which helps simplify servicing.

#### System overview

## Overview (continued)

#### **Coated modules**

The following devices are equipped as standard with coated modules:

- Blocksize format units
- Booksize format units
- Chassis format units
- Control Units
- Sensor Modules
- Terminal Modules
- Advanced Operator Panel (AOP30)

The coating on the modules protects the sensitive SMD components against corrosive gases, chemically active dust and moisture.

#### Nickel-plated busbars

All of the copper busbars used are nickel-plated in order to achieve the best possible immunity to environmental effects. Furthermore, there is no need to clean the contacts on the customer terminals as otherwise required for bare copper connections.

#### Note:

For some components, parts of the copper busbars cannot be nickel-plated for technical reasons.

## Function

# Communication with higher-level controller and customer terminal block

As customer interface to a higher-level control, as standard there is a PROFIBUS or PROFINET communication interface on the Control Unit CU320-2; there are also expansions such as the Terminal Module TM31, the Terminal Board TB30 and modules to communicate via CANopen or EtherNet/IP.

These interfaces can be used to connect the system to the higher-level controller using analog and digital signals, or to connect additional units.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### **Open-loop and closed-loop control functions**

SINAMICS S120 can use a dynamic, high-precision closed-loop vector control (drive object type VECTOR), or a highly dynamic closed-loop servo control (drive object type SERVO).

#### Software and protective functions

The software functions available as standard are described below:

Software and protective functions	Description
Setpoint input	The setpoint can be specified both internally and externally; internally as a fixed setpoint, motorized potentiometer setpoint or jog setpoint, externally via the communications interface or an analog input. The internal fixed setpoint and the motorized potentiometer setpoint can be switched or adjusted via control commands from any interface.
Motor identification	The automatic motor identification function makes commissioning faster and easier and optimizes closed-loop control of the drive.
Ramp-function generator	A user-friendly ramp-function generator with separately adjustable ramp-up and ramp-down times, together with adjustable rounding times in the lower and upper speed ranges, allows the drive to be smoothly accelerated and braked. This results in a good speed control response and contributes to the reduction of stress on the mechanical system. The down ramp can be parameterized separately for a quick stop.
V <sub>dc max</sub> controller	The V <sub>dc max</sub> controller automatically prevents overvoltages in the DC link, if the set down ramp is too short, for example. This may also extend the set ramp-down time.
	Note: This function only makes sense for single-axis applications.
Kinetic buffering (KIP)	For brief line supply failures, the kinetic energy of the rotating drive is used to buffer the DC link and therefore prevents fault trips. The drive converter remains operational as long as the drive can provide regenerative energy as a result of its motion and the DC link voltage does not drop below the shutdown threshold. When the line supply recovers within this time, the drive is again seamlessly accelerated up to its setpoint speed.
Automatic restart	The automatic restart switches the drive on again when the power is restored after a power failure, and ramps up to the current speed setpoint.
Flying restart	The flying restart function allows the converter to be switched to a motor that is still turning. With the voltage sensing capability provided by the optional VSM10, the flying restart time for large induction motors can be significantly reduced because the motor does not need to be de-magnetized.
Technology controller	Using the technology controller (PID controller) function module, level or flow controls and complex tension controls can be implemented, for example. The existing D component can act both on the system deviation well as on the actual value (factory setting). The P, I, and D components are set separately.
Free function blocks (FFB)	Using the freely programmable function blocks, it is easy to implement logic and arithmetic functions for controlling the SINAMICS drive. The blocks can be programmed at the operator panel or the STARTER commissioning tool.
Drive Control Chart (DCC)	Drive Control Chart (DCC) is an additional tool for the easy configuration of technological functions for SINAMICS. The block library contains a large selection of control, arithmetic and logic blocks as well as extensive open-loop and closed-loop control functions. The user-friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of charts that have already been created. DCC is an add-on for the STARTER commissioning tool ( $\rightarrow$ Tools and Engineering).
$f^2 t$ sensing for motor protection	A motor model stored in the converter software calculates the motor temperature based on the current speed and load. More exact measurement of the temperature, which also takes into account the influence of the ambient temperature, is possible by means of direct temperature measurement using KTY84 sensors in the motor winding.
Motor temperature evaluation	Motor protection by evaluating a KTY84, Pt1000, PTC or Pt100 temperature sensor. When a KTY84 temperature sensor is con- nected, the limit values can be set for alarm or shutdown. When a PTC thermistor is connected, the system reaction to trigger- ing of the thermistor (alarm or trip) can be defined.
Motor blocking protection	

System overview

Function (continued)			
Software and protective functions	Description		
Brake control	"Simple brake control" for control of holding brakes: The holding brake is used to secure drives against unwanted motion when deactivated.		
	"Extended brake control" function module for complex brake control, e.g. for motor holding brakes and operational brakes: When braking with a feedback signal, the brake control reacts to the feedback signal contacts of the brake.		
Write protection	Write protection to prevent unintentional changing of the setting parameters (without password function).		
	Know-how protection for encrypting stored data, e.g. to protect configuration know-how, and to protect against changes and duplication (with password function).		
Web server	The integrated web server provides information about the drive unit via its web pages. The web server is accessed using a web browser via unsecured (http) or secured transfer protocol (https).		
Power unit protection			
Power unit protection	Description		
Ground fault monitoring at the output	A ground fault at the output is detected by a total current monitor and results in shutdown in grounded systems.		
	A short-circuit at the output (e.g. at the converter output terminals, in the motor cable or in the motor terminal box) is detected and the converter shuts down with a "fault".		
	An alarm is issued first when the overtemperature threshold responds. If the temperature continues to rise, the unit either shuts down or independently adjusts the pulse frequency or output current so that thermal load is reduced. Once the cause of the fault has been eliminated (e.g. cooling has been improved), the original operating values are automatically resumed.		

## Technical specifications

The most important directives and standards are listed below. These are used as the basis for the SINAMICS S120 built-in units in chassis format and they must be carefully observed to achieve an EMC-compliant configuration that is safe both functionally and in operation.

European directives	
2014/35/EU	Low-voltage directive: Directive of the European Parliament and Council of February 26, 2014, for the harmonization of the laws of the member states relating to the provision of electrical equipment designed for use within certain voltage limits on the market (amended version)
2014/30/EU	EMC directive: Directive of the European Parliament and Council of February 26, 2014, for the harmonization of the laws of the member states relating to electromagnetic compatibility (amended version)
2006/42/EC	Machinery Directive: Directive of the European Parliament and Council of May 17, 2006, on machinery and amending Directive 95/16/EC (amended version).
European standards	
EN ISO 3744	Acoustics – Determination of the sound power level and sound energy level for noise sources that result from sound pressure measurements – envelope surface procedure of the accuracy class 2 for a largely free sound field over a reflecting plane
EN ISO 13849-1	Safety of machinery – safety-related parts of control systems; Part 1: General design guidelines (EN ISO 13849-1: 2006) (replaces EN 954-1)
EN 60146-1-1	Semiconductor converters – General requirements and line-commutated converters Part 1-1: Specification of basic requirements
EN 60204-1	Safety of machinery – Electrical equipment of machines; Part 1: General requirements
EN 60529	Degrees of protection provided by enclosures (IP code)
EN 61508-1	Functional safety of electrical/electronic/programmable electronic safety-related systems Part 1: General requirements
EN 61800-2	Adjustable speed electrical power drive systems Part 2: General requirements – Rating specifications for low voltage adjustable frequency AC power drive systems
EN 61800-3	Adjustable speed electrical power drive systems Part 3: EMC requirements and specific test methods
EN 61800-5-1	Adjustable speed electrical power drive systems Part 5: Safety requirements Main section 1: Electrical and thermal requirements
EN 61800-5-2	Adjustable speed electrical power drive systems Part 5-2: Safety requirements – Functional safety (IEC 61800-5-2: 2007)
North American standard	
UL 508A	Industrial Control Panels
UL 508C	Power Conversion Equipment
UL 61800-5-1	Adjustable Speed Electrical Power Drive Systems - Part 5-1: Safety requirements – Electrical, thermal and energy
CSA C22.2 No. 14	Industrial Control Equipment
Certificates of suitability	
cULus, cURus	Testing by UL (Underwriters Laboratories, www.ul.com) according to UL and CSA standards
Mark of conformity and $(\rightarrow Appendix, Approva$	

3

Air-cooled units

## Technical specifications

## General technical specifications

Unless clearly specified otherwise, the following technical data are valid for all the following components of the air-cooled SINAMICS S120 drive system in chassis format.

Electrical specifications	
Rated voltages	380 480 V 3 AC ±10 % (-15 % <1 min)
	500 690 V 3 AC ±10 % (-15 % <1 min)
Line supply types	Grounded TN/TT systems and non-grounded IT systems
Line frequency	47 63 Hz
Overvoltage category	III to EN 61800-5-1
Electronics power supply	24 V DC, -15 % +20 % implemented as PELV circuit in accordance with EN 61800-5-1 Ground = negative pole grounded via the electronics
Rated short-circuit current per IEC, in conjunction with the specified fuses or circuit breakers	
• 1.1 447 kW	65 kA
• 448 671 kW	84 kA
• 672 1193 kW	170 kA
• > 1194 kW	200 kA
Rated short-circuit current SCCR (Short Circuit Current Rating) according to UL508C (up to 600 V), in conjunction with the specified fuses or circuit breakers	
• 1.1 447 kW	65 kA
• 448 671 kW	84 kA
• 672 1193 kW	170 kA
• > 1194 kW	200 kA
Control method	Vector/Servo control with and without encoder or V/f control
Fixed speeds	15 fixed speeds plus 1 minimum speed, parameterizable (in the default setting, 3 fixed setpoints plus 1 minimum speed are selectable using terminal block/PROFIBUS/ PROFINET)
Skippable speed ranges	4, parameterizable
Setpoint resolution	0.001 rpm digital (14 bits + sign) 12 bits analog
Braking operation	With Active Line Modules and Smart Line Modules, four-quadrant operation as standard (energy recovery). With Basic Line Modules, two-quadrant operation as standard, braking by means of an optional braking chopper, or alternatively by a Motor Module.
Mechanical specifications	
Degree of protection	IP00 or IP20 depending on type
Protection class	I acc. to EN 61800-5-1
Touch protection	EN 50274/DGUV regulation 3 when used as intended
Cooling method	Forced air cooling AF according to EN 60146

Air-cooled units

Ambient conditions	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation		
Ambient temperature	-25 +55 °C Class 1K4 acc. to EN 60721-3-1	<u>-25</u> +70 °C Class 2K4 acc. to EN 60721-3-2	Line-side components, Power Modules, Line Modules and Motor Modules: 0 40 °C without derating Up to 55 °C, see derating data Control Units, supplementary syste components, and Sensor Modules: 0 55 °C (for operation in a control cabinet) DC link components and motor-side components: 0 55 °C		
Relative humidity	5 95 %	5 95 % at 40 °C	5 95 %		
Condensation, splashwater, and ice formation not permitted (EN 60204, Part 1)	Class 1K4 acc. to EN 60721-3-1	Class 2K3 acc. to EN 60721-3-2	Class 3K3 acc. to EN 60721-3-3		
Environmental class/ harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3		
Organic/ biological influences	Class 1B1 acc. to EN 60721-3-1	Class 2B1 acc. to EN 60721-3-2	Class 3B1 acc. to EN 60721-3-3		
Degree of pollution	2 acc. to EN 61800-5-1				
Installation altitude	Up to 2000 m above sea level without derating >2000 m above sea level, see derating data				
Mechanical stability	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation		
Vibratory load	-	Class 2M2 acc. to EN 60721-3-2	Test values acc. to EN 60068-2-6 test Fc:		
			<ul> <li>10 58 Hz with constant deflection 0.075 mm</li> <li>58 150 Hz with constant acceleration 9.81 m/s<sup>2</sup> (1 × g)</li> </ul>		
Shock load	-	Class 2M2 acc. to EN 60721-3-2	Test values according to EN 60068-2-27 test 98 m/s <sup>2</sup> (10 × $g$ )/20 ms		
Compliance with standards					
Conformances/ certificates of suitability, according to	CE (EMC Directive No. 2014/30/EU, Low Voltage Directive No. 2014/35/EU, and Machinery Directive 2006/42/EC for functional safety) RCM, RoHS II cULus (only for devices connected to line supply voltages 380 480 V 3 AC and 500 600 V 3 AC)				
Radio interference suppression	SINAMICS S120 chassis format units are not designed for connection to the public grid (first environment). Radio interference suppression is compliant with the EMC product standard for variable-speed drives EN 61800-3, "Second environment" (industrial line supplies). EMC disturbances can occur when connected to the public grid. However, if additional measures are taken (e.g. $\rightarrow$ line filter), it can also be operated in the "first environment".				

Deviations from the specified class are <u>underlined</u>.

Air-cooled units

## Characteristic curves

#### Derating data, chassis format

Air-cooled SINAMICS G120 chassis format units and the associated system components are rated for an ambient temperature of 40 °C and installation altitudes up to 2000 m above sea level.

At ambient temperatures > 40 °C, the output current must be reduced. Ambient temperatures above 55 °C are not permissible.

At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease

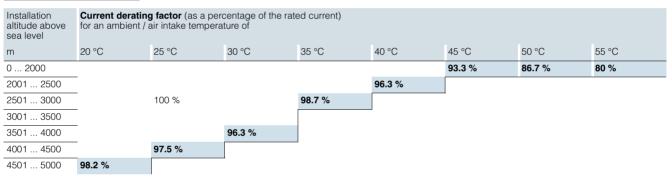
Due to the reduced cooling efficiency, it is necessary, on the one hand, to reduce the ambient temperature and on the other hand. to reduce the heat loss in the built-in unit by reducing the output current, whereby ambient temperatures lower than 40 °C may be offset to compensate.

The following table lists the permissible output currents depending on the installation altitude and ambient temperature. The specified values already include a permitted compensation in respect of installation altitude and ambient temperatures < 40 °C (temperature at the air intake of the built-in unit).

The values apply under the precondition that a cooling air flow through the devices is guaranteed as specified in the technical specifications.

As additional measure for installation altitudes from 2000 m up to 5000 m, an isolating transformer is required in order to reduce transient overvoltages according to EN 60664-1. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Current derating factors for SINAMICS S120 chassis units as a function of the ambient/air intake temperature and the installation altitude



#### Current derating for Power Modules and Motor Modules in chassis format as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased, the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications.

#### For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

The following table lists the rated output currents of the SINAMICS S120 Power Modules and Motor Modules with pulse frequency set in the factory as well as the current derating factors (permissible output currents referred to the rated output current) for higher pulse frequencies.

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 2 kHz

Power Module Motor Module	Type rating at 400 V	Output current at 2 kHz	Derating factor at pulse freque				
6SL3310 6SL3320	kW	A	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC							
1TE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %
1TE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %
1TE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %
1TE33-8AA3	200	380	96 %	87 %	77 %	54 %	50 %
1TE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %

Air-cooled units

## Characteristic curves (continued)

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 1.25 kHz

Motor Module	Type rating at 400 V or 690 V	Output current at <u>1.25 kHz</u>	Derating at pulse fr					
6SL3320	kW	А	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC								
1TE36-1AA3	315	605	83 %	72 %	64 %	60 %	40 %	36%
1TE37-5AA3	400	745	83 %	72 %	64 %	60 %	40 %	36%
1TE38-4AA3	450	840	87 %	79 %	64 %	55 %	40 %	37 %
1TE41-0AA3	560	985	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-2AA3	710	1260	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-4AA3	800	1405	97 %	95 %	74 %	60 %	50 %	47 %
500 690 V 3 AC								
1TG28-5AA3	75	85	93 %	89 %	71 %	60 %	40 %	-
1TG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %	-
1TG31-2AA3	110	120	92 %	88 %	71 %	60 %	40 %	-
1TG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %	-
1TG31-8AA3	160	175	92 %	87 %	70 %	60 %	40 %	-
1TG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %	-
1TG32-6AA3	250	260	92 %	88 %	71 %	60 %	40 %	-
1TG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %	-
1TG34-1AA3	400	410	89 %	82 %	65 %	55 %	35 %	-
1TG34-7AA3	450	465	92 %	87 %	67 %	55 %	35 %	-
1TG35-8AA3	560	575	91 %	85 %	64 %	50 %	35 %	-
1TG37-4AA3	710	735	87 %	79 %	64 %	55 %	25 %	-
1TG38-1AA3	800	810	97 %	95 %	71 %	55 %	35 %	-
1TG38-8AA3	900	910	92 %	87 %	67 %	55 %	33 %	-
1TG41-0AA3	1000	1025	91 %	86 %	64 %	50 %	30 %	-
1TG41-3AA3	1200	1270	87 %	79 %	55 %	40 %	25 %	-

The following tables list the maximum achievable output frequency as a function of the pulse frequency:

Maximum output frequencies achieved by increasing the pulse frequency in Vector mode

Maximum output frequencies achieved by increasing the pulse	Э	
frequency in Servo mode		

Pulse frequency	Max. achievable output frequency
1.25 kHz	100 Hz
2 kHz	160 Hz
2.5 kHz	200 Hz
4 kHz	300 Hz

Pulse frequency	Max. achievable output frequency
2 kHz	300 Hz
4 kHz	300/550 Hz <sup>1)</sup>

Air-cooled units

#### Characteristic curves (continued)

#### **Overload capability**

SINAMICS S120 chassis units have an overload reserve, e.g. to handle breakaway torques. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base-load current must, therefore, be used as a basis for the required load.

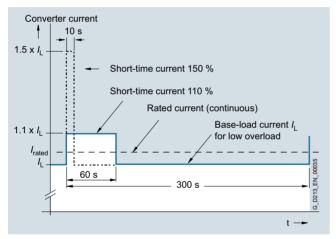
The permissible overload levels are valid under the prerequisite that the drive units are operated with their base-load current before and after the overload condition based on a duty cycle duration of 300 s.

Another precondition is that the Power Modules or the Motor Modules are operated at their factory-set pulse frequency at output frequencies > 10 Hz.

For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

#### Power Modules and Motor Modules

The base-load current for a low overload  $I_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s.



#### Low overload

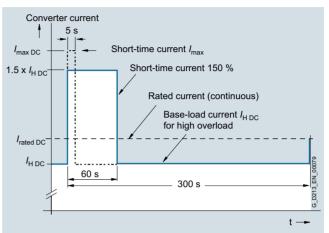
cycle of 150 % for 60 s or 160 % for 10 s. Converter current 10 s 1.6 x I<sub>H</sub> Short-time current 160 % 1.5 x I<sub>H</sub> Short-time current 150 % Rated current (continuous) Base-load current I<sub>H</sub> for high overload I<sub>rated</sub>  $I_{\rm H}$ 60 s Ш 300 s D213 ഠ t –

The base-load current for a high overload  $I_{\rm H}$  is based on a duty

High overload

### Line Modules

The base-load current for a high overload  $I_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s.



High overload

Air-cooled units

### Overview



The Power Module comprises a line rectifier, a DC link and a converter to supply the motor.

Power Modules are designed for drives that are not capable of regenerating energy to the mains supply. Regenerative energy produced while braking is converted to heat using braking resistors.

Power Modules in the chassis format can be connected to grounded TN/TT systems and non-grounded IT systems.

### Design

The Power Modules have the following interfaces as standard:

- 1 line supply connection
- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCPA, DCNA) for connecting a Braking Module
- 1 DC link connection (DCPS, DCNS) for connecting a dv/dt filter
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections

The Power Modules are controlled by the CU310-2 Control Unit that can be integrated into the Power Module.

The status of the Power Modules is indicated via three LEDs.

The scope of supply of the Power Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 1 24 V DC connecting cable for the power supply to the Control Unit
- 1 mounting plate for attaching the Control Unit
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

#### Application in multi-axis systems

Power Modules in chassis format can also be connected directly via DRIVE-CLiQ to a separate CU320-2 or SIMOTION D4x5-2 Control Unit or Controller Extension CX32-2. The appropriate DRIVE-CLiQ cable for the required distance must be ordered (see section MOTION-CONNECT connection systems).

#### Selection and ordering data

Type rating at 400 V	Rated output current	Power Module
kW	А	Article No.
Line voltage 380	480 V 3 AC	
110	210	6SL3310-1TE32-1AA3
132	260	6SL3310-1TE32-6AA3
160	310	6SL3310-1TE33-1AA3
200	380	6SL3310-1TE33-8AA3
250	490	6SL3310-1TE35-0AA3

Article No.

6SL3066-4CA00-0AA0

Description

Accessories for re-ordering

Dust protection blanking plugs	
(50 units)	

For DRIVE-CLiQ port

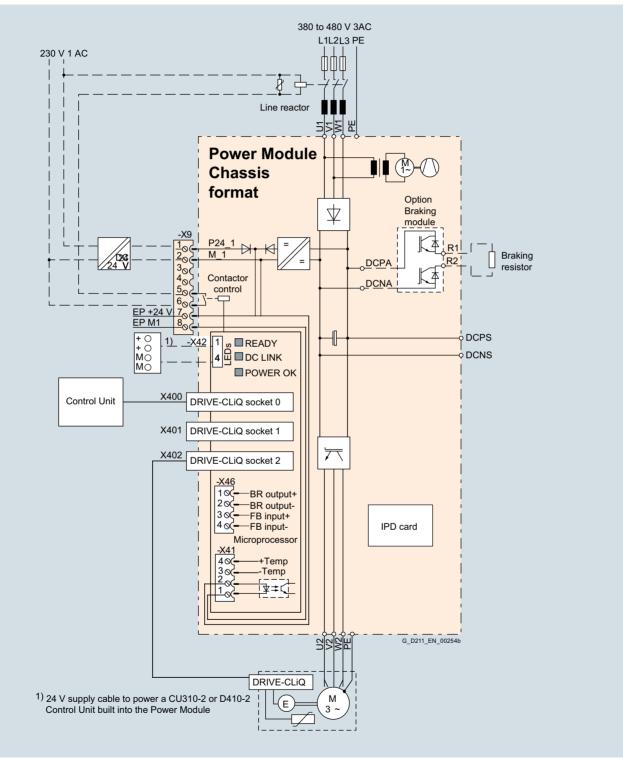
For line and motor-side components, Braking Modules as well as recommended line-side system components. see System components.

Air-cooled units

### **Power Modules**

## Integration

The Power Modules communicate with the higher-level control module via DRIVE-CLiQ. The Control Unit in this case could be a CU310-2, CU320-2 or a SIMOTION D Control Unit.



Connection example of a Power Module

#### Note:

The integrated 24 V power supply at connector X42 can have a maximum load of 2 A. When the Control Unit is supplied from the integrated power supply, the total load of the digital outputs must be carefully observed to ensure that the 2 A is not exceeded.

Air-cooled units

**Power Modules** 

## Technical specifications

### General technical specifications

Electrical specifications	
Line connection voltage Up to 2000 m above sea level	380 480 V 3 AC ±10 % (-15 % <1 min)
<ul> <li>Line power factor</li> <li>for a 3 AC line supply voltage</li> <li>and output power</li> <li>Basic fundamental (cos \u03c6<sub>1</sub>)</li> </ul>	>0.96
• Total ( $\lambda$ )	0.75 0.93
DC link voltage, approx. <sup>1)</sup>	1.35 × line voltage
Output voltage, approx.	0.97 x U <sub>line</sub>
Output frequency <sup>2)</sup>	
Control mode Servo	0 550 Hz
Control mode Vector	0 550 Hz
Control mode V/f	0 550 Hz
Main contactor control	
Terminal block -X9/5-6	240 V AC, max. 8 A 30 V DC, max. 1 A
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1

The DC link voltage is unregulated and load-dependent. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

2) Please note:

Please note:
 Note the correlation between max. output frequency, pulse frequency and current derating. Higher output frequencies on request. For further information, see https://support.industry.siemens.com/cs/document/104020669
 The correlation between the minimum output frequency and permissible output current (current derating). Information is provided in the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

#### **Power Modules**

## **Technical specifications** (continued)

Line voltage 380 480 V 3 AC	Power Modules						
		6SL3310- 1TE32-1AA3	6SL3310- 1TE32-6AA3	6SL3310- 1TE33-1AA3	6SL3310- 1TE33-8AA3	6SL3310- 1TE35-0AA3	
<b>Type rating</b> • At <i>I</i> <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	200	250	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	160	200	
• At I <sub>1</sub> (60 Hz 460 V) <sup>2)</sup>							
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp hp	150 150	200 200	250 200	300 250	400 350	
Output current	пр	100	200	200	200		
Rated current I <sub>rated O</sub>	А	210	260	310	380	490	
Base-load current IL <sup>3)</sup>	А	205	250	302	370	477	
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	178	233	277	340	438	
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	307	375	453	555	715	
Input current <ul> <li>Rated input current I<sub>rated I</sub></li> </ul>	٨	220	00.4	220	205	500	
Maximum input current Imax I	A	229	284	338	395	509	
	A	335	410	495	606	781	
<ul><li>• 24 V DC auxiliary power supply</li></ul>	A	0.8	0.8	0.9	0.9	0.9	
Pulse frequency <sup>5)</sup>	A	0.0	0.0	0.9	0.9	0.9	
	kHz	2	2	2	2	2	
Rated frequency     Dulas frequency	КПИ	2	2	2	2	2	
Pulse frequency, max.		0	0	0	0	0	
- Without current derating	kHz	2	2	2	2	2	
- With current derating	kHz	8	8	8	8	8	
Power loss, max. <sup>6)</sup>							
• At 50 Hz 400 V	kW	2.46	3.27	4	4.54	5.78	
• At 60 Hz 460 V	kW	2.54	3.36	4.07	4.67	5.96	
Cooling air requirement	m <sup>3</sup> /s	0.17	0.23	0.36	0.36	0.36	
<b>Sound pressure level L<sub>pA</sub></b> (1 m) at 50/60 Hz	dB	64/67	71/71	69/73	69/73	69/73	
Line connection U1, V1, W1		M10 screw					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Motor connection U2/T1, V2/T2, W2/T3		M10 screw					
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Cable length, max. <sup>7)</sup>							
Shielded	m	300	300	300	300	300	
Unshielded	m	450	450	450	450	450	
PE1/GND connection		M10 screw					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
PE2/GND connection		M10 screw					
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Degree of protection		IP20	IP20	IP20	IP20	IP20	
Dimensions							
Width	mm	326	326	326	326	326	
Height	mm	1400	1400	1533	1533	1533	
• Depth	mm	356 <sup>8)</sup>	356 <sup>8)</sup>	549	549	549	
Weight, approx.	kg	104	104	162	162	162	
Frame size	3	FX	FX	GX	GX	GX	
Minimum short-circuit current <sup>9)</sup>	А	3000	3600	4400	4400	8000	
a)							

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

<sup>2)</sup> Rated output of a typical 6-pole standard induction motor based on  $I_{\rm L}$  or  $I_{\rm H}$  for 460 V 3 AC 60 Hz.

<sup>3)</sup> The base-load current  $I_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{\rm 4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>8)</sup> Depth = 421 mm including front cover when CU310-2 Control Unit is installed.

<sup>9)</sup> Current required for reliably triggering protective devices.

Air-cooled units

### **Basic Line Modules**

Overview



Basic Line Modules are available for applications in which no energy is returned to the supply or where the energy exchange between motor and generator axes takes place in the DC link. Basic Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

The Basic Line Modules are available in different frame sizes. With frame sizes FB and GB, a fully controlled thyristor bridge is used to pre-charge the Basic Line Modules and connected Motor Modules. The thyristors normally operate with a trigger delay angle of  $0^{\circ}$ .

Basic Line Modules, frame size GD for 900 kW (400 V) or 1500 kW (690 V) include a diode bridge, and the DC link is pre-charged via a separate line-side pre-charging circuit.

A Braking Module of the appropriate frame size can be integrated into a Basic Line Module in order to permit, in conjunction with an external braking resistor, regenerative operation of the drive system ( $\rightarrow$  DC link components).

#### Design

The Basic Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 1 DC link connection (DCPA, DCNA) for connecting a Braking Module
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000 or PTC (Pt1000 can be used from firmware V4.7 HF17)
- 1 PE connection

The status of the Basic Line Modules is indicated via three LEDs.

The scope of supply of the Basic Line Modules includes:

- DRIVE-CLiQ cable to connect to a Control Unit
- DRIVE-CLiQ cable to connect the Control Unit to the first Motor Module
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

# Pre-charging circuit for the Basic Line Modules, frame size GD

Unlike Basic Line Modules in frame sizes FB and GB, a Basic Line Module in frame size GD requires a separate pre-charging circuit. The pre-charging circuit components must be ordered separately.

During startup, the pre-charging circuit ensures that the DC link capacitors of the Basic Line Module and the connected Motor Modules are pre-charged with current limiting. After pre-charging has been completed, the circuit breaker is closed and the pre-charging circuit bypassed; the Basic Line Module is then directly connected to the line supply.

The pre-charging circuit comprises a pre-charging contactor and pre-charging resistors; the circuit must be protected against overcurrent using suitable protection measures. To increase the permissible DC link capacitance, the pre-charging resistors can also be connected in parallel in each phase.

More information on the pre-charging circuit is to be found in the SINAMICS Low Voltage Engineering Manual.

For components for the pre-charging circuit and for recommended line-side system components, see System components.

### Selection and ordering data

Rated power at 400 V or 690 V	Rated DC link current	Basic Line Module						
kW	A	Article No.						
Line voltage 380 480 V 3 AC								
200	420	6SL3330-1TE34-2AA3						
250	530	6SL3330-1TE35-3AA3						
400	820	6SL3330-1TE38-2AA3						
560	1200	6SL3330-1TE41-2AA3						
710	1500	6SL3330-1TE41-5AA3						
900	1880	6SL3330-1TE41-8AA3						
Line voltage 500 6	90 V 3 AC							
250	300	6SL3330-1TG33-0AA3						
355	430	6SL3330-1TG34-3AA3						
560	680	6SL3330-1TG36-8AA3						
900	1100	6SL3330-1TG41-1AA3						
1100	1400	6SL3330-1TG41-4AA3						
1500	1880	6SL3330-1TG41-8AA3						
Description		Article No.						
Accessories for re-o	rdering							
<b>Dust protection blan</b> (50 units) For DRIVE-CLiQ port	king plugs	6SL3066-4CA00-0AA0						

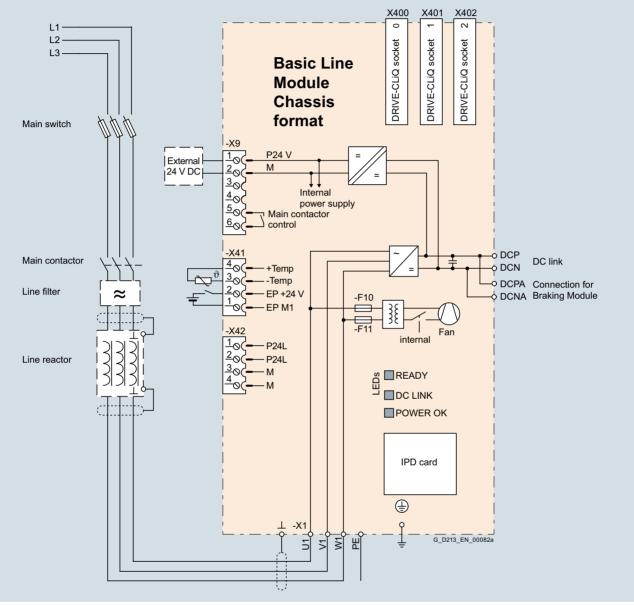
For line-side components and recommended line-side system components, see System components.

Air-cooled units

### **Basic Line Modules**

## Integration

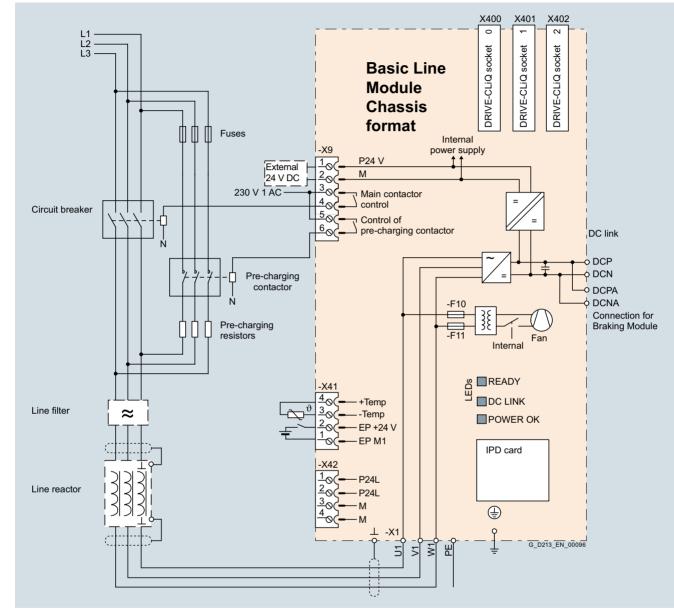
The Basic Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate Basic Line Modules.



Connection example of a Basic Line Module, frame sizes FB, GB

Air-cooled units

**Basic Line Modules** 



Connection example of a Basic Line Module, frame size GD

Integration (continued)

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Air-cooled units

### **Basic Line Modules**

### Technical specifications

#### General technical specifications

Electrical specifications							
Line power factor							
at rated power							
• Basic fundamental (cos $\varphi_1$ )	>0.96						
• Total ( $\lambda$ )	0.75	0.93					
Efficiency	>99 %						
DC link voltage, approx. <sup>1)</sup>		ine voltage under p ine voltage under f					
Main contactor control							
Terminal block -X9/5-6		C, max. 8 A C, max. 1 A					
Line voltage 380 480 V 3 AC		Basic Line Modu					
		6SL3330- 1TE34-2AA3	6SL3330- 1TE35-3AA3	6SL3330- 1TE38-2AA3	6SL3330- 1TE41-2AA3	6SL3330- 1TE41-5AA3	6SL3330- 1TE41-8AA3
Rated power							
<ul> <li>At I<sub>rated DC</sub> (50 Hz 400 V)</li> </ul>	kW	200	250	400	560	710	900
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	160	200	315	450	560	705
<ul> <li>At I<sub>rated DC</sub> (60 Hz 460 V)</li> </ul>	hp	305	385	615	860	1090	1390
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	245	305	485	690	860	1090
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	420	530	820	1200	1500	1880
<ul> <li>Base-load current I<sub>H DC</sub><sup>2)</sup></li> </ul>	А	328	413	640	936	1170	1467
<ul> <li>Maximum current I<sub>max DC</sub></li> </ul>	А	630	795	1230	1800	2250	2820
Input current     Ated current Irated I	A	365	460	710	1010	1265	1630
Maximum current Imax I	A	547	690	1065	1515	1203	2380
Max. pre-charging current (max. 3 s)	A	Internal	Internal	Internal	Internal	Internal	308
Current demand	A	Internal	Internal	Internal	Internal	Internal	306
	А	1.1	1.1	1.1	1.1	1.1	1.1
• 24 V DC auxiliary power supply DC link capacitance	A	1.1	1.1	1.1	1.1	1.1	1.1
Basic Line Module	μF	7200	9600	14600	23200	29000	34800
<ul> <li>Dasic Line Module</li> <li>Drive line-up, max.</li> </ul>	μr μF	57600	76800	116800	185600	232000	139200/278400 3)
• Drive line-up, max.	μr	57600	70800	110000	165600	232000	3)
Power loss, max. <sup>4)</sup>							
• At 50 Hz 400 V	kW	1.9	2.1	3.2	4.6	5.5	6.9
• At 60 Hz 460 V	kW	1.9	2.1	3.2	4.6	5.5	6.9
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.36	0.36	0.36
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	66/68	66/68	66/68	71/73	71/73	71/73
Line connection		Flat connector	Flat connector	Flat connector	Flat connector	Flat connector	Flat connector
U1, V1, W1	2	for M10 screw	for M10 screw	for M10 screw	for M12 screw	for M12 screw	for M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	6 × 185	6 × 185	6 × 185
DC link connection DCP, DCN	2	M10 screw	M10 screw	M10 screw	3 × hole for M12	3 × hole for M12	3 × hole for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	6 × 185	6 × 185	6 × 185
PE/GND connection	2			$2 \times \text{hole for M10}$	$2 \times \text{hole for M12}$		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	4 × 240	4 × 240	4 × 240
Cable length, max. <sup>5)</sup>							
Shielded	m	2600	2600	2600	4000	4000	4800
Unshielded	m	3900	3900	3900	6000	6000	7200
Degree of protection		IP00	IP00	IP00	IP00	IP00	IP00
Dimensions							
• Width	mm	310	310	310	310	310	310
Height	mm	1164	1164	1164	1653	1653	1653
• Depth	mm	352	352	352	550	550	550
Weight, approx.	kg	96	96	96	214	214	214
Frame size		FB	FB	FB	GB	GB	GD
Minimum short-circuit current <sup>6)</sup>	А	4400	5200	10000	12400	18400	18600

<sup>1)</sup> The DC link voltage is unregulated and load-dependent. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

 $^{2)}$  The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

3) The first value applies for one pre-charging resistor for each phase, the second value for two pre-charging resistors connected in parallel for each phase.

<sup>4)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>5)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> Current required for reliably triggering protective devices.

Air-cooled units

**Basic Line Modules** 

## Technical specifications (continued)

Line voltage 500 690 V 3 AC	Basic Line Modules							
		6SL3330- 1TG33-0AA3	6SL3330- 1TG34-3AA3	6SL3330- 1TG36-8AA3	6SL3330- 1TG41-1AA3	6SL3330- 1TG41-4AA3	6SL3330- 1TG41-8AA3	
Rated power		11000 07010						
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	250	355	560	900	1100	1500	
• At / <sub>H DC</sub> (50 Hz 690 V)	kW	195	280	440	710	910	1220	
• At I <sub>rated DC</sub> (50 Hz 500 V)	kW	175	250	390	635	810	1085	
• At / <sub>H DC</sub> (50 Hz 500 V)	kW	165	235	365	595	755	1015	
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	250	350	600	900	1250	1500	
• At / <sub>H DC</sub> (60 Hz 575 V)	hp	200	300	450	800	1000	1250	
DC link current	T.							
Rated current I <sub>rated DC</sub>	А	300	430	680	1100	1400	1880	
• Base-load current $I_{\rm H,DC}$ <sup>1)</sup>	А	234	335	530	858	1092	1467	
Maximum current I <sub>max DC</sub>	А	450	645	1020	1650	2100	2820	
Input current								
Rated current Irated I	А	260	375	575	925	1180	1580	
Maximum current Imax I	А	390	563	863	1388	1770	2370	
	А	Internal	Internal	Internal	Internal	Internal	234	
Current demand								
• 24 V DC auxiliary power supply	А	1.1	1.1	1.1	1.1	1.1	1.1	
DC link capacitance								
Basic Line Module	μF	3200	4800	7300	11600	15470	19500	
• Drive line-up, max.	μF	25600	38400	58400	92800	123760	78000/156000 <sup>2)</sup>	
Power loss, max. <sup>3)</sup>								
• At 50 Hz 690 V	kW	1.5	2.1	3.0	5.4	5.8	7.3	
• At 60 Hz 575 V	kW	1.5	2.1	3.0	5.4	5.8	7.3	
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.36	0.36	0.36	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	66/68	66/68	66/68	71/73	71/73	71/73	
Line connection U1, V1, W1		Flat connector for M10 screw	Flat connector for M10 screw	Flat connector for M10 screw	Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	6 × 185	6 × 185	6 × 185	
DC link connection DCP, DCN		M10 screw	M10 screw	M10 screw	$3 \times hole$ for M12	$3 \times hole$ for M12	$3 \times hole$ for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	6 ×185	6 × 185	6 × 185	
PE/GND connection		$2 \times \text{hole for M10}$	$2 \times \text{hole for M10}$	$2 \times \text{hole for M10}$	$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	4 × 240	4 × 240	4 × 240	
Cable length, max. <sup>4)</sup>								
Shielded	m	1500	1500	1500	2250	2250	2750	
Unshielded	m	2250	2250	2250	3375	3375	4125	
Degree of protection		IP00	IP00	IP00	IP00	IP00	IP00	
Dimensions								
• Width	mm	310	310	310	310	310	310	
Height	mm	1164	1164	1164	1653	1653	1653	
• Depth	mm	352	352	352	550	550	550	
Weight, approx.	kg	96	96	96	214	214	214	
Frame size		FB	FB	FB	GB	GB	GD	
Minimum short-circuit current <sup>5)</sup>	A	3000	4400	8000	10400	16000	18600	

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

 The first value applies for one pre-charging resistor for each phase, the second value for two pre-charging resistors connected in parallel for each phase.

<sup>3)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. <sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Current required for reliably triggering protective devices.

Air-cooled units

## Smart Line Modules

## Overview



Smart Line Modules are infeed/regenerative feedback units that supply power to connected Motor Modules. Furthermore, they are capable of feeding regenerative energy back into the grid. The infeed occurs over a diode jumper, while stable, line-commutated regenerative feedback takes place via IGBTs with 100 % continuous energy regeneration. The regenerative capability of the modules can be deactivated by means of parameterization.

Smart Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

The DC link is pre-charged by means of integrated pre-charging resistors.

To operate the Smart Line Module, the associated line reactor or a suitable transformer is required.

### Design

The Smart Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 1 DC link connection (DCPA, DCNA) for connecting a Braking Module
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 PE/protective conductor connection (2 connections for sizes HX and JX)

The status of the Smart Line Modules is indicated via three LEDs.

The scope of supply of the Smart Line Modules includes:

- DRIVE-CLiQ cable to connect to a Control Unit
- DRIVE-CLiQ cable for connection between the Control Unit and first Motor Module (type dependent)
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

## Selection and ordering data

Rated power at 400 V or 690 V	Infeed/regenerative feedback current	Smart Line Module				
kW	А	Article No.				
Line voltage 380 48	0 V 3 AC					
250	463	6SL3330-6TE35-5AA3				
355	614	6SL3330-6TE37-3AA3				
500	883	6SL3330-6TE41-1AA3				
630	1093	6SL3330-6TE41-3AA3				
800	1430	6SL3330-6TE41-7AA3				
Line voltage 500 69	0 V 3 AC					
450	463	6SL3330-6TG35-5AA3				
710	757	6SL3330-6TG38-8AA3				
1000	1009	6SL3330-6TG41-2AA3				
1400	1430	6SL3330-6TG41-7AA3				
Description		Article No.				
Accessories for re-ordering						
<b>Dust protection blank</b> (50 units)	ing plugs	6SL3066-4CA00-0AA0				

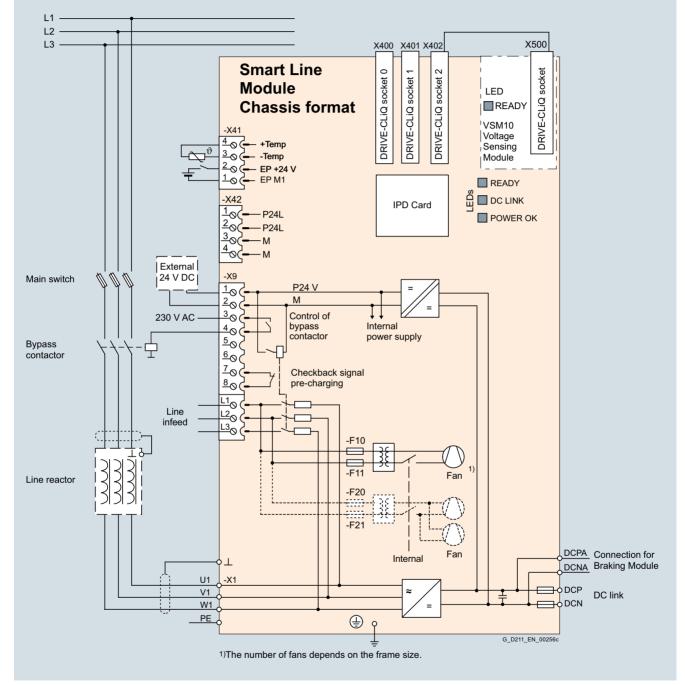
For DRIVE-CLiQ port

For line-side components, Braking Modules, and recommended system components, see System components.

Air-cooled units

**Smart Line Modules** 

## Integration



The Smart Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate the Smart Line Modules.

Connection example of a Smart Line Module

Air-cooled units

## Smart Line Modules

## Technical specifications

## General technical specifications

Electrical specifications	
Line power factor at rated power	
• Basic fundamental (cos $\varphi_1$ )	>0.96
• Total $(\lambda)$	0.75 0.93
Efficiency	>98.5 %
DC link voltage, approx. <sup>1)</sup>	$1.32 \times \text{line voltage under partial load}$ $1.30 \times \text{line voltage under full load}$
Main contactor control	
Terminal block -X9/5-6	240 V AC, max. 8 A 30 V DC, max. 1 A

 The DC link voltage is unregulated and load-dependent. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

**Smart Line Modules** 

Line voltage 380 480 V 3 AC		Smart Line Module	es			
		6SL3330- 6TE35-5AA3	6SL3330- 6TE37-3AA3	6SL3330- 6TE41-1AA3	6SL3330- 6TE41-3AA3	6SL3330- 6TE41-7AA3
Rated power						
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	250	355	500	630	800
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	235	315	450	555	730
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	385	545	770	970	1230
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	360	485	695	855	1125
DC link current						
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	550	730	1050	1300	1700
• Base-load current I <sub>H DC</sub> <sup>1)</sup>	А	490	650	934	1157	1513
Maximum current I <sub>max DC</sub>	А	825	1095	1575	1950	2550
Infeed/regenerative feedback current						
Rated current I <sub>rated I</sub>	А	463	614	883	1093	1430
Maximum current I <sub>max I</sub>	А	694	921	1324	1639	2145
Current demand						
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.35	1.35	1.4	1.5	1.7
• 400 V AC	А	1.8	1.8	3.6	5.4	5.4
DC link capacitance						
Smart Line Module	μF	8400	12000	16800	18900	28800
• Drive line-up, max.	μF	42000	60000	67200	75600	115200
Power loss. max. <sup>2)</sup>	r					
• At 50 Hz 400 V	kW	3.7	4.7	7.1	11.0	11.5
• At 60 Hz 460 V	kW	3.7	4.7	7.1	11.0	11.5
Cooling air requirement	m <sup>3</sup> /s	0.36	0.36	0.78	1.08	1.08
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69/73	69/73	70/73	70/73	70/73
Line connection U1, V1, W1		Flat connector for M10 screw	Flat connector for M10 screw	Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	4 × 240	6 × 240	6 × 240
DC link connection DCP, DCN		M10 screw	M10 screw	4 × hole for M12	4 × hole for M12	$4 \times \text{hole for M12}$
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	Busbar	Busbar	Busbar
PE/GND connection		Hole for M10	Hole for M10	-	-	-
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	-	-	-
PE1/GND connection		-	-	M12 screw	M12 screw	M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	-	-	240	240	240
PE2/GND connection		-	-	2 × M12 screw	2 × M12 screw	2 × M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	-	-	2 × 240	2 × 240	2 × 240
Cable length, max. <sup>3)</sup>						
Shielded	m	4000	4000	4800	4800	4800
Unshielded	m	6000	6000	7200	7200	7200
Degree of protection		IP00	IP00	IP00	IP00	IP00
Dimensions						
• Width	mm	310	310	503	704	704
Height	mm	1413	1413	1475	1480	1480
• Depth	mm	550	550	548	550	550
Weight, approx.	kg	150	150	294	458	458
	-					

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

А

GΧ

6200

GΧ

9200

<sup>3)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

JX

16000

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

Technical specifications (continued)

Frame size

Minimum short-circuit current 4)

ΗX

10400

3

JX

21000

3/23

<sup>&</sup>lt;sup>4)</sup> Current required for reliably triggering protective devices.

Air-cooled units

## Smart Line Modules

### Technical specifications (continued)

Line voltage 500 690 V 3 AC		Smart Line Modules					
		6SL3330-6TG35-5AA3	6SL3330-6TG38-8AA3	6SL3330-6TG41-2AA3	6SL3330-6TG41-7AA3		
Rated power							
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	450	710	1000	1400		
• At I <sub>H DC</sub> (50 Hz 690 V)	kW	405	665	885	1255		
<ul> <li>At I<sub>rated DC</sub> (50 Hz 500 V)</li> </ul>	kW	320	525	705	995		
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	295	480	640	910		
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	500	790	1115	1465		
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	450	740	990	1400		
DC link current							
Rated current Irated DC	А	550	900	1200	1700		
<ul> <li>Base-load current I<sub>H DC</sub><sup>1)</sup></li> </ul>	А	490	800	1068	1513		
Maximum current I <sub>max DC</sub>	А	825	1350	1800	2550		
Infeed/regenerative feedback current	:						
Rated current Irated I	А	463	757	1009	1430		
Maximum current I <sub>max I</sub>	А	694	1135	1513	2145		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.35	1.4	1.5	1.7		
• 500 V AC	А	1.3	2.9	4.3	4.3		
• 690 V AC	А	0.94	2.1	3.1	3.1		
DC link capacitance							
Smart Line Module	μF	5600	7400	11100	14400		
Drive line-up, max.	μF	28000	29600	44400	57600		
Power loss. max. <sup>2)</sup>	μι	20000	20000		01000		
• At 50 Hz 690 V	kW	4.3	6.5	12.0	13.8		
• At 60 Hz 575 V	kW	4.3	6.5	12.0	13.8		
Cooling air requirement	m <sup>3</sup> /s	0.36	0.78	1.08	1.08		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69/73	70/73	70/73	70/73		
Line connection		Flat connector for	Flat connector for	Flat connector for	Flat connector for		
		M10 screw	M12 screw	M12 screw	M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	4 × 240	6 × 240	6 × 240		
DC link connection DCP, DCN	0	M10 screw	4 × hole for M12	4 × hole for M12	4 × hole for M12		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	Busbar	Busbar	Busbar		
PE connection	0	Hole for M10	-	-	-		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	-	-	-		
PE1/GND connection	0	-	M12 screw	M12 screw	M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	-	240	240	240		
PE2/GND connection	0	-	2 × M12 screw	2 × M12 screw	2 × M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	-	2 × 240	2 × 240	2 × 240		
Cable length, max. <sup>3)</sup>							
Shielded	m	2250	2750	2750	2750		
Unshielded	m	3375	4125	4125	4125		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
• Width	mm	310	503	704	704		
• Height	mm	1413	1475	1480	1480		
• Depth	mm	550	548	550	550		
Weight, approx.	kg	150	294	458	458		
Frame size		GX	HX	JX	JX		
Minimum short-circuit current <sup>4)</sup>	А	6200	10500	12400	21000		

 $^{1)}$  The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. <sup>3)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>4)</sup> Current required for reliably triggering protective devices.

Selection and ordering data

## **SINAMICS S120 Chassis Format Converter Units**

Air-cooled units

### Active Line Modules

### Overview



The self-commutated infeed/regenerative feedback units with IGBTs generate a regulated DC link voltage. This means that the connected Motor Modules are decoupled from the line voltage. Line voltage fluctuations within the permissible supply toler-ances have no effect on the motor voltage.

If required, the Active Line Modules can also provide reactive power compensation.

Active Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

Active Line Modules are always operated together with the associated Active Interface Modules. These include the necessary pre-charging circuit as well as a Clean Power Filter.

#### Design

The Active Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 1 DC link connection (DCPA, DCNA) for connecting a Braking Module
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 2 PE connections

The status of the Active Line Modules is indicated via three LEDs.

The scope of supply of the Active Line Modules includes:

- DRIVE-CLiQ cable to connect to a Control Unit
- DRIVE-CLiQ cable to connect the Control Unit to the first Motor Module
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

	-				
Rated power at 400 V or 690 V	Rated infeed/ regenerative feedback current	Active Line Module			
kW	A	Article No.			
Line voltage 380 4	80 V 3 AC				
132	210	6SL3330-7TE32-1AA3			
160	260	6SL3330-7TE32-6AA3			
235	380	6SL3330-7TE33-8AA3			
300	490	6SL3330-7TE35-0AA3			
380	605	6SL3330-7TE36-1AA3			
450	745	6SL3330-7TE37-5AA3			
500	840	6SL3330-7TE38-4AA3			
630	985	6SL3330-7TE41-0AA3			
800	1260	6SL3330-7TE41-2AA3			
900	1405	6SL3330-7TE41-4AA3			
Line voltage 500 690 V 3 AC					
630	575	6SL3330-7TG35-8AA3			
800	735	6SL3330-7TG37-4AA3			
1100	1025	6SL3330-7TG41-0AA3			
1400	1270	6SL3330-7TG41-3AA3			
Description		Article No.			
Accessories for re-ordering					
Dust protection blan	king plugs	6SL3066-4CA00-0AA0			

(50 units) For DRIVE-CLiQ port

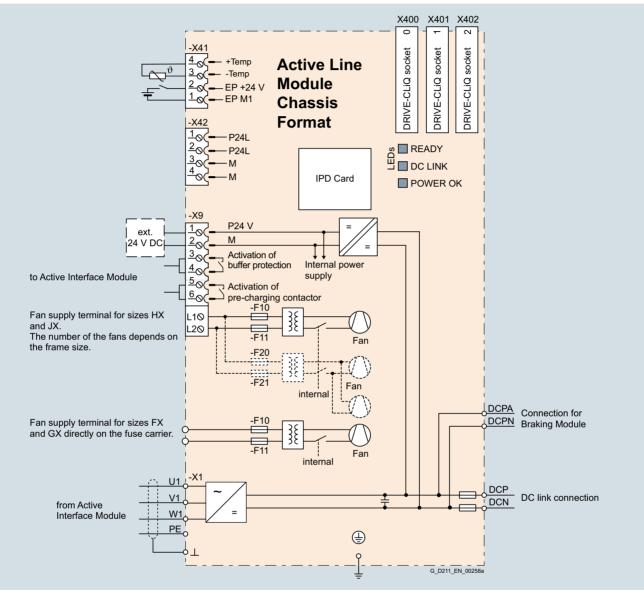
For line-side components, Braking Modules, and recommended system components, see System components.

Air-cooled units

### **Active Line Modules**

## Integration

The Smart Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate the Smart Line Modules.



Connection example of an Active Line Module

### Technical specifications

#### General technical specifications

Electrical specifications		
Line power factor		
• Basic fundamental (cos $\varphi_1$ )	1 (factory setting), can be altered by inputting a reactive current setpoint	
• Total ( $\lambda$ )	1 (factory setting)	
Efficiency	>97.5 % (including Active Interface Module)	
DC link voltage	The DC link voltage is regulated and can be adjusted as a voltage decoupled from the line voltage. Factory setting of the DC link voltage: $1.5 \times$ line voltage	
Radio interference suppression		
<ul> <li>Standard (Active Line Module with Active Interface Module)</li> </ul>	Category C3 to EN 61800-3	
With line filter	Category C2 to EN 61800-3	

Air-cooled units

Active Line Modules

Line voltage 380 480 V 3 AC		Active Line Modules					
		6SL3330- 7TE32-1AA3	6SL3330- 7TE32-6AA3	6SL3330- 7TE33-8AA3	6SL3330- 7TE35-0AA3	6SL3330- 7TE36-1AA3	
Rated power							
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	132	160	235	300	380	
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	115	145	210	270	335	
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	200	250	400	500	600	
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	150	200	300	400	500	
DC link current							
Rated current Irated DC	A	235	291	425	549	678	
• Base-load current $I_{\rm H DC}$ <sup>1)</sup>	А	209	259	378	489	603	
Maximum current I <sub>max DC</sub>	A	352	436	637	823	1017	
nfeed/regenerative feedback current							
Rated current Irated I	А	210	260	380	490	605	
Maximum current I <sub>max I</sub>	А	315	390	570	735	907	
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	A	1.1	1.1	1.35	1.35	1.4	
• 400 V AC	A	0.63	1.13	1.8	1.8	3.6	
DC link capacitance							
• Active Line Module	μF	4200	5200	7800	9600	12600	
Drive line-up, max.	μF	41600	41600	76800	76800	134400	
Power loss, max. <sup>2)</sup>							
• At 50 Hz 400 V	kW	2.2	2.7	3.9	4.8	6.2	
• At 60 Hz 460 V	kW	2.3	2.9	4.2	5.1	6.6	
Cooling air requirement	m <sup>3</sup> /s	0.17	0.23	0.36	0.36	0.78	
Sound pressure level L <sub>pA</sub> <sup>3)</sup> 1 m) at 50/60 Hz	dB	64/67	71/71	69/73	69/73	70/73	
Line supply connection J1, V1, W1		Flat connector for M10 screw	Flat connector fo M12 screw				
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	4 × 240	
DC link connection DCP, DCN		M10 screw	M10 screw	M10 screw	M10 screw	$4 \times hole$ for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	Busbar	
PE1/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	240	
PE2/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	$2 \times M12$ screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Cable length, max. <sup>4)</sup>							
• Shielded	m	2700	2700	2700	2700	3900	
Unshielded	m	4050	4050	4050	4050	5850	
Degree of protection		IP20	IP20	IP20	IP20	IP00	
Dimensions							
• Width	mm	326	326	326	326	503	
• Height	mm	1400	1400	1533	1533	1475	
Depth	mm	356	356	545	545	540	
Weight, approx.	kg	95	95	136	136	290	
Frame size		FX	FX	GX	GX	HX	
Minimum short-circuit current <sup>5)</sup>	А	6200	10500	10500	8000	9200	

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

Technical specifications (continued)

<sup>5)</sup> Current required for reliably triggering protective devices.

Air-cooled units

## Active Line Modules

### Technical specifications (continued)

Line voltage 380 480 V 3 AC		Active Line Modules				
		6SL3330- 7TE37-5AA3	6SL3330- 7TE38-4AA3	6SL3330- 7TE41-0AA3	6SL3330- 7TE41-2AA3	6SL3330- 7TE41-4AA3
Rated power						
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	450	500	630	800	900
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	400	465	545	690	780
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	600	700	900	1000	1250
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	600	700	800	900	1000
DC link current						
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	835	940	1103	1412	1574
<ul> <li>Base-load current I<sub>H DC</sub><sup>1)</sup></li> </ul>	А	700	837	982	1255	1401
Maximum current I <sub>max DC</sub>	А	1252	1410	1654	2120	2361
Infeed/regenerative feedback current						
Rated current Irated I	А	745	840	985	1260	1405
Maximum current I <sub>max I</sub>	А	1117	1260	1477	1890	2107
Current demand						
<ul> <li>24 V DC auxiliary power supply</li> </ul>	A	1.4	1.4	1.5	1.7	1.7
• 400 V AC	A	3.6	3.6	5.4	5.4	5.4
DC link capacitance						
Active Line Module	μF	15600	16800	18900	26100	28800
<ul> <li>Drive line-up, max.</li> </ul>	μF	134400	134400	230400	230400	230400
Power loss, max. <sup>2)</sup>						
• At 50 Hz 400 V	kW	7.3	7.7	10.1	12.1	13.3
• At 60 Hz 460 V	kW	7.7	8.2	10.8	13.0	14.2
Cooling air requirement	m <sup>3</sup> /s	0.78	0.78	1.08	1.08	1.08
Sound pressure level L <sub>pA</sub> <sup>3)</sup> (1 m) at 50/60 Hz	dB	70/73	70/73	71/73	71/73	71/73
Line supply connection U1, V1, W1		Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	6 × 240	6 × 240	6 × 240
DC link connection DCP, DCN		$4 \times hole$ for M12	$4 \times \text{hole for M12}$	$4 \times \text{hole for M12}$	$4 \times \text{hole for M12}$	$4 \times \text{hole for M12}$
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	Busbar	Busbar	Busbar	Busbar	Busbar
PE1/GND connection		M12 screw	M12 screw	M12 screw	M12 screw	M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240
PE2/GND connection		2 × M12 screw	2 × M12 screw	3 × M12 screw	3 × M12 screw	3 × M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	3 × 240	3 × 240	3 × 240
Cable length, max. <sup>4)</sup>						
Shielded	m	3900	3900	3900	3900	3900
Unshielded	m	5850	5850	5850	5850	5850
Degree of protection		IP00	IP00	IP00	IP00	IP00
Dimensions						
Width	mm	503	503	704	704	704
• Height	mm	1475	1475	1480	1480	1480
• Depth	mm	540	540	550	550	550
Weight, approx.	kg	290	290	450	450	450
Frame size		HX	HX	JX	JX	JX
Minimum short-circuit current <sup>5)</sup>	A	8800	10400	16000	21000	21000
		5000	10400	10000	21000	21000

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Current required for reliably triggering protective devices.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
 <sup>3)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

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Air-cooled units

Active Line Modules

Line voltage 500 690 V 3 AC		Active Line Modules			
		6SL3330-7TG35-8AA3	6SL3330-7TG37-4AA3	6SL3330-7TG41-0AA3	6SL3330-7TG41-3AA3
Rated power					
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	630	800	1100	1400
• At I <sub>H DC</sub> (50 Hz 690 V)	kW	620	705	980	1215
• At I <sub>rated DC</sub> (50 Hz 500 V)	kW	447	560	780	965
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	450	510	710	880
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	675	900	1250	1500
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	506	600	1000	1250
DC link current					
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	644	823	1148	1422
<ul> <li>Base-load current I<sub>H DC</sub><sup>1)</sup></li> </ul>	А	573	732	1022	1266
<ul> <li>Maximum current I<sub>max DC</sub></li> </ul>	А	966	1234	1722	2133
Infeed/regenerative feedback current					
Rated current Irated I	А	575	735	1025	1270
Maximum current I <sub>max I</sub>	А	862	1102	1537	1905
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.4	1.5	1.7	1.7
• 500 V AC	А	3.0	4.4	4.4	4.4
• 690 V AC	А	2.1	3.1	3.1	3.1
DC link capacitance					
Active Line Module	μF	7400	11100	14400	19200
• Drive line-up, max.	μF	59200	153600	153600	153600
Power loss, max. <sup>2)</sup>	•				
• At 50 Hz 690 V	kW	6.8	10.2	13.6	16.5
• At 60 Hz 575 V	kW	6.2	9.6	12.9	15.3
Cooling air requirement	m <sup>3</sup> /s	0.78	1.08	1.08	1.08
Sound pressure level L <sub>pA</sub> <sup>3)</sup> (1 m) at 50/60 Hz	dB	70/73	71/73	71/73	71/73
Line supply connection U1, V1, W1		Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw	Flat connector for M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	6 × 240	6 × 240	6 × 240
DC link connection DCP, DCN		$4 \times hole$ for M12	$4 \times hole$ for M12	$4 \times hole$ for M12	4 × hole for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	Busbar	Busbar	Busbar	Busbar
PE1/GND connection		M12 screw	M12 screw	M12 screw	M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240
PE2/GND connection		2 × M12 screw	3 × M12 screw	3 × M12 screw	3 × M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 x 240	3 x 240	3 x 240	3 x 240
Cable length, max. 4)					
Shielded	m	2250	2250	2250	2250
Unshielded	m	3375	3375	3375	3375
Degree of protection		IP00	IP00	IP00	IP00
Dimensions					
• Width	mm	503	704	704	704
Height	mm	1475	1480	1480	1480
• Depth	mm	540	550	550	550
Weight, approx.	kg	290	450	450	450
Frame size	5	HX	JX	JX	JX
Minimum short-circuit current <sup>5)</sup>	A	8400	10500	16000	20000

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

Technical specifications (continued)

 $^{5)}$  Current required for reliably triggering protective devices.

3

Air-cooled units

## Active Interface Modules

## Overview



Active Interface Modules are used in conjunction with Active Line Modules. Active Interface Modules contain a Clean Power Filter with basic RI suppression, the pre-charging circuit for the Active Line Module, the line voltage sensing circuit and monitoring sensors. The bypass contactor is an integral component in frame sizes FI and GI. This ensures a highly compact design. The bypass contactor must be provided separately for frame sizes HI and JI.

Line harmonics are largely suppressed by the Clean Power Filter.

## Design

Active Interface Modules have the following interfaces as standard:

- 1 line supply connection
- 1 load connection
- 1 connection for the 24 V DC electronics power supply
- 1 connection for the external 230 V AC supply (fan power supply)
- 1 DRIVE-CLiQ socket (on VSM10 Voltage Sensing Module)
- 1 connection for pre-charging circuit, frame sizes HI and JI
- 1 PE connection

The scope of supply of the Active Interface Modules includes:

- DRIVE-CLiQ cable for the connection between Active Interface Module and Active Line Module
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

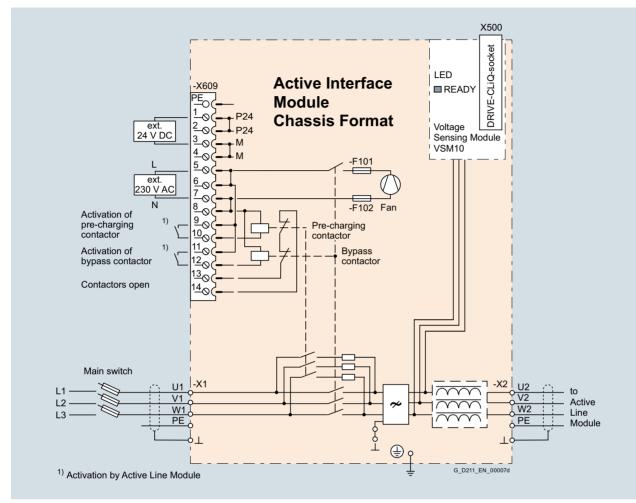
## Selection and ordering data

Suitable for Active Line Module chassis format, air-cooled	Rated power of the Active Line Modules at 400 V or 690 V	Active Interface Module
	kW	Article No.
Line voltage 380 480 V	' 3 AC	
6SL3330-7TE32-1AA3	132	6SL3300-7TE32-6AA1
6SL3330-7TE32-6AA3	160	6SL3300-7TE32-6AA1
6SL3330-7TE33-8AA3	235	6SL3300-7TE33-8AA1
6SL3330-7TE35-0AA3	300	6SL3300-7TE35-0AA1
6SL3330-7TE36-1AA3	380	6SL3300-7TE38-4AA1
6SL3330-7TE37-5AA3	450	6SL3300-7TE38-4AA1
6SL3330-7TE38-4AA3	500	6SL3300-7TE38-4AA1
6SL3330-7TE41-0AA3	630	6SL3300-7TE41-4AA1
6SL3330-7TE41-2AA3	800	6SL3300-7TE41-4AA1
6SL3330-7TE41-4AA3	900	6SL3300-7TE41-4AA1
Line voltage 500 690 V	' 3 AC	
6SL3330-7TG35-8AA3	630	6SL3300-7TG35-8AA1
6SL3330-7TG37-4AA3	800	6SL3300-7TG37-4AA1
6SL3330-7TG41-0AA3	1100	6SL3300-7TG41-3AA1
6SL3330-7TG41-3AA3	1400	6SL3300-7TG41-3AA1

Air-cooled units

Active Interface Modules

# Integration

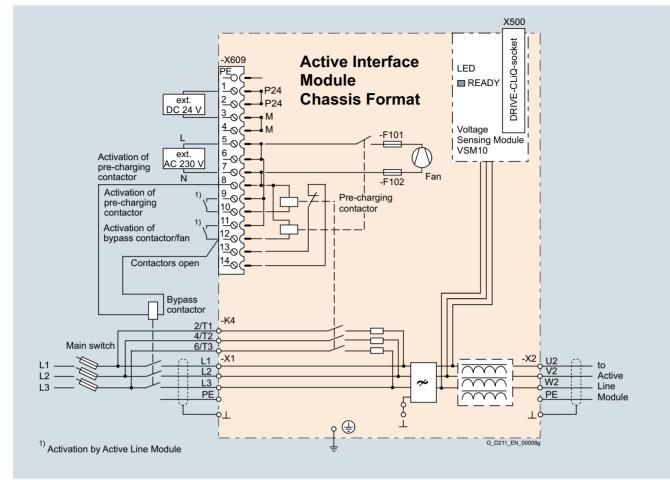


Connection example of an Active Interface Module with integrated bypass contactor (frame sizes FI and GI)

Air-cooled units

### **Active Interface Modules**

## Integration (continued)



Connection example of an Active Interface Module with externally mounted bypass contactor (frame sizes HI and JI)

Air-cooled units

Active Interface Modules

Line voltage 380 480 V 3 AC		Active Interface Modules					
		6SL3300-7TE32-6AA1		6SL3300-7TE33-8AA1	6SL3300-7TE35-0AA1		
Suitable for Active Line Module							
Rated power at 400 V	kW	132	160	235	300		
- Air-cooled		6SL3330-7TE32-1AA3	6SL3330-7TE32-6AA3	6SL3330-7TE33-8AA3	6SL3330-7TE35-0AA3		
- Liquid-cooled		-	-	-	6SL3335-7TE35-0AA3		
Rated current	А	210	260	380	490		
Bypass contactor		Included	Included	Included	Included		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.17	0.17	0.17	0.17		
• 230 V 2 AC							
- Inrush current	А	1.25	1.25	2.5	2.5		
- Holding current	А	0.6	0.6	1.2	1.2		
<b>DC link capacitance</b> of drive line-up, max. <sup>1)</sup>	μF	41600	41600	76800	76800		
Power loss, max. <sup>2)</sup>							
• At 50 Hz 400 V	kW	2.1	2.2	3.0	3.9		
• At 60 Hz 460 V	kW	2.1	2.2	3.0	3.9		
Cooling air requirement	m <sup>3</sup> /s	0.24	0.24	0.47	0.47		
Line/load connection L1, L2, L3 / U2, V2, W2		Flat connector for M10 screw					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185		
PE/GND connection		2 × M10 nut					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185		
Degree of protection		IP20	IP20	IP20	IP20		
Dimensions							
• Width	mm	325	325	325	325		
Height	mm	1400	1400	1533	1533		
• Depth	mm	355	355	544	544		
Weight, approx.	kg	135	135	190	190		
Frame size		FI	FI	GI	GI		
Minimum short-circuit current <sup>3)</sup>	А	6200	10500	10500	8000		

Technical specifications

 Information on higher capacities is included in the SINAMICS Low Voltage Engineering Manual.

 <sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> Current required for reliable triggering of the protective devices.

Air-cooled units

### **Active Interface Modules**

Line voltage 380 480 V 3 AC		Active Interface Modules					
		6SL3300-7TE38-4AA1		6SL3300-7TE41-4AA1			
Suitable for Active Line Module							
Rated power at 400 V	kW	380	450/500	630	800/900		
- Air-cooled		6SL3330-7TE36-1AA3	6SL3330-7TE37-5AA3 6SL3330-7TE38-4AA3	6SL3330-7TE41-0AA3	6SL3330-7TE41-2AA3 6SL3330-7TE41-4AA3		
Rated current	А	605	745/840	985	1260/1405		
Bypass contactor		3RT1476-6AP36	3WL1110-2BB34-4AN2-Z C22 <sup>1)</sup>	3WL1112-2BB34-4AN2-Z C22 <sup>1)</sup>	3WL1116-2BB34-4AN2-2 C22 <sup>1)</sup>		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.17	0.17	0.17	0.17		
• 230 V 2 AC							
- Inrush current	А	9.9	9.9	10.5	10.5		
- Holding current	А	4.6	4.6	4.9	4.9		
<b>DC link capacitance</b> of the drive line-up, max. <sup>2)</sup>	μF	134400	134400	230400	230400		
Power loss, max. <sup>3)</sup>							
• At 50 Hz 400 V	kW	5.5	6.1	7.5	8.5		
• At 60 Hz 460 V	kW	5.5	6.1	7.5	8.5		
Cooling air requirement	m <sup>3</sup> /s	0.4	0.4	0.4	0.4		
Line/load connection L1, L2, L3 / U2, V2, W2		$4 \times hole$ for M12	$4 \times hole$ for M12	$3 \times hole$ for M12	$3 \times \text{hole for M12}$		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	6 × 240	6 × 240		
PE/GND connection		2 × M12 nut	2 × M12 nut	4 × M12 nut	4 × M12 nut		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	4 × 240	4 × 240		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
• Width	mm	305	305	505	505		
• Height	mm	1750	1750	1750	1750		
• Depth	mm	544	544	544	544		
Weight, approx.	kg	390	390	480	480		
Frame size		Н	HI	JI	JI		
Minimum short-circuit current 4)	А	9200	8800/10400	16000	21000		

<sup>1)</sup> The breakers must always be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation by passes the pre-charging circuit and can therefore destroy the Active Line Module. 2) Information on higher capacities is included in the SINAMICS Low Voltage Engineering Manual.

<sup>3)</sup> The specified power loss represents the maximum value at 100 % utili-zation. The value is lower under normal operating conditions.

<sup>4)</sup> Current required for reliably triggering protective devices.

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Air-cooled units

**Active Interface Modules** 

Line voltage 500 690 V 3 AC		Active Interface Modules					
		6SL3300-7TG35-8AA1	6SL3300-7TG37-4AA1	6SL3300-7TG41-3AA1			
Suitable for Active Line Module							
<ul> <li>Rated power at 690 V</li> </ul>	kW	630	800	1100	1400		
- Air-cooled		6SL3330-7TG35-8AA3	6SL3330-7TG37-4AA3	6SL3330-7TG41-0AA3	6SL3330-7TG41-3AA3		
- Liquid-cooled		6SL3335-7TG35-8AA3	-	-	-		
Rated current	А	575	735	1025	1270		
Bypass contactor		3RT1476-6AP36	3RT1476-6AP36 (3 units)	3WL1212-4BB34-4AN2-Z C22 <sup>1)</sup>	3WL1216-4BB34-4AN2-2 C22 <sup>1)</sup>		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.17	0.17	0.17	0.17		
• 230 V 2 AC							
- Inrush current	А	9.9	10.5	10.5	10.5		
- Holding current	А	4.6	4.9	4.9	4.9		
<b>DC link capacitance</b> of the drive line-up, max. <sup>2)</sup>	μF	59200	153600	153600	153600		
Power loss, max. <sup>3)</sup>							
• At 50 Hz 690 V	kW	6.8	9.0	9.2	9.6		
• At 60 Hz 575 V	kW	6.8	9.0	9.2	9.6		
Cooling air requirement	m <sup>3</sup> /s	0.4	0.4	0.4	0.4		
Line/load connection L1, L2, L3 / U2, V2, W2		$4 \times hole$ for M12	3 × hole for M12	$3 \times hole$ for M12	$3 \times hole$ for M12		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	6 × 240	6 × 240	6 × 240		
PE/GND connection		2 × M12 nut	4 × M12 nut	4 × M12 nut	4 × M12 nut		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	4 × 240	4 × 240	4 × 240		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
Width	mm	305	505	505	505		
• Height	mm	1750	1750	1750	1750		
• Depth	mm	544	544	544	544		
Weight, approx.	kg	390	430	530	530		
Frame size		н	JI	JI	JI		
Minimum short-circuit current <sup>4)</sup>	А	8400	10500	16000	20000		
	A						

<sup>1)</sup> The breakers must always be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation bypasses the precharging circuit and can therefore destroy the Active Line Module.

Technical specifications (continued)

<sup>4)</sup> Current required for reliably triggering protective devices.

 <sup>&</sup>lt;sup>2)</sup> Information on higher capacities is included in the SINAMICS Low Voltage Engineering Manual.

<sup>&</sup>lt;sup>3)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

Selection and ordering data

## **SINAMICS S120 Chassis Format Converter Units**

Air-cooled units

## **Motor Modules**

## Overview



A Motor Module comprises a self-commutated converter with IGBTs. It generates a variable voltage with variable frequency from the DC link voltage that feeds the connected motor.

Multiple Motor Modules can be operated on a single DC link. This permits energy to be transferred between the Motor Modules. This means that if one Motor Module operating in generator mode produces energy, the energy can be used by another Motor Module operating in motor mode.

Motor Modules are controlled by a Control Unit.

### Design

The Motor Modules in the chassis format have the following interfaces as standard:

- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for connecting to the supply DC link
- 1 DC link connection (DCPA, DCNA) for connecting a Braking Module
- 1 DC link connection (DCPS, DCNS) for connecting a dv/dt filter
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections

The status of the Motor Modules is indicated via three LEDs.

- The scope of supply of the Motor Modules includes:
- DRIVE-CLiQ cable for connection to the Control Unit
- DRIVE-CLiQ cable for connection to the next Motor Module
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

Type rating at 400 V or 690 V	Rated output current	Motor Module
kW	A	Article No.
Line voltage 380 4 (DC link voltage 510	80 V 3 AC 720 V DC)	
110	210	6SL3320-1TE32-1AA3
132	260	6SL3320-1TE32-6AA3
160	310	6SL3320-1TE33-1AA3
200	380	6SL3320-1TE33-8AA3
250	490	6SL3320-1TE35-0AA3
315	605	6SL3320-1TE36-1AA3
400	745	6SL3320-1TE37-5AA3
450	840	6SL3320-1TE38-4AA3
560	985	6SL3320-1TE41-0AA3
710	1260	6SL3320-1TE41-2AA3
800	1405	6SL3320-1TE41-4AA3
Line voltage 500 6 (DC link voltage 675		
75	85	6SL3320-1TG28-5AA3
90	100	6SL3320-1TG31-0AA3
110	120	6SL3320-1TG31-2AA3
132	150	6SL3320-1TG31-5AA3
160	175	6SL3320-1TG31-8AA3
200	215	6SL3320-1TG32-2AA3
250	260	6SL3320-1TG32-6AA3
315	330	6SL3320-1TG33-3AA3
400	410	6SL3320-1TG34-1AA3
450	465	6SL3320-1TG34-7AA3
560	575	6SL3320-1TG35-8AA3
710	735	6SL3320-1TG37-4AA3
800	810	6SL3320-1TG38-1AA3
900	910	6SL3320-1TG38-8AA3
1000	1025	6SL3320-1TG41-0AA3
1200	1270	6SL3320-1TG41-3AA3

Description

Acces

Article No.

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Dust protection blanking plugs	6SL3066-4CA00-0AA0
(50 units)	
For DRIVE-CLiQ port	

For motor-side components and Braking Modules, see System components.

Air-cooled units

**Motor Modules** 

## Integration

X400 X401 X402 0 2 ~ DRIVE-CLiQ socket DRIVE-CLiQ socket socket Motor Module in chassis format DRIVE-CLIQ DCP DC link connection DCN DCPA Connection for Braking Module = DCNA Connection for DCPS dv/dt filter DCNS Τq -X9 P24 V 100 -X2 PE External 1200 Μ 24 V DC U2 300 V2 Μ Internal 400 W2 power 3~ <u>5</u>00 . supply <u>6</u>0( F10 Fan power supply terminal L10 for sizes HX and JX. L2O The number of fans depends on the -F11 frame size. -F20 35 -F21 Internal 38 Fan power supply terminal for sizes FX and GX directly on the fuse carrier -F11 Fan Internal -X41 <u>4</u>\_0 +Temp  $\Sigma^{\vartheta}$ 3\_0 READY -Temp EDs EP +24 \ <u>2\_0</u>( DC LINK 10 EP M1 ⇉ POWER OK -X42 100 – P24L 2.00 – P24L 300 - M <u>4</u>0( IPD Card - M -X46 1\_0 - BR output+ 2.00 - BR output-<u>3</u>0 FB input+ 4\_0( FB inputç G\_D213\_DE\_00085d

The Motor Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit.

Connection example of a Motor Module

3

Air-cooled units

### **Motor Modules**

## Technical specifications

### General technical specifications

Electrical specifications	
Efficiency	>98.5 %
DC link voltage (up to 2000 m above sea level)	510 720 V DC (line voltage 380 480 V 3 AC) or 675 1035 V DC (line voltage 500 690 V 3 AC)
Output frequency <sup>1)</sup>	
Control type Servo	0 550 Hz
Control type Vector	0 550 Hz
Control mode V/f	0 550 Hz
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1

https://support.industry.siemens.com/cs/document/104020669
The correlation between the minimum output frequency and permissible output current (current derating). Information is provided in the SINAMICS Low Voltage Engineering Manual.

Please note:
 The correlation between the maximum output frequency, pulse frequency and current derating. Higher output frequencies on request. For further

Air-cooled units

Motor Modules

rechnical specifications (continued)							
Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC	Motor Modules						
		6SL3320- 1TE32-1AA3	6SL3320- 1TE32-6AA3	6SL3320- 1TE33-1AA3	6SL3320- 1TE33-8AA3	6SL3320- 1TE35-0AA3	
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	200	250	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	160	200	
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	300	400	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	250	350	
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	210	260	310	380	490	
<ul> <li>Base-load current I<sup>(3)</sup></li> </ul>	А	205	250	302	370	477	
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	178	233	277	340	438	
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	307	375	453	555	715	
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	252	312	372	456	588	
- Active Line Module	А	227	281	335	411	529	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	245	304	362	444	573	
- Active Line Module	А	221	273	326	400	515	
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	224	277	331	405	523	
- Active Line Module	А	202	250	298	365	470	
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.8	0.8	0.9	0.9	0.9	
• 400 V AC	А	0.63	1.13	1.8	1.8	1.8	
DC link capacitance	μF	4200	5200	6300	7800	9600	
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	2	2	2	2	2	
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	2	2	2	2	2	
- With current derating	kHz	8	8	8	8	8	
Power loss, max. <sup>6)</sup>							
• At 50 Hz 400 V	kW	1.86	2.5	2.96	3.67	4.28	
• At 60 Hz 460 V	kW	1.94	2.6	3.1	3.8	4.5	
Cooling air requirement	m <sup>3</sup> /s	0.17	0.23	0.36	0.36	0.36	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	64/67	71/71	69/73	69/73	69/73	
DC link connection DCP, DCN		M10 screw					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		M6 threaded bolt					
Connection for dv/dt filter		M8 screw					
DCPS, DCNS	2						
Conductor cross-section, max. (IEC)	mm²	1 × 35	1 × 35	1 × 70	1 × 70	1 × 70	
Motor connection U2, V2, W2	2	M10 screw					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	
Cable length, max. <sup>8)</sup>		222	000	000	200	000	
Shielded	m	300	300	300	300	300	
Unshielded	m	450	450	450	450	450	

For footnotes, see next page.

Air-cooled units

#### **Motor Modules**

### Technical specifications (continued)

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules						
		6SL3320- 1TE32-1AA3	6SL3320- 1TE32-6AA3	6SL3320- 1TE33-1AA3	6SL3320- 1TE33-8AA3	6SL3320- 1TE35-0AA3		
PE1/GND connection		M10 screw						
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240		
PE2/GND connection		M10 screw						
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240		
Degree of protection		IP20	IP20	IP20	IP20	IP20		
Dimensions								
• Width	mm	326	326	326	326	326		
Height	mm	1400	1400	1533	1533	1533		
• Depth	mm	356	356	545	545	545		
Weight, approx.	kg	95	95	136	136	136		
Frame size		FX	FX	GX	GX	GX		

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

Line voltage 380 480 V 3 AC		Motor Modules			
DC link voltage 510 720 V DC		6SL3320-1TE36-1AA3 6SL3320-1TE37-5AA3		6SL3320-1TE38-4AA3	
Type rating					
• At I <sub>1</sub> (50 Hz 400 V) <sup>1)</sup>	kW	315	400	450	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	250	315	400	
• At / <sub>I</sub> (60 Hz 460 V) <sup>2)</sup>	hp	500	600	700	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	350	450	600	
Output current	ΠÞ		100	000	
Rated current Irated O	A	605	745	840	
<ul> <li>Base-load current l<sub>1</sub><sup>(3)</sup></li> </ul>	A	590	725	820	
• Base-load current $I_{\rm H}^{4)}$	A			700	
		460	570		
Maximum current I <sub>max O</sub>	A	885	1087	1230	
DC link current					
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>					
- Basic/Smart Line Module	А	726	894	1008	
- Active Line Module	А	653	805	907	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>					
- Basic/Smart Line Module	А	707	871	982	
- Active Line Module	А	636	784	884	
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> </ul>					
- Basic/Smart Line Module	А	646	795	897	
- Active Line Module	А	581	716	807	
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.0	1.0	1.0	
• 400 V AC	А	3.6	3.6	3.6	
DC link capacitance	μF	12600	15600	16800	
Pulse frequency <sup>5)</sup>	P**				
Rated frequency	kHz	1.25	1.25	1.25	
Pulse frequency, max.				1120	
- Without current derating	kHz	1.25	1.25	1.25	
- With current derating	kHz	7.5	7.5	7.5	
Power loss, max. <sup>6)</sup>	NIIZ	7.5	7.5	1.5	
• At 50 Hz 400 V	LAM	E 0.4	C C0	7 15	
	kW	5.84	6.68	7.15	
• At 60 Hz 460 V	kW	6.3	7.3	7.8	
Cooling air requirement	m <sup>3</sup> /s	0.78	0.78	0.78	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	70/73	70/73	70/73	
<b>DC link connection</b> DCP, DCN		4 × hole for M10 Busbar	4 × hole for M10 Busbar	4 × hole for M10 Busbar	
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		Connection for connection clip	Connection for connection clip	Connection for connection clip	
Connection for dv/dt filter DCPS, DCNS		M10 screw	M10 screw	M10 screw	
	mm <sup>2</sup>	1 × 185	1 × 185	1 × 185	
Motor connection U2, V2, W2		2 × M12 screw	2 × M12 screw	2 × M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	
Cable length, max. <sup>8)</sup>					
Shielded	m	300	300	300	
		N 11 1		. 11.11.1	

Air-cooled units

Technical	specifications	(continued)
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Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules				
		6SL3320-1TE36-1AA3	6SL3320-1TE37-5AA3	6SL3320-1TE38-4AA3		
PE1/GND connection		M12 screw	M12 screw	M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240		
PE2/GND connection		2 × M12 screw	2 × M12 screw	2 × M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240		
Degree of protection		IP00	IP00	IP00		
Dimensions						
• Width	mm	503	503	503		
Height	mm	1475	1475	1475		
Depth	mm	547	547	547		
Weight, approx.	kg	290	290	290		
Frame size		HX	HX	HX		

- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules			
		6SL3320-1TE41-0AA3	6SL3320-1TE41-4AA3		
Type rating					
• At / <sub>I</sub> (50 Hz 400 V) <sup>1)</sup>	kW	560	710	800	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	450	560	710	
• At I <sub>1</sub> (60 Hz 460 V) <sup>2)</sup>	hp	800	1000	1150	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	700	900	1000	
Output current					
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	985	1260	1405	
• Base-load current $I_{\rm I}$ <sup>3)</sup>	A	960	1230	1370	
• Base-load current $I_{\rm H}^{4)}$	A	860	1127	1257	
Maximum current I <sub>max O</sub>	A	1440	1845	2055	
DC link current	A	1440	1043	2000	
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>					
- Basic/Smart Line Module	A	1182	1512	1686	
- Active Line Module	A	1064	1361	1517	
<ul> <li>Base-load current I<sub>L DC</sub><sup>3)</sup></li> <li>when supplied via</li> </ul>	~	1004	1301	1517	
- Basic/Smart Line Module	А	1152	1474	1643	
- Active Line Module	A	1037	1326	1479	
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> </ul>	~	1037	1320	1475	
- Basic/Smart Line Module	А	1051	1345	1500	
- Active Line Module	A	946	1211	1350	
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	A	1.25	1.4	1.4	
• 400 V AC	A	5.4	5.4	5.4	
DC link capacitance	μF	18900	26100	28800	
Pulse frequency <sup>5)</sup>	μι	10000	20100	20000	
	kHz	1.25	1.25	1.25	
<ul><li>Rated frequency</li><li>Pulse frequency, max.</li></ul>	KLIZ	1.25	1.20	1.20	
		1.05	1.05	1.05	
- Without current derating	kHz	1.25	1.25	1.25	
- With current derating	kHz	7.5	7.5	7.5	
Power loss, max. <sup>6)</sup>					
• At 50 Hz 400 V	kW	9.5	11.1	12.0	
• At 60 Hz 460 V	kW	10.2	12.0	13.0	
Cooling air requirement	m <sup>3</sup> /s	1.08	1.08	1.08	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	71/73	71/73	71/73	
<b>DC link connection</b> DCP, DCN		4 × hole for M10 Busbar	4 × hole for M10 Busbar	4 × hole for M10 Busbar	
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		Connection for connection clip	Connection for connection clip	Connection for connection clip	
Connection for dv/dt filter DCPS, DCNS		2 x M10 screw	2 x M10 screw	2 x M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	
Motor connection U2, V2, W2		3 × M12 screw	3 × M12 screw	3 × M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	6 × 240	6 × 240	6 × 240	
Cable length, max. <sup>8)</sup>					
<b>u</b> ,					
Shielded	m	300	300	300	

Air-cooled units

Technical specifications	(continued)
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Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules			
		6SL3320-1TE41-0AA3	6SL3320-1TE41-2AA3	6SL3320-1TE41-4AA3	
PE1/GND connection		M12 screw	M12 screw	M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	
PE2/GND connection		3 × M12 screw	3 × M12 screw	3 × M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	3 × 240	3 × 240	3 × 240	
Degree of protection		IP00	IP00	IP00	
Dimensions					
• Width	mm	704	704	704	
Height	mm	1475	1475	1475	
Depth	mm	549	549	549	
Weight, approx.	kg	450	450	450	
Frame size		JX	JX	JX	

- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

Motor Modules

reclinical specifications (continued)							
Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules					
		6SL3320-1TG28-5AA3	6SL3320-1TG31-0AA3	6SL3320-1TG31-2AA3	6SL3320-1TG31-5AA3		
Type rating							
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	75	90	110	132		
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	55	75	90	110		
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	55	75	90		
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	45	55	75	90		
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	75	100	150		
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	75	100	125		
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	85	100	120	150		
<ul> <li>Base-load current I<sup>3</sup></li> </ul>	А	80	95	115	142		
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	76	89	107	134		
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	120	142	172	213		
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	102	120	144	180		
- Active Line Module	А	92	108	130	162		
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	99	117	140	175		
- Active Line Module	А	89	105	126	157		
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	90	106	128	160		
- Active Line Module	А	81	96	115	144		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.8	0.8	0.8	0.8		
• 500 V AC	А	0.7	0.7	0.7	0.7		
• 690 V AC	А	0.4	0.4	0.4	0.4		
DC link capacitance	μF	1200	1200	1600	2800		
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25		
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25		
- With current derating	kHz	7.5	7.5	7.5	7.5		
Power loss, max. <sup>6)</sup>							
• At 50 Hz 690 V	kW	1.17	1.43	1.89	1.8		
• At 60 Hz 575 V	kW	1.1	1.3	1.77	1.62		
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.17		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	64/67	64/67	64/67	64/67		
DC link connection DCP, DCN		M10 screw	M10 screw	M10 screw	M10 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185		
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		M6 stud	M6 stud	M6 stud	M6 stud		
Connection for dv/dt filter DCPS, DCNS		M8 screw	M8 screw	M8 screw	M8 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	1 × 70	1 × 70	1 × 70	1 × 70		
Motor connection U2, V2, W2		M10 screw	M10 screw	M10 screw	M10 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185		

Technical specifications (continued)

Air-cooled units

#### **Motor Modules**

### Technical specifications (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3320-1TG28-5AA3	6SL3320-1TG31-0AA3	6SL3320-1TG31-2AA3	6SL3320-1TG31-5AA3	
Cable length, max. <sup>8)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
PE1/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185	
PE2/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185	
Degree of protection		IP20	IP20	IP20	IP20	
Dimensions						
• Width	mm	326	326	326	326	
Height	mm	1400	1400	1400	1400	
• Depth	mm	356	356	356	356	
Weight, approx.	kg	95	95	95	95	
Frame size		FX	FX	FX	FX	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

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Air-cooled units

Motor Modules

Line voltage 500 690 V 3 AC		Motor Modules				
DC link voltage 675 1035 V DC		6SL3320-1TG31-8AA3 6SL3320-1TG32-2AA3 6SL3320-1TG32-6AA3 6SL3320-1TG33-3AA3				
<b>-</b>		6SL3320-1TG31-8AA3	65L332U-11G32-2AA3	65L332U-11G32-6AA3	65L3320-11G33-3AA3	
Type rating		100			A45	
• At <i>I</i> <sub>L</sub> (50 Hz 690 V) <sup>1</sup>	kW	160	200	250	315	
• At <i>I</i> <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	132	160	200	250	
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	110	132	160	200	
• At <i>I</i> <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	90	110	132	160	
• At / <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	150	200	250	300	
• At <i>I</i> <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	150	200	200	250	
Output current						
• Rated current <i>I</i> <sub>rated O</sub>	A	175	215	260	330	
Base-load current IL 3)	A	171	208	250	320	
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	A	157	192	233	280	
Maximum current I <sub>max O</sub>	А	255	312	375	480	
DC link current						
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>						
- Basic/Smart Line Module	A	210	258	312	396	
- Active Line Module	А	189	232	281	356	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>						
- Basic/Smart Line Module	А	204	251	304	386	
- Active Line Module	А	184	226	273	347	
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>						
- Basic/Smart Line Module	А	186	229	277	352	
- Active Line Module	А	168	206	250	316	
Current demand						
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.9	0.9	0.9	0.9	
• 500 V AC	А	1.5	1.5	1.5	1.5	
• 690 V AC	А	1.0	1.0	1.0	1.0	
DC link capacitance	μF	2800	2800	3900	4200	
Pulse frequency <sup>5)</sup>						
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	
<ul> <li>Pulse frequency, max.</li> </ul>						
- Without current derating	kHz	1.25	1.25	1.25	1.25	
- With current derating	kHz	7.5	7.5	7.5	7.5	
Power loss, max. <sup>6)</sup>						
• At 50 Hz 690 V	kW	2.67	3.09	3.62	4.34	
• At 60 Hz 575 V	kW	2.5	2.91	3.38	3.98	
Cooling air requirement	m <sup>3</sup> /s	0.36	0.36	0.36	0.36	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69/73	69/73	69/73	69/73	
DC link connection DCP, DCN		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	2 × 240	
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		M6 stud	M6 stud	M6 stud	M6 stud	
Connection for dv/dt filter DCPS, DCNS		M8 screw	M8 screw	M8 screw	M8 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	1 × 70	1 × 70	1 × 70	1 × 70	
Motor connection U2, V2, W2		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	2 × 240	

Technical specifications (continued)

Air-cooled units

#### **Motor Modules**

### Technical specifications (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3320-1TG31-8AA3	6SL3320-1TG32-2AA3	6SL3320-1TG32-6AA3	6SL3320-1TG33-3AA3	
Cable length, max. <sup>8)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
PE1/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	2 × 240	
PE2/GND connection		M10 screw	M10 screw	M10 screw	M10 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	2 × 240	
Degree of protection		IP20	IP20	IP20	IP20	
Dimensions						
• Width	mm	326	326	326	326	
Height	mm	1533	1533	1533	1533	
• Depth	mm	545	545	545	545	
Weight, approx.	kg	136	136	136	136	
Frame size		GX	GX	GX	GX	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules					
J.		6SL3320-1TG34-1AA3	6SL3320-1TG34-7AA3	6SL3320-1TG35-8AA3	6SL3320-1TG37-4AA3		
Type rating							
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	400	450	560	710		
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	315	400	450	630		
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	250	315	400	500		
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	200	250	315	450		
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	400	450	600	700		
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	350	450	500	700		
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	410	465	575	735		
• Base-load current IL 3)	A	400	452	560	710		
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	367	416	514	657		
Maximum current I <sub>max O</sub>	А	600	678	840	1065		
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	492	558	690	882		
- Active Line Module	А	443	502	621	794		
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	479	544	672	859		
- Active Line Module	А	431	489	605	774		
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>							
- Basic/Smart Line Module	А	437	496	614	784		
- Active Line Module	А	394	446	552	706		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.0	1.0	1.0	1.25		
• 500 V AC	А	3.0	3.0	3.0	4.4		
• 690 V AC	А	2.1	2.1	2.1	3.1		
DC link capacitance	μF	7400	7400	7400	11100		
Pulse frequency <sup>5)</sup>							
Rated frequency	kHz	1.25	1.25	1.25	1.25		
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25		
- With current derating	kHz	7.5	7.5	7.5	7.5		
Power loss, max. <sup>6)</sup>							
• At 50 Hz 690 V	kW	6.13	6.80	10.3	10.9		
• At 60 Hz 575 V	kW	5.71	6.32	9.7	10		
Cooling air requirement	m <sup>3</sup> /s	0.78	0.78	0.78	1.08		
<b>Sound pressure level </b> $L_{pA}$ (1 m) at 50/60 Hz	dB	70/73	70/73	70/73	71/73		
DC link connection DCP, DCN		4 × hole for M10 Busbar	4 × hole for M10 Busbar	$4 \times hole for M10$ Busbar	4 × hole for M10 Busbar		
Connection for Braking Module DCPA, DCNA <sup>7)</sup>		M8 stud	M8 stud	M8 stud	M8 stud		
Connection for dv/dt filter DCPS, DCNS		M10 screw	M10 screw	M10 screw	2 x M10 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	1 × 185	1 × 185	1 × 185	2 × 185		
Motor connection U2, V2, W2		2 × M12 screw	2 × M12 screw	2 × M12 screw	3 × M12 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	6 × 240		

Air-cooled units

#### **Motor Modules**

### Technical specifications (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3320-1TG34-1AA3	6SL3320-1TG34-7AA3	6SL3320-1TG35-8AA3	6SL3320-1TG37-4AA3	
Cable length, max. <sup>8)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
PE1/GND connection		M12 screw	M12 screw	M12 screw	M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	
PE2/GND connection		2 × M12 screw	2 × M12 screw	2 × M12 screw	3 × M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	3 × 240	
Degree of protection		IP00	IP00	IP00	IP00	
Dimensions						
• Width	mm	503	503	503	704	
Height	mm	1475	1475	1475	1475	
• Depth	mm	547	547	547	550	
Weight, approx.	kg	290	290	290	450	
Frame size		HX	HX	HX	JX	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Air-cooled units

Motor Modules

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules			
		6SL3320-1TG38-1AA3	6SL3320-1TG38-8AA3	6SL3320-1TG41-0AA3	6SL3320-1TG41-3AA3
Type rating					
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	800	900	1000	1200
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	710	800	900	1000
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	560	630	710	900
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	500	560	630	800
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	800	900	1000	1250
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	700	800	900	1000
Dutput current					
Rated current I <sub>rated O</sub>	А	810	910	1025	1270
• Base-load current $l_1^{(3)}$	А	790	880	1000	1230
• Base-load current $I_{\rm H}^{4)}$	А	724	814	917	1136
Maximum current I <sub>max O</sub>	А	1185	1320	1500	1845
DC link current					
Rated current <i>I</i> <sub>rated DC</sub> when supplied via					
- Basic/Smart Line Module	А	972	1092	1230	1524
- Active Line Module	А	875	983	1107	1372
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup></li> <li>when supplied via</li> </ul>					
- Basic/Smart Line Module	А	947	1064	1199	1485
- Active Line Module	А	853	958	1079	1337
Base-load current I <sub>H DC</sub> <sup>4)</sup> when supplied via					
- Basic/Smart Line Module	А	865	971	1094	1356
- Active Line Module	А	778	874	985	1221
Current demand					
24 V DC auxiliary power supply	А	1.25	1.4	1.4	1.4
500 V AC	А	4.4	4.4	4.4	4.4
690 V AC	А	3.1	3.1	3.1	3.1
DC link capacitance	μF	11100	14400	14400	19200
Pulse frequency <sup>5)</sup>					
Rated frequency	kHz	1.25	1.25	1.25	1.25
Pulse frequency, max.					
- Without current derating	kHz	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5
Power loss, max. <sup>6)</sup>					
At 50 Hz 690 V	kW	11.5	11.7	13.2	16.0
• At 60 Hz 575 V	kW	10.5	10.6	12.0	14.2
Cooling air requirement	m <sup>3</sup> /s	1.08	1.08	1.08	1.08
Sound pressure level L <sub>pA</sub> [1 m) at 50/60 Hz	dB	71/73	71/73	71/73	71/73
DC link connection DCP, DCN		4 × hole for M10 Busbar	4 × hole for M10 Busbar	$4 \times hole$ for M10 Busbar	4 × hole for M10 Busbar
Connection for Braking Module		M8 stud	M8 stud	M8 stud	M8 stud
DCPA, DCNA <sup>7)</sup>					
Connection for dv/dt filter		2 x M10 screw	2 x M10 screw	2 x M10 screw	2 x M10 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185
Motor connection J2, V2, W2		3 × M12 screw	3 × M12 screw	3 × M12 screw	3 × M12 screw
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	6 × 240	6 × 240	6 × 240	6 × 240

Technical specifications (continued)

Air-cooled units

#### **Motor Modules**

### Technical specifications (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3320-1TG38-1AA3	6SL3320-1TG38-8AA3	6SL3320-1TG41-0AA3	6SL3320-1TG41-3AA3	
Cable length, max. <sup>8)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
PE1/GND connection		M12 screw	M12 screw	M12 screw	M12 screw	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	
PE2/GND connection		3 × M12 screw				
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	3 × 240	3 × 240	3 × 240	3 × 240	
Degree of protection		IP00	IP00	IP00	IP00	
Dimensions						
• Width	mm	704	704	704	704	
• Height	mm	1475	1475	1475	1475	
• Depth	mm	550	550	550	550	
Weight, approx.	kg	450	450	450	450	
Frame size		JX	JX	JX	JX	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> The connecting cables are included in the scope of supply of the Braking Module.
- 8) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

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## **SINAMICS S120 Chassis Format Converter Units**

Air-cooled units

Mounting device for power blocks

## Overview



Power block mounting device for installing and removing the power blocks for the Basic Line Modules, Smart Line Modules, Active Line Modules, Power Modules, and Motor Modules in chassis format.

The mounting device is a mounting aid. It is placed in front of the module and attached to the module. The telescopic rails allow the device to be adjusted to the installation height of the power blocks.

Once the mechanical and electrical connections have been released, the Power block can be removed from the module.

The power block is guided and supported by the guide rails on the handling device.

Selection	and	ordering	data
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Description	Article No.
Mounting device	6SL3766-1FA00-0AA0
for installing and removing power blocks	

Liquid-cooled units

#### Overview



The SINAMICS S120 liquid-cooled drive units are specifically designed to address the requirements relating to liquid cooling; they are characterized by their high power density and optimized footprint. Liquid cooling dissipates heat much more efficiently than air cooling systems. As a result, liquid-cooled units are much more compact than air-cooled units with the same power rating. Since the heat losses generated by the liquid coolant, only very small cooling fans are required. This means that the devices are quiet in operation. Due to their compact dimensions and almost negligible cooling air requirement, liquid-cooled units are the preferred solution wherever installation space is restricted and/or the ambient operating conditions are rough.

Control cabinets with liquid cooling are easy to implement as sealed units with degrees of protection of IP55.

The product portfolio includes the following liquid-cooled SINAMICS S120 built-in units:

- Power Modules
- Basic Line Modules
- Active Line Modules
- Active Interface Modules
- Motor Modules

The associated system components such as line reactors, motor reactors, dv/dt filters plus VPL and sine-wave filters are air-cooled. Active Interface Modules are available in air-cooled and liquid-cooled versions.

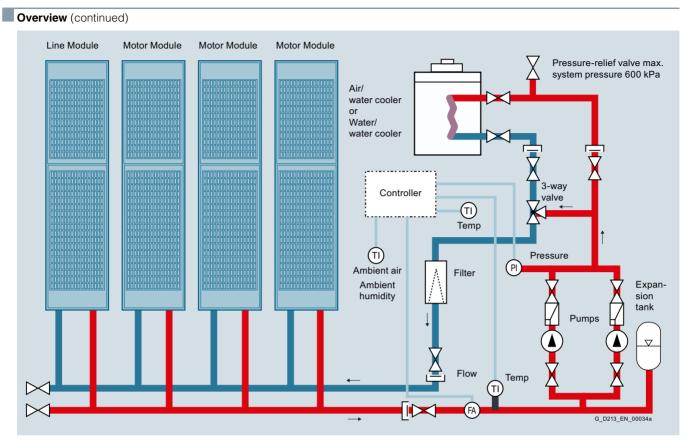
#### Highlights of the liquid-cooled units

- Up to a 60 % smaller footprint than air-cooled drive converters
- All main components such as power semiconductors, DC link capacitors and balancing resistors are cooled by the cooling circuit
- Only a low flow rate is required
- Uniform pressure drop of 0.7 bar
- Automatic protective functions
- Nickel-plated busbars
- Low noise
- Compatible with all components and functions and tools of the SINAMICS system family
- The power rating can be extended by connecting units in parallel
- No equipment fans

#### Cabinet units in liquid-cooled version

Liquid-cooled SINAMICS S120 drive units are also available as cabinet units, including cooling system (Heat Exchanger Module). See section SINAMICS S120 Cabinet Modules  $\rightarrow$  Liquid-cooled units.

Liquid-cooled units



Example of a drive line-up with SINAMICS S120 liquid-cooled units

#### Technical specifications

#### General technical specifications

Unless clearly specified otherwise, the following technical data are valid for all the following components of the liquid-cooled SINAMICS S120 drive system in chassis format.

Electrical specifications	
Rated voltages	380 480 V 3 AC ±10 % (-15 % <1 min) 500 690 V 3 AC ±10 % (-15 % <1 min)
Line supply types	Grounded TN/TT systems and non-grounded IT systems
Line frequency	47 63 Hz
Overvoltage category	III to EN 61800-5-1
Electronics power supply	24 V DC, -15 % +20 % implemented as PELV circuit in accordance with EN 61800-5-1 Ground = negative pole grounded via the electronics
Rated short-circuit currentper IEC, in conjunction with the specifiedfuses or circuit breakers• 1.1 447 kW• 448 671 kW• 672 1193 kW• > 1194 kW	65 kA 84 kA 170 kA 200 kA
Rated short-circuit current SCCR (Short Circuit Current Rating) according to UL508C (up to 600 V), in conjunction with the specified fuses or circuit breakers         • 1.1 447 kW         • 448 671 kW         • 672 1193 kW         • > 1194 kW	65 kA 84 kA 170 kA 200 kA

Liquid-cooled units

### **Technical specifications** (continued)

Electrical specifications	
Control method	Vector/Servo control with and without encoder or V/f control
Fixed speeds	15 fixed speeds plus 1 minimum speed, parameterizable (in the default setting, 3 fixed setpoints plus 1 minimum speed are selectable using terminal block/PROFIBUS/PROFINET)
Skippable speed ranges	4, parameterizable
Setpoint resolution	0.001 rpm digital (14 bits + sign) 12 bits analog
Braking operation	With Active Line Modules, four-quadrant operation as standard (energy recovery). With Basic Line Modules, two-quadrant operation as standard, braking by means of a Motor Module.

Degree of protection	IP00 (IP20, without taking into a	account the connecting busbars)				
Protection class	l acc. to EN 61800-5-1					
Touch protection	EN 50274/DGUV regulation 3 when used as intended					
Cooling method	Liquid cooling with integrated heat exchanger in aluminum or stainless steel version					
Ambient conditions	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation			
Ambient temperature (air)	-25 +55 °C Class 1K4 acc. to EN 60721-3-1	<u>-25</u> +70 °C Class 2K4 acc. to EN 60721-3-2	Line-side components, Power Modules, Line Modules and Motor Modules:			
			0 45 °C without derating >45 50 °C see derating characteristic curves			
			Control Units, supplementary system components, and Sensor Modules:			
			055 °C (for operation in a control cabinet)			
			DC link components and motor-side components: 0 55 °C			
Relative humidity Condensation, splashwater, and ice formation not permitted (EN 60204, Part 1)	<u>5 95 %</u> Class 1K4 acc. to EN 60721-3-1	Max. 95 % at 40 °C Class 2K4 acc. to EN 60721-3-2	5 <u>95 %</u> Class 3K3 acc. to EN 60721-3-3			
Environmental class/harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3			
Organic/biological influences	Class 1B1 acc. to EN 60721-3-1	Class 2B1 acc. to EN 60721-3-2	Class 3B1 acc. to EN 60721-3-3			
Degree of pollution	2 acc. to IEC/EN 61800-5-1					
Installation altitude	Up to 2000 m above sea level without derating, > 2000 m above sea level, refer to the derating data					
Mechanical stability	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation			
Vibratory load		Class 2M2 acc. to EN 60721-3-2	Test values acc. to EN 60068-2-6 test Fc:			
			<ul> <li>10 58 Hz with constant deflection 0.075 mm</li> </ul>			
			<ul> <li>58 150 Hz with constant acceleration 9.81 m/s<sup>2</sup> (1 × g)</li> </ul>			
Shock load		Class 2M2 acc. to EN 60721-3-2	Test values acc. to EN 60068-2-27 test Ea: 98 m/s <sup>2</sup> (10 × <i>g</i> )/20 ms			
Compliance with standards						
Conformances/certificates of suitability, according to	functional safety) RCM, RoHS II, DNV GL	l, Low Voltage Directive 2014/35/EU, cted to line supply voltages 380 48	and Machinery Directive 2006/42/EC for 30 V 3 AC and 500 600 V 3 AC			
Radio interference suppression	interference suppression is cor	mpliant with the EMC product standa	n to the public grid (first environment). Rad rd for variable-speed drives EN 61800-3, san occur when connected to the public gri			

1) In transport packaging.

Deviations from the specified class are underlined.

# Technical specifications (continued)

### Cooling circuit and coolant quality

The following tables and sections describe the quality requirements of the coolant used in the liquid-cooled SINAMICS S120 drive system in chassis format.

Cooling circuit	
<ul> <li>System pressure with reference to atmospheric pressure, max.</li> </ul>	600 kPa
Pressure drop at rated volumetric flow	70 kPa
<ul> <li>Recommended pressure range</li> </ul>	80 150 kPa (is applicable for water as coolant)
<ul> <li>Inlet temperature of liquid coolant</li> </ul>	Dependent on ambient temperature, no condensation permitted
	0 45° C without derating
	>45 50 °C, see derating data
	Antifreeze essential for temperature range between 0 °C and 5 °C
Coolant quality	
Coolant basis for aluminum heat sinks	Distilled, demineralized, completely desalinated water or deionized water with reduced electrical conductivity in accordance with ISO 3696, quality 3 or based on IEC 60993
<ul> <li>Electrical conductivity when filling</li> </ul>	<30 µS/cm (3 mS/m)
• pH value	5 8
<ul> <li>Components that can be oxidized as oxygen content</li> </ul>	<30 mg/l
<ul> <li>Residue after vaporization and drying at 110 °C</li> </ul>	<10 mg/kg
Coolant basis for stainless steel heat sinks	Filtered drinking, process, and cooling water
<ul> <li>Electrical conductivity</li> </ul>	<2500 µS/cm (250 mS/m)
• pH value	6.5 9
<ul> <li>Total salt content TDS</li> </ul>	<1550 mg/l
Chloride ions	<250 mg/l
• Sodium	<200 mg/l
Sulfate ions	<240 mg/l
Sulfide ions	<1 mg/l
Nitrate ions	<50 mg/l
• Iron	<1 mg/l
Silicate	<10 mg/l
<ul> <li>Ammonia (NH<sub>3</sub>), ammonium (NH<sub>4</sub>+)</li> </ul>	<1 mg/l
<ul> <li>Total hardness with a maximum of</li> </ul>	<1.78 mmol/l (10 °dH)
- Calcium hardness	<1.25 mmol/l (7 °dH), <57 mg/l calcium
- Magnesium hardness	< 1.43 mmol/l (8 °dH), <35 mg/l magnesium
- Carbonate hardness	<0.45 mmol/l (2.5 °dH)
• Suspended solids/suspended substances	
- Solids	<340 mg/l
- Size of entrained particles	<100 µm
	The coolant definition specified here should only be considered as recommendation. For units that have been shipped, the information and data provided in the equipment manual supplied should be observed.

The coolant definition specified here should only be considered as recommendation. For units that have been shipped, the information and data provided in the equipment manual supplied should be observed!

Liquid-cooled units

## Technical specifications (continued)

Antifreeze and inhibitors

Antifreeze	Antifrogen N	Antifrogen L	DOWCAL 100
Manufacturer	Clariant	Clariant	DOW
Chemical base	Ethylene glycol	Propylene glycol	Ethylene glycol
Minimum concentration	25 %	25 %	25 %
Antifreeze agent with minimum concentration	-10 °C	-10 °C	-10 °C
Maximum concentration	45 %	48 %	45 %
Antifreeze agent with maximum concentration	-30 °C	-30 °C	-30 °C
Inhibitor content	Contains inhibitors with nitrites	Contains inhibitors that are free of nitrates, amines, borates and phosphates	Contains inhibitors that are free of nitrates, amines and phosphates
Biocide action with a concentration of	>25 %	>25 %	>25 %

Biocides prevent corrosion that is caused by slime-forming, corrosive or iron-depositing bacteria. These can occur in closed cooling circuits with low water hardness and in open cooling circuits. Biocides must always be selected according to the relevant bacterial risks. Compatibility with inhibitors or antifreeze used with them must be checked on a case-by-case basis.

Inhibitors	Antifrogen N	ANTICORIT S 2000 A
Manufacturer	Clariant	Fuchs
Chemical base	Ethylene glycol	-
Minimum concentration	25 %	4 %
Maximum concentration	45 %	5 %

#### Recommended service

The manufacturer of the antifreeze/inhibitor should analyze the coolant at least once per annum. The concentration and boundary conditions of the antifreeze/inhibitor should be checked. It may be necessary to correct the concentration on the plant side.

### Technical specifications (continued)

#### Protection against condensation

With liquid-cooled units, warm air can condense on the cold surfaces of heat sinks, pipes and hoses. This condensation depends on the air humidity and the temperature difference between the ambient air and the coolant.

The water which is produced as a result of condensation can cause corrosion as well as electrical damage such as creepage shorts and flashovers. As the SINAMICS units cannot prevent condensation if it is caused by the prevailing climatic conditions, any potential risk of condensation must be prevented by appropriate engineering or by precautionary measures implemented by the customer. These measures include the following:

- a fixed coolant temperature that has been adjusted to the expected air humidity or ambient temperature ensures that critical differences between the coolant and ambient air temperatures do not develop or
- temperature regulation of the coolant as a function of the ambient air temperature

The temperature at which water vapor contained in the air condenses into water is known as the dew point. In order to reliably prevent condensation, the coolant temperature must always be higher than the dew point.

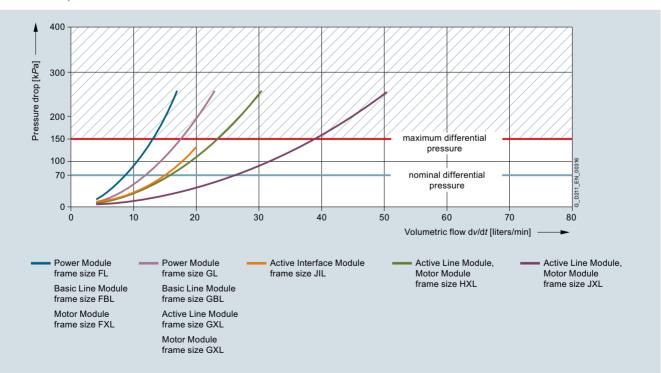
The table below specifies the dew point as a function of room temperature T and relative air humidity  $\Phi$  for an atmospheric pressure of 100 kPa (1 bar). This corresponds to an installation altitude of 0 up to approximately 500 m above sea level. Since the dew point drops as the air pressure decreases, the dew point values at higher installation altitudes are lower than the specified table values. It is therefore the safest approach to engineer the coolant temperature according to the values in the table for an installation altitude of zero.

A detailed description of the cooling circuits and the recommended coolant is given in the SINAMICS Low Voltage Engineering Manual.

Room temperature	Relative a	Relative air humidity $\Phi$									
Т	20 %	30 %	40 %	50 %	60 %	70 %	80 %	85 %	90 %	95 %	100 %
10 °C	<0 °C	<0 °C	<0 °C	0.2 °C	2.7 °C	4.8 °C	6.7 °C	7.6 °C	8.4 °C	9.2 °C	10 °C
20 °C	<0 °C	2 °C	6 °C	9.3 °C	12 °C	14.3 °C	16.4 °C	17.4 °C	18.3 °C	19.1 °C	20 °C
25 °C	0.6 °C	6.3 °C	10.5 °C	13.8 °C	16.7 °C	19.1 °C	21.2 °C	22.2 °C	23.2 °C	24.1 °C	24.9 °C
30 °C	4.7 °C	10.5 °C	14.9 °C	18.4 °C	21.3 °C	23.8 °C	26.1 °C	27.1 °C	28.1 °C	29 °C	29.9 °C
35 °C	8.7 °C	14.8 °C	19.3 °C	22.9 °C	26 °C	28.6 °C	30.9 °C	32 °C	33 °C	34 °C	34.9 °C
40 °C	12.8 °C	19.1 °C	23.7 °C	27.5 °C	30.6 °C	33.4 °C	35.8 °C	36.9 °C	37.9 °C	38.9 °C	39.9 °C
45 °C	16.8 °C	23.3 °C	28.2 °C	32 °C	35.3 °C	38.1 °C	40.6 °C	41.8 °C	42.9 °C	43.9 °C	44.9 °C
50 °C	20.8 °C	27.5 °C	32.6 °C	36.6 °C	40 °C	42.9 °C	45.5 °C	46.6 °C	47.8 °C	48.9 °C	49.9 °C

#### Characteristic curves

#### Pressure drop



Pressure drop for liquid-cooled built-in units in chassis format

The pressure drop characteristic curves are valid for water. If antifreeze is used, the characteristic curves typically shift to the left.

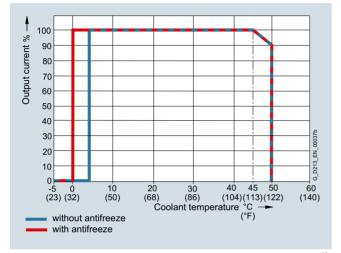
For further information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

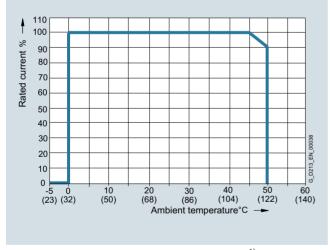
#### Characteristic curves (continued)

#### Derating

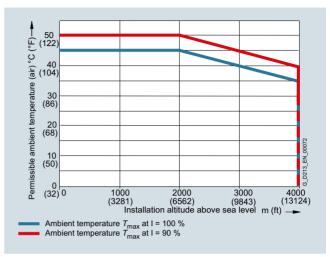
Liquid-cooled SINAMICS S120 chassis format units are rated for an ambient temperature of 45 °C and installation altitudes up to 2000 m above sea level. At ambient temperatures > 45 °C, the output current must be reduced. Ambient temperatures above 50 °C are not permissible. At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease.



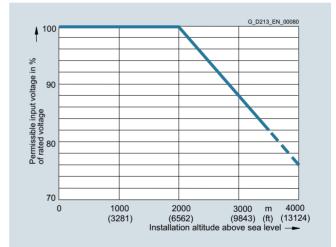
Current derating as a function of the temperature of the cooling liquid 1)



Current derating as a function of ambient temperature <sup>1)</sup>



Permissible ambient temperature as a function of installation altitude



Voltage derating as a function of installation altitude

1) The factors of the two curves must not be multiplied. The highest value in each case must be assumed for the purposes of calculation, so that the derating factor in the worst-case scenario is 0.9.

### Characteristic curves (continued)

Current derating for Power Modules and Motor Modules in chassis format as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased, the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

The following tables list the rated output currents of the SINAMICS S120 Power Modules and Motor Modules with pulse frequency set in the factory as well as the current derating factors (permissible output currents referred to the rated output current) for higher pulse frequencies.

#### Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 2 kHz

Power Module Motor Module	Type rating at 400 V	Output current at 2 kHz	Derating facto	r at pulse freque	ency		
6SL3315 6SL3325	kW	A	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC							
1TE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %
1TE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %
1TE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %
1TE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %
1TE41-4AS3 1)	800	1330	88 %	55 %	-	-	-

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 1.25 kHz

Motor Module	Type rating at 400 V or 690 V	Output current at 1.25 kHz	Derating f	actor at pulse fre	equency			
6SL3325	kW	А	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC								
1TE36-1AA3	315	605	83 %	72 %	64 %	60 %	40 %	-
1TE37-5AA3	400	745	83 %	72 %	64 %	60 %	40 %	-
1TE38-4AA3	450	840	87 %	79 %	64 %	60 %	40 %	-
1TE41-0AA3	560	985	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-2AA3	710	1260	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-4AA3	800	1405	97 %	95 %	74 %	60 %	50 %	47 %
500 690 V 3 AC								
1TG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %	-
1TG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %	-
1TG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %	-
1TG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %	-
1TG34-7AA3	450	465	92 %	87 %	67 %	55 %	35 %	-
1TG35-8AA3	560	575	91 %	85 %	64 %	50 %	35 %	-
1TG37-4AA3	710	735	84 %	74 %	53 %	40 %	25 %	-
1TG38-0AA3 <sup>2)</sup>	800	810	82 %	71 %	52 %	40 %	25 %	-
1TG38-1AA3	800	810	97 %	95 %	71 %	55 %	35 %	-
1TG41-0AA3	1000	1025	91 %	86 %	64 %	50 %	30 %	-
1TG41-3AA3	1200	1270	87 %	79 %	55 %	40 %	25 %	-
1TG41-6AP3	1500	1560	87 %	79 %	55 %	40 %	25 %	_

The following tables list the maximum achievable output frequency as a function of the pulse frequency:

Maximum output frequencies achieved by increasing the pulse frequency in Vector mode

Pulse frequency	Max. achievable output frequency
1.25 kHz	100 Hz
2 kHz	160 Hz
2.5 kHz	200 Hz
4 kHz	320 Hz
5 kHz	400 Hz

Maximum output frequencies achieved by increasing the pulse frequency in Servo mode

Pulse frequency	Max. achievable output frequency
2 kHz	300 Hz
4 kHz	300/550 Hz <sup>3)</sup>

<sup>&</sup>lt;sup>1)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance. The derating factor  $k_{\text{IGBT}}$  and the derating characteristic curves can be ignored (see section "Duty cycles" in the SINAMICS Low Voltage Engineering Manual).

<sup>&</sup>lt;sup>2)</sup> The Motor Module 6SL3325-1TG38-0AA3 is optimized for low overload; with an increased pulse frequency, the derating factor is higher than for the Motor Module 6SL3325-1TG38-1AA3.

Higher frequencies on request. For further information see https://support.industry.siemens.com/cs/document/104020669

Liquid-cooled units

### Characteristic curves (continued)

#### **Overload capability**

Liquid-cooled SINAMICS S120 units have an overload reserve, e.g. to handle breakaway torques. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base-load current must, therefore, be used as a basis for the required load.

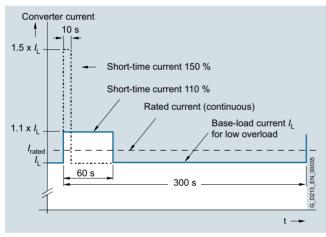
The permissible overload levels are valid under the prerequisite that the drive units are operated with their base-load current before and after the overload condition based on a duty cycle duration of 300 s.

Another precondition is that the Power Modules or the Motor Modules are operated at their factory-set pulse frequency at output frequencies > 10 Hz.

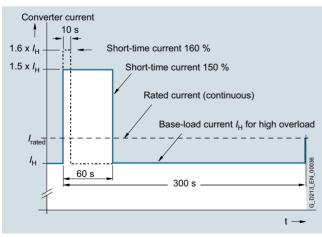
For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

#### Power Modules and Motor Modules

The base-load current for a low overload  $I_{\rm L}$  is the basis for a duty cycle of 110 % for 60 s or 150 % for 10 s.



Low overload



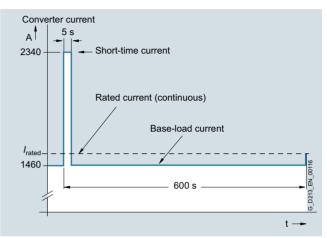
The base-load current  $I_{\rm H}$  for a high overload is based on a duty cycle of 150 % for 60 s or 160 % for 10 s.

#### High overload

#### The following applies to the Motor Module 6SL3325-1TG41-6AP3:

This Motor Module is particularly suited to high breakaway torques with applications such as drilling, mixers, centrifuges, and test bays. An **additional** duty cycle is required at output frequencies of 5 Hz to 10 Hz.

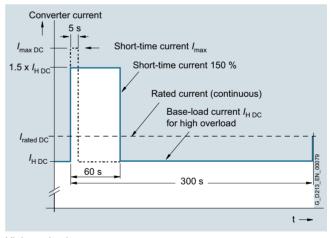
At output frequencies of 1 Hz to 5 Hz, the short-time current is 1900 A for 5 s.



High overload for Motor Module 6SL3325-1TG41-6AP3

#### Line Modules

The base-load current for a high overload  $I_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s.



High overload

Liquid-cooled units

**Power Modules** 

## Overview



The Power Module comprises a line rectifier, a DC link and a converter to supply the motor.

Power Modules are designed for drives that are not capable of regenerating energy to the mains supply. If the motor produces energy during braking, a Braking Module with braking resistors will be required.

Liquid-cooled Power Modules are especially suitable for applications where installation space is restricted and environmental conditions are harsh. Liquid cooling ensures efficient heat dissipation.

Power Modules in the chassis format can be connected to grounded TN/TT systems and non-grounded IT systems.

#### Design

The liquid-cooled Power Modules have the following interfaces as standard:

- 1 line supply connection
- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections
- 2 coolant connections

The CU310-2 Control Unit can be integrated into the liquidcooled Power Modules.

The status of the Power Modules is indicated via three LEDs.

The scope of supply of the Power Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 2 seals for coolant connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)
- <sup>1)</sup> Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies.

## Selection and ordering data

Type rating at 400 V	Rated output current	Power Module				
kW	А	Article No.				
Line voltage 380 480 V 3 AC						
110	210	6SL3315-1TE32-1AA3				
132	260	6SL3315-1TE32-6AA3				
160	310	6SL3315-1TE33-1AA3				
250 490		6SL3315-1TE35-0AA3				
Description		Article No.				
Accessories						
3-way valve 1)		VXF41/VXG41				
Actuator for 3-way va	alve <sup>1)</sup>					
• 230 V 1 AC		SAX31				
• 24 V AC/DC		SAX61/SAX81				
Accessories for re-ordering						
Dust protection blanking plugs (50 units)		6SL3066-4CA00-0AA0				

For DRIVE-CLiQ port

For additional information, refer to the manual.

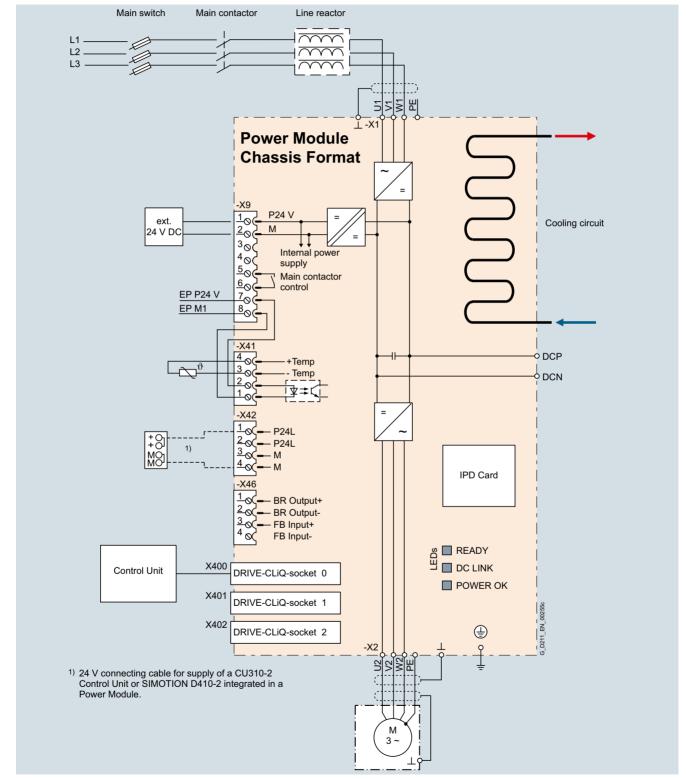
For line-side and motor-side components, see System components.

Liquid-cooled units

### **Power Modules**

### Integration

The Power Modules communicate with the higher-level control module via DRIVE-CLiQ. The Control Unit in this case could be a CU310-2, CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate liquid-cooled Power Modules.



Connection example of a liquid-cooled Power Module in the chassis format

#### Note:

The integrated 24 V power supply at connector X42 can have a maximum load of 2 A. When the Control Unit is supplied from the

integrated power supply, the total load of the digital outputs must be carefully observed to ensure that the 2 A is not exceeded.

3

Liquid-cooled units

**Power Modules** 

# Technical specifications

### General technical specifications

Electrical specifications			
Line connection voltage Up to 2000 m above sea level	380 480 V 3 AC ±10 % (-15 % < 1 min)		
Line power factor for a 3 AC line supply voltage and rated output			
• Basic fundamental (cos $\varphi_1$ )	>0.96		
<ul> <li>Total (λ)</li> </ul>	0.75 0.93		
Efficiency	> 98 %		
DC link voltage, approx.	1.35 × line voltage		
Output voltage, approx.	$0 \dots 0.97 \times U_{\text{line}}$		
Output frequency <sup>1)</sup>			
Control type Servo	0 550 Hz		
Control type Vector	0 550 Hz		
Control mode V/f	0 550 Hz		
Electronics power supply	24 V DC -15 %/+20 %		
Main contactor control			
Terminal block -X9/5-6	240 V AC, max. 8 A 30 V DC, max. 1 A		
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1.		

1) Please note:

The correlation between the maximum output frequency, pulse frequency and current derating. Higher output frequencies on request. For further information see https://support.industry.siemens.com/cs/document/104020669
 The correlation between the minimum output frequency and permissible output to uvrent (document derating)

output current (current derating). Information is provided in the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

#### **Power Modules**

#### **Technical specifications** (continued)

Line voltage 380 V 480 V 3 AC		Power Modules           6SL3315-1TE32-1AA3         6SL3315-1TE32-6AA3         6SL3315-1TE33-1AA3         6SL3315-1TE35-0AA3				
<b>Type rating</b> • At <i>l</i> <sub>L</sub> (50 Hz 400 V) <sup>1</sup> ) • At <i>l</i> <sub>H</sub> (50 Hz 400 V) <sup>1</sup> ) • At <i>l</i> <sub>L</sub> (60 Hz 460 V) <sup>2</sup> ) • At <i>l</i> <sub>H</sub> (60 Hz 460 V) <sup>2</sup> )	kW kW hp hp	<b>110</b> 90 150 150	<b>132</b> 110 200 200	<b>160</b> 132 250 200	<b>250</b> 200 400 350	
Output current         • Rated current lated 0, 3)         • Base-load current l_3)         • Base-load current l_4)         • Max. output current l_max 0	A A A A	210 205 178 307	260 250 233 375	310 302 277 453	490 477 438 715	
Input current • Rated current I <sub>rated I</sub> • Maximum current I <sub>max I</sub>	A A	230 336	285 411	340 496	540 788	
<ul><li>Current demand</li><li>24 V DC auxiliary power supply</li></ul>	A	1.4	1.4	1.5	1.5	
Pulse frequency <sup>5)</sup> • Rated frequency • Pulse frequency, max. - Without current derating - With current derating	kHz kHz kHz	2 2 8	2 2 8	2 2 8	2 2 8	
<ul> <li>Power loss, at 50 Hz 400 V <sup>6</sup>)</li> <li>Dissipated to coolant</li> <li>Dissipated to ambient air</li> <li>Total</li> </ul>	kW kW kW	2.36 0.06 2.42	2.97 0.07 3.04	3.31 0.09 3.4	5.29 0.14 5.43	
Coolant volume flow <sup>7)</sup>	l/min	9	9	12	12	
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.52	0.52	0.88	0.88	
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000	
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel	
Coolant connections Intake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4*, flat-sealing)				
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52	
Line supply connection U1, V1, W1 • Conductor cross-section, max. (IEC) DC link connection	mm <sup>2</sup>	Hole for M12 2 × 95 Hole for M12	Hole for M12 2 × 95 Hole for M12	Hole for M12 2 × 240 Hole for M12	Hole for M12 2 × 240 Hole for M12	
<ul><li>DCP, DCN</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	
Motor connection U2/T1, V2/T2, W2/T3		Hole for M12	Hole for M12	2 × hole for M12	$2 \times hole for M12$	
Conductor cross-section, max. (IEC)     Cable length, max <sup>9)     Shielded     Unshielded </sup>	mm <sup>2</sup> m m	2 × 95 300 450	2 × 95 300 450	2 × 240 300 450	2 × 240 300 450	
PE/GND connection     • Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × hole for M12 2 × 95	2 × hole for M12 2 × 95	2 × hole for M12 2 × 240	2 × hole for M12 2 × 240	
Dimensions • Width • Height • Depth	mm mm mm	265 836 549	265 836 549	265 983 549	265 983 549	
Weight, approx.	kg	77	77	108	108	
Frame size		FL	FL	GL	GL	
Minimum short-circuit current <sup>10)</sup>	А	3000	3600	4400	8000	

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.

<sup>3)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

<sup>4)</sup> The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

9) Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>Current required for reliably triggering protective devices.

Liquid-cooled units

**Basic Line Modules** 

### Overview



Basic Line Modules are used for applications where energy is not fed back into the line supply or where energy is exchanged in the DC link between axes operating in the motor and generator modes. The connected Motor Modules are pre-charged via the thyristor gate control. Basic Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

Liquid-cooled Basic Line Modules are especially suitable for applications where installation space is restricted and environmental conditions are harsh. Liquid cooling ensures efficient heat dissipation.

#### Design

The liquid-cooled Basic Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 PE connection
- 2 coolant connections

The status of the Basic Line Modules is indicated via three LEDs.

The scope of supply of the Power Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 2 seals for coolant connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

Rated power at 400 V or 690 V	Rated DC link current	Basic Line Module	
kW	А	Article No.	
Line voltage 380	480 V 3 AC		
360	740	6SL3335-1TE37-4AA3	
600	1220	6SL3335-1TE41-2AA3	
830	1730	6SL3335-1TE41-7AA3	
Line voltage 500	690 V 3 AC		
355	420	6SL3335-1TG34-2AA3	
630	730	6SL3335-1TG37-3AA3	
1100	1300	6SL3335-1TG41-3AA3	
1370	1650	6SL3335-1TG41-7AA3	
Description		Article No.	
Accessories			
3-way valve <sup>1)</sup>		VXF41/VXG41	
Actuator for 3-way	valve <sup>1)</sup>		
• 230 V 1 AC		SAX31	
• 24 V AC/DC		SAX61/SAX81	
Accessories for re-	ordering		
Dust protection bla	nkina pluas	6SL3066-4CA00-0AA0	

Dust protection blanking plugs 6SL3066-4CA00-0AAC (50 units) For DRIVE-CLiQ port

For line-side components, see System components.

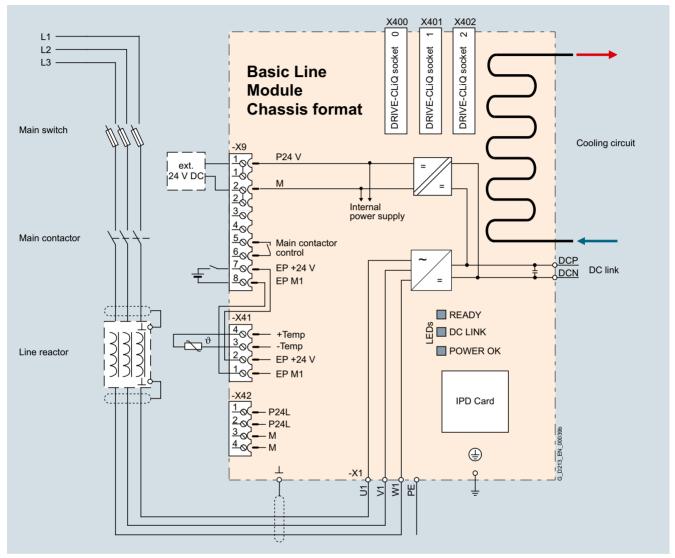
 Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies.

Liquid-cooled units

#### **Basic Line Modules**

### Integration

The liquid-cooled Basic Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate liquid-cooled Basic Line Modules.



Connection example of a Basic Line Module

#### Technical specifications

#### General technical specifications

Electrical specifications	
Line power factor at rated power	
• Basic fundamental (cos $\varphi_1$ )	>0.96
• Total ( $\lambda$ )	0.75 0.93
Efficiency	>99 %
DC link voltage, approx. 1)	1.35 × line voltage
Main contactor control	
Terminal block -X9/5-6	240 V AC, max. 8 A 30 V DC, max. 1 A

 The DC link voltage is unregulated and load-dependent. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

**Basic Line Modules** 

Line voltage 380 480 V 3 AC		Basic Line Modules		
Line voltage 380 480 v 3 AC		6SL3335-1TE37-4AA3	6SL3335-1TE41-2AA3	6SL3335-1TE41-7AA3
Rated power		0020000-11207-4740	0020000-11241-2000	0020000-11241-7740
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	360	600	830
• At I <sub>H</sub> (50 Hz 400 V)	kW	280	450	650
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	555	925	1280
• At I <sub>H</sub> (60 Hz 460 V)	hp	430	690	1000
DC link current	пр	-00		1000
<ul> <li>Rated current Irated DC</li> </ul>	А	740	1220	1730
• Base-load current $I_{H DC}^{(1)}$	A	578	936	1350
Maximum current I <sub>max DC</sub>	A	1110	1830	2595
nput current	,,	1110	1000	2000
<ul> <li>Rated current Irated I</li> </ul>	А	610	1000	1420
Maximum current I <sub>max I</sub>	A	915	1500	2130
Current demand	/ \	010	1000	2100
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.7	0.7	0.7
DC link capacitance	~	0.7	0.7	0.7
Basic Line Module	μF	12000	20300	26100
<ul> <li>Drive line-up, max.</li> </ul>	μF	96000	162400	208800
Power loss, at 50 Hz 400 V <sup>2)</sup>	μι		102+00	20000
<ul> <li>Dissipated to coolant</li> </ul>	kW	2.7	4.36	5.82
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.25	0.41	0.57
• Total	kW	2.95	4.77	6.39
Coolant volume flow <sup>3)</sup>	l/min	9	9	12
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.45	0.45	0.79
Pressure drop, typ. <sup>4)</sup> for volume flow	Pa	70000	70000	70000
Heat exchanger material		Aluminum	Aluminum	Aluminum
Coolant connections ntake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-seal	ing)	
<b>Sound pressure level L<sub>pA</sub></b> 1 m) at 50/60 Hz	dB	54	56	56
L <b>ine supply connection</b> J1, V1, W1		2 × M12 nut	2 × M12 nut	2 × M12 nut
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240
DC link connection DCP, DCN		2 × M12 nut Busbar	2 × M12 nut Busbar	2 × M12 nut Busbar
PE/GND connection		2 × M12 nut	2 × M12 nut	2 × M12 nut
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240
Cable length, max. <sup>5)</sup>				
Shielded	m	2600	4000	4800
• Unshielded	m	3900	6000	7200
Dimensions				
• Width	mm	160	160	160
Height	mm	1137	1137	1562
• Depth	mm	545	545	545
Weight, approx.	kg	108	108	185
Frame size		FBL	FBL	GBL

 $^{1)}$  The base-load current  $\mathit{I}_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $\mathit{I}_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

3) The value applies to coolants comprising water and a mixture of water and antifreeze agent.

 $^{\rm 5)}$  Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> Current required for reliably triggering protective devices.

3

Liquid-cooled units

#### **Basic Line Modules**

#### Technical specifications (continued)

Line voltage 500 690 V 3 AC		Basic Line Modules					
		6SL3335-1TG34-2AA3	6SL3335-1TG37-3AA3	6SL3335-1TG41-3AA3	6SL3335-1TG41-7AA3		
Rated power							
<ul> <li>At I<sub>rated DC</sub> (50 Hz 690 V)</li> </ul>	kW	355	630	1100	1370		
• At I <sub>H</sub> (50 Hz 690 V)	kW	275	475	840	1070		
• At I <sub>rated DC</sub> (50 Hz 500 V)	kW	245	420	750	950		
• At I <sub>H</sub> (50 Hz 500 V)	kW	200	345	610	775		
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	395	705	1230	1530		
• At I <sub>H</sub> (60 Hz 575 V)	hp	305	530	940	1195		
DC link current							
Rated current Irated DC	А	420	730	1300	1650		
Base-load current I <sub>H DC</sub> <sup>1)</sup>	А	328	570	1014	1287		
Maximum current I <sub>max DC</sub>	А	630	1095	1950	2475		
Input current							
Rated current Irated I	А	340	600	1070	1350		
Maximum current Imax I	А	510	900	1605	2025		
Current demand							
• 24 V DC auxiliary power supply	А	0.7	0.7	0.7	0.7		
DC link capacitance							
Basic Line Module	μF	4800	7700	15500	19300		
• Drive line-up, max.	μF	38400	61600	124000	154400		
Power loss, at 50 Hz 690 V <sup>2)</sup>	-						
<ul> <li>Dissipated to coolant</li> </ul>	kW	1.55	2.71	4.66	5.7		
Dissipated to ambient air	kW	0.21	0.38	0.43	0.55		
Total	kW	1.76	3.09	5.09	6.25		
Coolant volume flow <sup>3)</sup>	l/min	9	9	12	12		
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.45	0.45	0.79	0.79		
Pressure drop, typ. <sup>4)</sup> for volume flow	Pa	70000	70000	70000	70000		
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum		
Coolant connections Intake/return		Pipe thread ISO 228 G 3/ (external thread 3/4", flat-					
<b>Sound pressure level L<sub>pA</sub></b> (1 m) at 50/60 Hz	dB	54	54	56	56		
Line supply connection U1, V1, W1		2 × M12 nut	2 × M12 nut	$2 \times M12$ nut	2 × M12 nut		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	4 × 240		
DC link connection DCP, DCN		2 × M12 nut Busbar	2 × M12 nut Busbar	2 × M12 nut Busbar	2 × M12 nut Busbar		
PE/GND connection		2 × M12 nut	2 × M12 nut	2 × M12 nut	2 × M12 nut		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	4 × 240		
Cable length, max. <sup>5)</sup>							
Shielded	m	1500	1500	2250	2250		
Unshielded	m	2250	2250	3375	3375		
Dimensions							
• Width	mm	160	160	160	160		
• Height	mm	1137	1137	1562	1562		
• Depth	mm	545	545	545	545		
Weight, approx.	kg	108	108	185	185		
Frame size		FBL	FBL	GBL	GBL		
Minimum short-circuit current <sup>6)</sup>	А	4400	7200	16800	18900		

 $^{1)}$  The base-load current  $\mathit{I}_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $\mathit{I}_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
 <sup>3)</sup> The value applies to coolants comprising water and a mixture of water and

4) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> Current required for reliably triggering protective devices.

antifreeze agent.

Liquid-cooled units

Active Line Modules

### Overview



The self-commutated infeed/regenerative feedback units (with IGBTs in infeed and regenerative feedback directions) generate a regulated DC link voltage. This means that the connected Motor Modules are decoupled from the line voltage. Line voltage fluctuations within the permissible supply tolerances have no effect on the motor voltage.

If required, the Active Line Modules can also provide reactive power compensation.

Active Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

Liquid-cooled Active Line Modules are especially suitable for applications where installation space is restricted and environmental conditions are harsh. Liquid cooling ensures efficient heat dissipation.

Active Line Modules are always operated together with the associated Active Interface Modules. These include the necessary pre-charging circuit as well as a Clean Power Filter.

#### Design

The liquid-cooled Active Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 PE connection
- · 2 coolant connections

The status of the Active Line Modules is indicated via three LEDs.

The following are included in the scope of supply of the Active Line Modules:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 2 seals for coolant connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

Rated power at 400 V or 690 V	Rated infeed/ regenerative feedback current	Active Line Module	
kW	А	Article No.	
Line voltage 380	. 480 V 3 AC		
300	490	6SL3335-7TE35-0AA3	
380	605	6SL3335-7TE36-1AA3	
500	840	6SL3335-7TE38-4AA3	
630	985	6SL3335-7TE41-0AA3	
900	1405	6SL3335-7TE41-4AA3	
Line voltage 500	. 690 V 3 AC		
630	575	6SL3335-7TG35-8AA3	
800	735	6SL3335-7TG37-4AA3	
900	810	6SL3335-7TG38-1AA3	
1100	1020	6SL3335-7TG41-0AA3	
1400	1270	6SL3335-7TG41-3AA3	
1700	1560	6SL3335-7TG41-6AA3	
Description		Article No.	
Accessories			
3-way valve <sup>1)</sup>		VXF41/VXG41	
Actuator for 3-way	v valve <sup>1)</sup>		
• 230 V 1 AC		SAX31	
• 24 V AC/DC		SAX61/SAX81	
Accessories for re	e-ordering		

For DRIVE-CLiQ port

For line-side components and recommended system components, see system components.

 Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies. 5

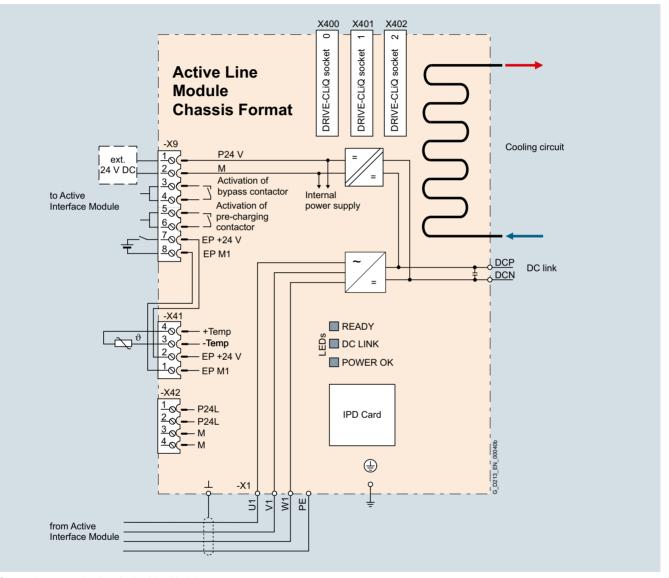
Liquid-cooled units

### **Active Line Modules**

### Integration

Active Line Modules are always operated together with the associated Active Interface Modules. Active Interface Modules contain a Clean Power Filter with basic RI suppression, the precharging circuit for the Active Line Module, line supply voltage sensing circuit and monitoring sensors.

The liquid-cooled Active Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate the Active Line Modules.



Connection example of an Active Line Module

#### Technical specifications

General technical specifications

Electrical specifications	
Line power factor	
• Basic fundamental (cos $\varphi_1$ )	1 (factory setting), can be altered by inputting a reactive current setpoint
<ul> <li>Total (λ)</li> </ul>	1 (factory setting)
Efficiency	>98.5 % (Active Line Modules) >99 % (Active Interface Module)
DC link voltage, approx.	The DC link voltage is regulated and can be adjusted as a voltage decoupled from the line voltage. Factory setting of the DC link voltage: $1.5 \times$ line voltage

Liquid-cooled units

**Active Line Modules** 

Line voltage 380 V 480 V 3 AC		Active Line Modules							
		6SL3335-	6SL3335-	6SL3335-	6SL3335-	6SL3335-			
<b>-</b>		7TE35-0AA3	7TE36-1AA3	7TE38-4AA3	7TE41-0AA3	7TE41-4AA3			
Rated power									
• At <i>I</i> <sub>rated DC</sub> (50 Hz 400 V)	kW	300	380	500	630	900			
• At / <sub>H DC</sub> (50 Hz 400 V)	kW	270	335	465	545	780			
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	500	600	700	900	1250			
• At / <sub>H DC</sub> (60 Hz 460 V)	hp	400	500	700	800	1000			
DC link current									
Rated current I <sub>rated DC</sub>	A	549	677	941	1100	1573			
<ul> <li>Base-load current I<sub>H DC</sub><sup>1)</sup></li> </ul>	A	489	603	837	982	1401			
Maximum current I <sub>max DC</sub>	А	823	1017	1410	1654	2361			
Infeed/regenerative feedback current									
<ul> <li>Rated current I<sub>rated I</sub></li> </ul>	А	490	605	840	985	1405			
<ul> <li>Maximum current I<sub>max I</sub></li> </ul>	А	735	907	1260	1477	2055			
Current demand									
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.5	1.6	1.6	1.6	1.6			
DC link capacitance									
Active Line Module	μF	9600	12600	17400	18900	28800			
• Drive line-up, max.	μF	76800	134400	134400	230400	230400			
Pulse frequency	kHz	4	2.5	2.5	2.5	2.5			
Power loss, at 50 Hz 400 V <sup>2)</sup>									
<ul> <li>Dissipated to coolant</li> </ul>	kW	3.42	4.65	5.52	7.46	9.58			
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.14	0.17	0.23	0.44	0.62			
Total	kW	3.56	4.82	5.75	7.9	10.2			
Coolant volume flow <sup>3)</sup>	l/min	12	16	16	27	27			
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.91	0.74	0.74	1.56	1.56			
Pressure drop, typ. <sup>4)</sup> for volume flow	Pa	70000	70000	70000	70000	70000			
Heat exchanger material		Stainless steel	Aluminum	Aluminum	Aluminum	Aluminum			
Coolant connections Intake/return		Pipe thread ISO 228 (external thread 3/4							
Sound pressure level L <sub>pA</sub> <sup>5)</sup> (1 m) at 50/60 Hz	dB	69/73	70/73	70/73	71/73	71/73			
Line supply connection U1, V1, W1		Hole for M12	2 x hole for M12	2 x hole for M12	2 x hole for M12	2 x hole for M12			
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	4 × 185	4 × 185	Busbar	Busbar			
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar			
PE/GND connection		$2 \times hole$ for M12	$2 \times hole$ for M12	$2 \times \text{hole for M12}$	$2 \times hole for M12$	$2 \times \text{hole for M12}$			
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	4 × 185	4 × 185	4 × 240	4 × 240			
Cable length, max. <sup>6)</sup>									
Shielded	m	2700	3900	3900	3900	3900			
Unshielded	m	4050	5850	5850	5850	5850			
Dimensions									
• Width	mm	150	265	265	295	295			
Height	mm	1172	1002	1002	1516	1516			
• Depth	mm	545	545	545	545	545			
Weight, approx.	kg	80	110	110	220	220			
Frame size	-	GXL	HXL	HXL	JXL	JXL			
Minimum short-circuit current <sup>7)</sup>	А	8000	9200	10400	16000	21000			

 $^{1)}$  The base-load current  $\mathit{I}_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $\mathit{I}_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

Technical specifications (continued)

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

<sup>3)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent. 4) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

<sup>6)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

7) Current required for reliably triggering protective devices.

Liquid-cooled units

#### **Active Line Modules**

#### **Technical specifications** (continued)

Line voltage 500 690 V 3 AC		Active Line Modules						
		6SL3335- 7TG35-8AA3	6SL3335- 7TG37-4AA3	6SL3335- 7TG38-1AA3	6SL3335- 7TG41-0AA3	6SL3335- 7TG41-3AA3	6SL3335- 7TG41-6AA3	
Rated power								
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	630	800	900	1100	1400	1700	
• At I <sub>H DC</sub> (50 Hz 690 V)	kW	620	705	670	1000	1215	1490	
• At <i>I</i> <sub>rated DC</sub> (50 Hz 500 V)	kW	447	560	620	780	965	1180	
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	450	510	485	710	880	1080	
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	675	900	975	1250	1500	1880	
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	506	600	765	1000	1250	1530	
DC link current	πp	500	000	705	1000	1230	1330	
Rated current I <sub>rated DC</sub>	А	644	823	907	1147	1422	1740	
• Base-load current / <sub>H DC</sub> <sup>1)</sup>	A	573	732	808	936	1266	1550	
Maximum current I <sub>max DC</sub>	A	966	1235	1360	1722	2133	2620	
Infeed/regenerative feedback current								
Rated current I     rated I	A	575	735	810	1025	1270	1560	
<ul> <li>Maximum current I<sub>max I</sub></li> </ul>	А	862	1100	1214	1537	1905	2055	
Current demand								
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.6	1.6	1.6	1.46	1.5	
DC link capacitance								
Active Line Module	μF	9670	10500	10500	16000	19330	21000	
<ul> <li>Drive line-up, max.</li> </ul>	μF	59200	153600	153600	153600	153600	210000	
Pulse frequency	kHz	2.5	2.5	2.5	2.5	2.5	2.5	
Power loss, at 50 Hz 690 V <sup>2)</sup>								
<ul> <li>Dissipated to coolant</li> </ul>	kW	5.45	7.45	8.28	10.37	12.98	17.17	
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.16	0.2	0.22	0.53	0.57	0.79	
Total	kW	5.61	7.65	8.5	10.9	13.55	17.96	
Coolant volume flow <sup>3)</sup>	I/min	16	16	16	27	27	27	
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.74	0.74	0.74	1.56	1.56	1.56	
Pressure drop, typ. <sup>4)</sup> for volume flow	Pa	70000	70000	70000	70000	70000	70000	
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum	Aluminum	Aluminum	
Coolant connections Intake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)						
Sound pressure level L <sub>pA</sub> <sup>5)</sup> (1 m) at 50/60 Hz	dB	70/73	71/73	71/73	71/73	71/73	71/73	
Line supply connection U1, V1, W1		2 × hole for M12	$2 \times \text{hole for M12}$	2 × hole for M12				
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	4 × 185	Busbar	Busbar	Busbar	
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	
PE/GND connection		$2 \times hole for M12$	$2 \times \text{hole for M12}$					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	4 × 185	Busbar	Busbar	Busbar	
Cable length, max. <sup>6)</sup>								
Shielded	m	2250	2250	2250	2250	2250	2250	
Unshielded	m	3375	3375	3375	3375	3375	3375	
Dimensions								
• Width	mm	265	265	265	295	295	295	
• Height	mm	1002	1002	1002	1516	1516	1516	
Depth	mm	545	545	545	545	545	545	
Weight, approx.	kg	110	110	110	220	220	230	
		. 10						
Frame size		HXL	HXL	HXL	JXL	JXL	JXL	

 $^{1)}$  The base-load current  $\mathit{I}_{H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $\mathit{I}_{max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

- The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- <sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>5)</sup> Total sound pressure level of Active Interface Module and Active Line Module.
- <sup>6)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> Current required for reliably triggering protective devices.

Liquid-cooled units

**Active Interface Modules** 

### Overview



The Active Interface Module essentially comprises a liquidcooled filter reactor and a liquid-cooled filter module. The filter module contains a Clean Power Filter with basic RI suppression, the pre-charging circuit for the Active Line Module, the line voltage sensing circuit and monitoring sensors.

A bypass contactor is provided separately. Active Interface Modules are used in conjunction with Active Line Modules.

Liquid-cooled Active Interface Modules cannot be supplied for all liquid-cooled Active Line Modules. Where they are not available, air-cooled Active Interface Modules can be ordered instead.

# Design

Active Interface Modules have the following interfaces as standard:

- 1 line supply connection
- 1 load connection
- 1 connection for the 24 V DC electronics power supply
- 1 connection for the external 230 V AC supply
- 1 DRIVE-CLiQ socket (on VSM10 Voltage Sensing Module)
- 1 connection for pre-charging circuit
- 1 PE connection
- 2 coolant connections

The scope of supply of the Active Interface Modules includes:

- Liquid-cooled filter reactor
- Liquid-cooled filter module
- Connection kit (cables and hoses)
- DRIVE-CLiQ cable for the connection between Active Interface Module and Active Line Module
- · 2 seals for coolant connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

#### Selection and ordering data

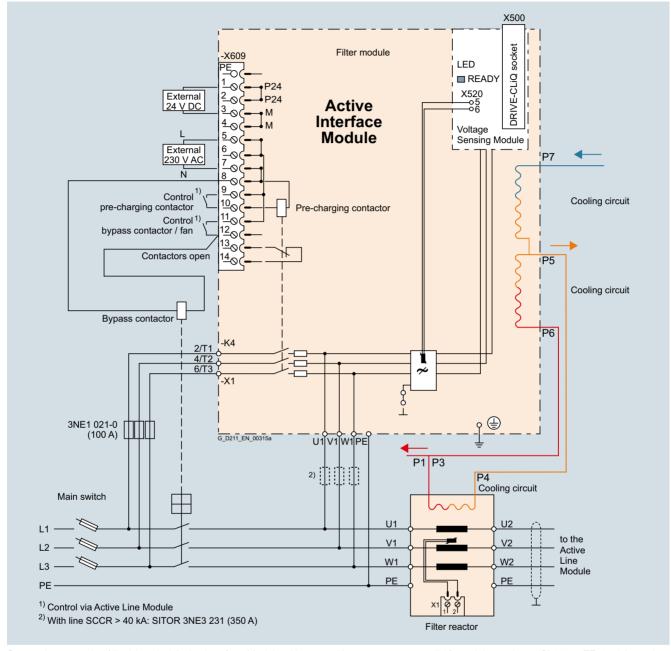
Suitable for Active Line Module chassis format, liquid-cooled	Rated power of the Active Line Modules at 400 V or 690 V	Active Interface Module, liquid-cooled	Active Interface Module, air-cooled
	kW	Article No.	Article No.
Line voltage 380 480 V 3 AC			
6SL3335-7TE35-0AA3	300	_ 1)	6SL3300-7TE35-0AA1
6SL3335-7TE36-1AA3	380	6SL3305-7TE38-4AA5	-
6SL3335-7TE38-4AA3	500	6SL3305-7TE38-4AA5	-
6SL3335-7TE41-0AA3	630	6SL3305-7TE41-4AA5	-
6SL3335-7TE41-4AA3	900	6SL3305-7TE41-4AA5	-
Line voltage 500 690 V 3 AC			
6SL3335-7TG35-8AA3	630	_ <sup>1)</sup>	6SL3300-7TG35-8AA1
6SL3335-7TG37-4AA3	800	6SL3305-7TG37-4AA5	-
6SL3335-7TG38-1AA3	900	6SL3305-7TG41-0AA5	-
6SL3335-7TG41-0AA3	1100	6SL3305-7TG41-0AA5	-
6SL3335-7TG41-3AA3	1400	6SL3305-7TG41-3AA5	-
6SL3335-7TG41-6AA3	1700	6SL3305-7TG41-6AA5	-

<sup>1)</sup> For these power ratings, no liquid-cooled Active Interface Modules are available. Air-cooled devices can be alternatively used. See the right-hand column and additional information in section Air-cooled Active Interface Modules from page 3/30.

Liquid-cooled units

#### Active Interface Modules

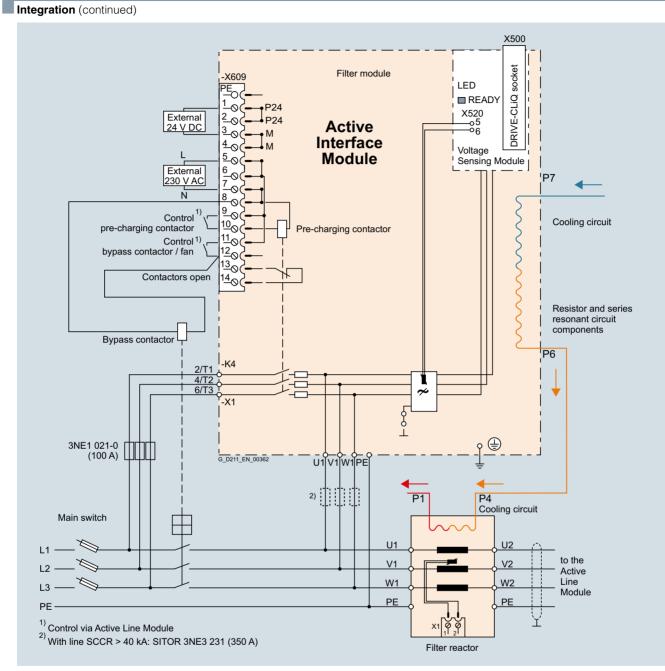
## Integration



Connection example of liquid-cooled Active Interface Module with external bypass contactor, valid for article numbers 6SL3305-7TE41-4AA5 and 6SL3305-7TG41-6AA5

Liquid-cooled units

Active Interface Modules



Connection example of liquid-cooled Active Interface Module with external bypass contactor, valid for article numbers 6SL3305-7TE38-4AA5, 6SL3305-7TG41-0AA5, and 6SL3305-7TG41-3AA5

Liquid-cooled units

### **Active Interface Modules**

# Technical specifications

Line voltage 380 480 V 3 AC		Active Interface Module					
		6SL3305-7TE38-4AA5		6SL3305-7TE41-4AA5	41-4AA5		
Suitable for Active Line Module • Rated power at 400 V - Liquid-cooled	kW	<b>380</b> 6SL3335-7TE36-1AA3	<b>500</b> 6SL3335-7TE38-4AA3	<b>630</b> 6SL3335-7TE41-0AA3	<b>900</b> 6SL3335-7TE41-4AA3		
Rated current Bypass contactor <sup>1)</sup>	A	605 3RT1476-6AP36	840 3WL1110-2BB34-4AN2-Z C22 <sup>2)</sup>	985 3WL1112-2BB34-4AN2-Z C22 <sup>2)</sup>	1405 3WL1116-2BB34-4AN2-Z Z = C22 <sup>2)</sup>		
Current demand • 24 V DC auxiliary power supply • 230 V 2 AC	A	0.17	0.17	0.17	0.17		
<ul> <li>Inrush current</li> <li>Holding current</li> </ul>	A A	1.0 0.1	1.0 0.1	1.0 0.1	1.0 0.1		
<b>DC link capacitance</b> of the drive line-up, max. <sup>3)</sup>	μF	134400	134400	230400	230400		
Coolant volume flow	l/min	10	10	16	16		
Pressure drop, typ. for volume flow	Pa	70000	70000	70000	70000		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	71/71	71/71	71/71	71/71		
Frame size		JIL	JIL	JIL	JIL		
Filter reactor							
Power loss <sup>4</sup> ) • At 50 Hz 400 V • At 60 Hz 460 V	kW kW	3.5 3.5	3.5 3.5	8.6 8.6	8.6 8.6		
Dissipated to ambient air	kW	1.2	1.2	0.9	0.9		
<ul> <li>Liquid volume</li> <li>Of integrated reactor cooler</li> <li>Of hoses supplied</li> </ul>	dm <sup>3</sup> dm <sup>3</sup> /m	0.6 0.285	0.6 0.285	0.6 0.285	0.6 0.285		
Coolant volume flow	l/min	10	10	8	8		
Pressure drop, typ. for volume flow	Pa	70000	70000	70000	70000		
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum		
Coolant connections Return and connection to filter module		Pipe thread ISO 228 G 3/ (external thread 3/4", flat-					
Line/load connection L1, L2, L3 / U2, V2, W2		Flat connector for M12 screws	Flat connector for M12 screws	Flat connector for M12 screws	Flat connector for M12 screws		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	M10 stud 1 × 240	M10 stud 1 × 240	M10 stud 1 × 240	M10 stud 1 × 240		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions • Width • Height • Depth	mm mm mm	349 700 575	349 700 575	382 698 575	382 698 575		
Weight, approx.	kg	230	230	299	299		
Filter module Power loss <sup>4</sup> ) • At 50 Hz 400 V	kW	2.7	2.7	3.6	3.6		
<ul> <li>At 60 Hz 460 V</li> <li>Dissipated to ambient air</li> </ul>	kW kW	2.7 0.15	2.7 0.15	3.6 0.15	3.6 0.15		
Liquid volume	dm <sup>3</sup>	1	1	1	1		
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum		
Coolant connections Intake and connection to filter reactor		Pipe thread ISO 228 G 3/ (external thread 3/4", flat-					
PE/GND connection	2	Flat connector for M8 screw	Flat connector for M8 screw	Flat connector for M8 screw	Flat connector for M8 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 120	2 × 120	2 × 120	2 × 120		
Degree of protection Dimensions		IP00	IP00	IP00	IP00		
Width     Height     Depth	mm mm mm	506 840 574	506 840 574	506 840 574	506 840 574		
Weight, approx.	kg	110	110	110	110		
	ng.						

<sup>1)</sup> The bypass contactor is not included in the scope of supply.

<sup>2)</sup> The breakers must only be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Active Line Module.

3)	Information on higher capacitances is included in the SINAMICS Low
	Voltage Engineering Manual.

<sup>4)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

**Active Interface Modules** 

Line voltage 500 690 V 3 AC		Active Interface Modules					
		6SL3305-7TG37-4AA5 6SL3305-7TG41-0AA5 6SL3305-7TG41-3A			6SL3305-7TG41-6AA5		
Suitable for Active Line Module <ul> <li>Rated power at 690 V</li> <li>Liquid-cooled</li> </ul>	kW	<b>800</b> 6SL3335-7TG37-4AA3	<b>900/1100</b> 6SL3335-7TG38-1AA3 6SL3335-7TG41-0AA3	<b>1400</b> 6SL3335-7TG41-3AA3	<b>1700</b> 6SL3335-7TG41-6AA3		
Rated current	А	735	1025	1270	1560		
Bypass contactor <sup>1)</sup>		3RT1476-6AP36 (3 units)	3WL1212-4BB34-4AN2-Z C22 <sup>2)</sup>	3WL1216-4BB34-4AN2-Z C22 <sup>2)</sup>	3WL1216-4BB34-4AN2-Z C22 <sup>2)</sup>		
Current demand • 24 V DC auxiliary power supply • 230 V 2 AC - Inrush current	A A	0.17	0.17 1.0	0.17	0.17 1.0		
- Holding current	А	0.1	0.1	0.1	0.1		
<b>DC link capacitance</b> of the drive line-up, max. <sup>3)</sup>	μF	153600	153600	153600	210000		
Coolant volume flow	l/min	10	16	16	16		
Pressure drop, typ. for volume flow	Pa	70000	70000	70000	70000		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	71/71	71/71	71/71	71/71		
Frame size		JIL	JIL	JIL	JIL		
Filter reactor							
Power loss <sup>4)</sup> • At 50 Hz 690 V • At 60 Hz 575 V • Dissipated to ambient air	kW kW kW	5.5 5.5 0.5	6.2 6.2 0.6	9.3 9.3 0.95	11.0 11.0 1.15		
<ul><li>Liquid volume</li><li>Of integrated reactor cooler</li><li>Of hoses supplied</li></ul>	dm <sup>3</sup> dm <sup>3</sup> /m	0.6 0.285	0.6 0.285	0.6 0.285	0.6 0.285		
Coolant volume flow	l/min	10	10	10	8		
Pressure drop, typ. for volume flow	Pa	70000	70000	70000	70000		
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum		
Coolant connections Return and connection to filter module		Pipe thread ISO 228 G 3/ (external thread 3/4", flat-					
Line/load connection L1, L2, L3 / U2, V2, W2		Flat connector for M12 screws	Flat connector for M12 screws	Flat connector for M12 screws	Flat connector for M12 screws		
<ul> <li>PE/GND connection</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup>	M10 stud 1 × 240	M10 stud 1 × 240	M10 stud 1 × 240	M10 stud 1 × 240		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions • Width • Height • Depth	mm mm mm	358 675 575	440 705 575	440 705 575	440 705 580		
Weight, approx.	kg	234	365	365	365		
Filter module Power loss <sup>4)</sup> • At 50 Hz 690 V • At 60 Hz 575 V	kW kW	4.0 4.0	5.0 5.0	5.0 5.0	7.5 7.5		
<ul> <li>Dissipated to ambient air</li> </ul>	kW dm <sup>3</sup>	0.15	0.15	0.15	0.15		
Liquid volume Heat exchanger material	um	Aluminum	Aluminum	Aluminum	Aluminum		
Coolant connections		Pipe thread ISO 228 G 3/		/ warningin			
Intake and connection to filter reactor		(external thread 3/4", flat-	sealing)				
PE/GND connection	2	Flat connector for M8 screw	Flat connector for M8 screw	Flat connector for M8 screw	Flat connector for M8 screw		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 120	2 × 120	2 × 120	2 × 120		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions • Width • Height • Depth	mm mm mm	506 840 574	506 840 574	506 840 574	506 840 574		
Weight, approx.	kg	110	110	110	110		

<sup>1)</sup> The bypass contactor is not included in the scope of supply.

Technical specifications (continued)

 <sup>2)</sup> The breakers must only be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Active Line Module.

<sup>3)</sup> Information on higher capacitances is included in the SINAMICS Low Voltage Engineering Manual.

<sup>4)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual. Selection and ordering data

### SINAMICS S120 Chassis Format Converter Units

Liquid-cooled units

### **Motor Modules**

### Overview



A Motor Module comprises a self-commutated converter with IGBTs. It generates a variable voltage with variable frequency from the DC link voltage that feeds the connected motor.

Multiple Motor Modules can be operated on a single DC link. This permits energy to be transferred between the Motor Modules. This means that if one Motor Module operating in generator mode produces energy, the energy can be used by another Motor Module operating in motor mode.

Motor Modules are controlled by a Control Unit.

Liquid-cooled Motor Modules are especially suitable for applications where installation space is restricted and environmental conditions are harsh. Liquid cooling ensures efficient heat dissipation.

#### Design

The liquid-cooled Motor Modules have the following interfaces as standard:

- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for connecting to the supply DC link
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections
- 2 coolant connections

The status of the Motor Modules is indicated via three LEDs.

The scope of supply of the Motor Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 2 seals for coolant connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

Type rating at 400 V or 690 V	Rated output current	Motor Module
kW	A	Article No.
Line voltage 380 48 (DC link voltage 510	0 V 3 AC . 720 V DC)	
110	210	6SL3325-1TE32-1AA3
132	260	6SL3325-1TE32-6AA3
160	310	6SL3325-1TE33-1AA3
250	490	6SL3325-1TE35-0AA3
315	605	6SL3325-1TE36-1AA3
400	745	6SL3325-1TE37-5AA3
450	840	6SL3325-1TE38-4AA3
560	985	6SL3325-1TE41-0AA3
710	1260	6SL3325-1TE41-2AA3
800	1405	6SL3325-1TE41-4AA3
800 <sup>1)</sup>	1330	6SL3325-1TE41-4AS3
Line voltage 500 69 (DC link voltage 675	0 V 3 AC . 1035 V DC)	
90	100	6SL3325-1TG31-0AA3
132	150	6SL3325-1TG31-5AA3
200	215	6SL3325-1TG32-2AA3
315	330	6SL3325-1TG33-3AA3
450	465	6SL3325-1TG34-7AA3
560	575	6SL3325-1TG35-8AA3
710	735	6SL3325-1TG37-4AA3
800	810	6SL3325-1TG38-0AA3
800	810	6SL3325-1TG38-1AA3
1000	1025	6SL3325-1TG41-0AA3
1200	1270	6SL3325-1TG41-3AA3
1500	1560	6SL3325-1TG41-6AP3
Description		Article No.
Accessories		
3-way valve 2)		VXF41/VXG41
Actuator for 3-way val	ve <sup>2)</sup>	
• 230 V 1 AC		SAX31
• 24 V AC/DC		SAX61/SAX81
Accessories for re-ord	lering	
<b>Dust protection blank</b> (50 units)	ing plugs	6SL3066-4CA00-0AA0
For DRIVE-CLiQ port		

For motor-side components, see System components.

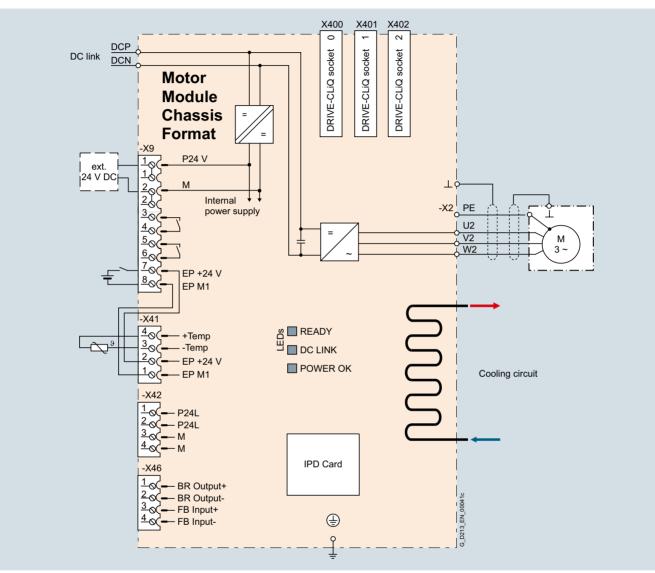
- <sup>1)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance.
- <sup>2)</sup> Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies.

Liquid-cooled units

**Motor Modules** 

## Integration

The liquid-cooled Motor Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit.



Connection example of a liquid-cooled Motor Module

#### Technical specifications

#### General technical specifications

Electrical specifications	
Efficiency	98.5 %
DC link voltage (up to 2000 m above sea level)	510 720 V DC (line voltage 380 480 V 3 AC) or 675 1035 V DC (line voltage 500 690 V 3 AC)
Output frequency <sup>1)</sup>	
<ul> <li>Control type Servo</li> </ul>	0 550 Hz
<ul> <li>Control type Vector</li> </ul>	0 550 Hz
<ul> <li>Control mode V/f</li> </ul>	0 550 Hz
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1.

1) Please note:

The correlation between the maximum output frequency, pulse frequency and current derating. Higher output frequencies on request.

For further information, see https://support.industry.siemens.com/cs/document/104020669
The correlation between the minimum output frequency and permissible output current (current derating).

The correlation between the minimum output frequency and permissible output current (current de Information is provided in the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

# Motor Modules

# **Technical specifications** (continued)

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC	Motor Modules						
		6SL3325- 1TE32-1AA3	6SL3325- 1TE32-6AA3	6SL3325- 1TE33-1AA3	6SL3325- 1TE35-0AA3	6SL3325- 1TE36-1AA3	
Type rating							
• At <i>I</i> <sub>1</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	250	315	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	200	250	
• At <i>I</i> <sub>1</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	400	500	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	350	350	
Output current							
Rated current Irated O	А	210	260	310	490	605	
• Base-load current $l_{1}^{(3)}$	А	205	250	302	477	590	
• Base-load current $I_{\rm H}^{-4}$	А	178	233	277	438	460	
Maximum current I <sub>max O</sub>	А	307	375	453	715	885	
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic Line Module	А	256	317	380	600	738	
- Active Line Module	А	230	287	340	538	664	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	250	305	368	581	719	
- Active Line Module	А	225	274	331	522	646	
<ul> <li>Base-load current I<sub>H DC</sub> <sup>4)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	227	284	338	534	561	
- Active Line Module	А	195	255	303	480	504	
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.4	1.4	1.5	1.5	1.6	
DC link capacitance	μF	4800	5800	8400	9600	12600	
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	2	2	2	2	1.25	
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	2	2	2	2	1.25	
- With current derating	kHz	8	8	8	8	7.5	
Power loss, max. <sup>6)</sup>							
• At 50 Hz 400 V	kW	1.61	1.95	2.29	3.56	4.81	
• At 60 Hz 460 V	kW	1.68	2.06	2.38	3.74	5.25	
Dissipated to ambient air	kW	0.06	0.07	0.09	0.14	0.16	
Coolant volume flow <sup>7</sup> )	I/min	9	9	12	12	16	
contract of the integrated heat exchanger	dm <sup>3</sup>	0.31	0.31	0.91	0.91	0.74	
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000	70000	
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel	Aluminum	
Coolant connections Intake/return		Pipe thread ISO 228 (external thread 3/4",	flat-sealing)				
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52	54	
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	
Motor connection U2, V2, W2		Hole for M12	Hole for M12	Hole for M12	Hole for M12	$2 \times \text{hole for M12}$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	4 × 185	
PE/GND connection		$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	$2 \times hole$ for M12	$2 \times \text{hole for M12}$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	4 × 185	

Liquid-cooled units

**Motor Modules** 

Technical specifications (continued)									
Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules	Motor Modules						
		6SL3325- 1TE32-1AA3	6SL3325- 1TE32-6AA3	6SL3325- 1TE33-1AA3	6SL3325- 1TE35-0AA3	6SL3325- 1TE36-1AA3			
Cable length, max <sup>9)</sup>									
Shielded	m	300	300	300	300	300			
Unshielded	m	450	450	450	450	450			
Dimensions									
• Width	mm	150	150	150	150	265			
• Height	mm	746	746	1172	1172	1002			
Depth	mm	545	545	545	545	545			
Weight, approx.	kg	41	41	80	80	110			
Frame size		FXL	FXL	GXL	GXL	HXL			

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $I_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- 9) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

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Liquid-cooled units

# Motor Modules

# **Technical specifications** (continued)

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules						
		6SL3325- 1TE37-5AA3	6SL3325- 1TE38-4AA3	6SL3325 -1TE41-0AA3	6SL3325- 1TE41-2AA3	6SL3325- 1TE41-4AA3	6SL3325- 1TE41-4AS3 <sup>1)</sup>	
Type rating								
• At / <sub>I</sub> (50 Hz 400 V) <sup>2)</sup>	kW	400	450	560	710	800	800	
• At I <sub>H</sub> (50 Hz 400 V) <sup>2)</sup>	kW	315	400	450	630	710	630	
• At <i>I</i> <sub>I</sub> (60 Hz 460 V) <sup>3)</sup>	hp	600	700	800	1000	1150	1000	
• At I <sub>H</sub> (60 Hz 460 V) <sup>3)</sup>	hp	450	600	700	900	1000	900	
Output current								
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	745	840	985	1260	1405	1330	
• Base-load current /L <sup>4)</sup>	А	725	820	960	1230	1370	1310	
<ul> <li>Base-load current I<sub>H</sub> <sup>5)</sup></li> </ul>	А	570	700	860	1127	1257	1150	
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	1087	1230	1440	1845	2055	2055	
DC link current								
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>								
- Basic Line Module	А	894	1025	1202	1512	1714	1550	
- Active Line Module	А	805	922	1080	1361	1544	1403	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>4)</sup> when supplied via</li> </ul>								
- Basic Line Module	А	871	1000	1170	1474	1670	1525	
- Active Line Module	А	784	898	1051	1326	1500	1405	
<ul> <li>Base-load current I<sub>H DC</sub><sup>5)</sup> when supplied via</li> </ul>								
- Basic Line Module	А	795	853	1048	1345	1532	1676	
- Active Line Module	А	716	767	942	1211	1377	1403	
Current demand								
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.6	1.46	1.46	1.46	1.46	
DC link capacitance	μF	17400	17400	21000	29000	29000	21000	
Pulse frequency <sup>6)</sup>								
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25	2	
<ul> <li>Pulse frequency, max.</li> </ul>								
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	2	
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	4	
Power loss, max. <sup>7)</sup>								
• At 50 Hz 400 V	kW	5.1	5.75	7.9	9.15	10.2	10.9	
• At 60 Hz 460 V	kW	5.61	6.33	8.55	10.05	11.2	12.3	
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.2	0.23	0.44	0.56	0.62	0.65	
Coolant volume flow <sup>8)</sup>	l/min	16	16	27	27	27	27	
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.74	0.74	1.56	1.56	1.56	1.56	
Pressure drop, typ. <sup>9)</sup> for volume flow	Pa	70000	70000	70000	70000	70000	70000	
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum	Aluminum	Aluminum	
Coolant connections Intake/return		Pipe thread ISO 2 (external thread 3	3/4", flat-sealing)					
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	54	56	56	56	56	
DC link connection DCP, DCN		Busbar	Busbar	Busbar	2 × hole for M12 Busbar	Busbar	Busbar	
Motor connection U2, V2, W2							2 × hole for M12	
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	4 × 240	4 × 240	4 × 240	4 × 240	
PE/GND connection	0		2 × hole for M12	2 × hole for M12	2 × hole for M12	2 × hole for M12	2 × hole for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	Busbar	Busbar	Busbar	Busbar	

For footnotes, see next page.

Liquid-cooled units

Motor Modules

Technical specifications (continued)							
Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules					
		6SL3325- 1TE37-5AA3	6SL3325- 1TE38-4AA3	6SL3325 -1TE41-0AA3	6SL3325- 1TE41-2AA3	6SL3325- 1TE41-4AA3	6SL3325- 1TE41-4AS3 <sup>1)</sup>
Cable length, max. <sup>10)</sup>							
Shielded	m	300	300	300	300	300	300
Unshielded	m	450	450	450	450	450	450
Dimensions							
• Width	mm	265	265	295	295	295	295
• Height	mm	1002	1002	1516	1516	1516	1516
• Depth	mm	545	545	545	545	545	545
Weight, approx.	kg	110	110	220	220	220	230
Frame size		HXL	HXL	JXL	JXL	JXL	JXL

- $^{1)}$  This Motor Module has been specifically designed for loads demanding a high dynamic performance. The derating factor  $k_{\rm IGBT}$  and the derating characteristic curves can be ignored (see section "Duty cycles" in the SINAMICS Low Voltage Engineering Manual).
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  ${\it I_L}$  or  ${\it I_H}$  for 400 V 3 AC 50 Hz.
- $^{3)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- <sup>4)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{5)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 6) Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>8)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 9) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>10)</sup>Sum of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

# Motor Modules

# **Technical specifications** (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC	Motor Modules						
		6SL3325- 1TG31-0AA3	6SL3325- 1TG31-5AA3	6SL3325- 1TG32-2AA3	6SL3325- 1TG33-3AA3	6SL3325- 1TG34-7AA3	6SL3325- 1TG35-8AA3
Type rating							
• At <i>I</i> <sub>1</sub> (50 Hz 690 V) <sup>1)</sup>	kW	90	132	200	315	450	560
• At / <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	75	110	160	250	400	450
• At <i>I</i> <sub>I</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	90	132	200	315	400
• At / <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	90	132	200	250	315
• At / <sub>I</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	150	200	300	450	600
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	125	200	250	450	500
Output current	-						
Rated current I <sub>rated O</sub>	А	100	150	215	330	465	575
• Base-load current $l_{1}^{(3)}$	А	95	142	208	320	452	560
• Base-load current $I_{\rm H}^{-4)}$	А	89	134	192	280	416	514
Maximum current I <sub>max O</sub>	А	142	213	312	480	678	840
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic Line Module	А	122	183	263	403	558	702
- Active Line Module	А	110	165	237	363	502	632
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	116	173	253	390	544	683
- Active Line Module	А	105	156	229	352	489	616
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	108	163	234	341	496	627
- Active Line Module	А	98	147	211	308	446	565
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.0	1.0	1.5	1.5	1.6	1.6
DC link capacitance	μF	2800	2800	4200	5800	9670	9670
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	7.5
Power loss, max. <sup>6)</sup>							
• At 50 Hz 690 V	kW	1.15	1.64	2.34	3.38	5.44	5.61
• At 60 Hz 575 V	kW	1.02	1.45	2.05	2.96	5.1	5.45
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.06	0.07	0.09	0.12	0.14	0.16
Coolant volume flow <sup>7)</sup>	l/min	9	9	12	12	16	16
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.31	0.31	0.91	0.91	0.74	0.74
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000	70000	70000
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel	Aluminum	Aluminum
Coolant connections Intake/return		Pipe thread ISO 2 (external thread 3					
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52	54	54
DC link connection DCP, DCN		Busbar	2 × hole for M12 Busbar	Busbar	Busbar	Busbar	2 × hole for M12 Busbar
Motor connection U2, V2, W2		Hole for M12	Hole for M12	Hole for M12	Hole for M12	2 × hole for M12	2 × hole for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	4 × 240	4 × 240	4 × 185	4 × 185

For footnotes, see next page.

Liquid-cooled units

**Motor Modules** 

	Technical s	pecifications	(continued)
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Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules						
		6SL3325- 1TG31-0AA3	6SL3325- 1TG31-5AA3	6SL3325- 1TG32-2AA3	6SL3325- 1TG33-3AA3	6SL3325- 1TG34-7AA3	6SL3325- 1TG35-8AA3	
PE/GND connection		$2 \times \text{hole for M12}$						
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	4 × 185	4 × 185	
Cable length, max <sup>9)</sup>								
Shielded	m	300	300	300	300	300	300	
Unshielded	m	450	450	450	450	450	450	
Dimensions								
Width	mm	150	150	150	150	265	265	
• Height	mm	728	728	1172	1172	1002	1002	
• Depth	mm	545	545	545	545	545	545	
Weight, approx.	kg	41	41	80	80	110	110	
Frame size		FXL	FXL	GXL	GXL	HXL	HXL	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $\mathit{I_{H}}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

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Liquid-cooled units

# Motor Modules

# **Technical specifications** (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules					
, , , , , , , , , , , , , , , , , , ,		6SL3325- 1TG37-4AA3	6SL3325- 1TG38-0AA3 <sup>1)</sup>	6SL3325- 1TG38-1AA3	6SL3325- 1TG41-0AA3	6SL3325- 1TG41-3AA3	6SL3325- 1TG41-6AP3 <sup>11)</sup>
Type rating			11000 07 10		110410/00	110410/00	110410/10
• At <i>I</i> <sub>1</sub> (50 Hz 690 V) <sup>2)</sup>	kW	710	800	800	1000	1200	1500
• At / <sub>H</sub> (50 Hz 690 V) <sup>2)</sup>	kW	630	710	710	900	1000	1260
• At I <sub>1</sub> (50 Hz 500 V) <sup>2)</sup>	kW	500	560	560	710	900	1000
• At I <sub>H</sub> (50 Hz 500 V) <sup>2)</sup>	kW	450	500	560	630	800	900
• At / <sub>1</sub> (60 Hz 575 V) <sup>3)</sup>	hp	700	800	800	1000	1250	1500
• At I <sub>H</sub> (60 Hz 575 V) <sup>3)</sup>	hp	700	700	700	900	1000	1250
Output current	ΠP						1200
Rated current I <sub>rated O</sub>	A	735	810	810	1025	1270	1560
• Base-load current $I_1^{(4)}$	A	710	790	790	1000	1230	1500
• Base-load current $I_{\rm H}^{5)}$	A	657	724	724	917	1136	1370
Maximum current I <sub>max O</sub>	A	1065	1185	1185	1500	1845	2250
DC link current							2200
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic Line Module	А	903	990	990	1250	1550	1903
- Active Line Module	А	808	891	891	1125	1395	1714
<ul> <li>Base-load current I<sub>L DC</sub> <sup>4)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	870	948	963	1219	1500	1800
- Active Line Module	А	781	870	869	1100	1353	1650
<ul> <li>Base-load current I<sub>H DC</sub><sup>5)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	795	885	883	1118	1384	1680
- Active Line Module	А	732	808	796	1009	1250	1550
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.6	1.46	1.46	1.46	1.46
DC link capacitance	μF	10500	10500	14000	16000	19330	21000
Pulse frequency <sup>6)</sup>							
Rated frequency	kHz	1.25	1.25	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	7.5
Power loss, max. <sup>7)</sup>							
• At 50 Hz 690 V	kW	7.65	8.47	9.56	10.87	13.49	17.9
• At 60 Hz 575 V	kW	6.67	7.39	8.34	9.55	11.84	15.7
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.2	0.22	0.43	0.53	0.57	0.78
Coolant volume flow <sup>8)</sup>	l/min	16	16	27	27	27	27
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.74	0.74	1.56	1.56	1.56	1.56
Pressure drop, typ. <sup>9)</sup> for volume flow	Pa	70000	70000	70000	70000	70000	70000
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum	Aluminum	Aluminum
Coolant connections Intake/return		Pipe thread ISO 2 (external thread 3					
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	54	56	56	56	56
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar
Motor connection U2, V2, W2		2 × hole for M12	$2 \times \text{hole for M12}$	2 × hole for M12	$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	$2 \times hole$ for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 x 185	Busbar	Busbar	Busbar	Busbar

For footnotes, see next page.

Liquid-cooled units

**Motor Modules** 

<b>Technical</b> s	pecifications	(continued)	)
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Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules						
		6SL3325- 1TG37-4AA3	6SL3325- 1TG38-0AA3 <sup>1)</sup>	6SL3325- 1TG38-1AA3	6SL3325- 1TG41-0AA3	6SL3325- 1TG41-3AA3	6SL3325- 1TG41-6AP3 <sup>11)</sup>	
PE/GND connection		$2 \times \text{hole}$ for M12	$2 \times \text{hole for M12}$	$2 \times \text{hole}$ for M12	$2 \times \text{hole}$ for M12	$2 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	Busbar	Busbar	Busbar	Busbar	
Cable length, max. <sup>10)</sup>								
Shielded	m	300	300	300	300	300	300	
Unshielded	m	450	450	450	450	450	450	
Dimensions								
Width	mm	265	265	295	295	295	295	
• Height	mm	1002	1002	1516	1516	1516	1516	
• Depth	mm	545	545	545	545	545	545	
Weight, approx.	kg	110	110	220	220	220	230	
Frame size		HXL	HXL	JXL	JXL	JXL	JXL	

- <sup>1)</sup> The device is optimized for a base pulse frequency of 1.25 kHz, for an increased pulse frequency – or for certain overloads the derating factor is higher than that for the device with article number 6SL3325-1TG38-1AAx.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{3)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{4)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>5)</sup> The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 6) Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>8)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 9) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>10)</sup>Sum of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.
- <sup>11)</sup>Additional duty cycle for output frequencies from 5 Hz to 10 Hz: Base-load current = 1460 A, short-time current = 2340 A for 5 s with a duty cycle duration of 600 s. For output frequencies from 1 Hz to 5 Hz, the short-time current is 1900 A for 5 s.

Liquid-cooled units

### Mounting device for liquid-cooled power units

### Overview



The mounting device is used to install or remove liquid-cooled power units (Power Modules, Line Modules, Motor Modules) into or out of a control cabinet. The mounting device can be used if the power units are mounted on mounting rails, which at the front have two M6 threads at a vertical distance of 20 mm to attach the mounting device.

The mounting device is a mounting aid. It is placed in front of the power unit and attached to the mounting rails below the power unit. The telescopic rails allow the mounting device to be adjusted to the installation height and width of the power unit. The power unit can be removed from the control cabinet after releasing the mechanical and electrical connections and the coolant connections. The power unit is guided and supported by the guide rails on the mounting device. To prevent it toppling over, the power unit must be secured to a crane, tripod, or similar assembly using the lifting lugs or the lifting equipment. The unit can then be lowered down from the mounting device.

## Selection and ordering data

Description

Mounting device for installing and removing power units

Article No. 6SL3766-1CA00-0AA0

Water-cooled units

### Overview



The water-cooled SINAMICS S120 chassis units are specifically designed for the operation of shared cooling circuits for the plant, motor, and converter.

They are especially suitable for applications where installation space is restricted and environmental conditions are harsh. They ensure efficient heat dissipation. The main difference to the current liquid-cooled SINAMICS S120 chassis units is the operation with a significantly reduced water quality. The components are resistant to a proportion of oxygen in the cooling water. Generally, the water usually used in industry can also be used for cooling the drive system. Additives such as antifreeze, inhibitors, or biocides are not required.

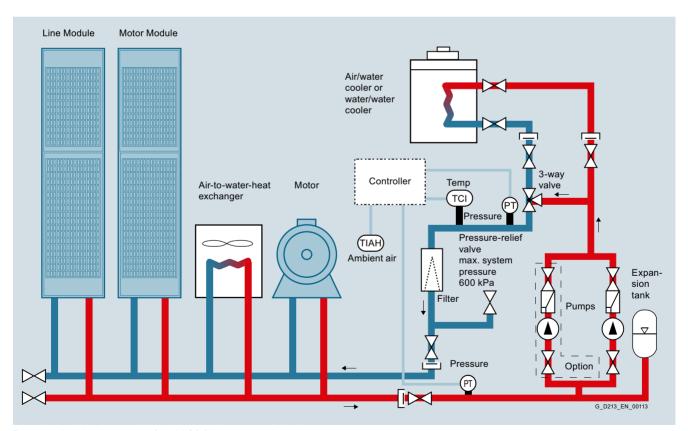
The new cooling concept saves space and costs. Water cooling for motor and converter ensures that less space is needed, as the converter cooling unit can be dispensed with due to the shared cooling circuit. This results in low acquisition and operating costs.

The devices with copper-nickel heat sinks are fitted with rail profiles at the bottom and can be stored on the floor in a way that is easy to assemble.

The product portfolio includes the following water-cooled SINAMICS S120 built-in units:

- Power Modules
- Active Line Modules
- Active Interface Modules
- Motor Modules

The associated system components such as motor reactors and dv/dt filters plus VPL are air-cooled.



Example of a drive line-up with SINAMICS S120 water-cooled units

Water-cooled units

# Technical specifications

## General technical specifications

Unless clearly specified otherwise, the following technical specifications are valid for all the following components of the water-cooled SINAMICS S120 drive system in chassis format.

Electrical specifications					
Rated voltages	380 480 V 3 AC ±10 % (-15 % <1 min) 500 690 V 3 AC ±10 % (-15 % <1 min)				
Line supply types	Grounded TN/TT systems and non-g	rounded IT systems			
Line frequency	47 63 Hz				
Overvoltage category	III to EN 61800-5-1				
Electronics power supply	24 V DC, -15 % +20 % implemented as PELV circuit in acco Ground = negative pole grounded v				
Rated short-circuit current per IEC, in conjunction with the specified fuses or circuit breakers					
• 1.1 447 kW	65 kA				
• 448 671 kW	84 kA				
• 672 1193 kW	170 kA				
• > 1194 kW	200 kA				
Rated short-circuit current SCCR (Short Circuit Current Rating) according to UL508C (up to 600 V), in conjunction with the specified fuses or circuit breakers					
• 1.1 447 kW	65 kA				
• 448 671 kW	84 kA				
• 672 1193 kW	170 kA				
• > 1194 kW	200 kA				
Control method	Vector/Servo control with and without	it encoder or V/f control			
Fixed speeds	15 fixed speeds plus 1 minimum spe 3 fixed setpoints plus 1 minimum sp				
Skippable speed ranges	4, parameterizable				
Setpoint resolution	0.001 rpm digital (14 bits + sign) 12 bits analog				
Braking operation	With Active Line Modules, four-quad Braking with a Motor Module.	rant operation as standard (energy	recovery).		
Mechanical specifications					
Degree of protection	IP00 (IP20, without taking into accou	int the connecting busbars)			
Protection class	I acc. to EN 61800-5-1				
Touch protection	EN 50274/DGUV regulation 3 when	used as intended			
Cooling method	Water cooling with integrated heat e	xchanger in copper-nickel version			
Ambient conditions	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation		
Ambient temperature (air)	-25 +55 °C Class 1K4 acc. to EN 60721-3-1	<u>-25</u> +70 °C Class 2K4 acc. to EN 60721-3-2	Line-side components, Line Modules, and Motor Modules: 0 45 °C without derating >45 50 °C see derating characteristic curves Control Units, supplementary system		
			components, and Sensor Modules: 055 °C (for operation in a control cabinet) DC link components and motor-side components: 055 °C		
Relative humidity Condensation, splashwater, and ice formation not permitted (EN 60204, Part 1)	<u>5 95 %</u> Class 1K4 acc. to EN 60721-3-1	Max. 95 % at 40 °C Class 2K4 acc. to EN 60721-3-2	5 <u>95 %</u> Class 3K3 acc. to EN 60721-3-3		
Environmental class/harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3		
Organic/biological influences	Class 1B1 acc. to EN 60721-3-1	Class 2B1 acc. to EN 60721-3-2	Class 3B1 acc. to EN 60721-3-3		
Degree of pollution	2 acc. to IEC/EN 61800-5-1				

Water-cooled units

(k			
Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation	
	Class 2M2 acc. to EN 60721-3-2	Test values acc. to EN 60068-2-6 test Fc: • 10 58 Hz with constant deflection 0.075 mm • 58 150 Hz with constant acceleration 9.81 m/s <sup>2</sup> (1 × g)	
	Class 2M2 acc. to EN 60721-3-2	Test values acc. to EN 60068-2-27 test Ea: 98 m/s <sup>2</sup> (10 × <i>g</i> )/20 ms	
CE (EMC Directive 2014/30/EU, Low Voltage Directive 2014/35/EU, and Machinery Directive 2006/42/EC for functional safety) RCM, RoHS II cULus (only for devices connected to line supply voltages 380 480 V 3 AC and 500 600 V 3 AC)			
interference suppression is com "Second environment" (industria	npliant with the EMC product standar al line supplies). EMC disturbances ca	d for variable-speed drives EN 61800-3,	
	<ul> <li>&gt; 2000 m above sea level, refer</li> <li>Storage <sup>1</sup>)</li> <li>CE (EMC Directive 2014/30/EU, for functional safety)</li> <li>RCM, RoHS II</li> <li>CULus (only for devices connect SINAMICS S120 chassis format interference suppression is con "Second environment" (industria</li> </ul>	Up to 2000 m above sea level without derating, > 2000 m above sea level, refer to the derating data Storage 1) Transport 1) Class 2M2 acc. to EN 60721-3-2 Class 2M2 acc. to EN 60721-3-2 Class 2M2 acc. to EN 60721-3-2 CE (EMC Directive 2014/30/EU, Low Voltage Directive 2014/35/EU, a for functional safety) RCM, RoHS II	

Deviations from the specified class are <u>underlined</u>.

Water-cooled units

# Technical specifications (continued)

#### Cooling circuit and coolant quality

The following tables and sections describe the quality requirements of the coolant used in the water-cooled SINAMICS S120 drive system in chassis format.

Cooling circuit						
System pressure with reference to atmospheric pressure, max.	600 kPa	600 kPa				
Pressure drop at rated volumetric flow	70 kPa					
Recommended pressure range	80 150 kPa (is applicable for water as coolant)					
Inlet temperature of liquid coolant	Dependent on ambient temperature, no condensation permitted					
	0 38 °C without derating					
	>38 43 °C see derating data					
	Antifreeze essential for temperature range between	0 °C and 5 °C				
	Note: Compared to the liquid-cooled chassis format units not required.	s, the inlet temperatures are 7 K lower, as a heat exchanger is				
Coolant quality						
	Coolant basis for copper-nickel heat sink: Filtered drinking, process, and cooling water	Coolant basis for stainless steel heat sink: Filtered drinking, process, and cooling water				
<ul> <li>Electrical conductivity</li> </ul>	<2900 µS/cm (>290 mS/m)	<2500 µS/cm (>250 mS/m)				
• pH value	6.5 9	6.5 9				
<ul> <li>Total salt content TDS</li> </ul>	<1800 mg/l	<1550 mg/l				
Chloride ions	<500 mg/l	<250 mg/l				
• Sodium	<200 mg/l	<200 mg/l				
Sulfate ions	<300 mg/l	<240 mg/l				
Sulfide ions	<1 mg/l	<1 mg/l				
Nitrate ions	<50 mg/l	<50 mg/l				
• Iron	<1 mg/l	<1 mg/l				
Silicate	<10 mg/l	<10 mg/l				
• Ammonia (NH <sub>3</sub> ), ammonium (NH <sub>4</sub> +)	<1 mg/l	<1 mg/l				
<ul> <li>Total hardness with a maximum of</li> </ul>	<1.78 mmol/l (10 °dH)	<1.78 mmol/l (10 °dH)				
- Calcium hardness	<1.25 mmol/l (7 °dH), <57 mg/l calcium	<1.25 mmol/l (7 °dH), <57 mg/l calcium				
- Magnesium hardness	< 1.43 mmol/l (8 °dH), <35 mg/l magnesium	< 1.43 mmol/l (8 °dH), <35 mg/l magnesium				
- Carbonate hardness	<0.45 mmol/l (2.5 °dH)	<0.45 mmol/l (2.5 °dH)				
Suspended solids/suspended substance	es					
- Solids	<340 mg/l	<340 mg/l				
- Size of entrained particles	<100 μm	- <100 μm				
	•	e considered as recommendation. For units that have been equipment manual supplied should be observed!				

Recommendation:

With an open pressure equalization tank, initial filling should be conducted using demineralized water (via ion exchanger).

#### Technical specifications (continued)

#### Antifreeze and biocide

The water-cooled built-in units can be operated within a temperature range above 5 °C without antifreeze. At operating temperatures of <5 °C, one of the following antifreeze agents must be used.

Antifreeze	Antifrogen N	Antifrogen L	DOWCAL 100
Manufacturer	Clariant	Clariant	DOW
Chemical base	Ethylene glycol	Propylene glycol	Ethylene glycol
Minimum concentration	25 %	25 %	25 %
Antifreeze agent with minimum concentration	-10 °C	-10 °C	-10 °C
Maximum concentration	45 %	48 %	45 %
Antifreeze agent with maximum concentration	-30 °C	-30 °C	-30 °C
Inhibitor content	Contains inhibitors with nitrites	Contains inhibitors that are free of nitrates, amines, borates and phosphates	Contains inhibitors that are free of nitrates, amines and phosphates
Biocide action with a concentration of	>25 %	>25 %	>25 %

Biocides prevent corrosion that is caused by slime-forming, corrosive or iron-depositing bacteria. These can occur in closed cooling circuits with low water hardness and in shared cooling circuits with open pressure equalization vessel. Biocides must always be selected according to the relevant bacterial risks. Compatibility with inhibitors or antifreeze used with them must be checked on a case-by-case basis.

#### Protection against condensation

With water-cooled units, warm air can condense on the cold surfaces of heat sinks, pipes, and hoses. This condensation depends on the air humidity and the temperature difference between the ambient air and the coolant.

The water which is produced as a result of condensation can cause corrosion as well as electrical damage such as creepage shorts and flashovers. As the SINAMICS units cannot prevent condensation if it is caused by the prevailing climatic conditions, any potential risk of condensation must be prevented by appropriate engineering or by precautionary measures implemented by the customer. These measures include the following:

- a fixed coolant temperature that has been adjusted to the expected air humidity or ambient temperature ensures that critical differences between the coolant and ambient air temperatures do not develop or
- temperature regulation of the coolant as a function of the ambient air temperature

#### Recommended service

The cooling water must be checked 3 months after the cooling circuit is initially filled and once every year thereafter. We recommend contacting a coolant manufacturer for the coolant inspection. If the cooling water becomes cloudy, is colored, or becomes contaminated by mold spores, the cooling circuit must be cleaned and refilled.

The temperature at which water vapor contained in the air condenses into water is known as the dew point. To prevent condensation reliably, the coolant temperature must always be higher than the dew point.

The table below specifies the dew point as a function of room temperature T and relative air humidity  $\Phi$  for an atmospheric pressure of 100 kPa (1 bar). This corresponds to an installation altitude of 0 up to approximately 500 m above sea level. Since the dew point drops as the air pressure decreases, the dew point values at higher installation altitudes are lower than the specified table values. It is therefore the safest approach to engineer the coolant temperature according to the values in the table for an installation altitude of zero.

Room temperature	Relative ai	r humidity	Þ								
Т	20 %	30 %	40 %	50 %	60 %	70 %	80 %	85 %	90 %	95 %	100 %
10 °C	<0 °C	<0 °C	<0 °C	0.2 °C	2.7 °C	4.8 °C	6.7 °C	7.6 °C	8.4 °C	9.2 °C	10 °C
20 °C	<0 °C	2 °C	6 °C	9.3 °C	12 °C	14.3 °C	16.4 °C	17.4 °C	18.3 °C	19.1 °C	20 °C
25 °C	0.6 °C	6.3 °C	10.5 °C	13.8 °C	16.7 °C	19.1 °C	21.2 °C	22.2 °C	23.2 °C	24.1 °C	24.9 °C
30 °C	4.7 °C	10.5 °C	14.9 °C	18.4 °C	21.3 °C	23.8 °C	26.1 °C	27.1 °C	28.1 °C	29 °C	29.9 °C
35 °C	8.7 °C	14.8 °C	19.3 °C	22.9 °C	26 °C	28.6 °C	30.9 °C	32 °C	33 °C	34 °C	34.9 °C
40 °C	12.8 °C	19.1 °C	23.7 °C	27.5 °C	30.6 °C	33.4 °C	35.8 °C	36.9 °C	37.9 °C	38.9 °C	39.9 °C
45 °C	16.8 °C	23.3 °C	28.2 °C	32 °C	35.3 °C	38.1 °C	40.6 °C	41.8 °C	42.9 °C	43.9 °C	44.9 °C
50 °C	20.8 °C	27.5 °C	32.6 °C	36.6 °C	40 °C	42.9 °C	45.5 °C	46.6 °C	47.8 °C	48.9 °C	49.9 °C

A detailed description of the cooling circuits and the recommended coolant is given in the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

### Characteristic curves

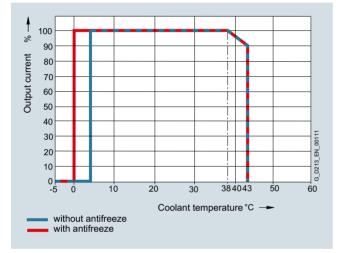
#### Derating

Water-cooled SINAMICS S120 chassis format units are rated for an ambient temperature of 45 °C and installation altitudes up to 2000 m above sea level. At ambient temperatures > 45 °C, the output current must be reduced. Ambient temperatures above 50 °C are not permissible. At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease.

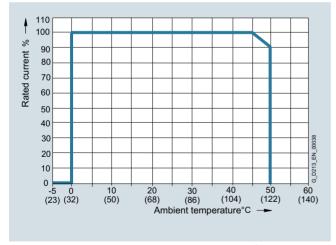
#### Note:

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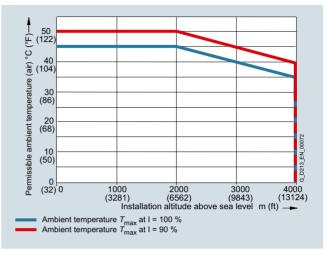
Compared to the liquid-cooled chassis format units, the inlet temperatures are 7 K lower, as a heat exchanger is not required.



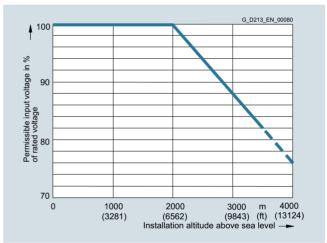
Current derating as a function of the temperature of the cooling liquid 1)



Current derating as a function of ambient temperature <sup>1)</sup>



Permissible ambient temperature as a function of installation altitude



Voltage derating as a function of installation altitude

Current derating as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased, the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>1)</sup> The factors of the two curves must not be multiplied. The highest value in each case must be assumed for the purposes of calculation, so that the derating factor in the worst-case scenario is 0.9.

Water-cooled units

# Characteristic curves (continued)

The following tables list the rated output currents of the SINAMICS S120 Motor Modules with pulse frequency set in the factory as well as the current derating factors (permissible output currents referred to the rated output current) for higher pulse frequencies.

### Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 2 kHz

Power Module Motor Module	Type rating at 400 V	Output current at 2 kHz	Derating factor at pulse frequency				
6SL3315 6SL3325	kW	А	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC							
1TE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %
1TE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %
1TE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %
1TE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %

#### Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 1.25 kHz

Motor Module	Type rating at 400 V or 690 V	Output current at 1.25 kHz	Derating factor at pulse frequency					
6SL3325	kW	А	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC								
1TE37-5AA7	400	745	83 %	72 %	64 %	60 %	40 %	-
1TE41-0AA7	560	985	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-2AA7	710	1260	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-4AA7	800	1405	97 %	95 %	74 %	60 %	50 %	47 %
500 690 V 3 AC								
1TG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %	-
1TG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %	-
1TG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %	-
1TG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %	-
1TG34-7AA7	450	465	92 %	87 %	67 %	55 %	35 %	-
1TG35-8AA7	560	575	91 %	85 %	64 %	50 %	35 %	-
1TG38-1AA7	800	810	97 %	95 %	71 %	55 %	35 %	-
1TG41-0AA7	1000	1025	91 %	86 %	64 %	50 %	30 %	-
1TG41-3AA7	1200	1270	87 %	79 %	55 %	40 %	25 %	-
1TG41-6AA7	1500	1560	87 %	79 %	55 %	40 %	25 %	-

The following tables list the maximum achievable output frequency as a function of the pulse frequency:

Maximum output frequencies achieved by increasing the pulse frequency in Vector mode

Maximum output frequencies achieved by increasing the pulse
frequency in Servo mode

Pulse frequency	Max. achievable output frequency
1.25 kHz	100 Hz
2 kHz	160 Hz
2.5 kHz	200 Hz
4 kHz	320 Hz
5 kHz	400 Hz

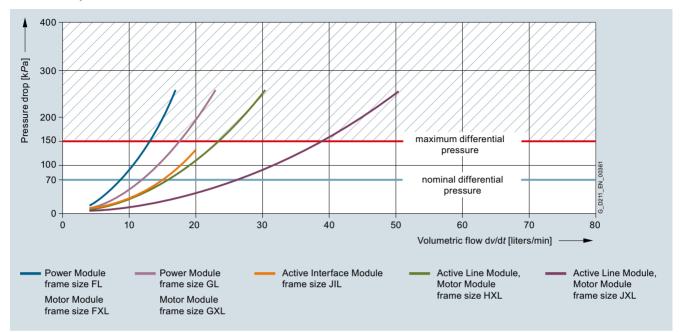
Pulse frequency	Max. achievable output frequency
2 kHz	300 Hz
4 kHz	300/550 Hz <sup>1)</sup>

 Higher frequencies on request. For further information see https://support.industry.siemens.com/cs/document/104020669

Water-cooled units

### Characteristic curves (continued)

Pressure drop



3

Pressure drop for water-cooled chassis format units

The pressure drop characteristic curves are valid for water. If antifreeze is used, the characteristic curves typically shift to the left.

For further information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

### Characteristic curves (continued)

#### **Overload capability**

Water-cooled SINAMICS S120 units have an overload reserve, e.g. to handle breakaway torques. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base-load current must, therefore, be used as a basis for the required load.

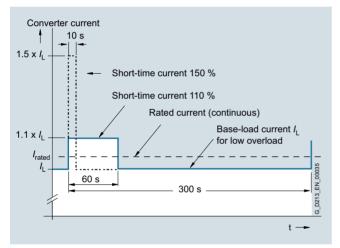
The permissible overload levels are valid under the prerequisite that the drive units are operated with their base-load current before and after the overload condition based on a duty cycle duration of 300 s.

Another precondition is that the Power Modules or the Motor Modules are operated at their factory-set pulse frequency at output frequencies > 10 Hz.

For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

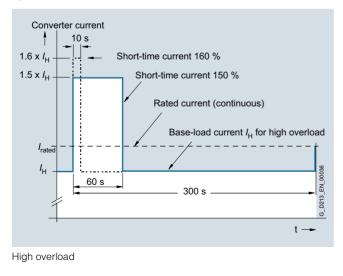
#### Power Modules and Motor Modules

The base-load current for a low overload  $I_{\rm L}$  is the basis for a duty cycle of 110 % for 60 s or 150 % for 10 s.



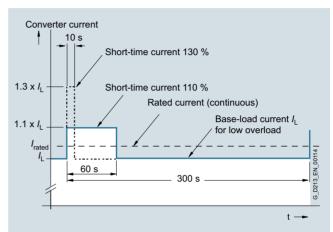
#### Low overload

The base-load current  $I_{\rm H}$  for a high overload is based on a duty cycle of 150 % for 60 s or 160 % for 10 s.

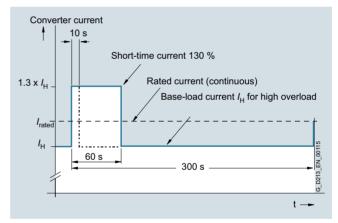


# The following applies to the 6SL3325-1TG41-3AA7 and 6SL3325-1TG41-6AA7 Motor Modules:

The short-time current for low overload must be reduced from 150 % to 130 % for 10 s. At 10 s and 60 s, the short-time current for high overload must be reduced to 130 %. The duty cycle remains unchanged.



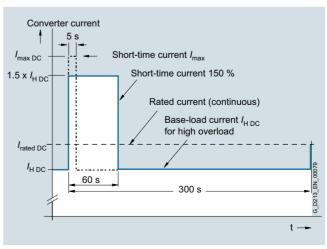
Low overload



#### High overload

#### Line Modules

The base-load current for a high overload  $I_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s.



High overload

Water-cooled units

## **Power Modules**

### Overview



The Power Module comprises a line rectifier, a DC link, and a converter to supply the motor.

Power Modules are designed for drives that are not capable of regenerating energy to the line supply system. If the motor produces energy during braking, a Braking Module with braking resistors will be required.

The water-cooled Power Modules are specifically designed for the operation of shared cooling circuits for the plant, motor and converter.

Power Modules in chassis format can be connected to grounded TN/TT systems and non-grounded IT systems.

#### Design

The water-cooled Power Modules have the following interfaces as standard:

- 1 line supply connection
- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC, or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections
- 2 cooling water ports

The CU310-2 Control Unit can be integrated into the watercooled Power Modules.

The status of the Power Modules is indicated via three LEDs.

The scope of supply of the Power Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- · 2 seals for cooling water connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)
- <sup>1)</sup> Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies.

## Selection and ordering data

Type rating	Rated output current	Power Module		
at 400 V				
kW	A	Article No.		
Line voltage 380 48	80 V 3 AC			
110	210	6SL3315-1TE32-1AA3		
132	260	6SL3315-1TE32-6AA3		
160	310	6SL3315-1TE33-1AA3		
250	490	6SL3315-1TE35-0AA3		
Description		Article No.		
Accessories				
3-way valve <sup>1)</sup>		VXF41/VXG41		
Actuator for 3-way va	alve <sup>1)</sup>			
• 230 V 1 AC		SAX31		
<ul> <li>24 V AC/DC</li> </ul>		SAX61/SAX81		
Accessories for re-ordering				
Dust protection blanking plugs (50 units)		6SL3066-4CA00-0AA0		

For DRIVE-CLiQ port

For additional information, refer to the manual.

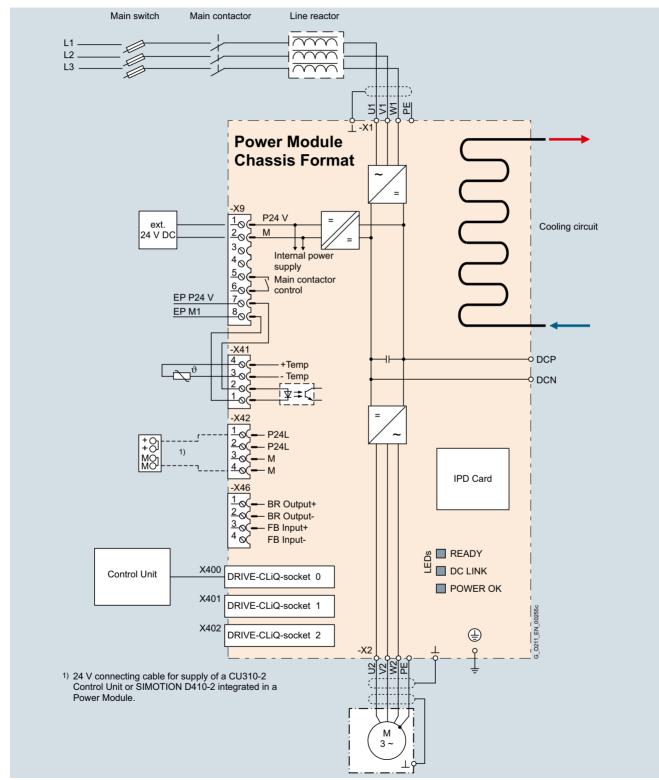
For line-side and motor-side components, see System components.

Water-cooled units

**Power Modules** 

## Integration

The Power Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case could be a CU310-2, CU320-2, or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate water-cooled Power Modules.



Connection example of a water-cooled Power Module in chassis format Note:

The integrated 24 V power supply at connector X42 can have a maximum load of 2 A. When the Control Unit is supplied from the integrated power supply, the total load of the digital outputs must be carefully observed to ensure that the 2 A is not exceeded.

Water-cooled units

#### **Power Modules**

## Technical specifications

#### General technical specifications

Electrical specifications	
Line connection voltage Up to 2000 m above sea level	380 480 V 3 AC ±10 % (-15 % <1 min)
Line power factor for a 3 AC line supply voltage and rated output	
• Basic fundamental (cos $\varphi_1$ )	>0.96
• Total ( $\lambda$ )	0.75 0.93
Efficiency	>98 %
DC link voltage, approx.	1.35 × line voltage
Output voltage, approx.	0 0.97 × U <sub>line</sub>
Output frequency 1)	
Control type Servo	0 550 Hz
Control type Vector	0 550 Hz
Control mode V/f	0 550 Hz
Electronics power supply	24 V DC -15 %/+20 %
Main contactor control	
Terminal block -X9/5-6	240 V AC, max. 8 A 30 V DC, max. 1 A
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1.

1) Please note:

The correlation between the maximum output frequency, pulse frequency and current derating. Higher output frequencies on request. For further information see

The correlation between the minimum output frequency and permissible output current (current derating). Information is provided in the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

**Power Modules** 

	Technical	specifications	(continued)
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Line voltage 380 V 480 V 3 AC		Power Modules			
		6SL3315-1TE32-1AA3	6SL3315-1TE32-6AA3	6SL3315-1TE33-1AA3	6SL3315-1TE35-0AA3
Type rating					
• At / <sub>1</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	250
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	200
• At / <sub>1</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	400
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	350
	пр	100	200	200	000
• Rated current <i>I</i> <sub>rated O</sub> • Base-load current <i>L</i> <sup>3</sup>	А	210	260	310	490
<ul> <li>Base-load current l<sub>1</sub><sup>3)</sup></li> </ul>	A	205	250	302	490
• Base-load current $I_{\rm H}^{(4)}$					
• Base-load current / <sub>H</sub>	A	178	233	277	438
• Max. output current I <sub>max O</sub>	A	307	375	453	715
Input current					
Rated current Irated I	А	230	285	340	540
Maximum current Imax I	A	336	411	496	788
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.4	1.4	1.5	1.5
Pulse frequency <sup>5)</sup>					
Rated frequency	kHz	2	2	2	2
<ul> <li>Pulse frequency, max.</li> </ul>		2	2	2	-
<ul> <li>Without current derating</li> </ul>	kHz	2	2	2	2
		8	8	8	8
- With current derating	kHz	0	0	0	0
Power loss, at 50 Hz 400 V <sup>6)</sup>					
<ul> <li>Dissipated to coolant</li> </ul>	kW	2.36	2.97	3.31	5.29
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.06	0.07	0.09	0.14
Total	kW	2.42	3.04	3.4	5.43
Coolant volume flow 7)	l/min	9	9	12	12
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.52	0.52	0.88	0.88
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel
Coolant connections		Pipe thread ISO 228 G 3 (external thread 3/4", flat-			
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52
Line supply connection U1, V1, W1		Hole for M12	Hole for M12	Hole for M12	Hole for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240
DC link connection DCP, DCN		Hole for M12	Hole for M12	Hole for M12	Hole for M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240
Motor connection		Hole for M12	Hole for M12	2 × hole for M12	2 × hole for M12
U2/T1, V2/T2, W2/T3 • Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240
Cable length, max <sup>9)</sup>					
• Shielded	m	300	300	300	300
	m				
Unshielded	m	450	450	450	450
<ul><li>PE/GND connection</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	$2 \times \text{hole for M12}$ $2 \times 95$	$2 \times \text{hole for M12}$ $2 \times 95$	$2 \times \text{hole for M12}$ $2 \times 240$	2 × hole for M12 2 × 240
Dimensions					
Width	mm	265	265	265	265
Height	mm	836	836	983	983
Depth	mm	549	549	549	549
Weight, approx.	kg	77	77	108	108
Frame size	мg	FL	FL	GL	GL
	•				
Minimum short-circuit current <sup>10)</sup>	А	3000	3600	4400	8000

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 460 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $I_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{\rm (4)}$  The base-load current  $l_{\rm (H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>Current required for reliably triggering protective devices.

Water-cooled units

#### **Active Line Modules**

### Overview



The self-commutated infeed/regenerative feedback units (with IGBTs in infeed and regenerative feedback directions) generate a regulated DC link voltage. This means that the connected Motor Modules are decoupled from the line voltage. Line voltage fluctuations within the permissible supply tolerances have no effect on the motor voltage.

If required, the Active Line Modules can also provide reactive power compensation.

Active Line Modules are designed for connection to grounded TN/TT and non-grounded IT supply systems.

The water-cooled Active Line Modules are specifically designed for the operation of shared cooling circuits for the plant, motor and converter.

Active Line Modules are always operated together with the associated Active Interface Modules. These include the necessary pre-charging circuit as well as a Clean Power Filter.

### Design

The water-cooled Active Line Modules have the following interfaces as standard:

- 1 line supply connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for supplying the connected Motor Modules
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC, or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 PE connection
- 2 cooling water ports

The status of the Active Line Modules is indicated via three LEDs.

The following are included in the scope of supply of the Active Line Modules:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- 2 seals for cooling water connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

#### Selection and ordering data

Rated power at 400 V or 690 V	Rated infeed/ regenerative feedback current	Active Line Module
kW	А	Article No.
Line voltage 380 4	480 V 3 AC	
630	985	6SL3335-7TE41-0AA7
900	1405	6SL3335-7TE41-4AA7
Line voltage 500 (	690 V 3 AC	
900	810	6SL3335-7TG38-1AA7
1100	1020	6SL3335-7TG41-0AA7
1400	1270	6SL3335-7TG41-3AA7
1700	1560	6SL3335-7TG41-6AA7
Description		Article No.
Accessories		
3-way valve 1)		VXF41
		VXG41
Actuator for 3-way	/alve <sup>1)</sup>	
• 230 V 1 AC		SAX31
• 24 V AC/DC		SAX61
		SAX81
Accessories for re-		
Dust protection blan (50 units)	nking plugs	6SL3066-4CA00-0AA0
For DBIVE-CLiO port		

For DRIVE-CLiQ port

For additional information, refer to the manual.

For line-side components and recommended system components, see system components.

 Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies.

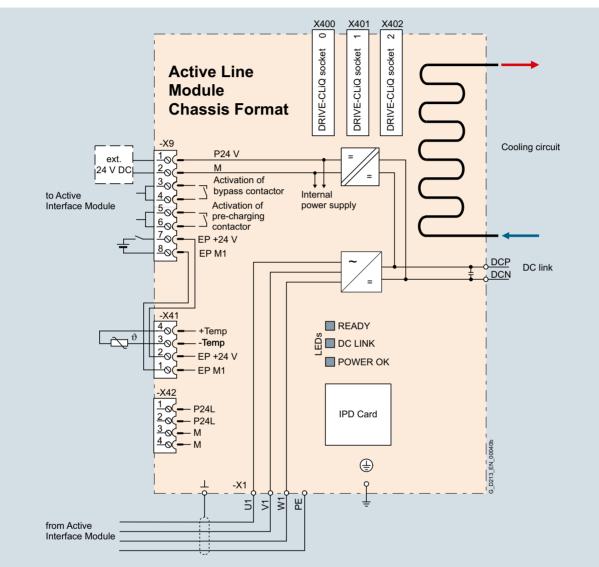
Water-cooled units

Active Line Modules

### Integration

Active Line Modules are always operated together with the associated Active Interface Modules. Active Interface Modules contain a Clean Power Filter with basic RI suppression, the pre-charging circuit for the Active Line Module, line voltage sensing circuit, and monitoring sensors.

The water-cooled Active Line Modules communicate with the higher-level control module via DRIVE-CLiQ. The control module in this case can be a CU320-2 or a SIMOTION D Control Unit. An external 24 V DC power supply is required to operate water-cooled Active Line Modules.



Connection example of an Active Line Module

### Technical specifications

General technical specifications

Electrical specifications				
Line power factor				
• Basic fundamental (cos $\varphi_1$ )	1 (factory setting), can be altered by inputting a reactive current setpoint			
<ul> <li>Total (λ)</li> </ul>	1 (factory setting)			
Efficiency	>98.5 % (Active Line Module) >99 % (Active Interface Module)			
DC link voltage, approx.	The DC link voltage is regulated and can be adjusted as a voltage decoupled from the line voltage. Factory setting of the DC link voltage: $1.5 \times$ line voltage			

Water-cooled units

#### **Active Line Modules**

### Technical specifications (continued)

Line voltage 380 V 480 V 3 AC		Active Line Modules		
		6SL3335-7TE41-0AA7	6SL3335-7TE41-4AA7	
Rated power				
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	630	900	
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	545	780	
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	900	1250	
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	800	1000	
DC link current				
Rated current Irated DC	А	1100	1573	
• Base-load current $I_{\rm H DC}^{(1)}$	А	982	1401	
Maximum current Imax DC	А	1654	2361	
Infeed/regenerative feedback current				
Rated current I <sub>rated I</sub>	А	985	1405	
<ul> <li>Maximum current I<sub>max I</sub></li> </ul>	А	1477	2055	
Current demand				
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.6	
DC link capacitance				
Active Line Module	μF	18900	28800	
• Drive line-up, max.	μF	230400	230400	
Pulse frequency	kHz	2.5	2.5	
Power loss, at 50 Hz 400 V <sup>2)</sup>				
<ul> <li>Dissipated to coolant</li> </ul>	kW	7.46	9.58	
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.44	0.62	
Total	kW	7.9	10.2	
Coolant volume flow <sup>3)</sup>	l/min	27	27	
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	1.56	1.56	
Pressure drop, typ. <sup>4)</sup> for volume flow	Pa	70000	70000	
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	
Coolant connections Intake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)		
Sound pressure level L <sub>pA</sub> <sup>5)</sup> (1 m) at 50/60 Hz	dB	71/73	71/73	
Line supply connection U1, V1, W1		2 x hole for M12	2 x hole for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	Busbar	Busbar	
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	
PE/GND connection		$2 \times hole for M12$	$2 \times hole for M12$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	
Cable length, max. <sup>6)</sup>				
Shielded	m	3900	3900	
Unshielded	m	5850	5850	
Dimensions				
• Width	mm	295	295	
Height	mm	1510	1510	
• Depth	mm	545	545	
Weight, approx.	kg	230	230	
Frame size		JXL	JXL	
Minimum short-circuit current 7)	А	16000	21000	

<sup>1)</sup> The base-load current  $I_{H DC}$  is the basis for a duty cycle of 150 % for 60 s or  $I_{max DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

<sup>3)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent. <sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

6) Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> Current required for reliably triggering protective devices.

Water-cooled units

Active Line Modules

#### Technical specifications (continued) Line voltage 500 ... 690 V 3 AC Active Line Modules 6SL3335-7TG38-1AA7 6SL3335-7TG41-0AA7 6SL3335-7TG41-3AA7 6SL3335-7TG41-6AA7 Rated power • At I<sub>rated DC</sub> (50 Hz 690 V) kW 900 1100 1400 1700 • At IH DC (50 Hz 690 V) 1490 kW 670 1000 1215 • At Irated DC (50 Hz 500 V) kW 620 780 965 1180 • At I<sub>H DC</sub> (50 Hz 500 V) kW 485 710 880 1080 • At I<sub>rated DC</sub> (60 Hz 575 V) 975 1250 1500 1880 hp • At I<sub>H DC</sub> (60 Hz 575 V) 765 1000 1250 1530 hp DC link current • Rated current Irated DC А 907 1147 1422 1740 Base-load current I<sub>H DC</sub><sup>1)</sup> 1550 А 808 936 1266 • Maximum current Imax DC 1722 2620 А 1360 2133 Infeed/regenerative feedback current Rated current Irated I 810 1025 1270 1560 А • Maximum current Imax I 2055 А 1214 1537 1905 Current demand • 24 V DC auxiliary power supply А 1.6 1.6 1.46 1.5 DC link capacitance μF 10500 16000 21000 Active Line Module 19330 μF 153600 153600 210000 • Drive line-up max 153600 Pulse frequency kHz 2.5 2.5 2.5 2.5 Power loss, at 50 Hz 690 V 2) Dissipated to coolant kW 8 28 10.37 12.98 17 17 · Dissipated to ambient air kW 0.22 0.53 0.57 0.79 Total kW 85 10.9 13 55 17.96 Coolant volume flow 3) l/min 16 27 27 27 dm<sup>3</sup> 0.74 1.56 Liquid volume 1.56 1.56 of the integrated heat exchanger Pressure drop, typ. 4) Ра 70000 70000 70000 70000 for volume flow Heat exchanger material Copper-nickel alloy Copper-nickel alloy Copper-nickel alloy Copper-nickel alloy Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing) **Coolant connections** Intake/return Sound pressure level LpA dB 71/73 71/73 71/73 71/73 (1 m) at 50/60 Hz 2 × hole for M12 Line supply connection U1, V1, W1 • Conductor cross-section, max. (IEC) $4 \times 185$ Busbar Busbar Busbar mm<sup>2</sup> **DC** link connection $2 \times hole$ for M12 2 × hole for M12 2 × hole for M12 2 × hole for M12 DCP, DCN Busbar Busbar Busbar Busbar **PE/GND** connection 2 × hole for M12 • Conductor cross-section, max. (IEC) mm<sup>2</sup> $4 \times 185$ Bushar Busbar Busbar Cable length, max. 6) Shielded 2250 2250 2250 2250 m Unshielded 3375 3375 3375 3375 m Dimensions Width 265 295 295 295 mm Height mm 987 1510 1510 1510 • Depth 545 545 545 545 mm 230 Weight, approx. kg 125 230 230

JXL

16000

 $^{1)}$  The base-load current  $\mathit{I}_{\rm H\,DC}$  is the basis for a duty cycle of 150 % for 60 s or  $\mathit{I}_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

А

HXL

12600

Frame size

Minimum short-circuit current 7)

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

<sup>3)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent. 4) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

JXL

24000

<sup>5)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

<sup>6)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> Current required for reliably triggering protective devices.

JXL

20000

Water-cooled units

### Overview



The Active Interface Module essentially comprises a watercooled filter reactor and a water-cooled filter module. The filter module contains a Clean Power Filter with basic RI suppression, the pre-charging circuit for the Active Line Module, the line voltage sensing circuit and monitoring sensors.

A bypass contactor is provided separately. Active Interface Modules are used in conjunction with Active Line Modules.

The water-cooled Active Interface Modules are specifically designed for the operation of shared cooling circuits for the plant, motor, and converter.

# Design

Active Interface Modules have the following interfaces as standard:

- 1 line supply connection
- 1 load connection
- 1 connection for the 24 V DC electronics power supply
- 1 connection for the external 230 V AC supply
- 1 DRIVE-CLiQ socket (on VSM10 Voltage Sensing Module)
- 1 connection for pre-charging circuit
- 1 PE connection
- 2 cooling water ports

The scope of supply of the Active Interface Modules includes:

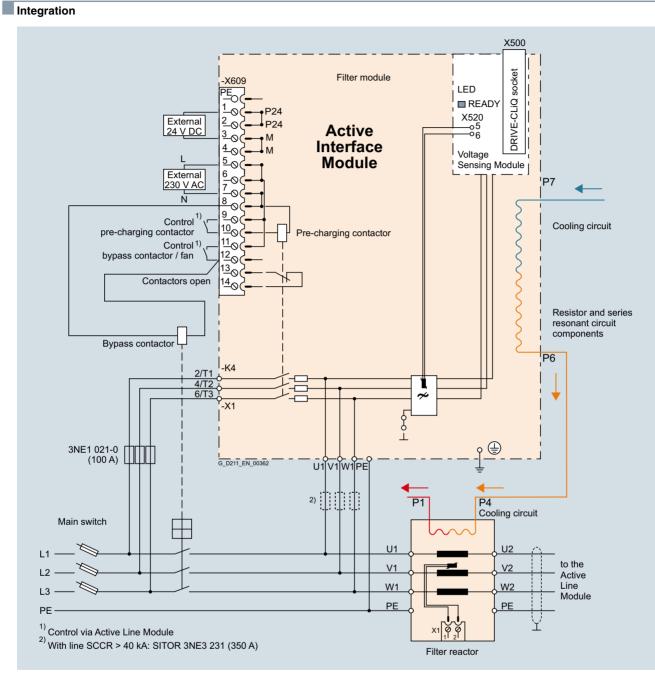
- Water-cooled filter reactor
- Water-cooled filter module
- Connection kit (cables and hoses)
- DRIVE-CLiQ cable for the connection between Active Interface Module and Active Line Module
- 2 seals for cooling water connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

#### Selection and ordering data

Suitable for Active Line Module in chassis format, water-cooled	Rated power of the Active Line Modules at 400 V or 690 V	Active Interface Module, water-cooled
	kW	Article No.
Line voltage 380 480	V 3 AC	
6SL3335-7TE41-0AA7	630	6SL3305-7TE41-4AA7
6SL3335-7TE41-4AA7	900	6SL3305-7TE41-4AA7
Line voltage 500 690	V 3 AC	
6SL3335-7TG38-1AA7	900	6SL3305-7TG41-0AA7
6SL3335-7TG41-0AA7	1100	6SL3305-7TG41-0AA7
6SL3335-7TG41-3AA7	1400	6SL3305-7TG41-3AA7
6SL3335-7TG41-6AA7	1700	6SL3305-7TG41-6AA7

Water-cooled units

Active Interface Modules



Connection example of water-cooled Active Interface Module with external bypass contactor

Water-cooled units

# Active Interface Modules

# Technical specifications

Line voltage 380 480 V 3 AC		Active Interface Module		
		6SL3305-7TE41-4AA7		
Suitable for Active Line Module				
<ul> <li>Rated power at 400 V</li> </ul>	kW	630	900	
- Water-cooled		6SL3335-7TE41-0AA7	6SL3335-7TE41-4AA7	
Rated current	А	985	1405	
Bypass contactor <sup>1)</sup>		3WL1112-2BB34-4AN2-Z C22 <sup>2)</sup>	3WL1116-2BB34-4AN2-Z C22 <sup>2)</sup>	
Current demand		a / 7	a / =	
<ul> <li>24 V DC auxiliary power supply</li> <li>230 V 2 AC</li> </ul>	A	0.17	0.17	
- Inrush current	А	1.0	1.0	
- Holding current	А	0.1	0.1	
<b>DC link capacitance</b> of the drive line-up, max. <sup>3)</sup>	μF	230400	230400	
Coolant volume flow	l/min	10	10	
Pressure drop, typ.	Pa	70000	70000	
for volume flow				
<b>Sound pressure level </b> $L_{pA}$ (1 m) at 50/60 Hz	dB	71/71	71/71	
Frame size		JIL	JIL	
Filter reactor				
Power loss <sup>4)</sup>				
• At 50 Hz 400 V	kW	6.0	8.6	
<ul><li>At 60 Hz 460 V</li><li>Dissipated to ambient air</li></ul>	kW kW	6.0 0.9	8.6 0.9	
Liquid volume				
Of integrated reactor cooler	dm <sup>3</sup>	0.6	0.6	
<ul> <li>Of hoses supplied</li> </ul>	dm <sup>3</sup> /m	0.285	0.285	
Coolant volume flow	l/min	10	10	
Pressure drop, typ. for volume flow	Pa	70000	70000	
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	
Coolant connections Return and connection to filter module		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)		
Line/load connection L1, L2, L3 / U2, V2, W2		Flat connector for M12 screws	Flat connector for M12 screws	
PE/GND connection	0	M10 stud	M10 stud	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	1 × 240	1 × 240	
Degree of protection		IP00	IP00	
Dimensions		202	202	
<ul><li>Width</li><li>Height</li></ul>	mm mm	382 698	382 698	
Depth	mm	575	575	
Weight, approx.	kg	299	299	
Filter module				
Power loss <sup>4)</sup>				
• At 50 Hz 400 V	kW	3.6	3.6	
<ul><li>At 60 Hz 460 V</li><li>Dissipated to ambient air</li></ul>	kW	3.6 0.15	3.6	
	kW dm <sup>3</sup>		0.15	
Liquid volume	ume	1 Openergiskel aller	1 Ocean consideration	
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	
Coolant connections Intake and connection to filter reactor		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)		

Water-cooled units

Active Interface Modules

Technical specifications (continued)				
Line voltage 380 480 V 3 AC		Active Interface Module 6SL3305-7TE41-4AA7		
				<ul><li>PE/GND connection</li><li>Conductor cross-section, max. (IEC)</li></ul>
Degree of protection		IP00	IP00	
Dimensions • Width • Height • Depth	mm mm mm	300 864 540	300 864 540	
Weight, approx.	kg	160	160	

1) The bypass contactor is not included in the scope of supply.

<sup>2)</sup> The breakers must only be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Active Line Module.

<sup>3)</sup> Information on higher capacitances is included in the SINAMICS Low Voltage Engineering Manual.

<sup>&</sup>lt;sup>4)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

# Active Interface Modules

Line voltage 500 690 V 3 AC		Active Interface Modules		
		6SL3305-7TG41-0AA7	6SL3305-7TG41-3AA7	6SL3305-7TG41-6AA7
Suitable for Active Line Module <ul> <li>Rated power at 690 V</li> <li>Water-cooled</li> </ul>	kW	<b>900/1100</b> 6SL3335-7TG38-1AA7 6SL3335-7TG41-0AA7	<b>1400</b> 6SL3335-7TG41-3AA7	<b>1700</b> 6SL3335-7TG41-6AA7
Rated current	A	1025	1270	1560
Bypass contactor <sup>1)</sup>		3WL1212-4BB34-4AN2-Z C22 <sup>2)</sup>	3WL1216-4BB34-4AN2-Z C22 <sup>2)</sup>	3WL1216-4BB34-4AN2-Z C22 <sup>2)</sup>
Current demand • 24 V DC auxiliary power supply • 230 V 2 AC	A	0.17	0.17	0.17
<ul> <li>Inrush current</li> <li>Holding current</li> </ul>	A A	1.0 0.1	1.0 0.1	1.0 0.1
<b>DC link capacitance</b> of the drive line-up, max. <sup>3)</sup>	μF	153600	153600	210000
Coolant volume flow	I/min	16	16	16
Pressure drop, typ. for volume flow	Pa	70000	70000	70000
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	71/71	71/71	71/71
Frame size		JIL	JIL	JIL
Filter reactor				
<b>Power loss <sup>4)</sup></b> • At 50 Hz 690 V • At 60 Hz 575 V • Dissipated to ambient air	kW kW kW	6.2 6.2 0.6	9.3 9.3 0.95	11.0 11.0 1.15
Liquid volume	1	0.0	0.00	1.10
<ul> <li>Of integrated reactor cooler</li> <li>Of hoses supplied</li> </ul>	dm <sup>3</sup> dm <sup>3</sup> /m	0.6 0.285	0.6 0.285	0.6 0.285
Coolant volume flow	I/min	10	10	8
Pressure drop, typ. for volume flow	Pa	70000	70000	70000
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy
Coolant connections Return and connection to filter module		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing	)	
Line/load connection L1, L2, L3 / U2, V2, W2		Flat connector for M12 screws	Flat connector for M12 screws	Flat connector for M12 screws
<ul><li>PE/GND connection</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	M10 stud 1 × 240	M10 stud 1 × 240	M10 stud 1 × 240
Degree of protection		IP00	IP00	IP00
Dimensions • Width • Height • Depth	mm mm mm	440 705 575	440 705 575	440 705 580
Weight, approx.	kg	365	365	365
Filter module				
Power loss <sup>4)</sup> • At 50 Hz 690 V • At 60 Hz 575 V	kW kW	5.0 5.0	5.0 5.0	7.5 7.5
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.15	0.15	0.15
Liquid volume	dm <sup>3</sup>	1	1	1
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy
Coolant connections Intake and connection to filter reactor		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing	)	

Water-cooled units

Active Interface Modules

Technical specifications (continued)					
Line voltage 500 690 V 3 AC		Active Interface Modules			
		6SL3305-7TG41-0AA7	6SL3305-7TG41-3AA7	6SL3305-7TG41-6AA7	
<ul><li>PE/GND connection</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	Flat connector for M8 screw $2 \times 120$	Flat connector for M8 screw $2 \times 120$	Flat connector for M8 screw 2 × 120	
Degree of protection		IP00	IP00	IP00	
Dimensions					
Width	mm	300	300	300	
Height	mm	864	864	864	
• Depth	mm	540	540	540	
Weight, approx.	kg	160	160	160	

1) The bypass contactor is not included in the scope of supply.

<sup>2)</sup> The breakers must only be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the bypass contactor to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Active Line Module. <sup>3)</sup> Information on higher capacitances is included in the SINAMICS Low Voltage Engineering Manual.

<sup>&</sup>lt;sup>4)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

### **Motor Modules**

### Overview



A Motor Module comprises a self-commutated converter with IGBTs. It generates a variable voltage with variable frequency from the DC link voltage that feeds the connected motor.

Multiple Motor Modules can be operated on a single DC link. This permits energy to be transferred between the Motor Modules. This means that if one Motor Module operating in generator mode produces energy, the energy can be used by another Motor Module operating in motor mode.

Motor Modules are controlled by a Control Unit.

The water-cooled Motor Modules are specifically designed for the operation of shared cooling circuits for the plant, motor, and converter.

### Design

The water-cooled Motor Modules have the following interfaces as standard:

- 1 motor connection
- 1 connection for the 24 V DC electronics power supply
- 1 DC link connection (DCP, DCN) for connecting to the supply DC link
- 3 DRIVE-CLiQ sockets
- 1 temperature sensor input for KTY84-130, Pt1000, PTC, or Pt100 (Pt1000 can be used from firmware V4.7 HF17)
- 1 connection for Safe Brake Adapter
- 1 connection for Safety Integrated
- 2 PE connections
- · 2 cooling water ports

The status of the Motor Modules is indicated via three LEDs.

The scope of supply of the Motor Modules includes:

- 1 DRIVE-CLiQ cable for connection to the Control Unit
- · 2 seals for cooling water connections
- 1 set of warning labels in 30 languages (BG, CN, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, JP, KR, LT, LV, MT, NL, NO, PL, PT, RO, RU, SE, SI, SK, TR)

### Selection and ordering data

Type rating at 400 V or 690 V	Rated output current	Motor Module
kW	А	Article No.
Line voltage 380 44 (DC link voltage 510		
110	210	6SL3325-1TE32-1AA3
132	260	6SL3325-1TE32-6AA3
160	310	6SL3325-1TE33-1AA3
250	490	6SL3325-1TE35-0AA3
400	745	6SL3325-1TE37-5AA7
560	985	6SL3325-1TE41-0AA7
710	1260	6SL3325-1TE41-2AA7
800	1405	6SL3325-1TE41-4AA7
Line voltage 500 69 (DC link voltage 675		
90	100	6SL3325-1TG31-0AA3
132	150	6SL3325-1TG31-5AA3
200	215	6SL3325-1TG32-2AA3
315	330	6SL3325-1TG33-3AA3
450	465	6SL3325-1TG34-7AA7
560	575	6SL3325-1TG35-8AA7
800	810	6SL3325-1TG38-1AA7
1000	1025	6SL3325-1TG41-0AA7
1200	1270	6SL3325-1TG41-3AA7
1500	1560	6SL3325-1TG41-6AA7

Description

Accessories	
3-way valve <sup>1)</sup>	VXF41
	VXG41
Actuator for 3-way valve <sup>1)</sup>	
• 230 V 1 AC	SAX31
• 24 V AC/DC	SAX61
	SAX81

Article No.

Accessories for re-ordering

Dust protection blanking plugs	6SL3066-4CA00-0AA0
(50 units)	
For DRIVE-CLiQ port	

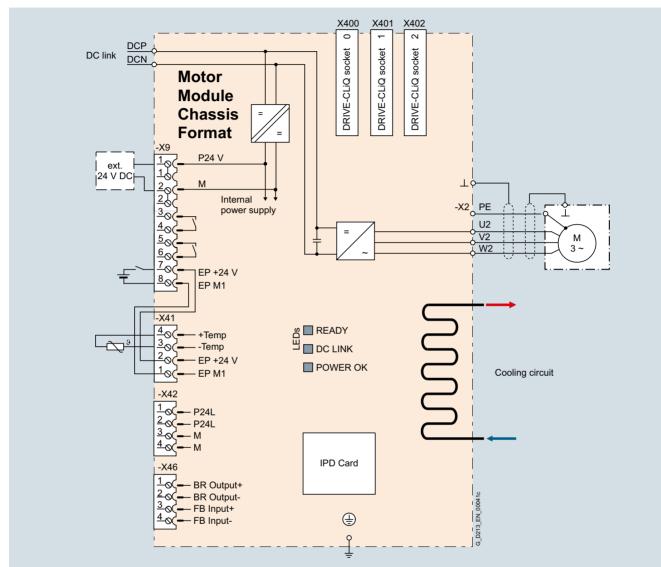
For motor-side components, see System components.

1) Recommended components for installing a flow control as condensation protection; manufactured by Siemens Building Technologies

Water-cooled units

**Motor Modules** 

# Integration



The water-cooled Motor Modules communicate with the higher-level control module via DRIVE-CLiQ.

The control module in this case can be a CU320-2 or a SIMOTION D Control Unit.

Connection example of a water-cooled Motor Module

Water-cooled units

### **Motor Modules**

### Technical specifications

### General technical specifications

Electrical specifications	
Efficiency	98.5 %
DC link voltage (up to 2000 m above sea level)	510 720 V DC (line voltage 380 480 V 3 AC) or 675 1035 V DC (line voltage 500 690 V 3 AC)
Output frequency <sup>1)</sup>	
Control type Servo	0 550 Hz
Control type Vector	0 550 Hz
Control mode V/f	0 550 Hz
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1.

1) Please note:

 The correlation between the maximum output frequency, pulse frequency and current derating. Higher output frequencies on request.
 For further information, see https://support.industry.siemens.com/cs/document/104020669 • The correlation between the minimum output frequency and permissible output current (current derating). Information is provided in the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Motor Modules

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules				
		6SL3325-1TE32-1AA3	6SL3325-1TE32-6AA3	6SL3325-1TE33-1AA3	6SL3325-1TE35-0AA3	
Type rating						
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	250	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	200	
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	400	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	350	
Output current						
Rated current I <sub>rated O</sub>	А	210	260	310	490	
• Base-load current $I_{L}^{(3)}$	А	205	250	302	477	
• Base-load current $I_{\rm H}^{-4}$	А	178	233	277	438	
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	307	375	453	715	
DC link current						
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>						
- Basic Line Module	А	256	317	380	600	
- Active Line Module	А	230	287	340	538	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>						
- Basic Line Module	А	250	305	368	581	
- Active Line Module	А	225	274	331	522	
<ul> <li>Base-load current I<sub>H DC</sub> <sup>4)</sup> when supplied via</li> </ul>						
- Basic Line Module	А	227	284	338	534	
- Active Line Module	А	195	255	303	480	
Current demand						
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.4	1.4	1.5	1.5	
DC link capacitance	μF	4800	5800	8400	9600	
Pulse frequency <sup>5)</sup>						
Rated frequency	kHz	2	2	2	2	
• Pulse frequency, max.						
- Without current derating	kHz	2	2	2	2	
- With current derating	kHz	8	8	8	8	
Power loss, max. <sup>6)</sup>						
• At 50 Hz 400 V	kW	1.61	1.95	2.29	3.56	
• At 60 Hz 460 V	kW	1.68	2.06	2.38	3.74	
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.06	0.07	0.09	0.14	
Coolant volume flow <sup>7)</sup>	l/min	9	9	12	12	
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.31	0.31	0.91	0.91	
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000	
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel	
Coolant connections Intake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)				
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52	
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	
Motor connection U2, V2, W2		Hole for M12	Hole for M12	Hole for M12	Hole for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	

Water-cooled units

#### **Motor Modules**

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules				
		6SL3325-1TE32-1AA3	6SL3325-1TE32-6AA3	6SL3325-1TE33-1AA3	6SL3325-1TE35-0AA3	
PE/GND connection		$2 \times hole$ for M12	$2 \times hole$ for M12	$2 \times hole$ for M12	$2 \times hole for M12$	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	
Cable length, max <sup>9)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
Dimensions						
Width	mm	150	150	150	150	
• Height	mm	746	746	1172	1172	
Depth	mm	545	545	545	545	
Weight, approx.	kg	41	41	80	80	
Frame size		FXL	FXL	GXL	GXL	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>4)</sup> The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 5) Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- 9) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Motor Modules

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules			
		6SL3325-1TE37-5AA7	6SL3325-1TE41-0AA7	6SL3325-1TE41-2AA7	6SL3325-1TE41-4AA7
Type rating					
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	400	560	710	800
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	315	450	630	710
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	600	800	1000	1150
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	450	700	900	1000
Output current					
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	745	985	1260	1405
<ul> <li>Base-load current I<sup>(3)</sup></li> </ul>	А	725	960	1230	1370
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	570	860	1127	1257
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	1087	1440	1845	2055
DC link current					
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>					
- Basic Line Module	А	894	1202	1512	1714
- Active Line Module	А	805	1080	1361	1544
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup></li> <li>when supplied via</li> </ul>					
- Basic Line Module	А	871	1170	1474	1670
- Active Line Module	А	784	1051	1326	1500
<ul> <li>Base-load current I<sub>H DC</sub> <sup>4)</sup></li> <li>when supplied via</li> </ul>					
- Basic Line Module	А	795	1048	1345	1532
- Active Line Module	А	716	942	1211	1377
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.46	1.46	1.46
DC link capacitance	μF	17400	21000	29000	29000
Pulse frequency <sup>5)</sup>					
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>					
- Without current derating	kHz	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5
Power loss, max. <sup>6)</sup>					
• At 50 Hz 400 V	kW	5.1	7.9	9.15	10.2
• At 60 Hz 460 V	kW	5.61	8.55	10.05	11.2
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.2	0.44	0.56	0.62
Coolant volume flow <sup>7)</sup>	l/min	16	27	27	27
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.74	1.56	1.56	1.56
Pressure drop, typ. 8) for volume flow	Pa	70000	70000	70000	70000
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy
Coolant connections Intake/return		Pipe thread ISO 228 G 3 (external thread 3/4", flat	/4 B -sealing)		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	56	56	56
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar
Motor connection U2, V2, W2		$2 \times hole$ for M12	2 × hole for M12	2 × hole for M12	2 × hole for M12
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 240	4 × 240	4 × 240

Water-cooled units

#### **Motor Modules**

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Motor Modules				
		6SL3325-1TE37-5AA7	6SL3325-1TE41-0AA7	6SL3325-1TE41-2AA7	6SL3325-1TE41-4AA7	
PE/GND connection		2 × hole for M12	$2 \times hole$ for M12	$2 \times hole$ for M12	$2 \times hole$ for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	Busbar	Busbar	Busbar	
Cable length, max <sup>9)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
Dimensions						
• Width	mm	265	295	295	295	
Height	mm	987	1510	1510	1510	
• Depth	mm	545	545	545	545	
Weight, approx.	kg	125	230	230	230	
Frame size		HXL	JXL	JXL	JXL	

- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $\mathit{I}_L$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  he base-load current  $\mathit{I}_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Motor Modules

recimical specifications (continued)							
Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules	Motor Modules				
		6SL3325-1TG31-0AA3	6SL3325-1TG31-5AA3	6SL3325-1TG32-2AA3	6SL3325-1TG33-3AA3		
Type rating							
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	90	132	200	315		
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	75	110	160	250		
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	90	132	200		
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	90	132	200		
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	150	200	300		
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	125	200	250		
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	100	150	215	330		
• Base-load current $I_{\rm L}^{(3)}$	А	95	142	208	320		
• Base-load current $I_{\rm H}^{4)}$	А	89	134	192	280		
Maximum current I <sub>max O</sub>	А	142	213	312	480		
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>							
- Basic Line Module	А	122	183	263	403		
- Active Line Module	А	110	165	237	363		
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	116	173	253	390		
- Active Line Module	А	105	156	229	352		
<ul> <li>Base-load current I<sub>H DC</sub> <sup>4)</sup> when supplied via</li> </ul>							
- Basic Line Module	А	108	163	234	341		
- Active Line Module	А	98	147	211	308		
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.0	1.0	1.5	1.5		
DC link capacitance	μF	2800	2800	4200	5800		
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25		
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25		
- With current derating	kHz	7.5	7.5	7.5	7.5		
Power loss, max. <sup>6)</sup>							
• At 50 Hz 690 V	kW	1.15	1.64	2.34	3.38		
• At 60 Hz 575 V	kW	1.02	1.45	2.05	2.96		
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.06	0.07	0.09	0.12		
Coolant volume flow <sup>7)</sup>	l/min	9	9	12	12		
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	0.31	0.31	0.91	0.91		
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	70000	70000		
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel		
Coolant connections Intake/return		Pipe thread ISO 228 G 3/ (external thread 3/4", flat-					
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52		
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar		
Motor connection U2, V2, W2		Hole for M12	Hole for M12	Hole for M12	Hole for M12		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	4 × 240	4 × 240		

Water-cooled units

#### **Motor Modules**

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3325-1TG31-0AA3	6SL3325-1TG31-5AA3	6SL3325-1TG32-2AA3	6SL3325-1TG33-3AA3	
PE/GND connection		$2 \times hole$ for M12				
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240	
Cable length, max <sup>9)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
Dimensions						
Width	mm	150	150	150	150	
Height	mm	728	728	1172	1172	
• Depth	mm	545	545	545	545	
Weight, approx.	kg	41	41	80	80	
Frame size		FXL	FXL	GXL	GXL	

- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Motor Modules

Line voltage 500 690 V 3 AC		Motor Modules		
DC link voltage 675 1035 V DC				
		6SL3325-1TG34-7AA7	6SL3325-1TG35-8AA7	
Type rating				
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	450	560	
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	400	450	
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	315	400	
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	250	315	
• At <i>I</i> <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	450	600	
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	450	500	
Output current				
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	465	575	
• Base-load current $I_{\rm L}^{(3)}$	А	452	560	
• Base-load current $I_{\rm H}^{(4)}$	А	416	514	
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	678	840	
DC link current				
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>				
- Basic Line Module	А	558	702	
- Active Line Module	А	502	632	
<ul> <li>Base-load current I<sub>L DC</sub> <sup>3)</sup> when supplied via</li> </ul>				
- Basic Line Module	А	544	683	
- Active Line Module	А	489	616	
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> </ul>				
- Basic Line Module	А	496	627	
- Active Line Module	А	446	565	
Current demand				
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.6	1.6	
DC link capacitance	μF	9670	9670	
Pulse frequency <sup>5)</sup>				
Rated frequency	kHz	1.25	1.25	
<ul> <li>Pulse frequency, max.</li> </ul>				
- Without current derating	kHz	1.25	1.25	
- With current derating	kHz	7.5	7.5	
Power loss, max. <sup>6)</sup>				
• At 50 Hz 690 V	kW	5.44	5.61	
• At 60 Hz 575 V	kW	5.1	5.45	
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.14	0.16	
Coolant volume flow <sup>7)</sup>	l/min	16	16	
Liquid volume	dm <sup>3</sup>	0.74	0.74	
of the integrated heat exchanger	GITT			
Pressure drop, typ. <sup>8)</sup> for volume flow	Pa	70000	70000	
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	
Coolant connections Intake/return		Pipe thread ISO 228 G 3/4 B (external thread 3/4", flat-sealing)		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	54	
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	
Motor connection U2, V2, W2		$2 \times hole$ for M12	$2 \times hole$ for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	

Water-cooled units

#### **Motor Modules**

Technical specifications (continued)				
Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules		
		6SL3325-1TG34-7AA7	6SL3325-1TG35-8AA7	
PE/GND connection		$2 \times hole for M12$	$2 \times hole$ for M12	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	
Cable length, max <sup>9)</sup>				
Shielded	m	300	300	
Unshielded	m	450	450	
Dimensions				
• Width	mm	265	265	
• Height	mm	987	987	
Depth	mm	545	545	
Weight, approx.	kg	125	125	
Frame size		HXL	HXL	

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.
- 8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Motor Modules

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules			
		6SL3325-1TG38-1AA7	6SL3325-1TG41-0AA7	6SL3325-1TG41-3AA7 1)	6SL3325-1TG41-6AA7 1)
Type rating					
• At I <sub>L</sub> (50 Hz 690 V) <sup>2)</sup>	kW	800	1000	1200	1500
• At I <sub>H</sub> (50 Hz 690 V) <sup>2)</sup>	kW	710	900	1000	1260
• At I <sub>L</sub> (50 Hz 500 V) <sup>2)</sup>	kW	560	710	900	1000
• At I <sub>H</sub> (50 Hz 500 V) <sup>2)</sup>	kW	560	630	800	900
• At I <sub>L</sub> (60 Hz 575 V) <sup>3)</sup>	hp	800	1000	1250	1500
• At I <sub>H</sub> (60 Hz 575 V) <sup>3)</sup>	hp	700	900	1000	1250
Output current					
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	810	1025	1270	1560
• Base-load current I <sub>L</sub> <sup>4)</sup>	А	790	1000	1230	1500
<ul> <li>Base-load current I<sub>H</sub><sup>5)</sup></li> </ul>	А	724	917	1136	1284
Maximum current I <sub>max O</sub>	А	1185	1500	1600	1950
DC link current					
<ul> <li>Rated current I<sub>rated DC</sub> when supplied via</li> </ul>					
- Basic Line Module	А	990	1250	1550	1903
- Active Line Module	А	891	1125	1395	1714
<ul> <li>Base-load current I<sub>L DC</sub> <sup>4)</sup> when supplied via</li> </ul>					
- Basic Line Module	А	963	1219	1500	1800
- Active Line Module	А	869	1100	1353	1650
<ul> <li>Base-load current I<sub>H DC</sub><sup>5)</sup> when supplied via</li> </ul>					
- Basic Line Module	А	883	1118	1384	1680
- Active Line Module	А	796	1009	1250	1550
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.46	1.46	1.46	1.46
DC link capacitance	μF	14000	16000	19330	21000
Pulse frequency <sup>6)</sup>					
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>					
- Without current derating	kHz	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5
Power loss, max. <sup>7)</sup>					
• At 50 Hz 690 V	kW	9.56	10.87	13.49	17.9
• At 60 Hz 575 V	kW	8.34	9.55	11.84	15.7
<ul> <li>Dissipated to ambient air</li> </ul>	kW	0.43	0.53	0.57	0.78
Coolant volume flow <sup>8)</sup>	l/min	27	27	27	27
Liquid volume of the integrated heat exchanger	dm <sup>3</sup>	1.56	1.56	1.56	1.56
Pressure drop, typ. <sup>9)</sup> for volume flow	Pa	70000	70000	70000	70000
Heat exchanger material		Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy	Copper-nickel alloy
Coolant connections Intake/return		Pipe thread ISO 228 G 3, (external thread 3/4", flat-			
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	56	56	56	56
DC link connection DCP, DCN		2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar	2 × hole for M12 Busbar
Motor connection U2, V2, W2		2 × hole for M12	$2 \times hole$ for M12	$2 \times hole for M12$	$2 \times hole for M12$
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	Busbar	Busbar	Busbar	Busbar

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For footnotes, see next page.

Water-cooled units

#### **Motor Modules**

#### Technical specifications (continued)

Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules				
		6SL3325-1TG38-1AA7	6SL3325-1TG41-0AA7	6SL3325-1TG41-3AA7 1)	6SL3325-1TG41-6AA7 1)	
PE/GND connection		$2 \times hole$ for M12				
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	Busbar	Busbar	Busbar	Busbar	
Cable length, max. <sup>10)</sup>						
Shielded	m	300	300	300	300	
Unshielded	m	450	450	450	450	
Dimensions						
• Width	mm	295	295	295	295	
• Height	mm	1510	1510	1510	1510	
• Depth	mm	545	545	545	545	
Weight, approx.	kg	230	230	230	240	
Frame size		JXL	JXL	JXL	JXL	

- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.
- $^{3)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- <sup>4)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{5)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- 6) Additional notes regarding the correlation between the pulse frequency and maximum output current/output frequency are provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. To ensure safe dissipation of the minor power loss released to the ambient air, it is important to follow the instructions pertaining to control cabinet installation in the SINAMICS Low Voltage Engineering Manual.
- <sup>8)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

9) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>Sum of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Water-cooled units

Mounting device for water-cooled power units

### Overview



The mounting device is used to install or remove water-cooled power units (Power Modules, Line Modules, Motor Modules, Filter Module on the Active Interface Module) in or out of a control cabinet. The mounting device can be used if the power units are mounted on mounting rails, which at the front have two M6 threads at a vertical distance of 20 mm to attach the mounting device.

The mounting device is a mounting aid. It is placed in front of the power unit and attached to the mounting rails below the power unit. The telescopic rails allow the mounting device to be adjusted to the installation height and width of the power unit. The power unit can be removed from the control cabinet after releasing the mechanical and electrical connections and the coolant connections. The power unit is guided and supported by the guide rails on the mounting device. To prevent it toppling over, the power unit must be secured to a crane, tripod, or similar assembly using the lifting lugs or the lifting equipment. The unit can then be lowered down from the mounting device.

### Selection and ordering data

Description	
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Mounting device for installing and removing power units Article No. 6SL3766-1CA00-0AA0

System components

### Line-side power components

### Technical specifications

### General technical specifications

Unless clearly specified otherwise, the following technical data are valid for all the following system components of the air-cooled and liquid-cooled SINAMICS S120 drive system in chassis format.

Electrical specifications						
Rated voltages	380 480 V 3 AC ±10 % (-15 % <	1 min)				
	500 690 V 3 AC $\pm 10$ % (-15 % $<$	500 690 V 3 AC ±10 % (-15 % <1 min)				
Line supply types	Grounded TN/TT systems and non-	grounded IT systems				
Line frequency	47 63 Hz					
Overvoltage category	III to EN 61800-5-1					
Electronics power supply	24 V DC, -15 % +20 % implemented as PELV circuit in acc Ground = negative pole grounded					
Mechanical specifications						
Degree of protection	IP00 or IP20 depending on type					
Protection class	I acc. to EN 61800-5-1					
Touch protection	EN 50274/DGUV regulation 3 when	used as intended				
Ambient conditions	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation			
Ambient temperature	-25 +55 °C Class 1K4 acc. to EN 60721-3-1	- <u>25</u> +70 ℃ Class 2K4 acc. to EN 60721-3-2	Line-side components: 0 40 °C without derating Up to 55 °C, see derating data Control Units, supplementary system components, and Sensor Modules: 0 55 °C (for operation in a control cabinet) DC link components and motor-side components: 0 55 °C			
Relative humidity Condensation, splashwater, and ice formation not permitted (EN 60204, Part 1)	<u>5 95 %</u> Class 1K4 acc. to EN 60721-3-1	5 95 % at 40 °C Class 2K4 acc. to EN 60721-3-2	5 <u>95 %</u> Class 3K3 acc. to EN 60721-3-3			
Environmental class/harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3			
Organic/biological influences	Class 1B1 acc. to EN 60721-3-1	Class 2B1 acc. to EN 60721-3-2	Class 3B1 acc. to EN 60721-3-3			
Degree of pollution	2 acc. to IEC/EN 61800-5-1	2 acc. to IEC/EN 61800-5-1	2 acc. to IEC/EN 61800-5-1			
Installation altitude	Up to 2000 m above sea level witho >2000 m above sea level, see dera					
Mechanical stability	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation			
Vibratory load	-	Class 2M2 acc. to EN 60721-3-2	<ul> <li>Test values</li> <li>acc. to EN 60068-2-6 test Fc:</li> <li>1058 Hz with constant deflection</li> <li>0.075 mm</li> <li>58 150 Hz with constant acceleration 9.81 m/s<sup>2</sup> (1 × g)</li> </ul>			
Shock load	-	Class 2M2 acc. to EN 60721-3-2	Test values according to EN 60068-2-27 test Ea: 98 m/s <sup>2</sup> (10 × <i>g</i> )/20 ms			
Compliance with standards						
Conformances/certificates of suitability, according to	safety)	w Voltage Directive 2014/35/EU, Machine connected to line supply voltages 380				
Radio interference suppression	Radio interference suppression is c "Second environment" (industrial lin	ts are not designed for connection to the compliant with the EMC product standard e supplies). EMC disturbances can occu e taken (e.g. $\rightarrow$ line filter), it can also be	for variable-speed drives EN 61800-3, ur when connected to the public grid.			

Deviations from the specified class are underlined.

System components

Line-side power components > Line filters

# Overview



In conjunction with line reactors and a logically consistent configuration of the plant or system, line filters limit the interference conducted by the Line Modules and Power Modules to the limit values of Category C2 acc. to EN 61800-3.

The line filters are suitable for TN and TT supply systems grounded at the neutral point.

### Selection and ordering data

Line filters for Power Modules

Suitable for Power Module in the chassis format, air-cooled	Type rating of the Power Module at 400 V	Rated input current of the Power Module	Line filter
6SL3310	kW	A	Article No.
Line voltage 380 480 V 3 AC			
1TE32-1AA3	110	229	6SL3000-0BE32-5AA0
1TE32-6AA3	132	284	6SL3000-0BE34-4AA0
1TE33-1AA3	160	338	
1TE33-8AA3	200	395	
1TE35-0AA3	250	509	6SL3000-0BE36-0AA0

#### Line filters for Basic Line Modules

Suitable for Basic Line Module chassis format, air-cooled	Rated power of the Basic Line Module at 400 V or 690 V	Rated input current of the Basic Line Module	Line filter
6SL3330	kW	A	Article No.
Line voltage 380 480 V 3 AC			
1TE34-2AA3	200	365	6SL3000-0BE34-4AA0
1TE35-3AA3	250	460	6SL3000-0BE36-0AA0
1TE38-2AA3	400	710	6SL3000-0BE41-2AA0
1TE41-2AA3	560	1010	
1TE41-5AA3	710	1265	6SL3000-0BE41-6AA0
1TE41-8AA3	900	1581	
Line voltage 500 690 V 3 AC			
1TG33-0AA3	250	260	6SL3000-0BG34-4AA0
1TG34-3AA3	355	375	
1TG36-8AA3	560	575	6SL3000-0BG36-0AA0
1TG41-1AA3	900	925	6SL3000-0BG41-2AA0
1TG41-4AA3	1100	1180	
7TG41-8AA3	1500	1580	6SL3000-0BG41-6AA0

System components

### Line-side power components > Line filters

# Selection and ordering data (continued)

Line filters for Smart Line Modules

Suitable for Smart Line Module in chassis format, air-cooled	Rated power of the Smart Line Module at 400 V or 690 V	Rated input current of the Smart Line Module	Line filter
6SL3330	kW	A	Article No.
Line voltage 380 480 V 3 AC			
6TE35-5AA3	250	463	6SL3000-0BE35-0AA0
6TE37-3AA3	355	614	6SL3760-0MB00-0AA0
6TE41-1AA3	500	883	6SL3760-0MC00-0AA0
6TE41-3AA3	630	1093	
6TE41-7AA3	800	1430	
Line voltage 500 690 V 3 AC			
6TG35-5AA3	450	463	6SL3760-0ME00-0AA0
6TG38-8AA3	710	757	6SL3760-0MN00-0AA0
6TG41-2AA3	1000	1009	
6TG41-7AA3	1400	1430	6SL3760-0MG00-0AA0

### Line filters for Active Line Modules

Suitable for Active Line Module chassis format, air-cooled	Rated power of the Active Line Module at 400 V or 690 V	Rated input current of the Active Line Module	Line filter
6SL3330	kW	A	Article No.
Line voltage 380 480 V 3 AC			
7TE32-1AA3	132	210	6SL3000-0BE33-1AA0
7TE32-6AA3	160	260	
7TE33-8AA3	235	380	6SL3000-0BE35-0AA0
7TE35-0AA3	300	490	
7TE36-1AA3	380	605	6SL3760-0MB00-0AA0
7TE37-5AA3	450	745	
7TE38-4AA3	500	840	6SL3760-0MC00-0AA0
7TE41-0AA3	630	985	
7TE41-2AA3	800	1260	
7TE41-4AA3	900	1405	
Line voltage 500 690 V 3 AC			
7TG35-8AA3	630	575	6SL3760-0ME00-0AA0
7TG37-4AA3	800	735	6SL3760-0MN00-0AA0
7TG41-0AA3	1100	1025	
7TG41-3AA3	1400	1270	6SL3760-0MG00-0AA0

Note:

Line filters are not available for liquid-cooled drive units.

1TE41-2AA3

System components

1TE41-8AA3

Line-side power components > Line filters

Line voltage 380 480 V 3 AC		Line filter				
		6SL3000- 0BE32-5AA0	6SL3000- 0BE34-4AA0	6SL3000- 0BE36-0AA0	6SL3000- 0BE41-2AA0	6SL3000- 0BE41-6AA0
Rated current	А	250	440	600	1200	1600
Power loss <sup>1)</sup> At 50 Hz	kW	0.015	0.047	0.053	0.119	0.153
Load/line supply connection		$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$	1 × hole for M10	1 × hole for M12	1 × hole for M12
		Provided for busbar connection	Provided for busbar connection			
PE connection		Hole for M8	Hole for M8	Hole for M10	Hole for M10	Hole for M10
Degree of protection		IP00	IP00	IP00	IP00	IP00
Dimensions						
• Width	mm	360	360	400	425	505
Height	mm	240	240	265	265	265
Depth	mm	116	116	140	145	145
Weight, approx.	kg	12.3	12.3	19	25.2	28.8
Suitable for Power Module in cha	ssis format		-			
Air-cooled	6SL3310-	1TE32-1AA3	1TE32-6AA3	1TE35-0AA3	-	-
			1TE33-1AA3			
			1TE33-8AA3			
Suitable for Basic Line Module in	chassis forn	nat	-			-
Air-cooled	6SL3330-	-	1TE34-2AA3	1TE35-3AA3	1TE38-2AA3	1TE41-5AA3
					1TE41-2AA3	1TE41-8AA3

Technical specifications

Line voltage 500 690 V 3 AC		Line filter				
		6SL3000-0BG34-4AA0	6SL3000-0BG36-0AA0	6SL3000-0BG41-2AA0	6SL3000-0BG41-6AA0	
Rated current	A	440	600	1200	1600	
Power loss <sup>1)</sup> At 50 Hz	kW	0.047	0.053	0.119	0.153	
Load/line supply connection		1 × hole for M10	1 × hole for M10	2 × hole for M12	2 × hole for M12	
		Provided for busbar connection				
PE connection		Hole for M8	Hole for M10	Hole for M10	Hole for M10	
Degree of protection		IP00	IP00	IP00	IP00	
Dimensions						
• Width	mm	360	400	425	505	
Height	mm	240	265	265	265	
Depth	mm	116	140	145	145	
Weight, approx.	kg	12.3	19	25.2	28.8	
Suitable for Basic Line Module i	n chassis for	mat				
Air-cooled	6SL3330-	1TG33-0AA3 1TG34-3AA3	1TG36-8AA3	1TG41-1AA3 1TG41-4AA3	1TG41-8AA3	

The specified power loss represents the maximum value at 100 % utili-zation. The value is lower under normal operating conditions.

System components

# Line-side power components > Line filters

	Line filter						
	6SL3000-0BE33-1AA0	6SL3000-	0BE35-0AA0	6SL3760-0MB00	)-0AA0	6SL3760-0MC00-0AA	
А	400	600		840		1405	
kW	0.042	0.06		0.058		0.111	
	M10 connecting lugs	M10 conn	necting lugs	M10 connecting	lugs	M10 connecting lugs	
	Hole for M8	Hole for N	/10	Hole for M10		Hole for M10	
	IP00	IP00		IP00		IP00	
mm	360	390		425		505	
mm	240	265		265		265	
mm	116	140		145		145	
kg	12.7	19.9		25.9		28.9	
in chassis for	mat						
6SL3330-	-	6TE35-5A	A3	6TE37-3AA3		6TE41-1AA3 6TE41-3AA3 6TE41-7AA3	
in chassis for	rmat						
6SL3330-	7TE32-1AA3	7TE33-8AA3		7TE36-1AA3		7TE38-4AA3	
	7TE32-6AA3	7TE35-0A	A3	7TE37-5AA3		7TE41-0AA3	
						7TE41-2AA3	
						7TE41-4AA3	
	Line filter						
	6SL3760-0ME00-0AA0	6	6SL3760-0MN0	0-0AA0	6SL376	60-0MG00-0AA0	
A	600		1025		1270		
kW	0.063	(	0.063 0.09		0.097		
	M10 connecting lugs	1	M12 connecting lugs M12		M12 co	onnecting lugs	
	Hole for M10	ł	Hole for M10		Hole fo	Hole for M10	
	IP00	I	IP00		IP00		
mm	400	2	425		505		
mm	365	3	365		365		
mm	140		145		145		
kg	27	3	36.7		36.7		
in chassis for	mat						
6SL3330-	6TG35-5AA3		6TG38-8AA3 6TG41-2AA3		6TG41	-7AA3	
		t	51G41-2AA5				
in chassis for	rmat	t	51641-2AA3				
	kW         mm         mm         mm         mm         mm         kg         in         chassis for         6SL3330-         in         6SL3330-         in         A         kW         in         chassis for         6SL3330-         in         kW         in         kg         kg         kg         kg         kg         kg         kg	KW       6SL3000-0BE33-1AA0         A       400         kW       0.042         I       M10 connecting lugs         I       Hole for M8         I       IP00         mm       360         mm       240         mm       116         kg       12.7         Kg       12.7         SSL3330-       Fassis formation         SSL3330-       Fassis formation         SSL3330-       Fassis formation         KW       Oo         KW       Oo         KW       SL330-         KW       SL330-         KW       SL330-         KW       SL330-         KW       SL3760-OME00-OAA0         KW       Oo63         KW       Oo63         MI0 connecting lugs         KW       Hole for M10         IP00       MIN         MIN       SGS         MIN       SGS	A         6SL3000-0BE33-1AA0         6SL3000-0BE33-1AA0           A         400         600           kW         0.042         0.06           kW         0.042         0.06           I         Hole for M8         Hole for M           I         Hole for M8         Hole for M           IP00         IP00         IP00           mm         360         390           mm         116         140           kg         12.7         19.9           in chassis formation         116         140           kg         12.7         19.9           in chassis formation         fors.330-         F           6SL3330-         -         6TE35-5A           fSL3330-         TTE32-1AA3         TTE33-8A           TTE32-6AA3         TTE33-6A           KW         0.063         T           KW         0.063         I           KW         0.063         I           IP00         IP00         I           mm         400         I           mm         365         I           mm         140         I           kg         27	Image: Note: Not	A       400       6SL3000-0BE33-1AA0       6SL3760-0MB00         A       400       600       840         kW       0.042       0.06       0.058         kW       0.042       0.06       0.058         M10 connecting lugs       M10 connecting lugs       M10 connecting lugs       M10 connecting lugs         M10       Hole for M8       Hole for M10       Hole for M10       Hole for M10         Mm       360       390       425       Proto         mm       360       390       425       Proto         mm       240       265       265       Proto       Proto         mm       116       140       145       Proto       Proto	6SL3000-0BE33-1AA0         6SL3000-0BE35-0AA0         6SL3760-0MB00-0AA0           A         400         600         840           KW         0.042         0.06         0.058           M10 connecting lugs         M10 connecting lugs         M10 connecting lugs         M10 connecting lugs           Hole for M8         Hole for M10         Hole for M10         Hole for M10           mm         360         390         425         500           mm         240         265         265         500           mm         116         140         145         500           in chassis formation         6TE37-3AA3         6TE37-3AA3         6TE37-3AA3         7TE36-1AA3           fSL3330-         7TE32-1AA3 7TE32-6AA3         7TE38-5AA3         6TE37-3AA3         7TE37-5AA3         7TE37-5AA3           in chassis format 6SL3760-0ME00-0AA0         6SL3760-0MN00-0AA0         6SL3760-0MN00-0AA0         6SL3760-0MN00-0AA0         6SL3760-0MN00-0AA0         6SL3760-0MN00-0AA0           A         600         1025         1270         0077           KW         0.063         M12 connecting lugs         M12 connecting lugs         M12 connecting lugs         M12 connecting lugs           M10         0.063         M12 conn	

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

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System components

Line-side power components > Line reactors



With a high line short-circuit power (i.e. low line supply cable inductance) a line reactor is required in order to

- protect the drive converter itself from excessively high harmonic currents and therefore overload
- limit the harmonics to permissible values. The harmonic currents are limited by the complete inductance comprising the line reactor and line supply cable inductance.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

### Selection and ordering data

#### Line reactors for SINAMICS S120 Power Modules

Suitable for Power Module in chassis format, air-cooled	Suitable for Power Module in chassis format, liquid-cooled	Type rating of the Power Modules at 400 V	Rated input current of the Power Module	Line reactor
6SL3310	6SL3315	kW	A	Article No.
Line voltage 380 480 V 3 A	AC			
1TE32-1AA3	1TE32-1AA3	110	229/230	6SL3000-0CE32-3AA0
1TE32-6AA3	1TE32-6AA3	132	284/285	6SL3000-0CE32-8AA0
1TE33-1AA3	1TE33-1AA3	160	338/340	6SL3000-0CE33-3AA0
1TE33-8AA3	-	200	395	6SL3000-0CE35-1AA0
1TE35-0AA3	1TE35-0AA3	250	509/540	

#### Line reactors for SINAMICS S120 Basic Line Modules

Suitable for Basic Line Module chassis format, <u>air-cooled</u>	Suitable for Basic Line Module chassis format, liquid-cooled	Rated power of the Basic Line Module at 400 V or 690 V	Rated input current of the Basic Line Module	Line reactor
6SL3330	6SL3335	kW	А	Article No.
Line voltage 380 480 V	' 3 AC			
1TE34-2AA3	-	200	365	6SL3000-0CE35-1AA0
1TE35-3AA3	-	250	460	
-	1TE37-4AA3	360	610	6SL3000-0CE36-3AA0
1TE38-2AA3	-	400	710	6SL3000-0CE37-7AA0
1TE41-2AA3	-	560	1010	6SL3000-0CE41-0AA0
-	1TE41-2AA3	600	1000	
1TE41-5AA3	-	710	1265	6SL3000-0CE41-5AA0
-	1TE41-7AA3	830	1420	
1TE41-8AA3	-	900	1581	6SL3000-0CE41-6AA0
Line voltage 500 690 \	/ 3 AC			
1TG33-0AA3	-	250	260	6SL3000-0CH32-7AA0
-	1TG34-2AA3	355	340	6SL3000-0CH33-4AA0
1TG34-3AA3	-	355	375	6SL3000-0CH34-8AA0
1TG36-8AA3	-	560	575	6SL3000-0CH36-0AA0
-	1TG37-3AA3	630	600	
1TG41-1AA3	-	900	925	6SL3000-0CH41-2AA0
_	1TG41-3AA3	1100	1070	
1TG41-4AA3	-	1100	1180	
-	1TG41-7AA3	1370	1350	6SL3000-0CH41-6AA0
1TG41-8AA3	-	1500	1580	

System components

# Line-side power components > Line reactors

### Selection and ordering data (continued)

Line reactors for SINAMICS S120 Smart Line Modules

Suitable for Smart Line Module in chassis format, <u>air-cooled</u>	Rated power of the Smart Line Module at 400 V or 690 V	Rated input current of the Smart Line Module	Line reactor
6SL3330	kW	A	Article No.
Line voltage 380 480 V 3 AC			
6TE35-5AA3	250	463	6SL3000-0EE36-2AA0
6TE37-3AA3	355	614	
6TE41-1AA3	500	883	6SL3000-0EE38-8AA0
6TE41-3AA3	630	1093	6SL3000-0EE41-4AA0
6TE41-7AA3	800	1430	
Line voltage 500 690 V 3 AC			
6TG35-5AA3	450	463	6SL3000-0EH34-7AA0
6TG38-8AA3	710	757	6SL3000-0EH37-6AA0
6TG41-2AA3	1000	1009	6SL3000-0EH41-4AA0
6TG41-7AA3	1400	1430	

### Technical specifications

Line voltage 380 480 V 3 AC	Line reactor						
		6SL3000- 0CE32-3AA0	6SL3000- 0CE32-8AA0	6SL3000- 0CE33-3AA0	6SL3000- 0CE35-1AA0	6SL3000- 0CE36-3AA0	6SL3000- 0CE37-7AA0
Rated current	А	224	278	331	508	628	773
Nominal inductance L <sub>N</sub>	μΗ	76	62	52	42	27	22
Power loss <sup>1)</sup> At 50 Hz	kW	0.274	0.247	0.267	0.365	0.368	0.351
Line/load connection		$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$	$1 \times \text{hole for M12}$	$1 \times \text{hole for M12}$	$1 \times \text{hole for M12}$
		Provided for bus- bar connection					
PE connection		M6 screw					
Degree of protection		IP00	IP00	IP00	IP00	IP00	IP00
Dimensions							
• Width	mm	270	270	270	300	300	300
Height	mm	248	248	248	269	269	269
Depth	mm	200	200	200	212	212	212
Weight, approx.	kg	24.5	26	27.8	38	41.4	51.3
Suitable for Power Module in cha	ssis format						
Air-cooled	6SL3310-	1TE32-1AA3	1TE32-6AA3	1TE33-1AA3	1TE33-8AA3	-	-
					1TE35-0AA3		
Liquid-cooled	6SL3315-	1TE32-1AA3	1TE32-6AA3	1TE33-1AA3	1TE35-0AA3	-	-
Suitable for Basic Line Module in	chassis forn	nat					
Air-cooled	6SL3330-	-	-	-	1TE34-2AA3 1TE35-3AA3	-	1TE38-2AA3
Liquid-cooled	6SL3335-	-	-	-	-	1TE37-4AA3	-

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

System components

Line-side power components > Line reactors

Line voltage 380 480 V 3 A0	C	Line reactor					
		6SL3000-0CE41-0AA0	6SL3000-0CE41-5AA0	6SL3000-0CE41-6AA0			
Rated current	А	1060	1485	1600			
Nominal inductance L <sub>N</sub>	μH	16	13	13			
<b>Power loss <sup>1)</sup></b> At 50 Hz	kW	0.498	0.776	0.606			
Line/load connection		1 × hole for M12	1 × hole for M12	1 × hole for M12			
		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection			
PE connection		M6 screw	M6 screw	M6 screw			
Degree of protection		IP00	IP00	IP00			
Dimensions							
• Width	mm	350	460	416			
Height	mm	321	435	435			
Depth	mm	211	235	235			
Weight, approx.	kg	69.6	118	123			
Suitable for Basic Line Modu	le in chassis for	nat					
Air-cooled	6SL3330-	1TE41-2AA3	1TE41-5AA3	1TE41-8AA3			
Liquid-cooled	6SL3335-	1TE41-2AA3	1TE41-7AA3	-			
Line voltage 380 480 V 3 A	C	Line reactor					
Ū		6SL3000-0EE36-2AA0	6SL3000-0EE38-8AA0	6SL3000-0EE41-4AA0			
Rated current	A	615	885	1430			
Nominal inductance L <sub>N</sub>	μH	55	35	25			
Power loss <sup>1)</sup> At 50 Hz	kW	0.56	0.81	1.08			
Line/load connection		1 × hole for M10	2 × hole for M10	2 × hole for M10			
		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection			
PE connection		M6 thread	M6 thread	M6 thread			
Degree of protection		IP00	IP00	IP00			
Dimensions							
• Width	mm	300	442	544			
Height	mm	264	376	386			
Depth	mm	203	263	232			
Weight, approx.	kg	57	85.5	220			
Suitable for Smart Line Modu	le in chassis for	mat					
Air-cooled	6SL3330-	6TE35-5AA3	6TE41-1AA3	6TE41-3AA3			
		6TE37-3AA3		6TE41-7AA3			

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

System components

# Line-side power components > Line reactors

Technical specifications (	continued)						
Line voltage 500 690 V 3 AC	Line reactor						
		6SL3000- 0CH32-7AA0	6SL3000- 0CH33-4AA0	6SL3000- 0CH34-8AA0	6SL3000- 0CH36-0AA0	6SL3000- 0CH41-2AA0	6SL3000- 0EH41-6AA0
Rated current	А	270	342	482	597	1167	1600
Nominal inductance L <sub>N</sub>	μН	100	81	65	46	30	17
Power loss <sup>1)</sup> At 50 Hz	kW	0.277	0.27	0.48	0.485	0.783	0.977
Line/load connection		$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$	$1 \times \text{hole for M12}$	$1 \times \text{hole for M12}$	$2 \times \text{hole for M12}$	$2 \times hole$ for M12
		Provided for bus- bar connection	Provided for bus bar connection				
PE connection		M6 screw	M6 screw				
Degree of protection		IP00	IP00	IP00	IP00	IP00	IP00
Dimensions							
• Width	mm	270	270	350	350	460	416
Height	mm	248	248	321	321	435	435
• Depth	mm	200	200	232	232	235	250
Weight, approx.	kg	27.9	38.9	55.6	63.8	147	134
Suitable for Basic Line Module	in chassis forr	nat					
Air-cooled	6SL3330-	1TG33-0AA3	-	1TG34-3AA3	1TG36-8AA3	1TG41-1AA3 1TG41-4AA3	1TG41-8AA3
Liquid-cooled	6SL3335-	-	1TG34-2AA3	_	1TG37-3AA3	1TG41-3AA3	1TG41-7AA3

Line voltage 500 690 V 3 AC		Line reactor				
		6SL3000-0EH34-7AA0	6SL3000-0EH37-6AA0	6SL3000-0EH41-4AA0		
Rated current	А	465	760	1430		
Nominal inductance L <sub>N</sub>	μΗ	115	70	40		
Power loss <sup>1)</sup> At 50 Hz	kW	0.82	0.95	1.85		
Line/load connection		1 × hole for M10	$2 \times hole for M10$	$2 \times hole for M10$		
		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection		
PE connection		M6 nut	M6 nut	M6 nut		
Degree of protection		IP00	IP00	IP00		
Dimensions						
• Width	mm	360	442	655		
• Height	mm	325	370	383		
Depth	mm	229	303	288		
Weight, approx.	kg	58	145	239		
Suitable for Smart Line Module in	n chassis form	nat				
Air-cooled	6SL3330-	6TG35-5AA3	6TG38-8AA3	6TG41-2AA3 6TG41-7AA3		

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

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System components

Line-side power components > Recommended line-side system components

# Selection and ordering data

Appropriate line-side power components are assigned depending on the power rating of the Power Modules, Basic Line Modules, Smart Line Modules or Active Line Modules. Further information about the main contactors, switch disconnectors, fuses and circuit breakers is provided in the Catalogs IC 10 and LV 10.

#### Assignment of line-side power components to air-cooled and liquid-cooled Power Modules in chassis format

	Type rating at 400 V	Rated input current		Suitable for Power Module in chassis format	Main contactor	Switch disconnector without handle and shaft	Switch disconnector with handle and shaft
		Air-cooled	Liquid-cooled				
	kW	A	A	6SL3310 <sup>1)</sup> 6SL3315 <sup>2)</sup>	Article No.	Article No.	Article No.
	Line voltage	380 480 V	3 AC				
	110	229	230	1TE32-1AA3	3RT1064-6AP36	3KL5530-1AB01	3KL5530-1GB01
-	132	284	285	1TE32-6AA3	3RT1065-6AP36	3KL5730-1AB01	3KL5730-1GB01
-	160	338	340	1TE33-1AA3	3RT1066-6AP36	-	
	200	395	-	1TE33-8AA3	3RT1075-6AP36	-	-
	250	509	540	1TE35-0AA3	3RT1076-6AP36	3KL6130-1AB02	3KL6130-1GB02

Type rating at 400 V	Rated input current		Suitable for Power Module in chassis format			Cable protection fuse incl. semiconductor protection	
	Air-cooled Liquid-cooled			Rated current		Rated current	
kW	A	A	6SL3310 <sup>1)</sup> 6SL3315 <sup>2)</sup>	A	Article No.	A	Article No.
Line voltage	e 380 480 V	3 AC					
110	229	230	1TE32-1AA3	250	3NA3144	315	3NE1230-2
132	284	285	1TE32-6AA3	300	3NA3250	350	3NE1331-2
160	338	340	1TE33-1AA3	355	3NA3254	450	3NE1333-2
200	395	-	1TE33-8AA3	400	3NA3260		
250	509	540	1TE35-0AA3	630	3NA3372	2 × 315/630	3NE1230-2 or 3NE1436-2

System components

Line-side power components > Recommended line-side system components

### Selection and ordering data (continued)

Assignment of line-side power components to air-cooled and liquid-cooled Basic Line Modules in chassis format

Rated power at 400 V or 690 V	Rated input current	Suitable for Basic Line Module	Main contactor	Fixed-mounted circuit breaker	Switch disconnector without handle and shaft	Switch disconnector with handle and shaft
kW	А		Туре	Article No.	Article No.	Article No.
Line voltage 3	80 480 V 3 A	c				
200	365	6SL3330-1TE34-2AA3 1)	3RT1075	-	3KL6130-1AB02	3KL6130-1GB02
250	460	6SL3330-1TE35-3AA3 1)	3RT1076	-	3KL6130-1AB02	3KL6130-1GB02
360	610	6SL3335-1TE37-4AA3 2)	3RT1076	-	3KL6130-1AB02	3KL6130-1GB02
400	710	6SL3330-1TE38-2AA3 <sup>1)</sup>	<b>3RT1066</b> (3 units)	-	3KL6230-1AB02	3KL6230-1GB02 <sup>3)</sup>
560	1010	6SL3330-1TE41-2AA3 <sup>1)</sup>	-	3WL1112-2BB34-4AN2-Z C22 <sup>4)</sup>	-	-
600	1000	6SL3335-1TE41-2AA3 <sup>2)</sup>	-	3WL1112-2BB34-4AN2-Z C22 <sup>4)</sup>	-	-
710	1265	6SL3330-1TE41-5AA3 <sup>1)</sup>	-	3WL1116-2BB34-4AN2-Z C22 <sup>4)</sup>	-	-
830	1420	6SL3335-1TE41-7AA3 <sup>2)</sup>	-	3WL1116-2BB34-4AN2-Z C22 <sup>4)</sup>	-	-
900	1630	6SL3330-1TE41-8AA3 <sup>1)</sup>	-	3WL1220-2BB34-4AN2-Z C22 <sup>4)</sup>	-	-
Line voltage §	690 V 3 A	C				
250	260	6SL3330-1TG33-0AA3 1)	3RT1066	-	3KL5730-1AB01	3KL5730-1GB01
355	375	6SL3330-1TG34-3AA3 <sup>1)</sup>	3RT1075	-	3KL6130-1AB02	3KL6130-1GB02
	340	6SL3335-1TG34-2AA3 <sup>2)</sup>				
560	575	6SL3330-1TG36-8AA3 <sup>1)</sup>	3RT1076	-	3KL6130-1AB02	3KL6130-1GB02
630	600	6SL3335-1TG37-3AA3 <sup>2)</sup>	3RT1076	-	3KL6130-1AB02	3KL6130-1GB02
900	925	6SL3330-1TG41-1AA3 <sup>1)</sup>	-	3WL1210-4BB34-4AN2-Z C22 <sup>4)</sup>	-	-
1100	1180	6SL3330-1TG41-4AA3 1)	-	3WL1212-4BB34-4AN2-Z	-	-
	1070	6SL3335-1TG41-3AA3 <sup>2)</sup>		C22 <sup>4)</sup>		
1370	1350	6SL3335-1TG41-7AA3 <sup>2)</sup>	-	3WL1216-4BB34-4AN2-Z C22 <sup>4)</sup>	-	-
1500	1580	6SL3330-1TG41-8AA3 <sup>1)</sup>	-	3WL1220-4BB34-4AN2-Z C22 <sup>4)</sup>	-	-

<sup>1)</sup> 6SL3330-... is the air-cooled version.

2) 6SL3335-... is the liquid-cooled version.

<sup>3)</sup> Suitable only for 3NE1 fuses up to size 3.

<sup>&</sup>lt;sup>4)</sup> The breakers must always be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the circuit breakers in order to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Line Module.

System components

Line-side power components > Recommended line-side system components

Rated power	Rated input	Suitable for Basic Line Module	Cable protection	fuse	Cable protection	
at 400 V or 690 V	current				incl. semiconduc	tor protection
			Rated current		Rated current	
kW	А		А	Article No.	А	Article No.
Line voltage	380 480 V 3 AC					
200	365	6SL3330-1TE34-2AA3 1)	500	3NA3365	450	3NE1333-2
250	460	6SL3330-1TE35-3AA3 1)	630	3NA3372	500	3NE1334-2
360	610	6SL3335-1TE37-4AA3 <sup>2)</sup>	2 × 315	<b>3NA3352</b> (2 units)	2 × 450	<b>3NE1333-2</b> (2 units)
400	710	6SL3330-1TE38-2AA3 1)	800	3NA3475	800	3NE1438-2
560	1010	6SL3330-1TE41-2AA3 <sup>1)</sup>	1250	3NA3482	2 × 560	<b>3NE1435-2</b> (2 units)
600	1000	6SL3335-1TE41-2AA3 <sup>2)</sup>	2 × 500	<b>3NA3365</b> (2 units)	2 × 560	<b>3NE1435-2</b> (2 units)
710	1265	6SL3330-1TE41-5AA3 <sup>1)</sup>	2 × 800	<b>3NA3475</b> (2 units)	2 × 710	<b>3NE1437-2</b> (2 units)
830	1420	6SL3335-1TE41-7AA3 <sup>2)</sup>	3 × 500	<b>3NA3365</b> (3 units)	2 × 800	<b>3NE1438-2</b> (2 units)
900	1630	6SL3330-1TE41-8AA3 <sup>1)</sup>	3 × 630	<b>3NA3372</b> (3 units)	3 × 630	<b>3NE1436-2</b> (3 units)
Line voltage	500 690 V 3 AC					
250	260	6SL3330-1TG33-0AA3 1)	315	3NA3252-6	315	3NE1230-2
355	375	6SL3330-1TG34-3AA3 1)	500	3NA3365-6	450	3NE1333-2
	340	6SL3335-1TG34-2AA3 <sup>2)</sup>	355	3NA3354-6		
560	575	6SL3330-1TG36-8AA3 <sup>1)</sup>	2 × 315	<b>3NA3252-6</b> (2 units)	630	3NE1436-2
630	600	6SL3335-1TG37-3AA3 <sup>2)</sup>	2 × 300	<b>3NA3250-6</b> (2 units)	2 × 350	<b>3NE1331-2</b> (2 units)
900	925	6SL3330-1TG41-1AA3 <sup>1)</sup>	2 × 500	<b>3NA3365-6</b> (2 units)	2 × 500	<b>3NE1334-2</b> (2 units)
1100	1180	6SL3330-1TG41-4AA3 <sup>1)</sup>	3 × 500	<b>3NA3365-6</b> (3 units)	2 × 630	<b>3NE1436-2</b> (2 units)
	1070	6SL3335-1TG41-3AA3 <sup>2)</sup>	3 × 400	<b>3NA3360-6</b> (3 units)	2 × 670	<b>3NE1447-2</b> (2 units)
1370	1350	6SL3335-1TG41-7AA3 <sup>2)</sup>	3 × 500	<b>3NA3365-6</b> (3 units)	3 × 560	<b>3NE1435-2</b> (3 units)
1500	1580	6SL3330-1TG41-8AA3 1)	4 × 500	<b>3NA3365-6</b> (4 units)	3 × 630	<b>3NE1436-2</b> (3 units)

Power components for the pre-charging circuit of the Basic Line Module in chassis format, frame size GD

Rated power at 400 V or 690 V	Rated input current	Suitable for Basic Line Module	Pre-charging resistors		Pre-charging contactor	Cable protection for pre-charging a	
			Pre-charging current <sup>3)</sup>			Rated current	
kW	А	6SL3330	A	Article No.	Туре	A	Article No.
Line voltage 380.	480 V 3 AC						
900	1630	1TE41-8AA3	91 <sup>4)</sup> 182 <sup>5)</sup>		3RT1034 <sup>4)</sup> 3RT1044 <sup>5)</sup>	50 100	3NE1817-0 <sup>4)</sup> 3NE1021-0 <sup>5)</sup>
Line voltage 500.	690 V 3 AC						
1500	1580	1TG41-8AA3	86 <sup>4)</sup> 172 <sup>5)</sup>		3RT1034 <sup>4)</sup> 3RT1044 <sup>5)</sup>	50 100	3NE1817-0 <sup>4)</sup> 3NE1021-0 <sup>5)</sup>

#### Note:

The dimension drawings of the pre-charging resistors are to be found in the dimension drawing collection for Catalog D 21.3 in the Information and Download Center (www.siemens.com/industry/infocenter).

<sup>1)</sup> 6SL3330-...is the air-cooled version.

<sup>2)</sup> 6SL3335-... is the liquid-cooled version.

<sup>3)</sup> Line current present at the start of the pre-charging process (initial rms value). <sup>4)</sup> With one pre-charging resistor per phase.

<sup>5)</sup> With two pre-charging resistors connected in parallel per phase.

System components

#### Line-side power components > Recommended line-side system components

### Selection and ordering data (continued)

Assignment of line-side power components to Smart Line Modules in chassis format

Rated power at 400 V or 690 V	Rated input current	Suitable for Smart Line Module	Main contactor	Fixed-mounted circuit breaker	Switch disconnector without handle and shaft	Switch disconnector with handle and shaft
kW	А	6SL3330	Article No.	Article No.	Article No.	Article No.
Line voltage	380 480 V 3 A	NC .				•
250	463	6TE35-5AA3	3RT1476-6AP36	-	3KL6130-1AB02	3KL6130-1GB02
355	614	6TE37-3AA3	3RT1476-6AP36	-	3KL6230-1AB02	3KL6230-1GB02
500	883	6TE41-1AA3	-	<b>3WL1210-4CB34-4AN2-Z</b> C22 <sup>1)</sup>	-	-
630	1093	6TE41-3AA3	-	<b>3WL1212-4CB34-4AN2-Z</b> C22 <sup>1)</sup>	-	-
800	1430	6TE41-7AA3	-	<b>3WL1216-4CB34-4AN2-Z</b> C22 <sup>1)</sup>	-	-
Line voltage	500 690 V 3 A	IC				
450	463	6TG35-5AA3	3RT1466-6AP36	-	3KL6130-1AB02	3KL6130-1GB02
710	757	6TG38-8AA3	3RT1466-6AP36	-	3KL6230-1AB02	3KL6230-1GB02

				<b>C22</b> <sup>1)</sup>		
Line volta	ge 500 690 V	′ 3 AC				
450	463	6TG35-5AA3	3RT1466-6AP36	-	3KL6130-1AB02	3KL6130-1GB02
710	757	6TG38-8AA3	<b>3RT1466-6AP36</b> (3 units)	-	3KL6230-1AB02	3KL6230-1GB02
1000	1009	6TG41-2AA3	-	<b>3WL1212-4CB34-4AN2-Z</b> C22 <sup>1)</sup>	-	-
1400	1430	6TG41-7AA3	-	<b>3WL1216-4CB34-4AN2-Z</b> C22 <sup>1)</sup>	-	-

Rated power at 400 V or 690 V	Rated input current	Suitable for Smart Line Module			Cable protection fus incl. semiconductor	
			Rated current		Rated current	
kW	А	6SL3330	A	Article No.	А	Article No.
Line voltage 3	80 480 V 3 A	c				
250	463	6TE35-5AA3	500	3NA3365	560	3NE1435-2
355	614	6TE37-3AA3	630	3NA3372	710	3NE1437-2
500	883	6TE41-1AA3	1000	3NA3480	2 × 500	<b>3NE1334-2</b> (2 units)
630	1093	6TE41-3AA3	1250	3NA3482	2 × 630	<b>3NE1436-2</b> (2 units)
800	1430	6TE41-7AA3	2 × 800	<b>3NA3475</b> (2 units)	2 × 850	<b>3NE1448-2</b> (2 units)
Line voltage 5	00 690 V 3 A	С				
450	463	6TG35-5AA3	500	3NA3365-6	560	3NE1435-2
710	757	6TG38-8AA3	2 × 400	<b>3NA3360-6</b> (2 units)	850	3NE1448-2
1000	1009	6TG41-2AA3	3 × 355	<b>3NA3354-6</b> (3 units)	2 × 560	<b>3NE1435-2</b> (2 units)
1400	1430	6TG41-7AA3	3 × 500	<b>3NA3365-6</b> (3 units)	2 × 850	<b>3NE1448-2</b> (2 units)

<sup>1)</sup> The breakers must always be switched ON and OFF by the sequence control. An interlocking set 3WL9111-0BA21-0AA0 as described in Catalog LV 10 should be provided for the circuit breakers in order to exclude the risk of unintentional manual operation. Manual operation bypasses the pre-charging circuit and can therefore destroy the Line Module.

System components

Line-side power components > Recommended line-side system components

### Selection and ordering data (continued)

Assignment of line-side power components to air-cooled and liquid-cooled Active Line Modules or Active Interface Modules in chassis format

Rated power at 400 V or 690 V	Rated input current	Suitable for Active Interface Module	Suitable for Active Line Module	Bypass contactor
kW	A			Article No.
Line voltage 380 48	0 V 3 AC			
132	210	6SL3300-7TE32-6AA1	6SL3330-7TE32-1AA3	Included in Active Interface Module
160	260	6SL3300-7TE32-6AA1	6SL3330-7TE32-6AA3	Included in Active Interface Module
235	380	6SL3300-7TE33-8AA1	6SL3330-7TE33-8AA3	Included in Active Interface Module
300	490	6SL3300-7TE35-0AA1	6SL3330-7TE35-0AA3 6SL3335-7TE35-0AA3	Included in Active Interface Module
380	605	6SL3300-7TE38-4AA1 6SL3305-7TE38-4AA5	6SL3330-7TE36-1AA3 6SL3335-7TE36-1AA3	3RT1476-6AP36
450	745	6SL3300-7TE38-4AA1	6SL3330-7TE37-5AA3	<b>3WL1110-2BB34-4AN2-Z</b> C22 <sup>1)</sup>
500	840	6SL3300-7TE38-4AA1 6SL3305-7TE38-4AA5	6SL3330-7TE38-4AA3 6SL3335-7TE38-4AA3	<b>3WL1110-2BB34-4AN2-Z</b> C22 <sup>1)</sup>
630	985	6SL3300-7TE41-4AA1 6SL3305-7TE41-4AA5 6SL3305-7TE41-4AA7	6SL3330-7TE41-0AA3 6SL3335-7TE41-0AA3 6SL3335-7TE41-0AA7	<b>3WL1112-2BB34-4AN2-Z</b> C22 <sup>1)</sup>
800	1260	6SL3300-7TE41-4AA1	6SL3330-7TE41-2AA3	<b>3WL1116-2BB34-4AN2-Z</b> C22 <sup>1)</sup>
900	1405	6SL3300-7TE41-4AA1 6SL3305-7TE41-4AA5 6SL3305-7TE41-4AA7	6SL3330-7TE41-4AA3 6SL3335-7TE41-4AA3 6SL3335-7TE41-4AA7	<b>3WL1116-2BB34-4AN2-Z</b> C22 <sup>1)</sup>
Line voltage 500 69	0 V 3 AC			
630	575	6SL3300-7TG35-8AA1	6SL3330-7TG35-8AA3 6SL3335-7TG35-8AA3	3RT1476-6AP36
800	735	6SL3300-7TG37-4AA1 6SL3305-7TG37-4AA5	6SL3330-7TG37-4AA3 6SL3335-7TG37-4AA3	<b>3RT1476-6AP36</b> (3 units)
900	810	6SL3305-7TG41-0AA5 6SL3305-7TG41-0AA7	6SL3335-7TG38-1AA3 6SL3335-7TG38-1AA7	<b>3WL1212-4BB34-4AN2-Z</b> C22 <sup>1)</sup>
1100	1025	6SL3300-7TG41-3AA1 6SL3305-7TG41-0AA5 6SL3305-7TG41-0AA7	6SL3330-7TG41-0AA3 6SL3335-7TG41-0AA3 6SL3335-7TG41-0AA7	<b>3WL1212-4BB34-4AN2-Z</b> C22 <sup>1)</sup>
1400	1270	6SL3300-7TG41-3AA1 6SL3305-7TG41-3AA5 6SL3305-7TG41-3AA7	6SL3330-7TG41-3AA3 6SL3335-7TG41-3AA3 6SL3335-7TG41-3AA7	<b>3WL1216-4BB34-4AN2-Z</b> C22 <sup>1)</sup>
1700	1560	6SL3305-7TG41-6AA5 6SL3305-7TG41-6AA7	6SL3335-7TG41-6AA3 6SL3335-7TG41-6AA7	<b>3WL1216-4BB34-4AN2-Z</b> C22 <sup>1)</sup>

System components

Line-side power components > Recommended line-side system components

### Selection and ordering data (continued)

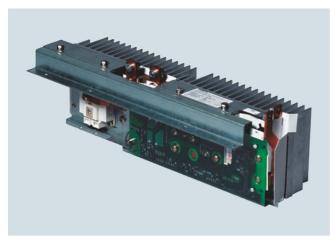
Rated power at 400 V or 690 V	Rated input current	Suitable for Active Inter- face Module	Suitable for Active Line Module	Switch disconnector without handle and shaft	Switch disconnector with handle and shaft	Cable prote	ection fuse	Cable pro incl. semi- protection	tection fuse conductor
						Rated current		Rated current	
kW	A	6SL3300 6SL3305	6SL3330 6SL3335	Article No.	Article No.	A	Article No.	A	Article No.
Line voltage	380 480 V	3 AC							
132	210	7TE32-6AA1	7TE32-1AA3	3KL5530-1AB01	3KL5530-1GB01	315	3NA3252	315	3NE1230-2
160	260	7TE32-6AA1	7TE32-6AA3	3KL5730-1AB01	3KL5730-1GB01	355	3NA3254	350	3NE1331-2
235	380	7TE33-8AA1	7TE33-8AA3	3KL5730-1AB01	3KL5730-1GB01	500	3NA3365	500	3NE1334-2
300	490	7TE35-0AA1	7TE35-0AA3 7TE35-0AA3 <sup>1)</sup>	3KL6130-1AB02	3KL6130-1GB02	630	3NA3372	630	3NE1436-2
380	605	7TE38-4AA1 7TE38-4AA5 <sup>1)</sup>	7TE36-1AA3 7TE36-1AA3 <sup>1)</sup>	3KL6230-1AB02	3KL6230-1GB02	800	3NA3475	800	3NE1438-2
500	840	7TE38-4AA1 7TE38-4AA5 <sup>1)</sup>	7TE38-4AA3 7TE38-4AA3 <sup>1)</sup>	-	-	2 × 425	<b>3NA3362</b> (2 units)	2 × 500	<b>3NE1334-2</b> (2 units)
630	985	7TE41-4AA1 7TE41-4AA5 <sup>1)</sup> 7TE41-4AA7 <sup>1)</sup>	7TE41-0AA3 7TE41-0AA3 <sup>1)</sup> 7TE41-0AA7 <sup>1)</sup>	-	-	2 × 500	<b>3NA3365</b> (2 units)	2 × 630	<b>3NE1436-2</b> (2 units)
800	1260	7TE41-4AA1	7TE41-2AA3	-	-	3 × 425	<b>3NA3362</b> (2 units)	2 × 850	<b>3NE1448-2</b> (2 units)
900	1405	7TE41-4AA1 7TE41-4AA5 <sup>1)</sup> 7TE41-4AA7 <sup>1)</sup>	7TE41-4AA3 7TE41-4AA3 <sup>1)</sup> 7TE41-4AA7 <sup>1)</sup>	-	-	3 × 500	<b>3NA3365</b> (3 units)	2 × 850	<b>3NE1448-2</b> (2 units)
Line voltage	500 690 V	3 AC							
560/630	575	7TG35-8AA1	7TG35-8AA3 7TG35-8AA3 <sup>1)</sup>	3KL6130-1AB02	3KL6130-1GB02	2 × 315	<b>3NA3352-6</b> (2 units)	670	3NE1447-2
800	735	7TG37-4AA1 7TG37-4AA5 <sup>1)</sup>	7TG37-4AA3 7TG37-4AA3 <sup>1)</sup>	3KL6230-1AB02	3KL6230-1GB02	2 × 400	<b>3NA3360-6</b> (2 units)	850	3NE1448-2
900	810	7TG41-0AA5 <sup>1)</sup> 7TG41-0AA7 <sup>1)</sup>	7TG38-1AA3 <sup>1)</sup> 7TG38-1AA7 <sup>1)</sup>	-	-	2 × 500	<b>3NA3365-6</b> (2 units)	2 x 560	<b>3NE1435-2</b> (2 units)
1100	1025	7TG41-3AA1 7TG41-0AA5 <sup>1)</sup> 7TG41-0AA7 <sup>1)</sup>	7TG41-0AA3 7TG41-0AA3 <sup>1)</sup> 7TG41-0AA7 <sup>1)</sup>	-	-	3 × 355	<b>3NA3354-6</b> (3 units)	2 × 630	<b>3NE1436-2</b> (2 units)
1400	1270	7TG41-3AA1 7TG41-3AA5 <sup>1)</sup> 7TG41-3AA7 <sup>1)</sup>	7TG41-3AA3 7TG41-3AA3 <sup>1)</sup> 7TG41-3AA7 <sup>1)</sup>	-	-	3 × 500	<b>3NA3365-6</b> (3 units)	2 × 800	<b>3NE1438-2</b> (2 units)
1700	1560	7TG41-6AA5 <sup>1)</sup> 7TG41-6AA7 <sup>1)</sup>	7TG41-6AA3 <sup>1)</sup> 7TG41-6AA7 <sup>1)</sup>	-	-	4 x 500	<b>3NA3365-6</b> (4 units)	3 x 630	<b>3NE1436-2</b> (3 units)

<sup>1)</sup> Liquid-cooled version, 6SL3305-... or 6SL3335-...

System components

DC link components > Braking Modules

#### Overview



A Braking Module and the matching external braking resistor are required to bring drives to a controlled standstill in the event of a power failure (e.g. with an EMERGENCY STOP) or to limit the DC link voltage for brief periods of regenerative operation, e.g. if the Line Module is not capable of energy recovery.

The Braking Module includes the power electronics and the associated control circuit. During operation, the DC link energy is converted to heat loss in an external braking resistor.

The Braking Module works independently of the converter control.

Several Braking Modules can be operated in parallel, but a separate braking resistor must be connected to each Braking Module.

Braking Modules are designed to be integrated into air-cooled Motor Modules, Line Modules or Power Modules and are cooled by the fans on these modules. The supply voltage for the electronics is taken from the DC link. The Braking Modules are connected to the DC link by means of the busbar sets included in the scope of supply or flexible cables and, in the case of Basic Line Modules of frame size GB or GD, using a separate cable harness set.

The activation threshold of the Braking Module can be adjusted by means of a DIP switch. The braking power values specified in the technical specifications apply to the upper activation threshold.

#### Design

The Braking Modules have the following interfaces as standard:

- 1 DC link connection
- 1 braking resistor connection
- 1 digital input (inhibit Braking Module / acknowledge error)
- 1 digital output (Braking Module inhibited)
- 1 DIP switch for adjusting the activation threshold

Information about Braking Module activation thresholds and other notes are included in the SINAMICS Low Voltage Engineering Manual.

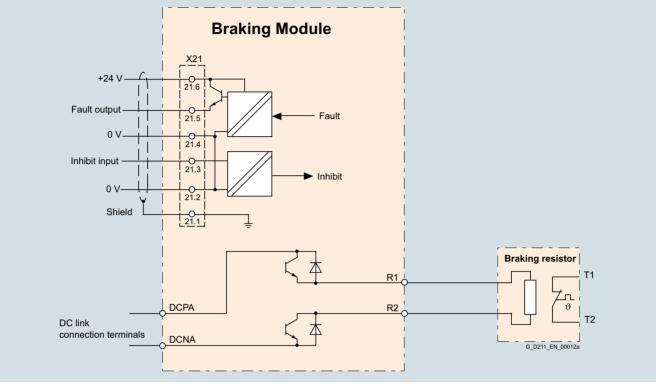
Selection and ordering data								
Rated power P <sub>DB</sub>	Peak power P <sub>15</sub>	Frame size	Braking Module					
kW	kW		Article No.					
Line voltage 3 DC link voltag	380 480 V ge 510 720	3 AC ) V DC						
25	125	FX/FB	6SL3300-1AE31-3AA0					
50	250	GX/GB/GD	6SL3300-1AE32-5AA0					
50	250	HX/JX	6SL3300-1AE32-5BA0					
Line voltage & DC link voltage								
25	125	FX/FB	6SL3300-1AF31-3AA0					
50	250	GX/GB/GD	6SL3300-1AF32-5AA0					
50	250	HX/JX	6SL3300-1AF32-5BA0					
Line voltage 6 DC link voltag								
25	125	FX/FB	6SL3300-1AH31-3AA0					
50	250	GX/GB/GD	6SL3300-1AH32-5AA0					
50	250	HX/JX	6SL3300-1AH32-5BA0					
Description			Article No.					
Accessories								

Cable harness set for mounting a Braking Module of frame size GX into a Basic Line Module of frame size GB or GD 6SL3366-2NG00-0AA0

System components

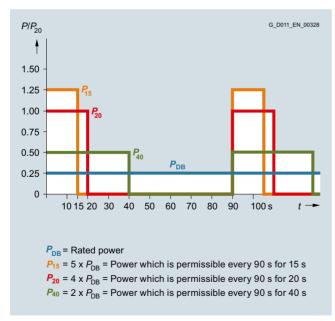
#### DC link components > Braking Modules

### Integration



Connection example of a Braking Module

#### Characteristic curves



Load diagram for Braking Modules and braking resistor

System components

DC link components > Braking Modules

## Technical specifications

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Braking Module		
		6SL3300-1AE31-3AA0	6SL3300-1AE32-5AA0	6SL3300-1AE32-5BA0
Power				
Rated power P <sub>DB</sub>	kW	25	50	50
<ul> <li>Peak power P<sub>15</sub></li> </ul>	kW	125	250	250
Power P <sub>20</sub>	kW	100	200	200
• Power P <sub>40</sub>	kW	50	100	100
Activation thresholds (adjustable via DIP switch)	V	774 (factory setting) or 673	774 (factory setting) or 673	774 (factory setting) or 673
Digital inputs in accordance with IEC 61131-2 Type 1				
Voltage	V	24 DC	24 DC	24 DC
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	V	-3 +5	-3 +5	-3 +5
High level	V	15 30	15 30	15 30
• Current consumption at 24 V DC, typ.	mA	10	10	10
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	1.5	1.5	1.5
Digital outputs sustained-short-circuit-proof				
Voltage	V	24 DC	24 DC	24 DC
Load current per digital output, max.	mA	500	500	500
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	1.5	1.5	1.5
R1/R2 connection		M8 nut	M8 nut	M8 nut
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	35	50	50
Weight, approx.	kg	3.6	7.3	7.5

Air-cooled	Frame size	FX/FB	GX/GB/GD <sup>1)</sup>	HX/JX

Line voltage 500 600 V 3 AC DC link voltage 675 900 V DC		Braking Module		
		6SL3300-1AF31-3AA0	6SL3300-1AF32-5AA0	6SL3300-1AF32-5BA0
Power				
<ul> <li>Rated power P<sub>DB</sub></li> </ul>	kW	25	50	50
<ul> <li>Peak power P<sub>15</sub></li> </ul>	kW	125	250	250
Power P <sub>20</sub>	kW	100	200	200
• Power P <sub>40</sub>	kW	50	100	100
Activation thresholds (adjustable via DIP switch)	V	967 (factory setting) or 841	967 (factory setting) or 841	967 (factory setting) or 841
Digital inputs in accordance with IEC 61131-2 Type 1				
Voltage	V	24 DC	24 DC	24 DC
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	V	-3 +5	-3 +5	-3 +5
High level	V	15 30	15 30	15 30
• Current consumption at 24 V DC, typ.	mA	10	10	10
Conductor cross-section, max.	mm <sup>2</sup>	1.5	1.5	1.5
Digital outputs sustained-short-circuit-proof				
Voltage	V	24 DC	24 DC	24 DC
• Load current per digital output, max.	mA	500	500	500
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	1.5	1.5	1.5
R1/R2 connection		M8 nut	M8 nut	M8 nut
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	35	50	50
Weight, approx.	kg	3.6	7.3	7.5
Suitable for installation in air-cooled F	Power Me	odules, Line Modules or Motor Mo	dules	
Air-cooled	Frame size	FX/FB	GX/GB/GD <sup>1)</sup>	HX/JX

<sup>1)</sup> Cable harness set 6SL3366-2NG00-0AA0 is required to connect the Braking Module to a Basic Line Module of frame size GB or GD.

System components

### DC link components > Braking Modules

### Technical specifications (continued)

Line voltage 660 690 V 3 AC DC link voltage 890 1035 V DC		Braking Module		
		6SL3300-1AH31-3AA0	6SL3300-1AH32-5AA0	6SL3300-1AH32-5BA0
Power				
Rated power P <sub>DB</sub>	kW	25	50	50
Peak power P <sub>15</sub>	kW	125	250	250
• Power P <sub>20</sub>	kW	100	200	200
• Power P <sub>40</sub>	kW	50	100	100
Activation thresholds (adjustable via DIP switch)	V	1158 (factory setting) or 1070	1158 (factory setting) or 1070	1158 (factory setting) or 1070
Digital inputs in accordance with IEC 61131-2 Type 1				
Voltage	V	24 DC	24 DC	24 DC
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	V	-3 +5	-3 +5	-3 +5
High level	V	15 30	15 30	15 30
• Current consumption at 24 V DC, typ.	mA	10	10	10
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	1.5	1.5	1.5
Digital outputs sustained-short-circuit-proof				
Voltage	V	24 DC	24 DC	24 DC
• Load current per digital output, max.	mA	500	500	500
<ul> <li>Conductor cross-section, max.</li> </ul>	mm <sup>2</sup>	1.5	1.5	1.5
R1/R2 connection		M8 nut	M8 nut	M8 nut
Conductor cross-section, max.	mm <sup>2</sup>	35	50	50
Weight, approx.	kg	3.6	7.3	7.5
Suitable for installation in air-cooled F	Power Mo	odules, Line Modules or Motor Mod	dules	
Air-cooled	Frame size	FX/FB	GX/GB/GD <sup>1)</sup>	HX/JX

<sup>1)</sup> Cable harness set 6SL3366-2NG00-0AA0 is required to connect the Braking Module to a Basic Line Module of frame size GB or GD.

System components

DC link components > Braking resistors

#### Overview



Excess energy in the DC link is dissipated via the braking resistor.

The braking resistor is connected to a Braking Module.

By positioning the braking resistor outside the cabinet or switchgear room, it is possible to extract the heat losses away from the Line Modules / Motor Modules. This reduces the level of air conditioning required.

The maximum permissible cable length between the Braking Module and braking resistor is 100 m.

Two braking resistors with different rated and peak power values are available for the devices.

The braking resistor is monitored on the basis of the duty cycle. A temperature switch (NC contact) is also fitted. This responds when the maximum permissible temperature is exceeded and can be evaluated by a controller.

Information about possible duty cycles of the braking resistors and other notes are included in the SINAMICS Low Voltage Engineering Manual.

#### Selection and ordering data Suitable for Braking resistor Rated power PDB **Braking Module** kW 6SL 3300-... Article No Line voltage 380 ... 480 V 3 AC DC link voltage 510 ... 720 V DC 6SL3000-1BE31-3AA0 1AE31-3AA0 25 50 1AE32-5 . A0 6SL3000-1BE32-5AA0 Line voltage 500 ... 600 V 3 AC DC link voltage 675 ... 900 V DC 25 1AF31-3AA0 6SL3000-1BF31-3AA0 50 1AF32-5 . A0 6SL3000-1BF32-5AA0 Line voltage 660 ... 690 V 3 AC DC link voltage 890 ... 1035 V DC 6SL3000-1BH31-3AA0 25 1AH31-3AA0 50 1AH32-5 . A0 6SL3000-1BH32-5AA0

#### Characteristic curves



 $P_{15} = 5 \times P_{DB}$  = Power which is permissible every 90 s for 15 s  $P_{20} = 4 \times P_{DB}$  = Power which is permissible every 90 s for 20 s  $P_{40} = 2 \times P_{DB}$  = Power which is permissible every 90 s for 40 s

Load diagram for Braking Modules and braking resistors

System components

### DC link components > Braking resistors

### Technical specifications

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Braking resistor	
		6SL3000-1BE31-3AA0	6SL3000-1BE32-5AA0
Resistance	Ω	4.4 (±7.5 %)	2.2 (±7.5 %)
Rated power <i>P</i> <sub>DB</sub> (continuous braking power)	kW	25	50
Power P <sub>15</sub>	kW	125	250
Power P <sub>20</sub>	kW	100	200
Power P <sub>40</sub>	kW	50	100
Current, max.	А	189	378
Power connection		M10 stud	M10 stud
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	50	70
Degree of protection		IP20	IP20
Dimensions			
Width	mm	740	810
Height	mm	605	1325
• Depth	mm	486	486
Weight, approx.	kg	50	120 (265)
Suitable for Braking Module	Туре	6SL3300-1AE31-3AA0	6SL3300-1AE32-5 . A0

Line voltage 500 600 V 3 AC DC link voltage 675 900 V DC		Braking resistor	
		6SL3000-1BF31-3AA0	6SL3000-1BF32-5AA0
Resistance	Ω	6.8 (±7.5 %)	3.4 (±7.5 %)
Rated power <i>P</i> <sub>DB</sub> (continuous braking power)	kW	25	50
Power P <sub>15</sub>	kW	125	250
Power P <sub>20</sub>	kW	100	200
Power P <sub>40</sub>	kW	50	100
Current, max.	А	189	378
<ul><li>Power connection</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	M10 stud 50	M10 stud 70
Degree of protection		IP20	IP20
Dimensions • Width • Height • Depth	mm mm mm	740 605 486	810 1325 486
Weight, approx.	kg	50	120
Suitable for Braking Module	Туре	6SL3300-1AF31-3AA0	6SL3300-1AF32-5 . A0

Line voltage 660 690 V 3 AC DC link voltage 890 1035 V DC		Braking resistor	
		6SL3000-1BH31-3AA0	6SL3000-1BH32-5AA0
Resistance	Ω	9.8 (±7.5 %)	4.9 (±7.5 %)
Rated power <i>P</i> <sub>DB</sub> (continuous braking power)	kW	25	50
Power P <sub>15</sub>	kW	125	250
Power P <sub>20</sub>	kW	100	200
Power P <sub>40</sub>	kW	50	100
Current, max.	А	125	255
Power connection		M10 stud	M10 stud
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	50	70
Degree of protection		IP20	IP20
Dimensions			
Width	mm	740	810
Height	mm	605	1325
• Depth	mm	486	486
Weight, approx.	kg	50	120
Suitable for Braking Module	Туре	6SL3300-1AH31-3AA0	6SL3300-1AH32-5 . A0

System components

DC link components > DC link fuses

### Selection and ordering data

Suitable DC link fuses are assigned depending on the power rating of the Motor Modules. Further information about the fuses listed is provided in the Catalogs IC 10 and LV 10.

Assignment of the DC link fuses to the Motor Modules in chassis format, liquid-cooled and water-cooled

Type rating at 400 V	Rated DC link current for power supplied via	Suitable for Motor Module chassis format	DC link f	use acco	rding to	EC	DC link f	use acco	rding to I	JL <sup>1)</sup>
	Basic Line Module / Active Line Module		Rated current	Quan- tity/ Phase	Frame size		Rated current	Quan- tity/ Phase	Frame size	
kW	А	6SL3325	А			Article No.	A			Article No.
Line volta	ge 380 480 V 3 AC									
110	256/230	1TE32-1AA3	315	1	1	3NE3230-0B	315	1	1	3NE3230-0B
							315	1	2L	3NB1231-4KK11
132	317/287	1TE32-6AA3	400	1	1	3NE3232-0B	400	1	1	3NE3232-0B
							400	1	2L	3NB1234-4KK11
160	380/340	1TE33-1AA3	450	1	1	3NE3233	450	1	1	3NE3233
							500	1	ЗL	3NB1337-4KK11
250	600/538	1TE35-0AA3	630	1	2	3NE3236	630	1	2	3NE3236
							800	1	ЗL	3NB1345-4KK11
315	738/664	1TE36-1AA3	800	1	2	3NE3338-8	800	1	2	3NE3338-8
							800	1	ЗL	3NB2345-4KK16
400	894/805	1TE37-5AA3 1TE37-5AA7	500	2	2	3NE3334-0B	1000	1	3L	3NB2350-4KK16
450	1025/922	1TE38-4AA3	560	2	2	3NE3335	560	2	2	3NE3335
							1000	1	ЗL	3NB2350-4KK16
560	1202/1080	1TE41-0AA3 1TE41-0AA7	630	2	2	3NE3336	630	2	2	3NE3336
		TTE41-UAA7					1400	1	3L	3NB2355-4KK16
710	1512/1361	1TE41-2AA3 1TE41-2AA7	900	2	2	3NE3340-8	2100	1	3L	3NB2364-4KK17
800	1714/1544	1TE41-4AA3	900	2	2	3NE3340-8	900	2	2	3NE3340-8
		1TE41-4AA7					2100	1	3L	3NB2364-4KK17
800	1550/1403	1TE41-4AS3 <sup>2)</sup>	900	2	2	3NE3340-8	2100	1	3L	3NB2364-4KK17

<sup>1)</sup> To achieve a UL-approved system, it is absolutely essential to use the fuse types specified in the table.

 2) This Motor Module has been specifically designed for loads demanding a high dynamic performance.

System components

#### DC link components > DC link fuses

### Selection and ordering data (continued)

Type rating at 690 V	Rated DC link current for power supplied via		DC link f	use acco	rding to	EC	DC link f	use acco	rding to	UL <sup>1)</sup>
	Basic Line Module / Active Line Module		Rated current	Quan- tity/ Phase	Frame size		Rated current	Quan- tity/ Phase	Frame size	
kW	А	6SL3325	А			Article No.	А			Article No.
Line volta	age 500 690 V 3 AC									
90	122/110	1TG31-0AA3	160	1	1	3NE3224	160	1	1	3NE3224
							200	1	1L	3NB1126-4KK11
132	183/165	1TG31-5AA3	200	1	1	3NE3225	200	1	1	3NE3225
							250	1	1L	3NB1128-4KK11
200	263/237	1TG32-2AA3	315	1	1	3NE3230-0B	315	1	1	3NE3230-0B
							315	1	2L	3NB1231-4KK11
315	403/363	1TG33-3AA3	450	1	2	3NE3233	450	1	2	3NE3233
							500	1	3L	3NB1337-4KK11
450	558/502	1TG34-7AA3 1TG34-7AA7	630	1	2	3NE3336	800	1	3L	3NB1345-4KK11
560	702/632	1TG35-8AA3	400	2	1	3NE3232-0B	400	2	1	3NE3232-0B
		1TG35-8AA7					800	1	3L	3NB2345-4KK16
710	903/759	1TG37-4AA3	560	2	2	3NE3335	1000	1	3L	3NB2350-4KK16
800	990/891	1TG38-0AA3 <sup>2)</sup>	560	2	2	3NE3335	1000	1	3L	3NB2350-4KK16
800	990/891	1TG38-1AA3	560	2	2	3NE3335	560	2	2	3NE3335
		1TG38-1AA7					1000	1	3L	3NB2350-4KK16
1000	1250/1125	1TG41-0AA3	710	2	2	3NE3337-8	710	2	2	3NE3337-8
		1TG41-0AA7					1600	1	3L	3NB2357-4KK16
1200	1550/1395	1TG41-3AA3	900	2	2	3NE3340-8	900	2	2	3NE3340-8
		1TG41-3AA7					2100	1	3L	3NB2364-4KK17
1500	1903/1605	1TG41-6AA3 1TG41-6AA7	710	3	2	3NE3337-8	2400	1	3L	3NB2366-4KK17

<sup>1)</sup> To achieve a UL-approved system, it is absolutely essential to use the fuse types specified in the table.

2) Device 6SL3325-1TG38-0AA3 is optimized for a base pulse frequency of 1.25 kHz, for an increased pulse frequency or for certain overloads, the derating factor is higher than for the device 6SL3325-1TG38-1AA3.

System components

Motor-side power components > Motor reactors

#### Overview



Motor reactors reduce the voltage load on the motor windings by reducing the voltage gradients at the motor terminals that occur during converter operation. At the same time, the capacitive charge/discharge currents that place an additional load on the converter output when long motor cables are used, are reduced. For group drives, output reactors should always be used. The maximum permissible output frequency when a motor reactor is used is 150 Hz.

The motor reactor must be installed as close as possible to the Motor Module or Power Module. Up to two motor reactors can be connected in series.

Motor reactors are approved for use only in conjunction with Vector and V/f control modes.

For additional notes on the use of motor reactors, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Selection and ordering data

Suitable for Power Modu	ıle	Suitable for Motor Modu	le	Type rating at 400 V	Rated output current	Motor reactor
Air-cooled	Liquid-cooled	Air-cooled	Liquid-cooled	kW	А	Article No.
Line voltage 380 480	V 3 AC					
6SL3310-1TE32-1AA3	6SL3315-1TE32-1AA3	6SL3320-1TE32-1AA3	6SL3325-1TE32-1AA3	110	210	6SL3000-2BE32-1AA0
6SL3310-1TE32-6AA3	6SL3315-1TE32-6AA3	6SL3320-1TE32-6AA3	6SL3325-1TE32-6AA3	132	260	6SL3000-2BE32-6AA0
6SL3310-1TE33-1AA3	6SL3315-1TE33-1AA3	6SL3320-1TE33-1AA3	6SL3325-1TE33-1AA3	160	310	6SL3000-2BE33-2AA0
6SL3310-1TE33-8AA3	-	6SL3320-1TE33-8AA3	-	200	380	6SL3000-2BE33-8AA0
6SL3310-1TE35-0AA3	6SL3315-1TE35-0AA3	6SL3320-1TE35-0AA3	6SL3325-1TE35-0AA3	250	490	6SL3000-2BE35-0AA0
-	-	6SL3320-1TE36-1AA3	6SL3325-1TE36-1AA3	315	605	6SL3000-2AE36-1AA0
-	-	6SL3320-1TE37-5AA3	6SL3325-1TE37-5AA3 6SL3325-1TE37-5AA7	400	745	6SL3000-2AE38-4AA0
-	-	6SL3320-1TE38-4AA3	6SL3325-1TE38-4AA3	450	840	-
-	-	6SL3320-1TE41-0AA3	6SL3325-1TE41-0AA3 6SL3325-1TE41-0AA7	560	985	6SL3000-2AE41-0AA0
-	-	6SL3320-1TE41-2AA3	6SL3325-1TE41-2AA3 6SL3325-1TE41-2AA7	710	1260	6SL3000-2AE41-4AA0
-	-	6SL3320-1TE41-4AA3	6SL3325-1TE41-4AA3 6SL3325-1TE41-4AA7	800	1405	
			6SL3325-1TE41-4AS3 1)	800	1330	

System components

### Motor-side power components > Motor reactors

### Selection and ordering data (continued)

Suitable for Power Module		Suitable for Motor Modu	le	Type rating at 690 V	Rated output current	Motor reactor
Air-cooled	Liquid-cooled	Air-cooled	Liquid-cooled	kW	А	Article No.
Line voltage 500	690 V 3 AC					
_	-	6SL3320-1TG28-5AA3	-	75	85	6SL3000-2AH31-0AA0
_	-	6SL3320-1TG31-0AA3	6SL3325-1TG31-0AA3	90	100	_
_	-	6SL3320-1TG31-2AA3	-	110	120	6SL3000-2AH31-5AA0
_	-	6SL3320-1TG31-5AA3	6SL3325-1TG31-5AA3	132	150	
_	-	6SL3320-1TG31-8AA3	-	160	175	6SL3000-2AH31-8AA0
_	-	6SL3320-1TG32-2AA3	6SL3325-1TG32-2AA3	200	215	6SL3000-2AH32-4AA0
_	-	6SL3320-1TG32-6AA3	-	250	260	6SL3000-2AH32-6AA0
_	-	6SL3320-1TG33-3AA3	6SL3325-1TG33-3AA3	315	330	6SL3000-2AH33-6AA0
_	-	6SL3320-1TG34-1AA3	-	400	410	6SL3000-2AH34-5AA0
_	-	6SL3320-1TG34-7AA3	6SL3325-1TG34-7AA3 6SL3325-1TG34-7AA7	450	465	6SL3000-2AH34-7AA0
_	_	6SL3320-1TG35-8AA3	6SL3325-1TG35-8AA3 6SL3325-1TG35-8AA7	560	575	6SL3000-2AH35-8AA0
_	-	6SL3320-1TG37-4AA3	6SL3325-1TG37-4AA3	710	735	6SL3000-2AH38-1AA0
_	-	6SL3320-1TG38-1AA3	6SL3325-1TG38-0AA3	800	810	_
			6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA7			
_	-	6SL3320-1TG38-8AA3	-	900	910	6SL3000-2AH41-0AA0
_	_	6SL3320-1TG41-0AA3	6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7	1000	1025	6SL3000-2AH41-1AA0
_	_	6SL3320-1TG41-3AA3	6SL3325-1TG41-3AA3 6SL3325-1TG41-3AA7	1200	1270	6SL3000-2AH41-3AA0

### Technical specifications

Line voltage 380 480 V 3 AC		Motor re	actor (for	pulse freq	uencies of	f 2 kHz to 4	kHz)					
		6SL3000 2BE32-1,		6SL3000 2BE32-6			6SL3000- 2BE33-2AA0		6SL3000- 2BE33-8AA0		0- 0AA0	
Rated current	А	210		260		310	310		380			
Power loss, max. <sup>1)</sup>	kW	0.486		0.5	0.5			0.5		0.5		
Load connection		1 × hole	for M10	1 × hole	for M10	1 × hole	for M10	1 × hole	for M10	1 × hole	e for M12	
PE connection		M8 screv	v	M8 scre	w	M8 scre	W	M8 scre	N	M8 scre	ew	
Cable length, max. between the motor reactor and motor (number of reactors in series)		(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	
Shielded	m	300	525	300	525	300	525	300	525	300	525	
Unshielded	m	450	787	450	787	450	787	450	787	450	787	
Degree of protection		IP00	IP00		IP00		IP00		IP00			
Dimensions												
• Width	mm	300		300	300		300		300			
Height	mm	285		315	315		285		285		365	
• Depth	mm	257		277	277		257			277		
Weight, approx.	kg	66		66		66	66			100		
Suitable for Power Module			6SL3310- 1TE32-1AA3		)- SAA3	6SL3310- 1TE33-1AA3		6SL3310 1TE33-8		6SL3310- 1TE35-0AA3		
					5- SAA3	6SL3315 1TE33-1				6SL331 1TE35-		
Suitable for Motor Module					)- SAA3		6SL3320- 1TE33-1AA3		6SL3320- 1TE33-8AA3		20- 0AA3	
		6SL3325 1TE32-1/		6SL3325 1TE32-6			6SL3325- 1TE33-1AA3				25- 0AA3	
• Rated output current of Motor Module	A	210		260		310		380		490		

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

System components

Motor-side power components > Motor reactors

Line voltage 380 480 V 3 AC		Motor	reactor (fo	or pulse	e frequenc	ies of 1	.25 kHz to	2.5 kH	z)				
		6SL30 2AE36		6SL30	00-2AE38-	4AA0		6SL3000- 2AE41-0AA0		6SL3000-2AE41-4AA0			
Rated current	А	605		745		840		985		1260		1405	
Power loss, max. <sup>1)</sup>	kW	0.9		0.84		0.943		1.062		0.9		1.054	
Load connection		1 × ho	le for M12	$1 \times \text{hole for M12}$		1 × hole for M12		$1 \times ho$	le for M12	2 × ho	le for M12	$2 \times hol$	e for M12
PE connection		M10 s	crew	M10 screw		M10 screw		M10 s	crew	M10 s	crew	M10 sc	rew
Cable length, max. between the motor reactor and motor (number of reactors in series)		(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)
Shielded	m	300	525	300	525	300	525	300	525	300	525	300	525
Unshielded	m	450	787	450	787	450	787	450	787	450	787	450	787
Degree of protection		IP00		IP00		IP00		IP00		IP00		IP00	
Dimensions													
• Width	mm	410		410		410		410		460		460	
• Height	mm	392		392		392		392		392		392	
• Depth	mm	292		292		292		302		326		326	
Weight, approx.	kg	130		140		140		146		179		179	
Suitable for Motor Module		6SL33 1TE36		6SL33 1TE37		6SL332 1TE38-		6SL33 1TE41		6SL33 1TE41		6SL332 1TE41-	
		6SL33 1TE36		6SL33 1TE37		6SL332 1TE38-		6SL33 1TE41		6SL33 1TE41		6SL332 1TE41-	
				6SL33 1TE37				6SL33 1TE41		6SL33 1TE41		6SL332 1TE41-	
												6SL332 1TE41-	<u>25</u> - -4AS3 <sup>2)</sup>
Rated output current of Motor Module	А	605		745		840		985		1260		1405	

Motor reactor (for pulse frequencies of 1.25 kHz to 2.5 kHz)

		6SL300	00-2AH31	-0AA0		6SL30	00-2AH31	1-5AA0			6SL3000- 2AH31-8AA0		100- 2-4AA0
Rated current	А	85		100		120		150	150		175		
Power loss, max. <sup>1)</sup>	kW	0.257		0.3		0.318		0.335		0.4		0.425	
Load connection			nnector ) screw		Flat connector for M10 screw		Flat connector for M10 screw		onnector 0 screw		Flat connector for M10 screw		onnector 0 screw
PE connection		M6 scr	ew	M6 sc	rew	M6 sc	rew	M6 sc	rew	M6 sc	rew	M6 sc	rew
Cable length, max. between the motor reactor and motor (number of reactors in series)		(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)
Shielded	m	300	525	300	525	300	525	300	525	300	525	300	525
Unshielded	m	450	787	450	787	450	787	450	787	450	787	450	787
Degree of protection		IP00		IP00		IP00		IP00		IP00		IP00	
Dimensions													
• Width	mm	270		270		270		270		300		300	
• Height	mm	248		248		248		248		285		285	
• Depth	mm	200		200		200		200		212		212	
Weight, approx.	kg	25		25		25.8		25.8		34		34	
Suitable for Motor Module		6SL332 1TG28		6SL33	-0AA3	6SL33 1TG31	820- 1-2AA3	6SL33	-5AA3	6SL33 1TG31	20-  -8AA3	6SL33	2-2AA3
• Rated output current of Motor Module	А	85		100		120		150		175		215	

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

Line voltage 500 ... 690 V 3 AC

<sup>2)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance.

System components

### Motor-side power components > Motor reactors

### Technical specifications (continued)

Line voltage 500 690 V 3 AC		Motor r	eactor (f	or pulse	frequen	cies of 1.	25 kHz t	o 2.5 kHz	)				
		6SL300 2AH32-		6SL300 2AH33		6SL300 2AH34		6SL300 2AH34-		6SL3000- 2AH35-8AA0		6SL3000- 2AH38-1AA0	
Rated current	А	260		330		410		465		575		735	
Power loss, max. <sup>1)</sup>	kW	0.44		0.45	0.45		0.545			0.8		0.96	
Load connection		Flat cor for M10			nnector ) screw	Flat connector for M12 screw		Flat connector for M12 screw		Flat connector for M12 screw			nnector 2 screw
PE connection		M6 scre	ew	M6 scr	ew	M8 scr	ew	M8 scre	ew	M8 scr	ew	M8 scr	ew
Cable length, max. between the motor reactor and motor (number of reactors in series)		(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)
Shielded	m	300	525	300	525	300	525	300	525	300	525	300	525
Unshielded	m	450	787	450	787	450	787	450	787	450	787	450	787
Degree of protection		IP00	IP00		IP00		IP00		IP00			IP00	
Dimensions													
• Width	mm	300		300		350		410		410		410	
Height	mm	285		285		330		392		392		392	
• Depth	mm	212		212		215		292		292		279	
Weight, approx.	kg	40		46		68		80		80		146	
Suitable for Motor Module			6SL		-3AA3	6SL3320- 1TG34-1AA3		6SL3320- 1TG34-7AA3 6SL3325- 1TG34-7AA3 6SL3325- 1TG34-7AA7		6SL3320- 1TG35-8AA3 6SL3325- 1TG35-8AA3 6SL3325- 1TG35-8AA7		6SL3320- 1TG37-4AA3 6SL3325- 1TG37-4AA3	
Rated output current of Motor Module	А	260		330		410		465		575		735	

	/ <b>(</b>	200 000		110 10			100		100		
Line voltage 500 690 V 3 AC		Motor reacto	r (for pulse	e frequenci	es of 1.25 kHz I	o 2.5 kHz)					
Ū.		6SL3000-2AH	· ·		-2AH41-0AA0		-2AH41-1AA0	6SL300	0-2AH41-3AA0		
Rated current	A	810		910		1025		1270	1270		
Power loss, max. <sup>1)</sup>	kW	1.0		0.97		1.05		0.95			
Load connection		Flat connector for M12 screw			Flat connector for M12 screw		nector screw	Flat con for M12			
PE connection		M8 screw		M8 screv	N	M8 screv	V	M8 scre	W		
Cable length, max. between the motor reactor and motor											
(number of reactors in series)		(1)	(2)	(1)	(2)	(1)	(2)	(1)	(2)		
Shielded	m	300	525	300	525	300	525	300	525		
Unshielded	m	450 787		450	450 787		787	450	787		
Degree of protection		IP00		IP00		IP00		IP00			
Dimensions											
• Width	mm	410		410	410		410		460		
Height	mm	392		392		392		392			
Depth	mm	279		279		317		296			
Weight, approx.	kg	146		150		163		153			
Suitable for Motor Module		6SL3325-1TG 6SL3325-1TG	6SL3320-1TG38-1AA3 6SL3325-1TG38-0AA3 6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA7		-1TG38-8AA3	6SL3320-1TG41-0AA3 6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7		6SL3320-1TG41-3AA 6SL3325-1TG41-3AA 6SL3325-1TG41-3AA			
• Rated output current of Motor Module	А	810		910		1025		1270			

<sup>1)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

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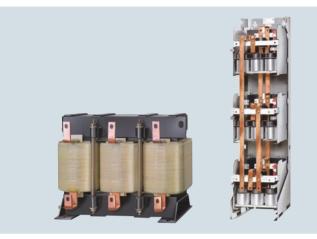
System components

Motor-side power components > dv/dt filter plus VPL

### Design

The dv/dt filter plus VPL consists of two components, which are also supplied as separate mechanical units:

- dv/dt reactor
- Voltage limiting network, which cuts off the voltage peaks and feeds the energy back to the DC link.



dv/dt filter plus VPL (Voltage Peak Limiter) limit the voltage rate-of-rise dv/dt to values < 500 V/ $\mu$ s and the typical voltage peaks to the following values in accordance with the limit value curve according to IEC/TS 60034-17: 2006:

<1000 V at  $U_{\rm line}$  < 575 V

<1250 V at 660 V <  $U_{\text{line}}$  < 690 V

Standard motors with standard insulation and without insulated bearings with a supply voltage of up to 690 V can be used for converter operation if a dv/dt filter plus VPL is used.

dv/dt filters plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables: 300 m (e.g. Protodur NYCWY)
- Unshielded cables: 450 m (e.g. Protodur NYY)

For shorter cable lengths (100 m shielded, 150 m unshielded), see also dv/dt filter compact plus VPL.

#### Notice:

The maximum permissible cable length between the dv/dt filter plus VPL and the Power Module/Motor Module is 5 m.

System components

Motor-side power components > dv/dt filter plus VPL

### Selection and ordering data

Suitable for Power Mode	ule	Suitable for Motor Module		Type rating at 400 V/ 690 V	Rated output current	dv/dt filter plus VPL
Air-cooled	Liquid-cooled	Air-cooled	Liquid-cooled	kW	А	Article No.
Line voltage 380 480	V 3 AC					
6SL3310-1TE32-1AA3	6SL3315-1TE32-1AA3	6SL3320-1TE32-1AA3	6SL3325-1TE32-1AA3	110	210	6SL3000-2DE32-6AA0
6SL3310-1TE32-6AA3	6SL3315-1TE32-6AA3	6SL3320-1TE32-6AA3	6SL3325-1TE32-6AA3	132	260	-
6SL3310-1TE33-1AA3	6SL3315-1TE33-1AA3	6SL3320-1TE33-1AA3	6SL3325-1TE33-1AA3	160	310	6SL3000-2DE35-0AA0
6SL3310-1TE33-8AA3	-	6SL3320-1TE33-8AA3	-	200	380	
6SL3310-1TE35-0AA3	6SL3315-1TE35-0AA3	6SL3320-1TE35-0AA3	6SL3325-1TE35-0AA3	250	490	_
_	-	6SL3320-1TE36-1AA3	6SL3325-1TE36-1AA3	315	605	6SL3000-2DE38-4AA0
-	-	6SL3320-1TE37-5AA3	6SL3325-1TE37-5AA3 6SL3325-1TE37-5AA7	400	745	_
_	-	6SL3320-1TE38-4AA3	6SL3325-1TE38-4AA3	450	840	_
_	-	6SL3320-1TE41-0AA3	6SL3325-1TE41-0AA3 6SL3325-1TE41-0AA7	560	985	6SL3000-2DE41-4AA0
_	-	6SL3320-1TE41-2AA3	6SL3325-1TE41-2AA3 6SL3325-1TE41-2AA7	710	1260	_
-	_	6SL3320-1TE41-4AA3	6SL3325-1TE41-4AA3 6SL3325-1TE41-4AA7	800	1405	
			6SL3325-1TE41-4AS3 1)	800	1330	
Line voltage 500 690	) V 3 AC					
_	-	6SL3320-1TG28-5AA3	-	75	85	6SL3000-2DH31-0AA0
_	-	6SL3320-1TG31-0AA3	6SL3325-1TG31-0AA3	90	100	_
_	-	6SL3320-1TG31-2AA3	-	110	120	6SL3000-2DH31-5AA0
-	-	6SL3325-1TG31-5AA3	6SL3320-1TG31-5AA3	132	150	_
_	-	6SL3320-1TG31-8AA3	-	160	175	6SL3000-2DH32-2AA0
_	-	6SL3320-1TG32-2AA3	6SL3325-1TG32-2AA3	200	215	_
-	-	6SL3320-1TG32-6AA3	-	250	260	6SL3000-2DH33-3AA0
-	-	6SL3320-1TG33-3AA3	6SL3325-1TG33-3AA3	315	330	
-	-	6SL3320-1TG34-1AA3	-	400	410	6SL3000-2DH34-1AA0
-	_	6SL3320-1TG34-7AA3	6SL3325-1TG34-7AA3 6SL3325-1TG34-7AA7	450	465	6SL3000-2DH35-8AA0
-	-	6SL3320-1TG35-8AA3	6SL3325-1TG35-8AA3 6SL3325-1TG35-8AA7	560	575	
-	-	6SL3320-1TG37-4AA3	6SL3325-1TG37-4AA3	710	735	6SL3000-2DH38-1AA0
-	-	6SL3320-1TG38-1AA3	6SL3325-1TG38-0AA3 6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA7	800	810	
_	-	6SL3320-1TG38-8AA3	-	900	910	6SL3000-2DH41-3AA0
_	-	6SL3320-1TG41-0AA3	6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7	1000	1025	
	-	6SL3320-1TG41-3AA3	6SL3325-1TG41-3AA3 6SL3325-1TG41-3AA7	1200	1270	

System components

Motor-side power components > dv/dt filter plus VPL

Line voltage 380 480 V 3 AC		dv/dt filter plus VPL			
-		6SL3000-2DE32-6AA0	6SL3000-2DE35-0AA0	6SL3000-2DE38-4AA0	6SL3000-2DE41-4AA
I <sub>th max</sub>	А	260	490	840	1405
Degree of protection		IP00	IP00	IP00	IP00
Cable length, max. between dv/dt filter and motor <sup>2)</sup>					
Shielded	m	300	300	300	300
Unshielded	m	450	450	450	450
Conformity		CE	CE	CE	CE
Certificate of suitability		cURus	cURus	cURus	cURus
dv/dt reactor					
Power loss, max. <sup>3)</sup>					
• At 50 Hz 400 V	kW	0.701	0.874	1.106	1.111
• At 60 Hz 460 V	kW	0.729	0.904	1.115	1.154
• At 150 Hz 400 V	kW	0.78	0.963	1.226	1.23
Connections					
• To the Power Module/ Motor Module		$1 \times \text{hole for M10}$	$1 \times \text{hole for M12}$	$1 \times \text{hole for M12}$	$2 \times hole$ for M12
To load		$1 \times \text{hole for M10}$	$1 \times \text{hole for M12}$	$1 \times \text{hole for M12}$	$2 \times hole$ for M12
• PE		M6 screw	M6 screw	M6 screw	M6 screw
Dimensions					
• Width	mm	410	460	460	445
Height	mm	370	370	385	385
Depth	mm	229	275	312	312
Weight, approx.	kg	66	122	149	158
Voltage Peak Limiter (VPL)	Ng	00	122		100
Power loss, max.					
• At 50 Hz 400 V	kW	0.029	0.042	0.077	0.134
• At 60 Hz 460 V	kW	0.027	0.039	0.072	0.125
• At 150 Hz 400 V	kW	0.025	0.036	0.066	0.114
Connections		0.020	0.000	0.000	0.114
To dv/dt reactor		M8 nut	70 mm <sup>2</sup> terminals	$1 \times \text{hole for M8}$	$1 \times \text{hole for M10}$
To DC link		M8 nut	70 mm <sup>2</sup> terminals	$1 \times \text{hole for M8}$	$1 \times \text{hole for M10}$
• PE			35 mm <sup>2</sup> terminals		
• PE		M8 stud	35 mm terminais	M8 stud	M8 stud
		005	202	200	200
• Width	mm	265	392	309	309
Height	mm	263	285	1313	1313
• Depth	mm	190	210	400	400
Weight, approx.	kg	6	16	48	72
Suitable for Power Module		6SL3310-1TE32-1AA3 6SL3315-1TE32-1AA3 6SL3310-1TE32-6AA3 6SL3315-1TE32-6AA3	6SL3310-1TE33-1AA3 6SL3315-1TE33-1AA3 6SL3310-1TE33-8AA3 6SL3310-1TE35-0AA3 6SL3315-1TE35-0AA3	-	-
Suitable for Motor Module		6SL3320-1TE32-1AA3 6SL3325-1TE32-1AA3 6SL3320-1TE32-6AA3 6SL3325-1TE32-6AA3	6SL3320-1TE33-1AA3 6SL3325-1TE33-1AA3 6SL3320-1TE33-8AA3 6SL3320-1TE35-0AA3 6SL3325-1TE35-0AA3	6SL3320-1TE36-1AA3 6SL3325-1TE36-1AA3 6SL3320-1TE37-5AA3 6SL3325-1TE37-5AA3 6SL3325-1TE37-5AA7 6SL3320-1TE38-4AA3 6SL3325-1TE38-4AA3	6SL3320-1TE41-0AA 6SL3325-1TE41-0AA 6SL3325-1TE41-0AA 6SL3325-1TE41-0AA 6SL3325-1TE41-2AA 6SL3325-1TE41-2AA 6SL3325-1TE41-4AA 6SL3325-1TE41-4AA 6SL3325-1TE41-4AA

<sup>1)</sup> These dv/dt filters include two dv/dt reactors. The technical specifications listed refer to a dv/dt reactor. For additional information on dv/dt filters, please refer to the SINAMICS Low Voltage Engineering Manual.

 $^{2)}$  Longer cable lengths for specific configurations are available on request.  $\sim$ 

<sup>3)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance.

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System components

### Motor-side power components > dv/dt filter plus VPL

## Technical specifications (continued)

Line voltage 500 690 V 3 AC		dv/dt filter plus VPL					
		6SL3000-2DH31-0AA0	6SL3000-2DH31-5AA0	6SL3000-2DH32-2AA0	6SL3000-2DH33-3AA0		
I <sub>th max</sub>	А	100	150	215	330		
Degree of protection		IP00	IP00	IP00	IP00		
Cable length, max. between dv/dt filter and motor <sup>1)</sup>							
Shielded	m	300	300	300	300		
Unshielded	m	450	450	450	450		
Conformity		CE	CE	CE	CE		
Certificate of suitability <sup>2)</sup>		cURus	cURus	cURus	cURus		
dv/dt reactor							
Power loss, max.							
• At 50 Hz 500/690 V	kW	0.49	0.389	0.578	0.595		
• At 60 Hz 575 V	kW	0.508	0.408	0.604	0.62		
• At 150 Hz 500/690 V	kW	0.541	0.436	0.645	0.661		
Connections							
To the Power Module/ Motor Module		$1 \times \text{hole for M10}$					
• To load		$1 \times \text{hole for M10}$					
• PE		M6 screw	M6 screw	M6 screw	M6 screw		
Dimensions							
• Width	mm	350	350	460	460		
Height	mm	320	320	360	360		
• Depth	mm	227	227	275	275		
Weight, approx.	kg	48	50	83	135		
Voltage Peak Limiter (VPL)							
Power loss, max.							
• At 50 Hz 500/690 V	kW	0.016	0.02	0.032	0.042		
• At 60 Hz 575 V	kW	0.015	0.019	0.03	0.039		
• At 150 Hz 500/690 V	kW	0.013	0.018	0.027	0.036		
Connections							
<ul> <li>To dv/dt reactor</li> </ul>		M8 nut	M8 nut	70 mm <sup>2</sup> terminals	70 mm <sup>2</sup> terminals		
• To DC link		M8 nut	M8 nut	70 mm <sup>2</sup> terminals	70 mm <sup>2</sup> terminals		
• PE		M8 stud	M8 stud	35 mm <sup>2</sup> terminals	35 mm <sup>2</sup> terminals		
Dimensions							
• Width	mm	263	263	392	392		
• Height	mm	265	265	285	285		
• Depth	mm	188	188	210	210		
Weight, approx.	kg	6	6	16	16		
Suitable for Motor Module		6SL3320-1TG28-5AA3 6SL3320-1TG31-0AA3 6SL3325-1TG31-0AA3	6SL3320-1TG31-2AA3 6SL3320-1TG31-5AA3 6SL3325-1TG31-5AA3	6SL3320-1TG31-8AA3 6SL3320-1TG32-2AA3 6SL3325-1TG32-2AA3	6SL3320-1TG32-6AA3 6SL3320-1TG33-3AA3 6SL3325-1TG33-3AA3		

<sup>1)</sup> Longer cable lengths for specific configurations are available on request.

System components

Motor-side power components > dv/dt filter plus VPL

Line voltage 500 690 V 3 AC		dv/dt filter plus VPL			
		6SL3000-2DH34-1AA0	6SL3000-2DH35-8AA0	6SL3000-2DH38-1AA0 1)	6SL3000-2DH41-3AA0
I <sub>th max</sub>	А	410	575	810	1270
Degree of protection		IP00	IP00	IP00	IP00
Cable length, max. between dv/dt filter and motor <sup>2)</sup>					
Shielded	m	300	300	300	300
Unshielded	m	450	450	450	450
Conformity		CE	CE	CE	CE
Certificate of suitability <sup>3)</sup>		cURus	cURus	cURus	cURus
dv/dt reactor					
Power loss, max.					
• At 50 Hz 500/690 V	kW	0.786	0.862	0.828	0.865
• At 60 Hz 575 V	kW	0.826	0.902	0.867	0.904
• At 150 Hz 500/690 V	kW	0.884	0.964	0.927	0.966
Connections					
• To the Power Module/ Motor Module		1 × hole for M12	$1 \times \text{hole for M12}$	$2 \times hole$ for M12	$2 \times hole$ for M12
To load		1 × hole for M12	$1 \times \text{hole for M12}$	$2 \times hole$ for M12	$2 \times hole$ for M12
• PE		M6 screw	M6 screw	M6 screw	M6 screw
Dimensions					
• Width	mm	460	460	445	445
Height	mm	385	385	385	385
• Depth	mm	312	312	312	312
Weight, approx.	kg	147	172	160	164
Voltage Peak Limiter (VPL)	Ng		112	100	
Power loss, max.	_				_
• At 50 Hz 500/690 V	kW	0.051	0.063	0.106	0.15
• At 60 Hz 575 V	kW	0.048	0.059	0.1	0.13
• At 150 Hz 500/690 V	kW	0.048	0.054	0.091	0.128
Connections	KVV	0.043	0.034	0.091	0.120
To dv/dt reactor		$1 \times hole for M8$	$1 \times \text{hole for M8}$	$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$
To DC link		$1 \times \text{hole for M8}$ 1 × hole for M8	$1 \times \text{hole for M8}$	1 × hole for M10	$1 \times \text{hole for M10}$ 1 × hole for M10
• PE		M8 stud	M8 stud	M8 stud	M8 stud
Dimensions		000	000	000	000
• Width	mm	309	309	309	309
Height	mm	1313	1313	1313	1313
• Depth	mm	400	400	400	400
Weight, approx.	kg	48	48	72	73
Suitable for Motor Module		6SL3320-1TG34-1AA3	6SL3320-1TG34-7AA3 6SL3325-1TG34-7AA3 6SL3325-1TG34-7AA7 6SL3320-1TG35-8AA3 6SL3325-1TG35-8AA3 6SL3325-1TG35-8AA7	6SL3320-1TG37-4AA3 6SL3325-1TG37-4AA3 6SL3320-1TG38-1AA3 6SL3325-1TG38-0AA3 6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA7	6SL3320-1TG38-8AA3 6SL3320-1TG41-0AA3 6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7 6SL3320-1TG41-3AA3 6SL3325-1TG41-3AA3 6SL3325-1TG41-3AA7

<sup>1)</sup> These dv/dt filters include two dv/dt reactors. The technical specifications listed refer to a dv/dt reactor. For additional information on dv/dt filters, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>2)</sup> Longer cable lengths for specific configurations are available on request.

<sup>3)</sup> Only for line voltages 500 ... 600 V 3 AC.

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System components

#### Motor-side power components > dv/dt filter compact plus VPL

#### Overview



dv/dt filters compact plus VPL (**V**oltage **P**eak Limiter) limit the voltage rate-of-rise dv/dt to values of < 1600 V/µs and the typical voltage peaks to the following values in accordance with the limit value curve A according to IEC 60034-25: 2007:

<1150 V at  $U_{\text{line}} < 575$  V

<1400 V at 660 V <  $U_{\rm line}$  < 690 V

Standard motors with standard insulation and without insulated bearings with a supply voltage of up to 690 V can be used for converter operation if a dv/dt filter compact plus VPL is used.

dv/dt filters compact plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables: 100 m (e.g. Protodur NYCWY)
- Unshielded cables: 150 m (e.g. Protodur NYY)

For longer cable lengths (> 100 m shielded,

> 150 m unshielded) refer to dv/dt filter plus VPL.

#### Notice:

- The max. permissible cable length between the dv/dt filter and Motor Module is 5 m
- Operation with output frequencies < 10 Hz is permissible for max. 5 min.

#### Design

The dv/dt filter compact plus VPL consists of two components, which are supplied together as a compact mechanical unit:

- dv/dt reactor
- Voltage limiting network, which cuts off the voltage peaks and feeds the energy back to the DC link.

System components

Motor-side power components > dv/dt filter compact plus VPL

Suitable for Power Mode	ule	Suitable for Motor Modu	le	Type rating at 400 V/690 V	dv/dt filter compact plus VPL
Air-cooled	Liquid-cooled	Air-cooled	Liquid-cooled	kW	Article No.
Line voltage 380 480	) V 3 AC				
6SL3310-1TE32-1AA3	6SL3315-1TE32-1AA3	6SL3320-1TE32-1AA3	6SL3325-1TE32-1AA3	110	6SL3000-2DE32-6EA0
6SL3310-1TE32-6AA3	6SL3315-1TE32-6AA3	6SL3320-1TE32-6AA3	6SL3325-1TE32-6AA3	132	_
6SL3310-1TE33-1AA3	6SL3315-1TE33-1AA3	6SL3320-1TE33-1AA3	6SL3325-1TE33-1AA3	160	6SL3000-2DE35-0EA0
6SL3310-1TE33-8AA3	_	6SL3320-1TE33-8AA3	-	200	
6SL3310-1TE35-0AA3	6SL3315-1TE35-0AA3	6SL3320-1TE35-0AA3	6SL3325-1TE35-0AA3	250	
_	-	6SL3320-1TE36-1AA3	6SL3325-1TE36-1AA3	315	6SL3000-2DE38-4EA0
-	_	6SL3320-1TE37-5AA3	6SL3325-1TE37-5AA3 6SL3325-1TE37-5AA7	400	
_	_	6SL3320-1TE38-4AA3	6SL3325-1TE38-4AA3	450	
-	-	6SL3320-1TE41-0AA3	6SL3325-1TE41-0AA3 6SL3325-1TE41-0AA7	560	6SL3000-2DE41-4EA0
-	-	6SL3320-1TE41-2AA3	6SL3325-1TE41-2AA3 6SL3325-1TE41-2AA7	710	_
-	-	6SL3320-1TE41-4AA3	6SL3325-1TE41-4AA3 6SL3325-1TE41-4AA7	800	
			6SL3325-1TE41-4AS3 1)	800	
Line voltage 500 690	) V 3 AC				
-	-	6SL3320-1TG28-5AA3	-	75	6SL3000-2DG31-0EA0
-	_	6SL3320-1TG31-0AA3	6SL3325-1TG31-0AA3	90	_
_	-	6SL3320-1TG31-2AA3	-	110	6SL3000-2DG31-5EA0
_	-	6SL3320-1TG31-5AA3	6SL3325-1TG31-5AA3	132	
_	-	6SL3320-1TG31-8AA3	-	160	6SL3000-2DG32-2EA0
_	-	6SL3320-1TG32-2AA3	6SL3325-1TG32-2AA3	200	
_	-	6SL3320-1TG32-6AA3	-	250	6SL3000-2DG33-3EA0
_	-	6SL3320-1TG33-3AA3	6SL3325-1TG33-3AA3	315	
_	-	6SL3320-1TG34-1AA3	-	400	6SL3000-2DG34-1EA0
_	_	6SL3320-1TG34-7AA3	6SL3325-1TG34-7AA3 6SL3325-1TG34-7AA7	450	6SL3000-2DG35-8EA0
-	_	6SL3320-1TG35-8AA3	6SL3325-1TG35-8AA3 6SL3325-1TG35-8AA7	560	
_	-	6SL3320-1TG37-4AA3	6SL3325-1TG37-4AA3	710	6SL3000-2DG38-1EA0
_	-	6SL3320-1TG38-1AA3	6SL3325-1TG38-0AA3	800	
-	-	-	6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA7	800	
_	-	6SL3320-1TG38-8AA3	-	900	6SL3000-2DG41-3EA0
	-	6SL3320-1TG41-0AA3	6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7	1000	
_	-	6SL3320-1TG41-3AA3	6SL3325-1TG41-3AA3 6SL3325-1TG41-3AA7	1200	

For additional information on dv/dt filters, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>1)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance.

System components

### Motor-side power components > dv/dt filter compact plus VPL

### Technical specifications

Line voltage 380 480 V 3 AC		dv/dt filter compact plus VPL					
		6SL3000-2DE32-6EA0 6SL3000-2DE35-0EA0 6		6SL3000-2DE38-4EA0	6SL3000-2DE41-4EA0		
Rated current	А	260	490	840	1405		
I <sub>th max</sub>	А	260	490	840	1405		
Power loss, max.							
• At 50 Hz 400 V	kW	0.21	0.29	0.518	Reactor: 1.027 VPL: 0.127 Total: 1.154		
• At 60 Hz 460 V	kW	0.215	0.296	0.529	Reactor: 1.077 VPL: 0.12 Total: 1.197		
• At 150 Hz 400 V	kW	0.255	0.344	0.609	Reactor: 1.354 VPL: 0.09 Total: 1.444		
Power connection input and output side		Hole for M10	Hole for M10	Hole for M12	$2 \times elongated hole,$ 14 × 18 mm		
Conductor cross-section, max. (IEC)		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection	Provided for busbar connection		
DC link connection DCPS, DCNS		M8 threaded socket	M8 threaded socket	Hole for M8	Hole for M8		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	16	25	50	95		
PE/GND connection		M6 threaded socket	M6 threaded socket	M6 threaded socket	M6 threaded socket (reactor and VPL)		
Motor cable length, max.							
Shielded	m	100	100	100	100		
Unshielded	m	150	150	150	150		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
• Width	mm	310	350	440	Reactor: 430 VPL: 277		
Height	mm	283	317	369	Reactor: 385 VPL: 360		
Depth	mm	238	260	311	Reactor: 323 VPL: 291		
Weight, approx.	kg	41	61	103	Reactor: 168.8 VPL: 19.2 Total: 188		
Conformity		CE	CE	CE	CE		
Certificates of suitability		cURus	cURus	cURus	cURus		
Suitable for Power Module		6SL3310-1TE32-1AA3 6SL3315-1TE32-1AA3 6SL3310-1TE32-6AA3 6SL3315-1TE32-6AA3	6SL3310-1TE33-1AA3 6SL3315-1TE33-1AA3 6SL3310-1TE33-8AA3 6SL3310-1TE35-0AA3 6SL3315-1TE35-0AA3				
Suitable for Motor Module		6SL3320-1TE32-1AA3 6SL3325-1TE32-1AA3 6SL3320-1TE32-6AA3 6SL3325-1TE32-6AA3	6SL3320-1TE33-1AA3 6SL3325-1TE33-1AA3 6SL3320-1TE33-8AA3 6SL3320-1TE35-0AA3 6SL3325-1TE35-0AA3	6SL3320-1TE36-1AA3 6SL3325-1TE36-1AA3 6SL3320-1TE37-5AA3 6SL3325-1TE37-5AA3 6SL3325-1TE37-5AA7 6SL3320-1TE38-4AA3 6SL3325-1TE38-4AA3	6SL3320-1TE41-0AA3 6SL3325-1TE41-0AA3 6SL3325-1TE41-0AA7 6SL3325-1TE41-0AA7 6SL3325-1TE41-2AA3 6SL3325-1TE41-2AA7 6SL3325-1TE41-2AA7 6SL3325-1TE41-4AA3 6SL3325-1TE41-4AA3 6SL3325-1TE41-4AA7 6SL3325-1TE41-4AS3 <sup>1)</sup>		

System components

Motor-side power components > dv/dt filter compact plus VPL

Line voltage 500 690 V 3 AC		dv/dt filter compact plus VPL					
		6SL3000-2DG31-0EA0	6SL3000-2DG31-5EA0	6SL3000-2DG32-2EA0	6SL3000-2DG33-3EA0		
Rated current	А	100	150	215	330		
I <sub>th max</sub>	А	100	150	215	330		
Power loss, max.							
• At 50 Hz 500/690 V	kW	0.227	0.27	0.305	0.385		
• At 60 Hz 575 V	kW	0.236	0.279	0.316	0.399		
• At 150 Hz 500/690 V	kW	0.287	0.335	0.372	0.48		
Power connection input and output side		Hole for M10	Hole for M10	Hole for M10	Hole for M10		
Conductor cross-section, max. (IEC)		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection	Provided for busbar connection		
DC link connection DCPS, DCNS		M8 threaded socket	M8 threaded socket	Hole for M8	Hole for M8		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	16	16	25	25		
PE/GND connection		M6 threaded socket	M6 threaded socket	M6 threaded socket	M6 threaded socket		
Motor cable length, max.							
Shielded	m	100	100	100	100		
Unshielded	m	150	150	150	150		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
• Width	mm	310	310	350	350		
Height	mm	283	283	317	317		
• Depth	mm	238	238	260	260		
Weight, approx.	kg	34	36	51	60		
Conformity		CE	CE	CE	CE		
Certificate of suitability <sup>1)</sup>		cURus	cURus	cURus	cURus		
Suitable for Motor Module		6SL3320-1TG28-5AA3 6SL3320-1TG31-0AA3 6SL3325-1TG31-0AA3	6SL3320-1TG31-2AA3 6SL3320-1TG31-5AA3 6SL3325-1TG31-5AA3	6SL3320-1TG31-8AA3 6SL3320-1TG32-2AA3 6SL3325-1TG32-2AA3	6SL3320-1TG32-6AA 6SL3320-1TG33-3AA 6SL3325-1TG33-3AA		

System components

### Motor-side power components > dv/dt filter compact plus VPL

### Technical specifications (continued)

Line voltage 500 690 V 3 AC		dv/dt filter compact plus VPL					
		6SL3000-2DG34-1EA0	6SL3000-2DG35-8EA0	6SL3000-2DG38-1EA0	6SL3000-2DG41-3EA0		
Rated current	А	410	575	810	1270		
I <sub>th max</sub>	А	410	575	810	1270		
Power loss, max.							
• At 50 Hz 500/690 V	kW	0.55	0.571	Reactor: 0.88 VPL: 0.084 Total: 0.964	Reactor: 0.926 VPL: 0.124 Total: 1.05		
• At 60 Hz 575 V	kW	0.568	0.586	Reactor: 0.918 VPL: 0.08 Total: 0.998	Reactor: 0.993 VPL: 0.111 Total: 1.104		
• At 150 Hz 500/690 V	kW	0.678	0.689	Reactor: 1.137 VPL: 0.059 Total: 1.196	Reactor: 1.23 VPL: 0.089 Total: 1.319		
Power connection input and output side		Hole for M12	Hole for M12	$2 \times elongated hole,$ 14 × 18 mm	$2 \times elongated hole,$ 14 × 18 mm		
Conductor cross-section, max. (IEC)		Provided for busbar connection	Provided for busbar connection	Provided for busbar connection	Provided for busbar connection		
DC link connection DCPS, DCNS		Hole for M8	Hole for M8	Hole for M8	Hole for M8		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	50	50	95	95		
PE/GND connection		M6 threaded socket	M6 threaded socket	M6 threaded socket (reactor and VPL)	M6 threaded socket (reactor and VPL)		
Motor cable length, max.							
Shielded	m	100	100	100	100		
Unshielded	m	150	150	150	150		
Degree of protection		IP00	IP00	IP00	IP00		
Dimensions							
• Width	mm	440	440	Reactor: 430 VPL: 277	Reactor: 430 VPL: 277		
Height	mm	369	369	Reactor: 385 VPL: 360	Reactor: 385 VPL: 360		
• Depth	mm	311	311	Reactor: 323 VPL: 291	Reactor: 323 VPL: 291		
Weight, approx.	kg	87	100	Reactor: 171.2 VPL: 18.8 Total: 190	Reactor: 175.8 VPL: 19.2 Total: 195		
Conformity		CE	CE	CE	CE		
Certificate of suitability <sup>1)</sup>		cURus	cURus	cURus	cURus		
Suitable for Motor Module		6SL3320-1TG34-1AA3	6SL3320-1TG34-7AA3 6SL3325-1TG34-7AA3 6SL3325-1TG34-7AA7 6SL3320-1TG35-8AA3 6SL3325-1TG35-8AA3 6SL3325-1TG35-8AA7	6SL3320-1TG37-4AA3 6SL3325-1TG37-4AA3 6SL3320-1TG38-1AA3 6SL3325-1TG38-0AA3 6SL3325-1TG38-1AA3 6SL3325-1TG38-1AA3	6SL3320-1TG38-8AA3 6SL3320-1TG41-0AA3 6SL3325-1TG41-0AA3 6SL3325-1TG41-0AA7 6SL3320-1TG41-3AA3 6SL3325-1TG41-3AA3 6SL3325-1TG41-3AA7		

 $^{1)}$  Only for line voltages 500  $\dots$  600 V 3 AC.

System components

Motor-side power components > Sine-wave filter

#### Overview



If a sine-wave filter is connected to the output of the Power Module or Motor Module, the voltage between the motor terminals is virtually sinusoidal. This reduces the voltage load on the motor windings and prevents motor noise induced by the pulse frequency.

The pulse frequency of the modules must be set to 4 kHz for the sine-wave filters. The max. output frequency with sine-wave filter is limited to 150 Hz.

As a result, the max. possible output current and the max. achievable output voltage of the units are reduced. The voltage drops across the sine-wave filter, a factor which must also be taken into account in the drive design.

A sine-wave filter must be installed as close as possible to the Motor Module or Power Module.

It is only permissible to operate the sine-wave filter when the motor is connected (sine-wave filters are not no-load proof)!

For additional information on sine-wave filters, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Selection and ordering data

Suitable for Power Module		Suitable for Motor Module		Type rating at 400 V	Rated output current	Sine-wave filter
Air-cooled	Liquid-cooled	Air-cooled	Liquid-cooled	kW	А	Article No.
Line voltage 380 480	V 3 AC					
6SL3310-1TE32-1AA3	6SL3315-1TE32-1AA3	6SL3320-1TE32-1AA3	6SL3325-1TE32-1AA3	110	210	6SL3000-2CE32-3AA0
6SL3310-1TE32-6AA3	6SL3315-1TE32-6AA3	6SL3320-1TE32-6AA3	6SL3325-1TE32-6AA3	132	260	
6SL3310-1TE33-1AA3	6SL3315-1TE33-1AA3	6SL3320-1TE33-1AA3	6SL3325-1TE33-1AA3	160	310	6SL3000-2CE32-8AA0
6SL3310-1TE33-8AA3	-	6SL3320-1TE33-8AA3	-	200	380	6SL3000-2CE33-3AA0
6SL3310-1TE35-0AA3	6SL3315-1TE35-0AA3	6SL3320-1TE35-0AA3	6SL3325-1TE35-0AA3	250	490	6SL3000-2CE34-1AA0

System components

### Motor-side power components > Sine-wave filter

### Technical specifications

Line voltage 380 480 V 3 AC		Sine-wave filter						
		6SL3000-2CE32-	3AA0	6SL3000- 2CE32-8AA0	6SL3000- 2CE33-3AA0	6SL3000- 2CE34-1AA0		
Rated current	А	225		276	333	408		
Power loss, max.								
• At 50 Hz 400 V	kW	0.221		0.235	0.245	0.34		
• At 60 Hz 460 V	kW	0.265		0.282	0.294	0.408		
• At 150 Hz 400 V	kW	0.48		0.5	0.53	0.75		
Load connection		Flat connector for	M10 screw	Flat connector for M10 screw	Flat connector for M10 screw	Flat connector for M10 screw		
PE connection		$1 \times \text{hole for M10}$		$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$	$1 \times \text{hole for M10}$		
Cable length, max. between sine-wave filter and motor								
Shielded	m	300		300	300	300		
Unshielded	m	450	450		450	450		
Degree of protection		IP00		IP00	IP00	IP00		
Dimensions								
• Width	mm	620		620	620	620		
• Height	mm	300		300	370	370		
• Depth	mm	320		320	360	360		
Weight, approx.	kg	124		127	136	198		
Conformity		CE		CE	CE	CE		
Certificate of suitability		cURus		cURus	cURus	cURus		
Suitable for Power Module		6SL3310- 1TE32-1AA3	6SL3310- 1TE32-6AA3	6SL3310- 1TE33-1AA3	6SL3310- 1TE33-8AA3	6SL3310- 1TE35-0AA3		
		6SL3315- 1TE32-1AA3	6SL3315- 1TE32-6AA3	6SL3315- 1TE33-1AA3		6SL3315- 1TE35-0AA3		
Suitable for Motor Module		6SL3320- 1TE32-1AA3	6SL3320- 1TE32-6AA3	6SL3320- 1TE33-1AA3	6SL3320- 1TE33-8AA3	6SL3320- 1TE35-0AA3		
		6SL3325- 1TE32-1AA3	6SL3325- 1TE32-6AA3	6SL3325- 1TE33-1AA3		6SL3325- 1TE35-0AA3		
Rated output current of the Motor Module or Power Module at a pulse frequency of 4 kHz	A	170	215	270	330	380		

System components

**Control Units** 

#### Overview



CU310-2 PN Control Unit



CU320-2 PN Control Unit

#### System architecture with a central Control Unit

Electronically coordinated single-motor drives work together to perform your drive tasks. In multi-axis drives, the individual drives are controlled from the higher-level control systems in such a way as to achieve the desired coordinated movement. This requires cyclic data exchange between the controller and the drives. A central Control Unit controls the drives for all connected axes and also establishes the technological links between the drives and/or axes. Since all the required data is stored in the central Control Unit, it does not need to be transferred. Inter-axis connections can be established within a Control Unit and easily configured in the STARTER commissioning tool using a mouse.

- The SINAMICS Control Unit can handle simple technological tasks by itself
- The **CU310-2 DP** or **CU310-2 PN** Control Units are used in conjunction with Power Modules and single-motor drives.
- The CU320-2 DP or CU320-2 PN Control Units are used in conjunction with all Motor Modules or Line Modules for single or multi-motor drives.
- Sophisticated motion control tasks can be implemented with the support of the more powerful D410-2, D425-2, D435-2, and D445-2 Control Units of SIMOTION D (graded according to performance).

# You can obtain further information about SIMOTION in the Industry Mall and Catalog PM 21.

Each of these Control Units is based on an object-oriented SINAMICS standard firmware, which contains all common control modes and can be scaled to meet even the most advanced performance requirements.

The drive controls are supplied as ready-to-configure drive objects:

- Infeed Control for mains infeed
- Vector control
  - Speed-controlled drives with high speed and torque stability in general machine and plant construction
  - Particularly suitable for induction motors
  - Optimized pulse patterns for efficient motor/converter systems
- · Servo control
- Drives with highly dynamic motion control
- Angular-locked synchronism with isochronous PROFIBUS/ PROFINET
- For use in machine tools and clocked production machines

The most commonly used v/f control modes are stored in the "Vector control" drive object and are ideal for implementing even simple applications such as group drives with SIEMOSYN motors.

#### CompactFlash card

The functions of the drives are stored on a CompactFlash card. This card contains the firmware and parameter settings for all drives in the form of a project. The CompactFlash card can also hold additional projects, which means that the correct project can be accessed immediately when series machines of different types are commissioned. When the Control Unit has booted, the data on the CompactFlash card is read and loaded to the RAM.

The firmware is organized in objects. Drive objects are used to implement open-loop and closed-loop control functions for Line Modules, Motor Modules, Power Modules and other system components connected by DRIVE-CLiQ.

System components

#### **Control Units**

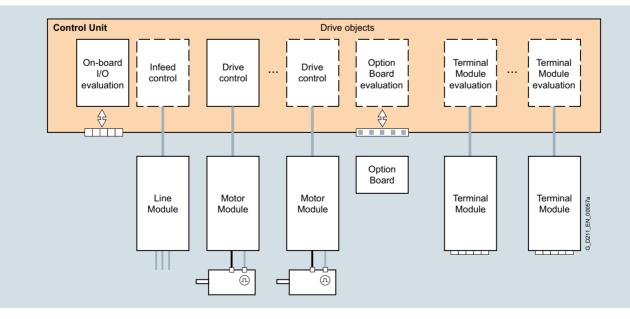
### Overview (continued)

#### Overview of key open-loop and closed-loop control functions

	Closed-loop control types S120	Open-loop control types S120	Main functions S120 for booksize/chassis	Comment, note
Infeed Control	<ul> <li>Chassis <ul> <li>Current control with VSM10</li> <li>V<sub>DC</sub> control with VSM10</li> <li>V<sub>DC</sub> control with VSM10</li> <li>Network functionalities (island grids)</li> </ul> </li> <li>Induction motor <ul> <li>Torque control with/without encoder</li> <li>Speed control with/without encoder</li> </ul> </li> <li>Torque motor <ul> <li>Torque control with encoder</li> <li>Speed control with/without encoder</li> </ul> </li> <li>Induction motor, torque motor <ul> <li>Position control with encoder</li> </ul> </li> <li>Reluctance motor <ul> <li>Torque control with/without encoder</li> </ul> </li> <li>Speed control with/without encoder</li> <li>Speed control with/without encoder</li> </ul>	<ul> <li>Booksize/chassis</li> <li>Basic Mode Rectification only</li> <li>Smart Mode Rectification and regenerative feedback</li> <li>Linear V/f characteristic</li> <li>Constant-frequency V/f characteristic (textile)</li> <li>Independent voltage setpoint input</li> </ul>	<ul> <li>Mains identification</li> <li>Controller optimization</li> <li>Harmonics filter</li> <li>Automatic restart</li> <li>Data set changeover</li> <li>Extended setpoint input</li> <li>Motor identification</li> <li>Current/speed controller optimization</li> <li>Technology controller</li> <li>Basic positioner</li> <li>Automatic restart</li> <li>Flying restart with/without encoder</li> <li>Kinetic buffering</li> <li>Synchronization</li> <li>Droop</li> <li>Brake control</li> </ul>	The VSM10 is the Voltage Sensing Module; "current" is the line current; 3-phase with line frequency Mixed operation with V/f control modes is possible; it is for this reason that the V/f control modes are stored only once in the "Vector control" drive object Position control can be selected as a function module from both Servo and Vector mode Permanent-magnet 1FW4 synchronous motors can be oper- ated over the complete operating range in <u>Vector control</u> .
Servo control	<ul> <li>Induction motor</li> <li>Torque control with/without encoder</li> <li>Speed control with/without encoder</li> <li>Synchronous motor, linear motor and torque motor</li> <li>Torque control with encoder</li> <li>Speed control with encoder</li> <li>All motor types</li> <li>Position control with encoder</li> </ul>	<ul> <li>Linear V/f characteristic</li> <li>Constant-frequency V/f characteristic (textile)</li> <li>Independent voltage setpoint input</li> </ul>	<ul> <li>Data set changeover</li> <li>Setpoint input</li> <li>Motor identification</li> <li>Damping application</li> <li>Technology controller</li> <li>Basic positioner</li> <li>Brake control</li> </ul>	Mixed operation with V/f control modes is possible; it is for this reason that the V/f control modes are stored only once in the "Vector control" drive object Position control can be selected as a function module from both Servo and Vector mode.

#### Drive objects

A drive object is a self-contained software function with its own parameters and, where appropriate, its own fault messages and alarms.



System components

**Control Units** 

#### Overview (continued)

#### Extended technology with SIMOTION

SIMOTION D Control Units support the coordinated motion control of multiple drives. Technology objects are implemented in addition to drive objects on these Control Units. These are grouped to form technology packages and make available extended Motion Control functions (e.g. synchronous operation, cam disk, path interpolation and others) or technological functions (e.g. a cam controller, a temperature or pressure control). The IÈC 61131-3-compliant PLC integrated in SIMOTION D Control Units means that they are not just capable of controlling sequences of motions, but the entire machine including HMI and I/Os.

You can obtain further information about SIMOTION in the Industry Mall and Catalog PM 21.

#### Comprehensive package of open-loop and closed-loop control functions

A wide variety of standard functions such as setpoint input, data set changeover, controller optimization, kinetic buffering, etc. ensure a high degree of functional reliability and excellent flexibility when addressing the application.

#### **BICO** technology

Every drive object contains a large number of input and output variables which can be freely and independently interconnected using Binector Connector Technology (BICO). A binector is a logic signal which can assume the value 0 or 1. A connector is a numerical value, e.g. the actual speed or current setpoint.

#### Drive Control Chart (DCC)

Drive Control Chart (DCC) for SINAMICS S120 is a user-friendly tool with which drive-related closed-loop control, logic and arithmetic functions can be configured in graphical form. It extends the possibility of configuring technological functions for SINAMICS drives in an extremely easy way.

The user-friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of charts that have already been created.

The associated block library (DCB library) contains a large selection of closed-loop control, calculation and logic modules (Drive Control Blocks (DCB)) as well as more complex open-loop and closed-loop control functions.

Two types of DCB library are available, i.e. DCB Standard and DCB Extension. The DCB Standard library is supplied as standard with the SINAMICS DCC software.

DCC is an add-on for the STARTER commissioning tool.

#### Integral safety functions (Safety Integrated)

The Control Units support comprehensive safety functions.

The integrated safety functions are the Safety Integrated Basic Functions

- STO = Safe Torque Off
- SBC = Safe Brake Control
- SS1 = Safe Stop 1 (Time controlled)

and the Safety Integrated Extended Functions that require a license

- SS1 = Safe Stop 1 (time and acceleration controlled)
- SS2 = Safe Stop 2
- SOS = Safe Operating Stop
- SLS = Safely-Limited Speed
- SSM = Safe Speed Monitor
- SDI = Safe Direction
- SLP = Safely-Limited Position
- SP = Safe Position transmission
- SBT = Safe Brake Test

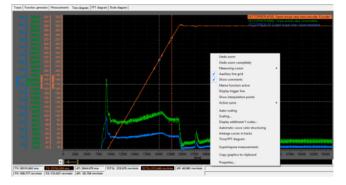
(Abbreviations in accordance with IEC 61800-5-2)

If the integrated safety functions are used, licenses, supplementary system components such as TM54F Terminal Modules, or suitable safety controls will be necessary.

#### Additional information about the integrated safety functions is provided in section Safety Integrated.

#### Diagnostics optimally supported by trace function

The time characteristic curves of input and output variables associated with drive objects can be measured by the integrated trace function and displayed using the STARTER commissioning tool. Several signals can be simultaneously traced. A recording can be triggered dependent on freely selectable boundary conditions, e.g. the value of an input or output variable.



System components

#### Control Units > CU320-2 Control Unit

#### Overview





CU320-2 PN and CU320-2 DP Control Units

The communication, open-loop and closed-loop control functions for one or more Line Modules and/or Motor Modules are executed in a CU320-2 Control Unit. The CU320-2 Control Unit is essentially designed for multi-axis operation. Communication with the higher-level control system is performed via PROFIBUS DP or PROFINET.

### Design

CU320-2 Control Units feature the following interfaces as standard:

- Fieldbus interface:
  - CU320-2 PN: 1 PROFINET interface with 2 ports (RJ45 sockets) with PROFIdrive V4 profile
  - CU320-2 DP: 1 PROFIBUS interface with PROFIdrive V4 profile
- 4 x DRIVE-CLiQ sockets for communication with other DRIVE-CLiQ nodes, e.g. Motor Modules, Active Line Modules, Sensor Modules, Terminal Modules
- 12 parameterizable digital inputs (floating)
- 8 parameterizable bidirectional digital inputs/digital outputs (non-floating)
- 1 serial RS232 interface (e.g. to connect the AOP30 Advanced Operator Panel)
- 1 interface for the BOP20 Basic Operator Panel
- 1 slot for the CompactFlash card on which firmware and parameters are stored
- 1 slot for mounting an option module (e.g. TB30 Terminal Board)
- CU320-2 DP: 2 rotary coding switches for manually setting the PROFIBUS address
- 1 Ethernet interface for commissioning and diagnostics
- 3 measuring sockets and one reference ground for commissioning support
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connector
- 1 ground connection

A shield connection for the signal cable shield of the option module is located on the CU320-2 Control Unit.

The available option slot is used to expand the interfaces, for example, to include additional terminals or for communication purposes.

The status of the CU320-2 Control Unit is indicated via multicolor LEDs.

As the firmware and parameter settings are stored on a plug-in CompactFlash card, the Control Unit can be changed without the need for software tools.

The CU320-2 Control Unit can be mounted on the side of the Line Module via brackets integrated in a Line Module. The CU320-2 Control Unit can also be fixed to the wall of the control cabinet using the integrated fixing lugs.

System components

Control Units > CU320-2 Control Unit

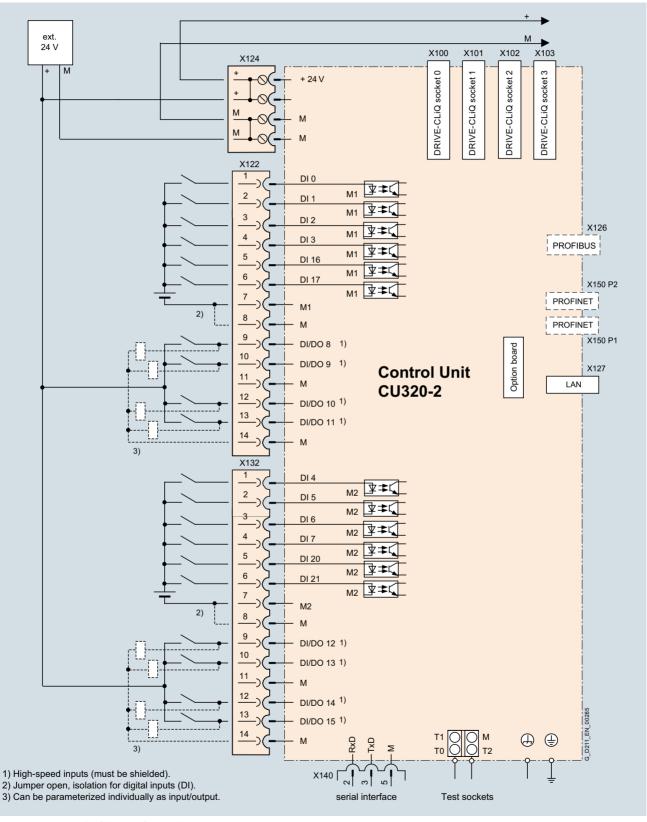
Selection and ordering data		Integration
Description CU320-2 PN Control Unit Without CompactFlash card	Article No. 6SL3040-1MA01-0AA0	DRIVE-CLiQ components, for example, Motor Modules and Active Line Modules, can be connected to a CU320-2 Contr Unit. The number of modules depends on the performance required, including duty type and additional functions.
CU320-2 DP Control Unit Without CompactFlash card	6SL3040-1MA00-0AA0	The BOP20 Basic Operator Panel can also be snapped onto CU320-2 Control Unit during operation for diagnostic purpo
Accessories		The CU320-2 Control Unit and other connected components
For CU320-2 PN: Industrial Ethernet FC • RJ45 Plug 145 (1 units)	6GK1901-1BB30-0AA0	commissioned and diagnosed with the STARTER commission ing tool and the installed SINAMICS Support Package or the AOP30 Advanced Operator Panel.
<ul> <li>RJ45 Plug 145 (1 units)</li> <li>RJ45 Plug 145 (10 units)</li> <li>Stripping tool</li> </ul>	6GK1901-18B30-0A80 6GK1901-18B30-0A80 6GK1901-1GA00	To operate the CU320-2 PN Control Unit, a CompactFlash c with firmware V4.4 or higher is required.
Standard cable GP 2x2	6XV1840-2AH10	To operate the CU320-2 DP Control Unit, a CompactFlash c with firmware V4.3 or higher is required.
<ul><li>Flexible cable GP 2x2</li><li>Trailing cable GP 2x2</li></ul>	6XV1870-2B 6XV1870-2D	
Trailing cable 2x2	6XV1840-3AH10	
Marine cable 2x2	6XV1840-4AH10	
For CU320-2 DP: PROFIBUS connector		
<ul> <li><u>Without</u> PG/PC connection</li> </ul>	6ES7972-0BA42-0XA0	
<u>With PG/PC connection</u>	6ES7972-0BB42-0XA0	
Spacers (2 units)	6SL3064-1BB00-0AA0	
Increases the depth of the CU320-2 DP Control Unit to 270 mm (if the integrated brackets are not to be used, but the depth still has to be 270 mm)		
STARTER commissioning tool <sup>1)</sup> On DVD-ROM	6SL3072-0AA00-0AG0	
Accessories for re-ordering		
<b>Dust protection blanking plugs</b> (50 units) For DRIVE-CLiQ port	6SL3066-4CA00-0AA0	

For more information on connectors and cables, please refer to Catalog IK PI and the Siemens Industry Mall: www.siemens.com/industrymall

System components

#### Control Units > CU320-2 Control Unit

#### Integration (continued)



Connection example of a CU320-2 Control Unit

System components

Control Units > CU320-2 Control Unit

# Technical specifications

PROFINET PROFIBUS	CU320-2 Control Unit 6SL3040-1MA01-0AA0 6SL3040-1MA00-0AA0
Power requirement, max.	1.0 A
At 24 V DC, without taking account of digital outputs, expansion option slot and DRIVE-CLiQ supply	
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Fuse protection, max.	20 A
Digital inputs	In accordance with IEC 61131-2 Type 1 12 floating digital inputs 8 bidirectional non-floating digital inputs/outputs
Voltage	-3 +30 V
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	-3 +5 V
High level	15 30 V
Current consumption at 24 V DC, typ.	9 mA
<ul> <li>Delay time of digital inputs <sup>1)</sup>, approx.</li> </ul>	
$-L \rightarrow H$	50 μs
- $H \rightarrow L$	100 µs
<ul> <li>Delay time of high-speed digital inputs <sup>1)</sup>, approx.</li> </ul>	
$- L \rightarrow H$	5 µs
- $H \rightarrow L$	50 μs
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Digital outputs	8 bidirectional non-floating digital inputs/outputs
continuously short-circuit proof	
Voltage	24 V DC
Load current per digital output, max.	500 mA
• Delay time <sup>1)</sup> , typ./max.	
$-L \rightarrow H$	150 µs/400 µs
$- H \rightarrow L$	75 μs/100 μs
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Power loss	24 W
PE connection	M5 screw
Ground connection	M5 screw
Dimensions	
• Width	50 mm
• Height	300 mm
• Depth	226 mm
Weight, approx.	2.3 kg

<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slice in which the digital input or output is processed.

System components

#### Control Units > CompactFlash card for CU320-2

#### Overview



The CompactFlash card contains the firmware and set parameters. The CompactFlash card is inserted into the appropriate slot of the CU320-2 Control Unit.

#### Design

A CU320-2 Control Unit can perform the communication, openloop and closed-loop control functions for several power units. The computing capacity requirement increases in proportion to the number of power units and system components and in relation to the dynamic response required. The computing capacity requirement and utilization of the CU320-2 Control Unit can be calculated with the SIZER for Siemens Drives engineering tool. The full computing capacity of the CU320-2 Control Unit is only available on systems with performance extension. For the CU320-2 Control Unit, the performance extension is necessary from the 4th axis.

In addition to the firmware, the CompactFlash card also contains licensing codes which are required to enable firmware options.

In addition to the Article No., the following firmware options can currently be ordered with or without performance extension:

- Safety Integrated Extended Functions, order code per axis F01 to F06
- High output frequency, order code J01
- DCB Extension, order code U01

Converter cabinets with a Control Unit already contain the CompactFlash card with the current firmware. The firmware options can be added as cabinet options.

The firmware options can also be enabled subsequently. You require the serial number of the CompactFlash card and the article number of the firmware option to be enabled. With this information, you can purchase the associated license code from a license database and enable the firmware option. The license code is only valid for the CompactFlash card declared and cannot be transferred to other CompactFlash cards.

Subsequent licensing is possible in the Internet via the WEB License Manager by generating a license key: www.siemens.com/automation/license

#### Selection and ordering data

Selection and ordering data	
Description	Article No.
CompactFlash card for CU320-2 Control Unit without Safety license	
<u>Without</u> performance extension	6SL3054-0EQ00-1BA0
<u>With</u> performance extension firmware option	6SL3054-0E❑01-1BA0
CompactFlash card for CU320-2 Control Unit <u>with</u> Safety license	
• For 1 axis	6SL3054-0ED0D-1BA0-Z F01
• For 2 axes	6SL3054-0EQ0Q-1BA0-Z F02
• For 3 axes	6SL3054-0E⊒0⊒-1BA0-Z F03
• For 4 axes	6SL3054-0E❑01-1BA0-Z F04
• For 5 axes	6SL3054-0E❑01-1BA0-Z F05
• For 6 axes	6SL3054-0E❑01-1BA0-Z F06
CompactFlash card for CU320-2	
Control Unit with/without safety license	
• With high output frequency <sup>1)</sup>	6SL3054-0E□0□-1BA0-Z J01
• With DCB Extension license (firmware V4.6 and higher) (further information about DCB Extension and license upgrades can be found under	6SL3054-0E□0□-1BA0-Z U01
Drive Control Chart (DCC) in section Tools and Engineering)	
Firmware version	↑ (
V4.7	н
V4.8	J ↑
Without performance extension	0
$\frac{\text{With}}{\text{option}} \text{ performance extension firmware}$	1
License upgrades	
Performance Extension     including Certificate of License     for additional licensing     of a CompactFlash card	6SL3074-0AA01-0AA0
Safety Integrated Extended	6SL3074-0AA10-0AA0
Functions including Certificate of License License upgrade for one axis on a CompactFlash card. This option must be ordered once for each axis, e.g. a maximum of 6 for one CompactFlash card	
• High output frequency <sup>1)</sup> Upgrading license to enable high output frequencies above 550 Hz for all axes on a CompactFlash card	6SL3074-0AA02-0AA0
• SINAMICS DCB Extension including Certificate of License Runtime license as of firmware V 4.6 for upgrading the license on a CompactFlash card (see section Tools and Engineering, SINAMICS Drive Control Chart engineering software)	6SL3077-0AA00-0AB0

A firmware version of  $\geq$  4.3 is required for the CU320-2 Control Unit.

The current firmware version at the time of publication of this catalog is version 4.8.

3

1) For further information, see

https://support.industry.siemens.com/cs/document/104020669

System components

Control Units > CompactFlash card for CU320-2

### More information

#### Firmware version

The firmware version is encoded as follows in the article number printed on the CompactFlash card:

Article No.:	65	SL3054-0 <b>00</b> -1BA0
Firmware version		$\uparrow$
	4	E
	5	F
Version		$\uparrow$
	.1	В
	.2	С
	.3	D
	.4	E
	.5	F
	.6	G
	.7	Н
	.8	J
		$\uparrow$
Without performance extension		0
With performance extension		1

With performance extension

A firmware version of  $\geq$  4.3 is required for the CU320-2 Control Unit.

The current firmware version at the time of publication of this catalog is version 4.8.

Firmware version 5.1 (6SL3054-1FB00-1BA0) scheduled for the end of 2017.

System components

#### Control Units > CU310-2 Control Unit

### Overview



2

CU310-2 PN and CU310-2 DP Control Units

The CU310-2 Control Unit for the communication and open-loop/ closed-loop control functions of a Power Module is combined with the Power Module to create a powerful single-motor drive. A PROFINET (PN) variant and a PROFIBUS (DP) variant are available for fieldbus communication.

# Design

CU310-2 Control Units feature the following interfaces as standard:

- Fieldbus interface
  - CU310-2 PN:
  - 1 PROFINET interface with 2 ports (RJ45 sockets) with PROFIdrive V4 profile
  - CU310-2 DP:
  - 1 PROFIBUS interface with PROFIdrive V4 profile
- 1 DRIVE-CLiQ socket to allow communication with other DRIVE-CLiQ nodes
- 1 encoder evaluation for evaluating the following encoder signals
  - Incremental encoder TTL/HTL
  - SSI encoders without incremental signals
- 6 parameterizable digital inputs (isolated) or alternatively 3 parameterizable, fail-safe digital inputs (isolated, can be used with firmware V4.5 and higher).
   The fail-safe digital inputs can be routed, i.e. they can be routed via PROFIsafe to a higher-level controller.
- 5 parameterizable digital inputs (floating)
- 1 digital output (isolated) or alternatively
   1 parameterizable, fail-safe digital output (isolated, can be used with firmware V4.5 or higher)
- 8 parameterizable bidirectional digital inputs/digital outputs (non-floating)
- 1 analog input, either ± 10 V (resolution 12 bits + sign) or ± 20 mA (11 bits + sign)
- 1 Ethernet interface (RJ45 socket) for commissioning and diagnostics
- 1 serial RS232 interface
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 temperature sensor input for KTY84-130, Pt1000 or PTC (Pt1000 can be used from firmware V4.7 HF17)
- 3 measuring sockets and one reference ground for commissioning support
- 1 slot for the CompactFlash card on which firmware and parameters are stored
- 1 PM-IF interface for communication with Power Modules in blocksize format
- 1 interface to the BOP20 Basic Operator Panel
- 1 PE connection

The status of the CU310-2 Control Unit is indicated via multi-color LEDs.

A BOP20 Basic Operator Panel can also be snapped directly onto the CU310-2 Control Unit for diagnostic procedures.

As the firmware and parameter settings are stored on a plug-in CompactFlash card, the Control Unit can be changed without the need for software tools.

A 24 V power supply must be connected to terminal X124 in order to use the digital outputs. To operate the CU310-2 Control Unit, a CompactFlash card with firmware V4.4 or higher

System components

### Control Units > CU310-2 Control Unit

Selection and ordering data		Integration
Description	Article No.	Power Modules in chassis format are controlled from the
CU310-2 PN Control Unit	6SL3040-1LA01-0AA0	CU310-2 Control Unit via the DRIVE-CLiQ interface. Sensor Modules and Terminal Modules must be connected to the fre
Without CompactFlash card		DRIVE-CLiQ sockets of the Power Module.
CU310-2 DP Control Unit	6SL3040-1LA00-0AA0	With the BOP20 Basic Operator Panel, parameters can be
Without CompactFlash card		changed directly on the device. The BOP20 Basic Operator
Accessories		Panel can also be snapped onto the CU310-2 Control Unit
For CU310-2 PN:		during operation to perform diagnostics.
Industrial Ethernet FC		The CU310-2 Control Unit and other connected components a
• RJ45 plug 180 (1 unit)	6GK1901-1BB10-2AA0	commissioned and diagnosed with the STARTER commission ing tool.
<ul> <li>RJ45 plug 180 (10 units)</li> </ul>	6GK1901-1BB10-2AB0	A CU310-2 DP Control Unit communicates with the higher-lev
<ul> <li>Stripping tool</li> </ul>	6GK1901-1GA00	control system using PROFIBUS and the PROFIdrive V4 profi
<ul> <li>Standard cable GP 2x2</li> </ul>	6XV1840-2AH10	A CU310-2 PN Control Unit communicates with the higher-lev
<ul> <li>Flexible cable GP 2x2</li> </ul>	6XV1870-2B	control system using PROFINET IO and the PROFIdrive V4
<ul> <li>Trailing cable GP 2x2</li> </ul>	6XV1870-2D	profile.
<ul> <li>Trailing cable 2x2</li> </ul>	6XV1840-3AH10	The SINAMICS S120 drive system with the CU310-2 PN Cont
Marine cable 2x2	6XV1840-4AH10	Unit then assumes the function of a PROFINET IO device and can perform the following functions:
For CU310-2 DP:		PROFINET IO device
PROFIBUS connector		<ul> <li>100 Mbit/s full duplex</li> </ul>
<ul> <li><u>Without</u> PG/PC connection</li> </ul>	6ES7972-0BA42-0XA0	
<u>With</u> PG/PC connection	6ES7972-0BB42-0XA0	<ul> <li>Supports real-time classes of PROFINET IO: - RT (Real-Time)</li> </ul>
STARTER commissioning tool <sup>1)</sup>	6SL3072-0AA00-0AG0	- IRT (Isonchronous Real-Time), minimum send clock 250
On DVD-ROM		<ul> <li>Connects to controls as PROFINET IO devices using</li> </ul>
Accessories for re-ordering		PROFIdrive compliant with Specification V4
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0	<ul> <li>Standard TCP/IP communication for engineering processe using the STARTER commissioning tool</li> </ul>
For DRIVE-CLiQ port		<ul> <li>Integrated 2-port switch with two RJ45 sockets based on the</li> </ul>
For more information on conne Catalog IK PI and the Siemens	ctors and cables, please refer to Industry Mall:	ERTEC ASIC. The optimum topology (line, star, tree) can therefore be configured without additional external switch

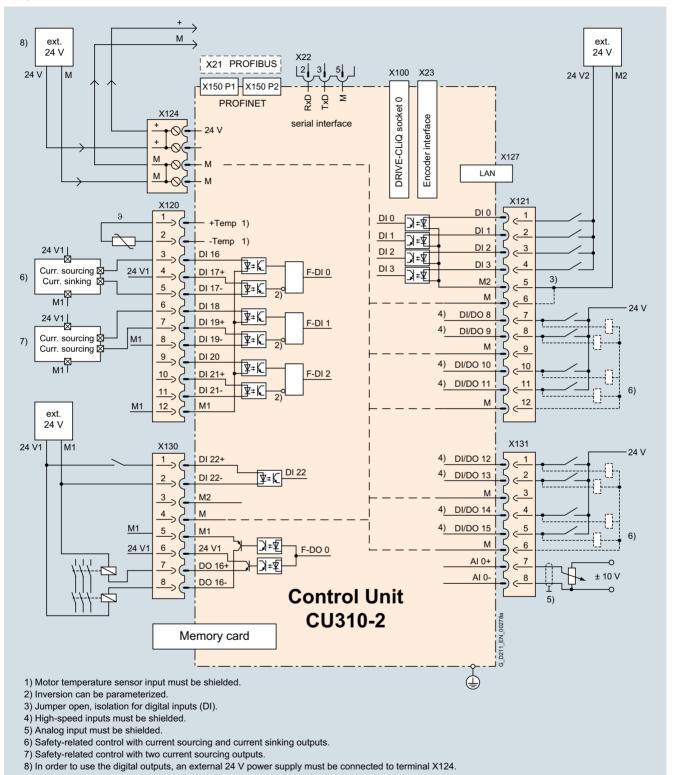
is required.

Catalog IK PI and the Siemens Industry Mall: www.siemens.com/industrymall 3

System components

#### Control Units > CU310-2 Control Unit

Integration (continued)



Connection example of CU310-2 Control Unit

System components

### Control Units > CU310-2 Control Unit

	CU310-2 Control Unit
PROFINET PROFIBUS	6SL3040-1LA01-0AA0 6SL3040-1LA00-0AA0
Power requirement, max.	0.35 A for CU310-2 Control Unit + 0.5 A for Power Module
At 24 V DC, without taking into account the digital outputs and DRIVE-CLiQ supply	
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Fuse protection, max.	20 A
Digital inputs	In accordance with IEC 61131-2 Type 1 5 floating digital inputs 8 bidirectional non-floating digital inputs/outputs 3 parameterizable, fail-safe digital inputs (isolated) or alternatively 6 parameterizable digital inputs (isolated)
• Voltage	-3 +30 V
Low level (an open digital input is interpreted as "low")	-3+5 V
High level	15 30 V
<ul> <li>Current consumption at 24 V DC, typ.</li> <li>Delay time of digital inputs <sup>1)</sup>, approx.</li> </ul>	10 mA
- Delay time of digital inputs '', approx. - L $\rightarrow$ H	F0 vo
$- \Box \rightarrow \Pi$	50 μs 100 μs
<ul> <li>Delay time of high-speed digital inputs <sup>1)</sup>, approx.</li> <li>(high-speed digital inputs can be used for position detection)</li> </ul>	100 µ3
- $L \rightarrow H$	5 µs
$-H \rightarrow L$	50 µs
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Digital outputs	8 bidirectional non-floating digital inputs/outputs
(continuously short-circuit proof)	
<ul> <li>Voltage</li> <li>Load current per digital output <sup>2)</sup>, max.</li> </ul>	24 V DC 500 mA
<ul> <li>Delay time <sup>1)</sup>, typ./max.</li> </ul>	500 MA
- L $\rightarrow$ H	150 μs/400 μs
$- H \rightarrow L$	75 µs/100 µs
<ul> <li>Conductor cross-section, max.</li> </ul>	1.5 mm <sup>2</sup>
	1 analog input for current or voltage input, switchable
Analog input <ul> <li>Common mode range</li> </ul>	±12 V
As voltage input	+12 v -10 +10 V; $R_i > 100 \Omega$
	Resolution: 12 bits + sign (referred to the maximum range that can be resolve $-11 \dots +11 \text{ V}$ )
As current input	-20 +20 mA; $R_{\rm i}$ > 250 $\Omega$
	Resolution: 11 bits + sign (referred to -22 +22 mA)
	Max. range that can be resolved: -44 +44 mA
Encoder evaluation	Incremental encoder TTL/HTL     SSI encoders without incremental signals
<ul> <li>Input current range TTL/HTL</li> </ul>	2 10 mA (typ. 5 mA)
Encoder supply	24 V DC / 0.35 A or
- Encoder fraguency may	5 V DC / 0.35 A
<ul> <li>Encoder frequency, max.</li> <li>SSI baud rate</li> </ul>	300 kHz 100 250 kBaud
SSI baud rate     Resolution absolute position SSI	30 bits
Cable length, max.	
- TTL encoder	100 m (only bipolar signals permitted) <sup>3)</sup>
- HTL encoder	100 m for unipolar signals
	300 m for bipolar signals <sup>3)</sup>
- SSI encoder	100 m
Power loss	<20 W
PE connection	M4 screw
Dimensions	
• Width	73 mm
Height	
• Height - CU310-2 PN	191 mm
5	191 mm 187 mm

<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slice in which the digital input or output is processed.

<sup>2)</sup> In order to use the digital outputs, an external 24 V power supply must be connected to terminal X124.

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<sup>3)</sup> Signal cables twisted in pairs and shielded.

System components

#### Control Units > CompactFlash card for CU310-2

### Overview



The CompactFlash card contains the firmware and set parameters. The CompactFlash card is plugged into the appropriate slot on the CU310-2 Control Unit.

#### Design

3

A CU310-2 Control Unit can perform the communication, openloop and closed-loop control functions for one Power Module. The performance extension is not required in this case.

In addition to the firmware, the CompactFlash card also contains licensing codes which are required to enable firmware options.

In addition to the Article No., the following firmware options can currently be ordered:

- Safety Integrated Extended Functions, order code F01
- High output frequency, order code J01
- DCB Extension, order code U01

The firmware options can also be enabled subsequently. You will need the serial number of the CompactFlash card and the Article No. of the firmware option to be enabled. With this information, you can purchase the associated license code from a license database and enable the firmware option. The license code is only valid for the CompactFlash card declared and cannot be transferred to other CompactFlash cards.

Subsequent licensing is possible in the Internet via the WEB License Manager by generating a license key: www.siemens.com/automation/license

#### Selection and ordering data

for all axes on a CompactFlash card

Description	Article No.
CompactFlash card for CU310-2 Control Units without safety license	6SL3054-0E❑00-1BA0
CompactFlash card for CU310-2 Control Units with safety license • Including Certificate of License	6SL3054-0E❑00-1BA0-Z F01
CompactFlash card for CU310-2 Control Units with/without safety license	
• With high output frequency <sup>1)</sup>	6SL3054-0E❑00-1BA0-Z J01
• With DCB Extension license (firmware V4.6 and higher) (further information about DCB Extension and license upgrades can be found under Drive Control Chart (DCC) in section Tools and Engineering)	6SL3054-0E❑00-1BA0-Z U01
Firmware version	$\uparrow$
V4.7	н
V4.8	J
License upgrades	
• Safety Integrated Extended Functions including Certificate of License Upgrading license for one axis on a CompactFlash card	6SL3074-0AA10-0AA0
<ul> <li>High output frequency<sup>1)</sup></li> <li>Upgrading license to enable</li> <li>high output frequencies above 550 Hz</li> </ul>	6SL3074-0AA02-0AA0

 For further information, see https://support.industry.siemens.com/cs/document/104020669

Supplementary system components

BOP20 Basic Operator Panel

### Overview





Parameters can be set, diagnostics information (e.g. alarm and fault messages) read out and faults acknowledged using the BOP20 Basic Operator Panel.

#### Design

The BOP20 Basic Operator Panel has a backlit two-line display area with six keys.

The integrated plug connector on the rear of the BOP20 Basic Operator Panel provides its power and establishes communication with the Control Unit.

Selection and ordering data	
Description	Article No.
BOP20 Basic Operator Panel	6SL3055-0AA00-4BA0
BOP20 Basic Operator Panel	65L3055-0AA00-4BA0

### Integration

The BOP20 Basic Operator Panel can be inserted on the following Control Units:

- SINAMICS S120
  - CU310-2 - CU320-2
  - 000202



CU310-2 PN Control Unit with inserted BOP20 Basic Operator Panel



CU320-2 PN Control Unit with inserted BOP20 Basic Operator Panel

Supplementary system components

#### Overview



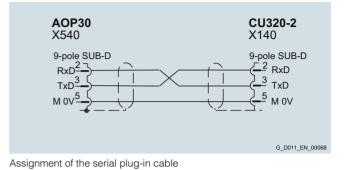
The AOP30 Advanced Operator Panel is an input/output device for converters of the SINAMICS series, preferably for cabinet installation.

It has the following characteristic curves:

- Graphical backlit LCD display for plain text display and a bar display of process variables
- LEDs for display of the operating states
- Help function describing causes of and remedies for faults and alarms
- Keypad for operational control of a drive
- Local/remote switchover for selecting the operating location (control priority assigned to operator panel or customer terminal block / communication channel)
- Numeric keypad for input of setpoint or parameter values
- Function keys for guided navigation in the menu
- Two-stage safety concept to protect against accidental or unauthorized changes to settings.
  - Operation of the drive from the operator panel can be disabled by the keyboard lock so that only parameter values and process variables can be displayed on the operator panel.
  - A password can be used to prevent the unauthorized modification of converter parameters.
- Front panel with degree of protection IP55

The AOP30 and SINAMICS drive communicate via the RS232 serial interface with PPI protocol.

The AOP30 may be omitted if the drive is only operated via PROFIBUS, for example, and no local display is required on the cabinet. The AOP30 can then be used simply for commissioning purposes and to obtain diagnostic information, in which case, it is plugged into the RS232 interface on the CU320-2 Control Unit. In this case, an external 24 V power supply (max. current requirement 200 mA) is required.



#### Design

The AOP30 is an operator panel with graphical display and membrane keyboard. The device can be installed in a cabinet door which is between 2 mm and 4 mm thick.

Features:

- Display with green backlighting, resolution 240 × 64 pixels
- · Membrane keyboard with 26 keys
- Connection for a 24 V power supply
- RS232 interface
- Time and date memory with internal battery backup
- 4 LEDs to indicate the operating state of the drive:
- RUN green
- ALARM yellow
- FAULT red
- Local/Remote green

#### Selection and ordering data

Description	Article No.
AOP30 Advanced Operator Panel	6SL3055-0AA00-4CA5
Accessories	
<b>RS232 plug-in cable</b> for connecting the AOP30 to the CU320-2	
1 m long	6FX8002-1AA01-1AB0
2 m long	6FX8002-1AA01-1AC0
3 m long	6FX8002-1AA01-1AD0
4 m long	6FX8002-1AA01-1AE0
5 m long	6FX8002-1AA01-1AF0
6 m long	6FX8002-1AA01-1AG0
7 m long	6FX8002-1AA01-1AH0
8 m long	6FX8002-1AA01-1AJ0
9 m long	6FX8002-1AA01-1AK0
10 m long	6FX8002-1AA01-1BA0

For the SINAMICS S120 Cabinet Modules, the AOP30 can be ordered as an option by specifying order code **K08**.

For the SINAMICS S150, the AOP30 Advanced Operator Panel is installed in the cabinet door as standard.

Supplementary system components

AOP30 Advanced Operator Panel

### Function

The current operating states, setpoints and actual values, parameters, indices, faults and alarms are displayed on the display panel.

German, English, French, Italian, Spanish and Chinese are stored on the CU320-2 Control Unit CompactFlash card as operator panel languages. The desired language must be downloaded to the AOP30 prior to commissioning.

In addition to these preinstalled languages, Russian and Portuguese (Brazil) are also available for subsequent installation. Further languages are available on request.

#### Integration

If just one CU320-2 Control Unit controls several power units (multi-motor drives) in the SINAMICS S120 drive system, the parameters, alarms and faults of all the connected devices can be simultaneously displayed and processed on the AOP30 Advanced Operator Panel.

AOP30 Advanced Operator Panel 6SL3055-0AA00-4CA5	
Power supply	24 V DC (20.4 28.8 V)
Current requirement	
<ul> <li>Without backlighting</li> </ul>	<100 mA
<ul> <li>For max. backlighting</li> </ul>	< 200 mA
Data interface	RS232 interface, PPI protocol
Backup battery	3 V lithium CR2032
Operating temperature	0 55 °C
Storage and transport temperature	-25 +70 °C
Degree of protection	IP20 for the inside of the cabinet IP55 for the outside of the cabinet
Dimensions	
• Width	212 mm
• Height	156 mm
• Depth	31 mm
Weight, approx.	0.55 kg

Supplementary system components

#### **CBC10** Communication Board

### Overview



The CBC10 Communication Board is used to interface the CU320-2 Control Unit and therefore the drive system to the CAN (Controller Area Network) protocol. The board's driver software fulfills the standards of the following CANopen specification of the CiA organization (CAN in Automation):

- Communication profiles in accordance with DS 301
- Drive profile in accordance with DSP 402 (in this case Profile Velocity Mode)
- EDS (Electronic Data Sheet) in accordance with DSP 306
- Operational status signaling in accordance with DSP 305

#### Note:

The CAN address is set on the CU320-2 DP Control Unit by means of the two address switches.

These address switches are not available on the CU320-2 PN Control Unit. In this case, the address can be set by means of parameters.

### Integration

The CBC10 Communication Board plugs into the option slot on the CU320-2 Control Unit. Two SUB-D connections for input and output are provided for the CAN interface on the CBC10 Communication Board.

#### Selection and ordering data

CBC10 Communication Board	6SL3055-0AA00-2CA0
Description	Article No.

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the CBC10 Communication Board can be ordered as an option by specifying order code **G20**.

CBC10 Communication Board 6SL3055-0AA00-2CA0	
Current requirement, max. at 24 V DC via CU320-2 Control Unit	0.05 A
Power loss, max.	3 W
Weight, approx.	0.1 kg

Supplementary system components

**CBE20 Communication Board** 

#### Overview



The CBE20 Communication Board can be used to connect to a PROFINET IO network via a CU320-2 Control Unit.

With the Communication Board CBE20, SINAMICS S120 and/or SINAMICS S150 is a PROFINET IO device in the sense of PROFINET and can perform the following functions:

- PROFINET IO device
- 100 Mbit/s full duplex
- Supports real-time classes of PROFINET IO: - RT (Real-Time)
- IRT (Isochronous Real-Time), minimum send cycle 500 μs
- Connection to control systems as PROFINET IO devices in accordance with PROFIdrive, Specification V4
- Standard TCP/IP communication for engineering processes using the STARTER commissioning tool
- Integrated 4-port switch with four RJ45 sockets based on the PROFINET ASIC ERTEC400. The optimum topology (line, star, tree) can therefore be configured without additional external switches
- Supports the functions "media redundancy" and "shared device"

The CBE20 Communication Board is required if:

- a SINAMICS S120 or SINAMICS S150 converter with a CU320-2 DP Control Unit (PROFIBUS) should be connected to a PROFINET-IO network
- SINAMICS Link is to be used to directly exchange data between several CU320-2 DP (PROFIBUS) or CU320-2 PN (PROFINET) Control Units without using a higher-level control system
- EtherNet/IP connectivity is required.

#### SINAMICS Link

SINAMICS Link can be used to directly exchange data between several CU320-2 DP (PROFIBUS) or CU320-2 PN (PROFINET) Control Units without using a higher-level control system. In this case, the CBE20 Communication Board is required. Possible applications for the SINAMICS Link include:

- Torque distribution for several drives
- · Setpoint cascading for several drives
- Load distribution for drives coupled through a material web
- Couplings between SINAMICS G or SINAMICS S with the CU320-2 Control Unit and SINAMICS DC Master with CUD Control Units.

Participants other than CU320-2 Control Units and/or CUD Control Units of the SINAMICS DC Master cannot be integrated into this communication.

SINAMICS Link is activated by appropriately parameterizing the Control Units of the participants.

### Selection and ordering data

Description	Article No.
CBE20 Communication Board	6SL3055-0AA00-2EB0
Accessories	
Industrial Ethernet FC	
• RJ45 Plug 180 (1 unit)	6GK1901-1BB10-2AA0
<ul> <li>RJ45 Plug 180 (10 units)</li> </ul>	6GK1901-1BB10-2AB0
Stripping tool	6GK1901-1GA00
Standard cable GP 2x2	6XV1840-2AH10
Flexible cable GP 2x2	6XV1870-2B
Trailing cable GP 2x2	6XV1870-2D
Trailing cable 2x2	6XV1840-3AH10
Marine cable 2x2	6XV1840-4AH10

For more information on connectors and cables, please refer to Catalog IK PI and the Siemens Industry Mall: www.siemens.com/industrymall

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the CBE20 Communication Board can be ordered as an option by specifying order code **G33**.

#### Integration

The CBE20 Communication Board plugs into the option slot on the CU320-2 Control Unit.

CBE20 Communication Board 6SL3055-0AA00-2EB0	
Current requirement at 24 V DC	0.16 A
Power loss	2.4 W
Weight, approx.	0.1 kg

Supplementary system components

### DMC20 DRIVE-CLiQ Hub Module

### Overview



The DMC20 DRIVE-CLiQ Hub Module is used to implement a star-shaped topology of a DRIVE-CLiQ line. Two DMC20 DRIVE-CLiQ Hub Modules can be connected in series (cascaded).

#### Design

The DMC20 DRIVE-CLiQ Hub Module in degree of protection IP20 is designed for mounting in control cabinets.

The following are located on the DMC20 DRIVE-CLiQ Hub Module:

- 6 DRIVE-CLiQ sockets for connecting 5 DRIVE-CLiQ devices
- 1 connection for the electronics power supply via the 24 V DC supply connector

The status of the DMC20 DRIVE-CLiQ Hub Module is indicated via a multi-color LED.

The DMC20 DRIVE-CLiQ Hub Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

### Selection and ordering data

Description	Article No.
DMC20 DRIVE-CLiQ Hub Module Without DRIVE-CLiQ cable	6SL3055-0AA00-6AA1
Accessories for re-ordering	
Accounted for the ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0

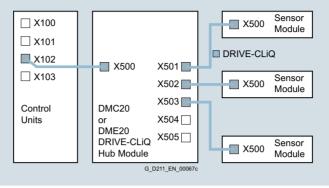
DMC20 DRIVE-CLiQ Hub Module 6SL3055-0AA00-6AA1	
Current requirement, max. at 24 V DC without DRIVE-CLiQ supply	0.15 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Degree of protection	IP20
Dimensions	
• Width	30 mm
Height	151 mm
• Depth	110 mm
Weight, approx.	0.36 kg
Certificate of suitability	cULus

Supplementary system components

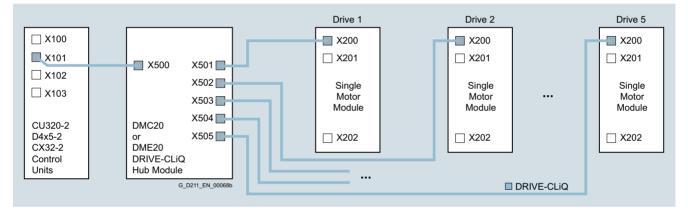
DMC20 DRIVE-CLiQ Hub Module

### Integration

Signals from more than one encoder can be collected with one DRIVE-CLiQ Hub Module and forwarded to the Control Unit through a single DRIVE-CLiQ cable.



With a DRIVE-CLiQ Hub Module, individual DRIVE-CLiQ nodes can be removed without interrupting the data exchange with the remaining devices in the DRIVE-CLiQ line.



Supplementary system components

### DME20 DRIVE-CLiQ Hub Module

### Overview



The DME20 DRIVE-CLiQ Hub Module is used to implement a star-shaped topology of a DRIVE-CLiQ line. Two DME20 DRIVE-CLiQ Hub Modules can be connected in series (cascaded).

### Design

The following are located on the DME20 DRIVE-CLiQ Hub Module:

- 6 DRIVE-CLiQ sockets for connecting 5 DRIVE-CLiQ devices
- 1 connection for the electronics power supply via the 24 V DC circular supply connector with conductor cross-section 4 × 0.75 mm<sup>2</sup> (pins 1+2 internally bridged; pins 3+4 internally bridged)

The scope of supply of the DME20 DRIVE-CLiQ Hub Modules includes:

• 6 blanking plugs for sealing unused DRIVE-CLiQ sockets

### Selection and ordering data

Description	Article No.
DME20 DRIVE-CLIQ Hub Module Without DRIVE-CLIQ cable; without electronics power supply cable and circular connector for 24 V DC	6SL3055-0AA00-6AB0
Accessories	
24 V DC power supply cable	
Ordering and delivery Phoenix Contact www.phoenixcontact.com	
<ul> <li>Shielded connector, 5-pole, can be assembled by the user</li> </ul>	Type No. 1508365
Unshielded connector, 4-pole, can be assembled by the user, Speedcon rapid interlock	Type No. 1521601
Accessories for re-ordering	
SINAMICS dust protection blanking plugs IP67 (6 units) For DRIVE-CLiQ port	6SL3066-4CA01-0AA0

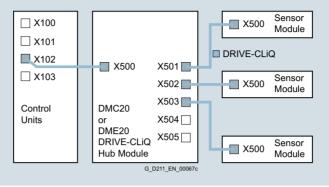
DME20 DRIVE-CLiQ Hub Module 6SL3055-0AA00-6AB0	
Current requirement, max. at 24 V DC without DRIVE-CLiQ supply	0.15 A
Conductor cross-section, max.	$4 \times 0.75 \text{ mm}^2$
Degree of protection	IP67
Dimensions	
• Width	99 mm
• Height	149 mm
• Depth	55.7 mm (without connector)
Weight, approx.	0.8 kg
Certificate of suitability	cULus

Supplementary system components

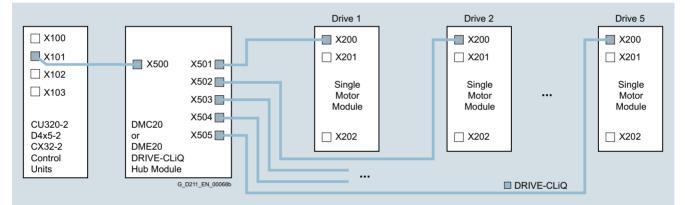
DME20 DRIVE-CLiQ Hub Module

### Integration

Signals from more than one encoder can be collected with one DRIVE-CLiQ Hub Module and forwarded to the Control Unit through a single DRIVE-CLiQ cable.



With a DRIVE-CLiQ Hub Module, individual DRIVE-CLiQ nodes can be removed without interrupting the data exchange with the remaining devices in the DRIVE-CLiQ line.



The DME20 DRIVE-CLiQ Hub Module in degree of protection IP67 is suitable for installation outside control cabinets.

Supplementary system components

### **TB30 Terminal Board**

### Overview



#### TB30 Terminal Board

The TB30 Terminal Board supports the addition of digital inputs/ digital outputs and analog inputs/analog outputs to the CU320-2 Control Unit.

### Design

The following are located on the TB30 Terminal Board:

- Power supply for digital inputs/digital outputs
- 4 digital inputs
- · 4 digital outputs
- 2 analog inputs
- 2 analog outputs

A shield connection for the signal cable shield is located on the Control Unit.

#### Selection and ordering data

Description	Article No.
TB30 Terminal Board	6SL3055-0AA00-2TA0

For SINAMICS S150, the TB30 Terminal Board can be ordered as an option by specifying order code  ${f G62}$ .

### Technical specifications

TB30 Terminal Board	
6SL3055-0AA00-2TA0	
Current requirement, max. at 24 V DC via CU320-2 Control Unit without taking account of digital outputs	0.05 A
<ul> <li>Conductor cross-section, max.</li> </ul>	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
Digital inputs In accordance with IEC 61131-2 Type 1	
Voltage	-3 +30 V
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	-3 +5 V
High level	15 30 V
• Current consumption at 24 V DC, typ.	6 mA
<ul> <li>Delay time of digital inputs <sup>1)</sup>, approx.</li> </ul>	
$- L \rightarrow H$	50 μs
$-H \rightarrow L$	100 µs
<ul> <li>Conductor cross-section, max.</li> </ul>	0.5 mm <sup>2</sup>
Digital outputs (continuously short-circuit proof)	
Voltage	24 V DC
Load current per digital output, max.	500 mA
<ul> <li>Delay time of digital outputs <sup>1)</sup>, approx.</li> </ul>	150 μs
<ul> <li>Conductor cross-section, max.</li> </ul>	0.5 mm <sup>2</sup>
Analog inputs (difference)	
<ul> <li>Voltage range (an open analog input is interpreted as 0 V)</li> </ul>	-10 +10 V
• Internal resistance R <sub>i</sub>	65 kΩ
Resolution <sup>2)</sup>	13 bits + sign
Conductor cross-section, max.	0.5 mm <sup>2</sup>
Analog outputs (continuously short-circuit proof)	
Voltage range	-10 +10 V
Max. load current	-3 +3 mA
Resolution	11 bits + sign
<ul> <li>Settling time, approx.</li> </ul>	200 µs
Conductor cross-section, max.	0.5 mm <sup>2</sup>
Power loss, max.	3 W
Weight, approx.	0.1 kg

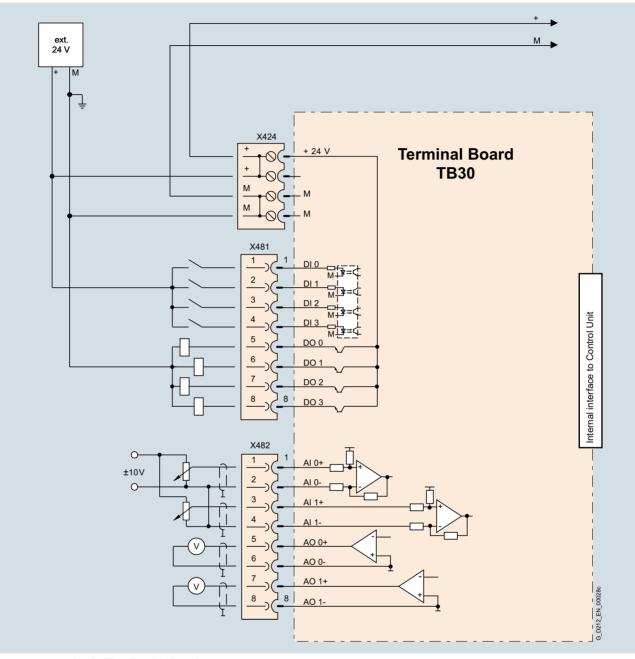
<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slot in which the digital input/output is processed.

Supplementary system components

TB30 Terminal Board

# Integration

The TB30 Terminal Board is inserted in the slot to optionally expand the CU320-2 Control Unit.



Connection example of a TB30 Terminal Board

Supplementary system components

### TM15 Terminal Module

#### Overview



The number of available digital inputs and outputs within a drive system can be expanded with the TM15 Terminal Module.

#### Design

The TM15 Terminal Module is equipped with the following:

- 24 bidirectional digital inputs/outputs (electrical isolation in 3 groups with 8 channels per group)
- 24 green status LEDs for indicating the logical signal state of the corresponding terminal
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC power supply connector
- 1 PE connection

The status of the TM15 Terminal Module is indicated via a multi-color LED.

The TM15 Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

The signal cable shield can be connected to the TM15 Terminal Module by means of a shield connection terminal, e.g. Phoenix Contact type SK8 or Weidmüller type KLBÜ CO 1. The shield connection terminal must not be used as a strain relief mechanism.

#### Selection and ordering data

Description	Article No.
TM15 Terminal Module	6SL3055-0AA00-3FA0
Without DRIVE-CLiQ cable	03L3035-0AA00-3FA0
Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0
For DRIVE-CLiQ port	

### Technical specifications

TM15 Terminal Module 6SL3055-0AA00-3FA0	
Current requirement, max. at 24 V DC without load	0.15 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Fuse protection, max.	20 A
Number of DRIVE-CLiQ sockets	2
I/O	
Digital inputs/outputs	Parameterizable channel-by-channel as DI or DO
<ul> <li>Number of digital inputs/outputs</li> </ul>	24
Isolation	Yes, in groups of 8
<ul> <li>Cables and connections</li> </ul>	Plug-in screw-type terminals
<ul> <li>Conductor cross-section, max.</li> </ul>	1.5 mm <sup>2</sup>
Digital inputs	
Voltage	-30 +30 V
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	-30 +5 V
High level	15 30 V
Current consumption at 24 V DC	9 mA
<ul> <li>Delay times of digital inputs, typ.<sup>1)</sup></li> </ul>	
$- L \rightarrow H$	50 µs
$-H \rightarrow L$	100 µs
Digital outputs (continuously short-circuit proof)	
Voltage	24 V DC
• Load current per digital output, max.	0.5 A
<ul> <li>Delay times (resistive load) <sup>1)</sup></li> </ul>	
- $L \rightarrow H$ , typ.	50 µs
- L $\rightarrow$ H, max.	100 µs
- $H \rightarrow L$ , typ.	150 μs
- $H \rightarrow L$ , max.	225 μs
<ul> <li>Total current of outputs (per group), max.</li> </ul>	
- To 60 °C	2 A
- To 50 °C	3 A
- To 40 °C	4 A
Power loss, max.	3 W
PE connection	M4 screw
Dimensions	
• Width	50 mm
• Height	150 mm
• Depth	111 mm
Weight, approx.	1 kg

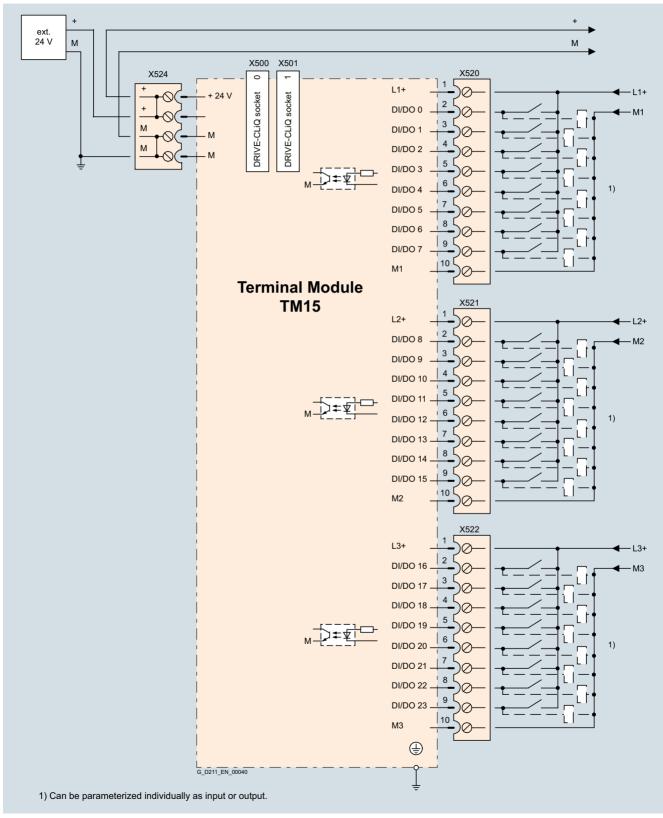
<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slot in which the digital input/output is processed.

Supplementary system components

TM15 Terminal Module

## Integration

The TM15 Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Connection example of TM15 Terminal Module

Supplementary system components

#### TM31 Terminal Module

### Overview



With the TM31 Terminal Module, the number of available digital inputs and outputs and the number of analog input and outputs within a drive can be expanded.

The TM31 Terminal Module also features relay outputs with changeover contact and a temperature sensor input.

#### Design

The following are located on the TM31 Terminal Module:

- 8 digital inputs
- 4 bidirectional digital inputs/outputs
- · 2 relay outputs with changeover contact
- 2 analog inputs
- · 2 analog outputs
- 1 temperature sensor input for KTY84-130, Pt1000 or PTC (Pt1000 can be used from firmware V4.7 HF17)
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the TM31 Terminal Module is indicated via a multi-color LED.

The TM31 Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

The signal cable shield can be attached to the TM31 Terminal Module via a shield connection terminal, e.g. type SK8 supplied by Phoenix Contact or type KLBÜ CO 1 supplied by Weidmüller. The shield connection terminal must not be used as a strain relief mechanism.

#### Selection and ordering data

Description	Article No.
TM31 Terminal Module Without DRIVE-CLiQ cable	6SL3055-0AA00-3AA1
Accessories for re-ordering	
Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the TM31 Terminal Module can be ordered as an option by specifying order code **G60** or **G61**.

Supplementary system components

TM31 Terminal Module

# Technical specifications

TM31 Terminal Module 6SL3055-0AA00-3AA1	
Current requirement, max. At 24 V DC without taking account of the digital outputs and DRIVE-CLiQ supply	0.5 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
Digital inputs In accordance with IEC 61131-2 Type 1	
Voltage	-3 +30 V
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	-3 +5 V
High level	15 30 V
• Current consumption at 24 V DC, typ.	9 mA
<ul> <li>Delay times of digital inputs <sup>1)</sup>, approx.</li> </ul>	
- $L \rightarrow H$	50 µs
- $H \rightarrow L$	100 µs
<ul> <li>Conductor cross-section, max.</li> </ul>	1.5 mm <sup>2</sup>
Digital outputs (continuously short-circuit proof)	
Voltage	24 V DC
<ul> <li>Load current per digital output, max.</li> </ul>	100 mA
<ul> <li>Total current of digital outputs, max.</li> </ul>	400 mA
<ul> <li>Delay times of digital outputs <sup>1)</sup></li> </ul>	
- Тур.	150 $\mu s$ with 0.5 A resistive load
- Max.	500 µs
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Analog inputs (a switch is used to toggle between voltage and current input)	
As voltage input	
- Voltage range	-10 +10 V
- Internal resistance R <sub>i</sub>	100 kΩ
- Resolution <sup>2)</sup>	11 bits + sign
As current input	
- Current ranges	4 20 mA, -20 +20 mA, 0 20 mA
- Internal resistance R <sub>i</sub>	250 Ω
- Resolution <sup>2)</sup>	10 bits + sign
Conductor cross-section, max.	1.5 mm <sup>2</sup>

TM31 Terminal Module 6SL3055-0AA00-3AA1	
Analog outputs (continuously short-circuit proof)	
Voltage range	-10 +10 V
Max. load current	-3 +3 mA
Current ranges	4 20 mA, -20 +20 mA, 0 20 mA
Load resistance, max.	500 Ω in the range -20 +20 mA
Resolution	11 bits + sign
<ul> <li>Conductor cross-section, max.</li> </ul>	1.5 mm <sup>2</sup>
Relay outputs (CO contacts)	
Max. load current	8 A
<ul> <li>Operational voltage, max.</li> </ul>	250 V AC, 30 V DC
<ul> <li>Switching capacity, max.</li> </ul>	
- At 250 V AC	2000 VA ( $\cos \varphi = 1$ ) 750 VA ( $\cos \varphi = 0.4$ )
- At 30 V DC	240 W (resistive load)
<ul> <li>Required minimum current</li> </ul>	100 mA
<ul> <li>Conductor cross-section, max.</li> </ul>	2.5 mm <sup>2</sup>
Power loss, max.	10 W
PE connection	M4 screw
Dimensions	
• Width	50 mm
Height	150 mm
• Depth	111 mm
Weight, approx.	0.49 kg

- <sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slot in which the digital input/output is processed.
- <sup>2)</sup> If the analog input is to be operated in the signal processing sense with continuously variable input voltage, the sampling frequency  $f_a = 1/t_{\text{time slice}}$  must be at least twice the value of the highest signal frequency  $f_{\text{max}}$ .

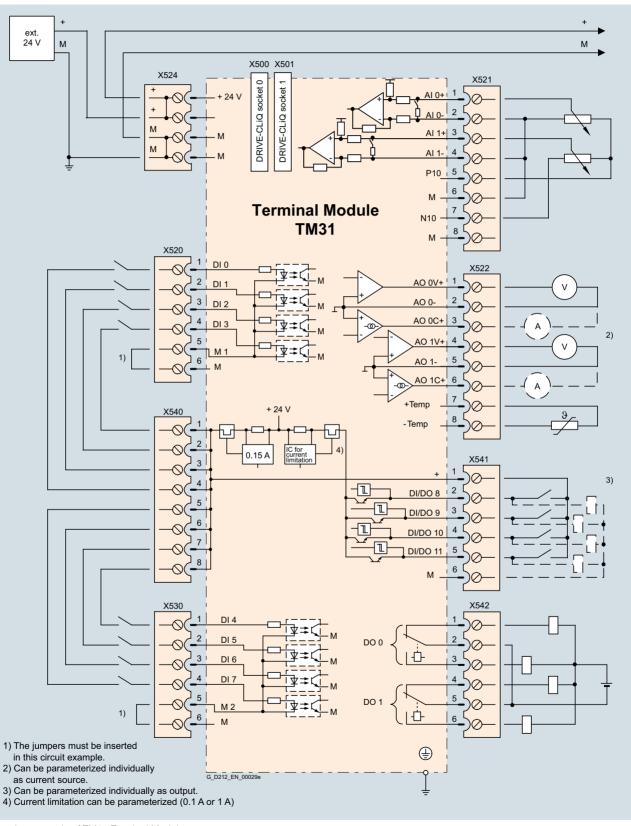
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Supplementary system components

#### TM31 Terminal Module

### Integration

The TM31 Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Connection example of TM31 Terminal Module

Supplementary system components

TM41 Terminal Module

#### Overview

The TM41 Terminal Module supplies TTL signals which emulate an incremental encoder, e.g. to a higher-level control. The encoder interface (incremental encoder emulation) can be linked to an encoder signal from the Control Unit, e.g. incremental encoder sin/cos, by parameter assignment.

The TM41 Terminal Module increases the number of digital inputs/outputs and analog inputs that are available in the drive system.

### Design

The following are located on the TM41 Terminal Module:

- 4 bidirectional digital inputs/outputs
- 4 digital inputs (with electrical isolation)
- 1 analog input
- 1 interface for emulation of TTL incremental encoder (RS422)
- 1 LED for signaling zero mark detection for encoder interface
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply and to supply the digital outputs via the 24 V DC power supply connector
- 1 PE connection

The status of the TM41 Terminal Module is indicated via a multi-color LED.

An LED next to the interface for TTL pulse encoder emulation is illuminated as soon as a zero mark is detected.

The TM41 Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

The signal cable shield can be attached to the TM41 Terminal Module via a shield connection terminal, e.g. type SK8 supplied by Phoenix Contact or type KLBÜ CO 1 supplied by Weidmüller. The shield connection terminal must not be used as a strain relief mechanism.

#### Selection and ordering data

Description	Article No.
TM41 Terminal Module	6SL3055-0AA00-3PA1
Without DRIVE-CLiQ cable	
Accessories for re-ordering	
<b>Dust protection blanking plugs</b> (50 units) For DRIVE-CLiQ port	6SL3066-4CA00-0AA0

Supplementary system components

### TM41 Terminal Module

### Technical specifications

TM41 Terminal Module	
6SL3055-0AA00-3PA1	
Current requirement (X524 at 24 V DC) without DRIVE-CLiQ supply or digital outputs (X514)	0.5 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
I/O	
Digital inputs/outputs	Individually parameterizable as DI or DO
<ul> <li>Number of digital inputs/outputs</li> </ul>	4
<ul> <li>Number of digital input/outputs (with isolation)</li> </ul>	4
<ul> <li>Cables and connections</li> </ul>	Plug-in screw-type terminals
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Digital inputs	
Voltage	
- Without electrical isolation	-3 +30 V
- With electrical isolation	-30 +30 V
<ul> <li>Low level (an open digital input is interpreted as "low")</li> </ul>	
- Without electrical isolation	-3 +5 V
- With electrical isolation	-30 +5 V
High level	15 30 V
<ul> <li>Current consumption at 24 V DC, typ.</li> </ul>	<9 mA
Delay times of digital inputs, max. 1)	
$- L \to H$	3 ms
- $H \rightarrow L$	3 ms
Digital outputs (continuously short-circuit proof)	
Voltage	24 V DC
• Load current per digital output, max.	0.5 A
<ul> <li>Delay times (resistive load) <sup>1)</sup></li> </ul>	
- $L \rightarrow H$ , typ.	50 μs
- $L \rightarrow H$ , max.	100 µs
- $H \rightarrow L$ , typ.	75 μs
- $H \rightarrow L$ , max.	150 μs
Analog input (difference)	
Voltage range	-10 +10 V
<ul> <li>Internal resistance</li> </ul>	≥100 kΩ
Resolution <sup>2)</sup>	12 bits + sign

TTL (RS422), A+, A-, B+, B-, zero track N+, N-
512 kHz
Any number of ratio/reduction ratio of pulses
12 W
M4 screw
30 mm
151 mm
110 mm

<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slot in which the digital input/output is processed.

<sup>2)</sup> If the analog input is to be operated in the signal processing sense with continuously variable input voltage, the sampling frequency  $f_a = 1/t_{time \ slice}$  must be at least twice the value of the highest signal frequency  $f_{max}$ .

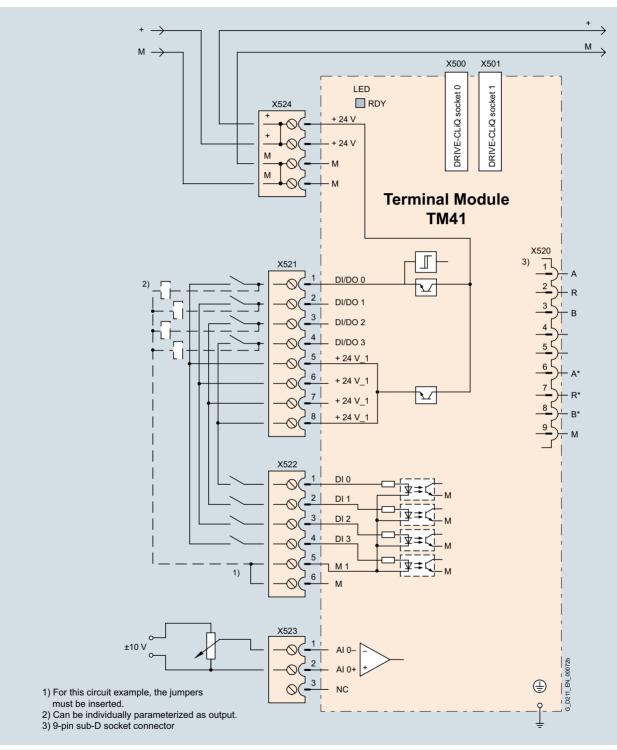
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Supplementary system components

TM41 Terminal Module

### Integration

The TM41 Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Connection example of TM41 Terminal Module

Supplementary system components

#### TM54F Terminal Module

### Overview



The TM54F Terminal Module is a dual-processor I/O interface with four fail-safe digital outputs and ten fail-safe digital inputs for utilization of the Safety Integrated functions of the SINAMICS S120 drive system via external actuators and sensors.

Every available safety function integrated in the drive can be controlled via the fail-safe digital inputs on the TM54F Terminal Module. In the event that the parameterized safety functions of several drives operated together on a Control Unit are to be executed together, then these drives can be grouped in the TM54F Terminal Module. The advantage of this approach is that only one fail-safe digital input needs to be connected for these drives.

The fail-safe digital inputs and outputs have two channels and are redundantly configured with an internal data cross-check using the two processors. A fail-safe digital output consists of one P-switching and one M-switching output as well as one digital input to read back the switching state. A fail-safe digital input consists of two digital inputs.

Safety sensors can be connected over two switchable 24 V sensor supplies and can be evaluated over the fail-safe digital inputs. The switchable 24 V sensor supply ensures that the fail-safe digital inputs can be dynamized to detect dormant errors (this dynamization is used to check the shutdown paths). An unswitchable 24 V sensor supply is additionally provided by the TM54F Terminal Module for connecting undynamizable safety sensors.

The TM54F Terminal Module must be directly connected to a Control Unit via a DRIVE-CLiQ cable. Only one TM54F Terminal Module can be assigned to each Control Unit. It is not permissible to make the TM54F connection via another DRIVE-CLiQ device, e.g. a Motor Module or a Line Module.

### Design

The following are located on the TM54F Terminal Module:

- 4 fail-safe digital outputs
- 10 fail-safe digital inputs
- 4 LEDs, single color for indicating the status of the read back channel of the fail-safe digital outputs
- 4 LEDs, dual-color for indicating the status of the fail-safe digital outputs
- 20 LEDs, dual-color for indicating the status of the fail-safe digital inputs
- 3 LEDs, single color for indicating the status of the 24 V sensor supplies
- 2 DRIVE-CLiQ sockets
- 2 connections for 24 V sensor supply, switchable
- 1 connection for 24 V sensor supply, not switchable
- 1 connection for the electronics power supply via the 24 V DC power supply connector
- 1 connection for the 24 V power supply to digital outputs and sensors
- 1 PE connection

The status of the TM54F Terminal Module is indicated via a multi-color LED.

The TM54F Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

The signal cable shield can be attached to the TM54F Terminal Module via a shield connection terminal, e.g. type SK8 supplied by Phoenix Contact or type KLBÜ CO 1 supplied by Weidmüller. The shield connection terminal must not be used as a strain relief mechanism.

Pins for connector coding are included in the TM54F Terminal Module scope of supply.

#### Selection and ordering data

Description	Article No.
TM54F Terminal Module Without DRIVE-CLiQ cable	6SL3055-0AA00-3BA0
Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0
For DRIVE-CLIQ port	

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the TM54F Terminal Module can be ordered as an option by specifying order code **K87**.

Supplementary system components

TM54F Terminal Module

# Technical specifications

TM54F Terminal Module 6SL3055-0AA00-3BA0	
Current requirement (X524 at 24 V DC) without DRIVE-CLiQ supply	0.2 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
Max. current requirement ext. 24 V for supplying the digital outputs and 24 V sensor supply (X514 at 24 V DC)	4 A
<ul> <li>Conductor cross-section, max.</li> </ul>	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
I/O	
<ul> <li>Number of fail-safe digital inputs</li> </ul>	10
<ul> <li>Number of fail-safe digital outputs</li> </ul>	4
24 V sensor supply	3, of which 2 can be temporarily shut down using an internal test routine for dynamizing fail-safe digital inputs, current carrying capacity 0.5 A each
<ul><li>Cables and connections</li><li>Conductor cross-section, max.</li></ul>	Plug-in screw-type terminals 1.5 mm <sup>2</sup>
<b>Digital inputs</b> in accordance with IEC 61131-2 Type 1, with galvanic isolation	
Voltage	-3 +30 V
<ul> <li>Low level         <ul> <li>(an open digital input is interpreted as "low")</li> </ul> </li> </ul>	-3 +5 V
High level	15 30 V
<ul> <li>Current consumption at 24 V DC, typ.</li> </ul>	>3.2 mA
• Delay time of digital inputs, approx.	
- $L \rightarrow H$ , typ.	30 µs
- $H \rightarrow L$ , typ.	60 µs
Safe state	Low level (for inputs that can be inverted: without inversion)
Digital outputs sustained-short-circuit-proof	
Voltage	24 V DC
<ul> <li>Load current per fail-safe digital output, max.<sup>2)</sup></li> </ul>	0.5 A
<ul> <li>Delay times (resistive load) <sup>1)</sup></li> </ul>	
- L $\rightarrow$ H, typ.	300 µs
- $H \rightarrow L$ , typ.	350 µs
Safe state	Output switched off

TM54F Terminal Module	
6SL3055-0AA00-3BA0 Scanning cycle t <sub>SI</sub> for fail-safe digital inputs or fail-safe digital outputs	4 25 ms (adjustable)
Power loss, max.	4.5 W at 24 V
PE connection	M4 screw
Dimensions	
• Width	50 mm
• Height	151 mm
• Depth	110 mm
Weight, approx.	0.9 kg
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1

<sup>1)</sup> The specified delay times refer to the hardware. The actual reaction time depends on the time slot in which the digital input/output is processed.

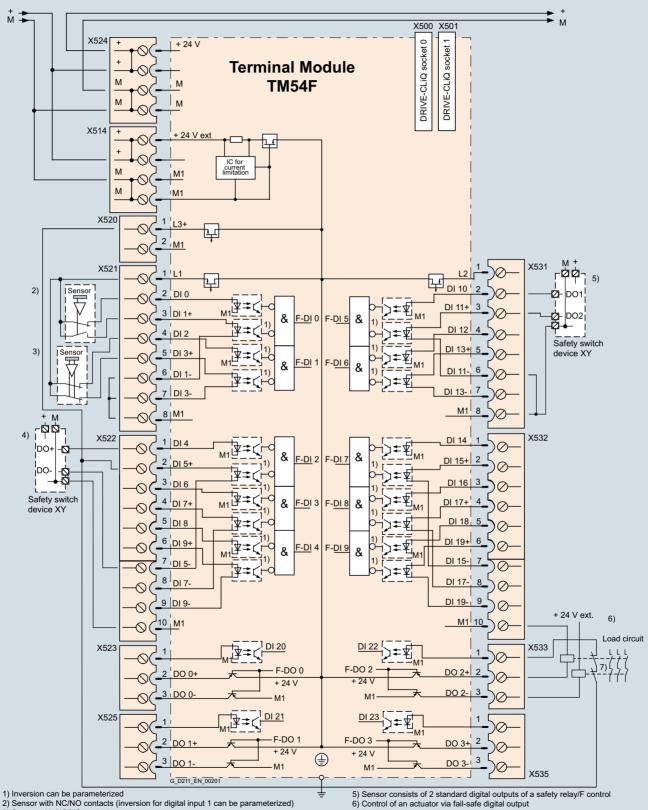
<sup>2)</sup> The total current of all fail-safe digital outputs must not exceed 5.33 A.

Supplementary system components

#### **TM54F Terminal Module**

### Integration

The TM54F Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



3) Sensor with NC/NC contacts

4) Sensor is a fail-safe digital output of a safety relay/F control

7) Positively-driven auxiliary contacts

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Supplementary system components

#### TM120 Terminal Module

### Overview



Four temperature sensors can be evaluated via the TM120 Terminal Module. The temperature sensor inputs are safely electrically isolated from the evaluation electronics in the TM120 Terminal Module and are suitable for evaluating the temperature of special motors, e.g. SIMOTICS L-1FN linear motors and SIMOTICS T-1FW6 built-in torque motors.

#### Design

The following are located on the TM120 Terminal Module:

- 4 temperature sensor inputs for KTY84-130, Pt1000 or PTC (Pt1000 can be used from firmware V4.7 HF17)
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the TM120 Terminal Module is indicated via a multi-color LED.

The TM120 Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

Selection and ordering data
-----------------------------

Description	Article No.
TM120 Terminal Module Without DRIVE-CLiQ cable	6SL3055-0AA00-3KA0
Accessories for re-ordering	
Dust protection blanking plugs (50 units) For DRIVE-CLiQ port	6SL3066-4CA00-0AA0

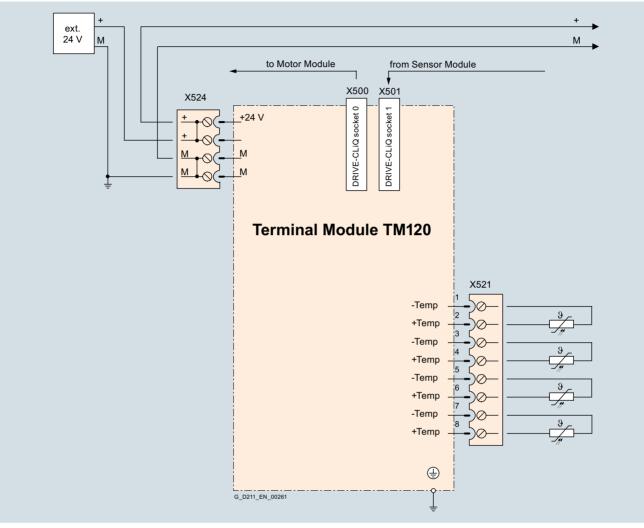
TM120 Terminal Module 6SL3055-0AA00-3KA0	
Current requirement, max. at 24 V DC	0.5 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
Temperature sensor inputs	
The inputs can be individually parameter- ized to evaluate sensors of type KTY84-130, Pt1000, PTC or temperature switches	
<ul> <li>Conductor cross-section</li> </ul>	0.2 6 mm <sup>2</sup>
Constant current per sensor, approx.	2 mA
<ul> <li>Safe electrical separation up to line voltage, max.</li> </ul>	480 V AC
Power loss, typically	2.4 W
PE connection	M4 screw
Dimensions	
Width	30 mm
• Height	150 mm
• Depth	111 mm
Weight, approx.	0.41 kg

Supplementary system components

### TM120 Terminal Module

### Integration

The TM120 Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Example connection of TM120 Terminal Module

Supplementary system components

TM150 Terminal Module

#### Overview



The TM150 Terminal Module is a DRIVE-CLiQ component for temperature evaluation. The temperature is measured in a temperature range from -99 °C to +250 °C for the following temperature sensors:

- Pt100 (with monitoring for wire breakage and short-circuit)
- Pt1000 (with monitoring for wire breakage and short-circuit, can be used from firmware V4.7 HF17)
- KTY84 (with monitoring for wire breakage and short-circuit)
- PTC (with short-circuit monitoring)
- Bimetallic NC contact (without monitoring)

For the temperature sensor inputs, for each terminal block the evaluation can be parameterized for  $1\times 2$ -wire,  $2\times 2$ -wire, 3-wire or 4-wire. There is no galvanic isolation in the TM150 Terminal Module.

The temperature channels of a TM150 can be subdivided into 3 groups and evaluated together.

#### Design

The following are located on the TM150 Terminal Module:

- 6 ... 12 temperature sensor inputs
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the TM150 Terminal Module is indicated via a multi-color LED.

The TM150 Terminal Module can be snapped onto a TH 35 standard mounting rail in accordance with EN 60715 (IEC 60715).

#### Selection and ordering data

<b>Dust protection blanking plugs</b> (50 units)	6SL3066-4CA00-0AA0
Accessories for re-ordering	
Without DRIVE-CLiQ cable	
TM150 Terminal Module	6SL3055-0AA00-3LA0
Description	Article No.

For DRIVE-CLiQ port

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the TM150 Terminal Module can be ordered as an option by specifying order code **G51** or **G51 to G54**.

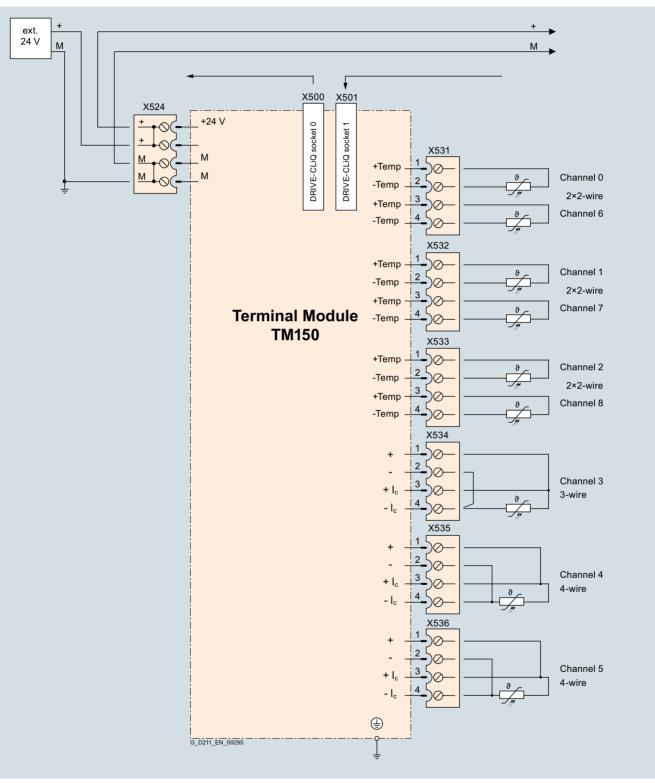
TM150 Terminal Module 6SL3055-0AA00-3LA0	
Current requirement, max. at 24 V DC	0.5 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
<ul> <li>Fuse protection, max.</li> </ul>	20 A
Temperature sensor inputs The inputs can be parameterized individually for the evaluation of sensors	
Conductor cross-section, max.	1.5 mm <sup>2</sup>
Measuring current per sensor, approx.	0.8 mA
Power loss	1.6 W
PE connection	M4 screw
Dimensions	
• Width	30 mm
Height	150 mm
• Depth	111 mm
Weight, approx.	0.41 kg

Supplementary system components

#### TM150 Terminal Module

### Integration

The TM150 Terminal Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Connection example of TM150 Terminal Module

3

Supplementary system components

VSM10 Voltage Sensing Module

#### Overview



The VSM10 Voltage Sensing Module enables the line or motor voltage characteristic to be measured precisely. The phase differential voltage can be measured, either grounded (in the delivery state with jumper plugged in) or isolated. The VSM10 Voltage Sensing Module is integrated in Active Interface Modules in chassis format and Smart Line Modules in chassis format.

In addition, the VSM10 is used to connect to rotating synchronous motors – or for a "quick flying restart" of rotating induction motors.

#### Design

The VSM10 Voltage Sensing Module has the following connections and interfaces:

- 1 connection for direct voltage sensing up to 690 V
- 1 connection for voltage sensing using voltage transformers, max. 100 V
- 2 analog inputs (reserved for monitoring of resonance in the Active Interface Module in chassis format)
- 1 temperature sensor input for KTY84-130, Pt1000 or PTC (Pt1000 can be used from firmware V4.7 HF17)
- 1 DRIVE-CLiQ socket
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 plug-in jumper for either grounded (delivery state) or isolated measurement
- 1 PE connection

The status of the VSM10 Voltage Sensing Module is indicated via a dual-color LED.

The VSM10 Voltage Sensing Module can be snapped onto a TH 35 DIN rail in accordance with EN 60715 (IEC 60715).

### Selection and ordering data

Description	Article No.
VSM10 Voltage Sensing Module	6SL3053-0AA00-3AA1
Without DRIVE-CLiQ cable	
Accessories for re-ordering	
Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0

For SINAMICS S150 and SINAMICS S120 Cabinet Modules, to implement the flying restart function, VSM10 can be ordered as an option with order code **K51**.

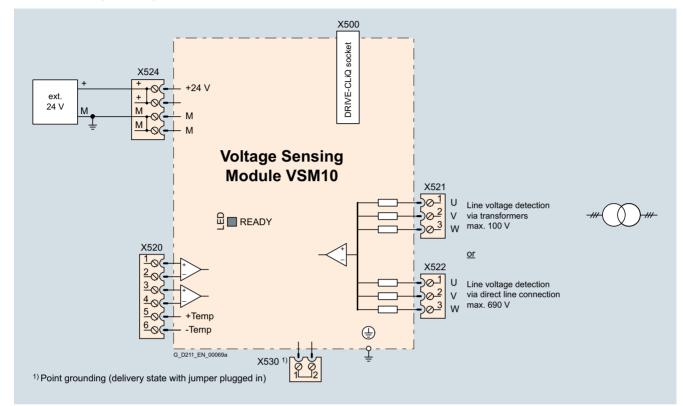
VSM10 Voltage Sensing Module 6SL3053-0AA00-3AA1	
Power requirement, max. at 24 V DC	0.2 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Power loss, max.	10 W
Line voltage detection	
<ul> <li>Insulation resistance neutral point – ground when jumper is not inserted</li> </ul>	>10 MΩ
Input resistance	
- Terminal X521	>362 k $\Omega$ /phase
- Terminal X522	>2.5 M $\Omega$ /phase
Analog inputs (reserved for monitoring an Active Interface Module in chassis format)	
<ul> <li>Internal resistance, approx. (between differential inputs)</li> </ul>	100 kΩ
Resolution	12 bits + sign
PE connection	M4 screw
Dimensions	
• Width	50 mm
• Height	150 mm
• Depth	111 mm
Weight, approx.	1 kg

Supplementary system components

### VSM10 Voltage Sensing Module

### Integration

The VSM10 Voltage Sensing Module communicates with the CU310-2 or CU320-2 Control Unit via DRIVE-CLiQ.



Connection example of a VSM10 Voltage Sensing Module

Supplementary system components

Safe Brake Adapter SBA

#### Overview



For SINAMICS S120, S150, G130 and G150 units, a Safe Brake Adapter SBA is required to safely control a motor holding brake via the Safe Brake Control (SBC) safety function according to IEC 61800-5-2.

The Safe Brake Adapter is available for a 230 V AC brake control voltage.

It can be ordered as supplementary component for SINAMICS S120 chassis format units as well as for SINAMICS G130 built-in units.

It is available as option (**K88**) for SINAMICS S120 Cabinet Modules and SINAMICS S150 or G150 cabinet units.

#### Note:

The SBA is approved for the IEC area. Safe Brake Adapter with UL approval are available on request. The UL approval is valid for a maximum permissible current consumption of 1.5 A (inductive).

#### Design

The Safe Brake Adapter SBA has the following connections and interfaces:

- 1 connection for the connecting cable to the Power Module/ Motor Module
- 1 connection for the external 230 V AC supply
- 1 connection for motor holding brake
- 1 connection for fast de-excitation

#### Selection and ordering data

Description	Article No.
Safe Brake Adapter 230 V AC/2 A	6SL3355-2DX00-1AA0
Accessories	

# Pre-assembled interface cable to connect 6SL3060-4DX04-0AA0 the SBA to the electronics module (4 m)

Technical specifications

Sate Brake Adapter
6SL3355-2DX00-1AA0

#### Electronics power supply

<ul> <li>Supply voltage (via the Control Interface Module)</li> </ul>	24 V DC (20.4 28.8 V DC)
Supply voltage of the motor holding brake	230 V AC
Current consumption, max perm. 1)	
<ul> <li>Motor holding brake</li> </ul>	2 A
<ul> <li>Fast de-energization</li> </ul>	2 A
Cable length, max.	
To the Control Interface Module	10 m
To the brake	300 m
Conductor cross-section	2.5 mm <sup>2</sup>
Dimensions	
Width	75 mm
• Height	111 mm
Depth	89 mm
Weight, approx.	0.25 kg
Safety Integrated	Safety Integrity Level 2 (SIL2) acc. to IEC 61508, Performance Level d (PLd) acc. to EN ISO 13849-1 and Control Category 3 acc. to EN ISO 13849-1

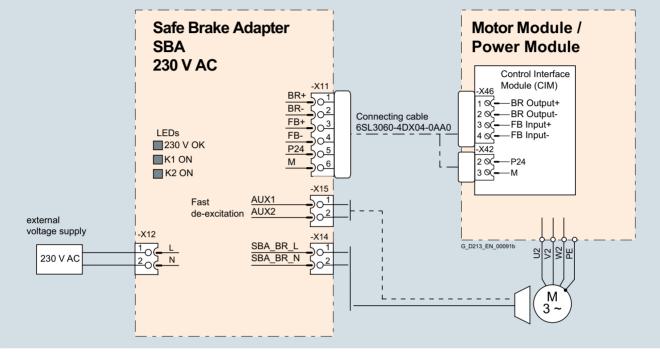
3

Supplementary system components

#### Safe Brake Adapter SBA

#### Integration

The control and feedback signal regarding the switching state of the SBA relay is implemented via terminals of the Control Interface Module (CIM) in the Motor Module/Power Module. The excitation coil of the holding brake is connected directly at the SBA. For SINAMICS S120, the brake supply voltage must be externally supplied at the SBA.



Connection example of a Safe Brake Adapter SBA

Encoder system connection

**Encoder system connection** 

### Overview

#### Motors without DRIVE-CLiQ interface

The encoder and temperature signals of motors without DRIVE-CLiQ interfaces, as well as those of external encoders, must be connected via Sensor Modules. Sensor Modules Cabinet-Mounted are available in degree of protection IP20 for control cabinet installation, as well as Sensor Modules External-Mounted in degree of protection IP67.

Only one encoder system can be connected to each Sensor Module.

### More information

Motor encoder and temperature signals must be connected to the corresponding Motor Module or Power Module and external encoders to the Control Unit. However, the DRIVE-CLiQ connections can also be bundled via DRIVE-CLiQ Hub Modules.

#### Safety Integrated

Suitable encoders are required in order to allow unrestricted use of Safety Integrated Extended Functions.

#### Belt-driven motor

Unfavorable material combinations generate static electricity between the belt pulley and the belt. Electrostatic charging must be prevented, since this can discharge via the motor shaft and the encoder, thereby causing disturbances in the encoder signals. One remedy is to use an anti-static belt.

Encoder system connection

### SMC10 Sensor Module Cabinet-Mounted

### Overview



The SMC10 Sensor Module Cabinet-Mounted is required to evaluate the encoder signals of motors without a DRIVE-CLiQ interface. External encoders can also be connected via the SMC10.

The following encoder signals can be evaluated:

- 2-pole resolver
- Multi-pole resolver

### Design

The SMC10 Sensor Module Cabinet-Mounted features the following connections and interfaces as standard:

- 1 encoder connection including motor temperature sensing (KTY84-130, Pt1000 or PTC) via SUB-D connector
- 1 DRIVE-CLiQ interface
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the SMC10 Sensor Module Cabinet-Mounted is indicated via a multi-color LED.

The SMC10 Sensor Module Cabinet-Mounted can be snapped onto a TH 35 standard mounting rail according to EN 60715 (IEC 60715).

The signal cable shield is connected via the encoder system connector and can also be connected to the SMC10 Sensor Module Cabinet-Mounted via a shield connection terminal, e.g. Phoenix Contact type SK8 or Weidmüller type KLBÜ CO 1. The shield connection terminal must not be used as a strain relief mechanism.

### Selection and ordering data

Description	Article No.
SMC10 Sensor Module Cabinet-Mounted Without DRIVE-CLiQ cable	6SL3055-0AA00-5AA3
Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the SMC10 Sensor Module Cabinet-Mounted can be ordered as an option by specifying order code  $\mathbf{K46}$ .

### Integration

SMC10 Sensor Modules Cabinet-Mounted communicate with a Control Unit via DRIVE-CLiQ.

#### Technical specifications

SMC10 Sensor Module Cabinet-Mounted 6SL3055-0AA00-5AA3	
<b>Current requirement, max.</b> at 24 V DC, without taking encoder into account	0.2 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
Fuse protection, max.	20 A
Power loss, max.	10 W
Encoders which can be evaluated	<ul><li> 2-pole resolvers</li><li> Multi-pole resolver</li></ul>
<ul> <li>Excitation voltage, rms</li> </ul>	4.1 V
Excitation frequency	5 16 kHz depending on the current controller clock cycle of the Motor Module or Power Module
Transformation ratio	0.5
Encoder frequency, max.	2 kHz (120000 rpm) depend- ing on the number of resolver pole pairs and current control- ler clock cycle of the Motor Module or Power Module
<ul> <li>Signal subdivision (interpolation), max.</li> </ul>	16384 times (14 bits)
<ul> <li>Cable length to encoder, max.</li> </ul>	130 m
PE connection	M4 screw
Dimensions	
• Width	30 mm
Height	150 mm
• Depth	111 mm
Weight, approx.	0.45 kg

Encoder system connection

SMC20 Sensor Module Cabinet-Mounted

### Overview



The SMC20 Sensor Module Cabinet-Mounted is required to evaluate the encoder signals of motors without a DRIVE-CLiQ interface. External encoders can also be connected via the SMC20.

The following encoder signals can be evaluated:

- Incremental encoder sin/cos 1 V<sub>pp</sub>
- Absolute encoder EnDat 2.1
- SSI encoder with incremental signals sin/cos 1 V<sub>pp</sub> (firmware version 2.4 and later)

The motor temperature can also be sensed using a PTC thermistor KTY84-130, Pt1000 or PTC.

### Design

The SMC20 Sensor Module Cabinet-Mounted features the following connections and interfaces as standard:

- 1 encoder connection including motor temperature sensing (KTY84-130, Pt1000 or PTC) via SUB-D connector
- 1 DRIVE-CLiQ interface
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the SMC20 Sensor Module Cabinet-Mounted is indicated via a multi-color LED.

The SMC20 Sensor Module Cabinet-Mounted can be snapped onto a TH 35 standard mounting rail according to EN 60715 (IEC 60715).

The signal cable shield is connected via the encoder system connector and can also be connected to the SMC20 Sensor Module Cabinet-Mounted via a shield connection terminal, e.g. Phoenix Contact type SK8 or Weidmüller type KLBÜ CO 1. The shield connection terminal must not be used as a strain relief mechanism.

# Selection and ordering data

Description	Article No.
SMC20 Sensor Module Cabinet-Mounted	6SL3055-0AA00-5BA3
Without DRIVE-CLiQ cable Accessories for re-ordering	
Dust protection blanking plugs (50 units)	6SL3066-4CA00-0AA0
For DRIVE-CLiQ port	

For the SINAMICS S150 and SINAMICS S120 Cabinet Modules, the SMC20 Sensor Module Cabinet-Mounted can be ordered as an option by specifying order code **K48**.

### Integration

SMC20 Sensor Modules Cabinet-Mounted communicate with a Control Unit via DRIVE-CLiQ.

#### Technical specifications

SMC20 Sensor Module Cabinet-Mounted 6SL3055-0AA00-5BA3	
<b>Current requirement, max.</b> at 24 V DC, without taking encoder into account	0.2 A
Conductor cross-section, max.	2.5 mm <sup>2</sup>
• Fuse protection, max.	20 A
Power loss, max.	10 W
Encoders which can be evaluated	<ul> <li>Incremental encoder sin/cos 1 V<sub>pp</sub></li> </ul>
	Absolute encoder EnDat 2.1
	<ul> <li>SSI encoder with incremental signals sin/cos 1 V<sub>pp</sub> (firm- ware version 2.4 and later)</li> </ul>
Encoder supply	5 V DC/0.35 A
<ul> <li>Encoder frequency incremental signals, max.</li> </ul>	500 kHz
<ul> <li>Signal subdivision (interpolation), max.</li> </ul>	16384 times (14 bits)
SSI baud rate	100 1000 kBaud
Cable length to encoder, max.	100 m
PE connection	M4 screw
Dimensions	
• Width	30 mm
• Height	150 mm
• Depth	111 mm
Weight, approx.	0.45 kg

Encoder system connection

### SMC30 Sensor Module Cabinet-Mounted

### Overview



The SMC30 Sensor Module Cabinet-Mounted is required to evaluate the encoder signals of motors without a DRIVE-CLiQ interface. External encoders can also be connected via the SMC30.

The following encoder signals can be evaluated:

- Incremental encoders TTL/HTL with/without open-circuit detection (open-circuit detection is only available with bipolar signals)
- SSI encoder with TTL/HTL incremental signals
- SSI encoder without incremental signals

The motor temperature can also be sensed using a PTC thermistor KTY84-130, Pt1000 or PTC.

#### Design

The SMC30 Sensor Module Cabinet-Mounted features the following connections and interfaces as standard:

- 1 encoder connection including motor temperature sensing (KTY84-130, Pt1000 or PTC) either via SUB-D connector or via terminals
- 1 DRIVE-CLiQ interface
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

The status of the SMC30 Sensor Module Cabinet-Mounted is indicated using a multi-color LED.

The SMC30 Sensor Module Cabinet-Mounted can be snapped onto a TH 35 standard mounting rail according to EN 60715 (IEC 60715).

The maximum encoder cable length between SMC30 modules and encoders is 100 m. For HTL encoders, this length can be increased to 300 m if the A+/A- and B+/B- signals are evaluated and the power supply cable has a minimum cross-section of  $0.5 \, \text{mm}^2$ 

The signal cable shield can be connected to the SMC30 Sensor Module Cabinet-Mounted via a shield connection terminal, e.g., Phoenix Contact type SK8 or Weidmüller type KLBÜ CO 1. The shield connection terminal must not be used as a strain relief mechanism.

### Selection and ordering data

Description	Article No.
SMC30 Sensor Module Cabinet-Mounted	6SL3055-0AA00-5CA2
Without DRIVE-CLiQ cable	
Accessories for re-ordering	
Dust protection blanking plugs (50 units) For DRIVE-CLiQ port	6SL3066-4CA00-0AA0
Ear the CINIANICC C150 and CIN	JAMICS S120 Cabinet Modules

the SMC30 Sensor Module Cabinet-Mounted can be ordered as an option by specifying order code K50.

#### Integration

SMC30 Sensor Modules Cabinet-Mounted communicate with a Control Unit via DRIVE-CLiQ.

SMC30 Sensor Module Cabinet-Mou 6SL3055-0AA00-5CA2	unted		
Current requirement, max.	0.2 A		
at 24 V DC, without taking encoder into account			
<ul> <li>Conductor cross-section, max.</li> </ul>	2.5 mm <sup>2</sup>		
<ul> <li>Fuse protection, max.</li> </ul>	20 A		
Power loss, max.	10 W		
Encoders which can be evaluated	Incremental encoder TTL/HTL		
	<ul> <li>SSI encoder with TTL/HTL incremental signals</li> </ul>		
	<ul> <li>SSI encoder without incremental signals</li> </ul>		
<ul> <li>Input current range TTL/HTL</li> </ul>	4 20 mA (typ. 10 mA)		
Encoder supply	24 V DC/0.35 A or 5 V DC/0.35 A		
<ul> <li>Encoder frequency, max.</li> </ul>	300 kHz		
SSI baud rate	100 1000 kBaud		
<ul> <li>Limiting frequency</li> </ul>	300 kHz		
<ul> <li>Resolution absolute position SSI</li> </ul>	30 bit		
Cable length, max.			
- TTL encoder	100 m (only bipolar signals permitted) <sup>1)</sup>		
- HTL encoder	100 m for unipolar signals 300 m for bipolar signals <sup>1)</sup>		
- SSI encoder	100 m		
PE connection	M4 screw		
Dimensions			
• Width	30 mm		
Height	150 mm		
• Depth	111 mm		
Weight, approx.	0.45 kg		

Connection system

### Signal cables

### Overview



MOTION-CONNECT DRIVE-CLiQ signal cable with IP20/IP67 connector

Signal cables are required for the DRIVE-CLiQ connection between different components. Signal cables are pre-assembled and are sold by the meter. The following signal cables are available:

- DRIVE-CLiQ signal cables
- MOTION-CONNECT DRIVE-CLiQ signal cables
- MOTION-CONNECT pre-assembled signal cables

Type of delivery for pre-assembled signal cables

Pre-assembled signal cables are available in units of 10 cm.

The cables are supplied on reels up to 30 kg or 100 m. Above 30 kg or 100 m, cable drums are used instead of reels.

# Application

### DRIVE-CLiQ signal cables without 24 V DC cores

are used to connect components with DRIVE-CLiQ connections which have a separate or external 24 V DC power supply.

#### MOTION-CONNECT DRIVE-CLiQ signal cables with 24 V DC cores

are used whenever components with DRIVE-CLiQ connections must meet high requirements such as mechanical stress and oil resistance, e.g. where a connection is made outside the control cabinet between

- Motor Modules and Sensor Modules
- Power Modules/Motor Modules and motors with DRIVE-CLiQ interface
- Motor Modules and direct measuring systems with DRIVE-CLiQ interface (incl. non-Siemens measuring systems)

#### MOTION-CONNECT pre-assembled signal cables

are used whenever motor encoders on motors without DRIVE-CLiQ interface are connected to Sensor Modules.

# Design

If pre-assembled signal cables are to be installed in a cable carrier in such a way that the connector would inhibit assembly, pre-assembled cables without assembled connector can also be supplied. In this case, the contacts of the cables are crimped and the connector housing is supplied separately. After installing the cables, the customer assembles the connector housing.

The 6FX.002-2....- signal cables are available with crimped contacts and with the connector housing supplied separately (not in the case of DRIVE-CLiQ signal cables and signal cables with exposed conductor ends).

Signal cables with **module-side** connector housing supplied as a separate accessory: In this case, the 6th position of the Article No. must be changed from **0** to **1**:

6FX.012-2C...-.... (not for signal cables for connecting via terminals or 6FX.002-2AH00-...., 6FX.002-2CA12-....).

Signal cables with **motor-side** connector housing supplied as a separate accessory. In this case, the 6th position of the Article No. must be changed from **0** to **4**:

6FX.042-2C...-... (not for signal cables for connecting via terminals or 6FX8002-2BA20-...., 6FX8002-2BA21-....).

### Note:

Once the contacts have latched into the insulator, they can no longer be removed.

Connection system

# Signal cables

# Selection and ordering data

Signal cable	Length	Connector/degree of protection module-side	Connector/degree of protection motor-side	Basic cable
				Article No.
Pre-assembled DRIVE-CLiQ signa	I cables (without 24 V DC	cores)		
Fixed lengths	0.11 m	RJ45/IP20	RJ45/IP20	6SL3060-4AB00-0AA0
	0.16 m			6SL3060-4AD00-0AA0
	0.21 m			6SL3060-4AF00-0AA0
	0.26 m			6SL3060-4AH00-0AA0
	0.31 m			6SL3060-4AK00-0AA0
	0.36 m			6SL3060-4AM00-0AA0
	0.41 m			6SL3060-4AP00-0AA0
	0.60 m			6SL3060-4AU00-0AA0
	0.95 m			6SL3060-4AA10-0AA0
	1.20 m			6SL3060-4AW00-0AA0
	1.45 m			6SL3060-4AF10-0AA0
	2.10 m			6SL3060-4AB20-0AA0
	2.80 m			6SL3060-4AJ20-0AA0
	5.00 m			6SL3060-4AA50-0AA0
To the decimeter	Max. 70 m	RJ45/IP20	RJ45/IP20	6FX2002-1DC00
	Max. 70 m	RJ45/IP67	RJ45/IP67	6FX2002-1DC20
DRIVE-CLIQ MOTION-CONNECT 5	00 signal cables (with 24 \	V DC cores)		
To the decimeter	Max. 100 m	RJ45/IP20	RJ45/IP20	6FX5002-2DC00
	Max. 100 m	RJ45/IP20	RJ45/IP67	6FX5002-2DC10
	Max. 100 m	RJ45/IP67	RJ45/IP67	6FX5002-2DC20
DRIVE-CLIQ MOTION-CONNECT 8	00PLUS signal cables (wit	th 24 V DC cores)		
To the decimeter	Max. 75 m	RJ45/IP20	RJ45/IP20	6FX8002-2DC00
	Max. 75 m	RJ45/IP20	RJ45/IP67	6FX8002-2DC10
	Max. 75 m	RJ45/IP67	RJ45/IP67	6FX8002-2DC20

Connection system

Signal cables

-					
Description	Article No. supplement				
Length codes for pre-assembled cables					
	6FX.0.2				
0 m		1			
100 m		2			
200 m		3			
0 m			Α		
10 m			в		
20 m			С		
30 m			D		
40 m			Е		
50 m			F		
60 m			G		
70 m			н		
80 m			J		
90 m			к		
0 m				Α	
1 m				в	
2 m				С	
3 m				D	
4 m				Е	
5 m				F	
6 m				G	
7 m				н	
8 m				J	
9 m				к	
0 m					0
0.1 m					1
0.2 m					2
0.3 m					3
0.4 m					4
0.5 m					5
0.6 m					6
0.7 m					7
0.8 m					8
Examples:	1.0 m	1	А	В	0
	2.2 m	1	А	С	2
	8.0 m	1	А	J	0
	299.0 m	3	Κ	Κ	0

Selection and ordering data (continued)

Length codes

Description	Article No. supplement			
Length codes for power/signal cables available by the meter <sup>1)</sup>				
	6FX.008		Α	0
50 m	1	F		
100 m	2	Α		
200 m	3	Α		
500 m	6	Α		

For further information on DRIVE-CLiQ signal cables, see section MOTION-CONNECT connection system in Catalog D 21.4 as well as in the Industry Mall.

More information

- Further information is available:
- Catalog D21.4 (SINAMICS S120 and SIMOTICS)
- Interactive Catalog CA 01
- Internet
  - www.siemens.com/motion-connect
  - www.siemens.com/industrymall

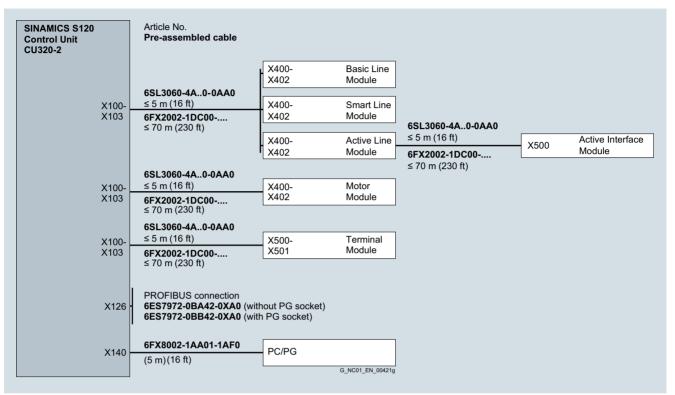
 $^{1)}$  Note type of delivery. Cables with core cross-section 4 x 4  $m^2$  or 4 x 4  $m^2$  with brake cores can be delivered in units of 1 m.

Connection system

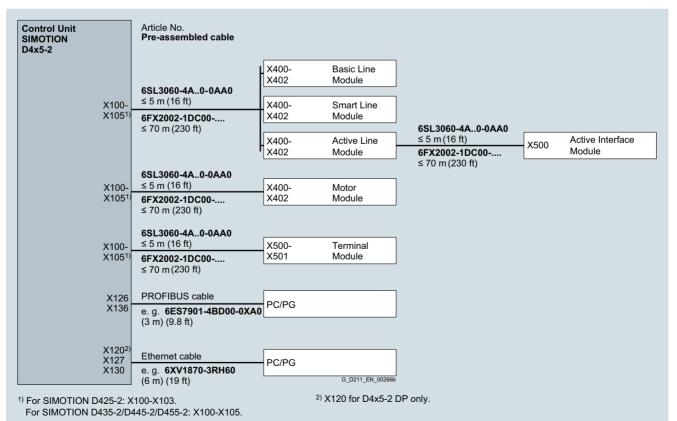
### **Signal cables**

### Integration

Connection overview for the CU320-2 Control Unit



#### SIMOTION D4x5-2 Control Unit connection overview



3

Connection system

Signal cables

# Integration (continued)

### **Connection overview for Line Modules and Motor Modules**

The DRIVE-CLiQ type 6SL3060-4A..0-0AA0 cables for the standard configuration are part of the scope of supply of the Line Modules and Motor Modules. In this case, the modules must be mounted directly adjacent in a line.

SINAMICS S120 Motor Module Chassis format		Article No. Pre-assembled cable	X400- X402	Basic Line Module			
			X400- X402	Smart Line Module	6SL3060-4A0-0AA0		
		6SL3060-4A0-0AA0	X400- X402	Active Line Module	≤ 5 m (16 ft) 6FX2002-1DC00	X500	Active Interface Module
	X400- X402	≤ 5 m (16 ft) 6FX2002-1DC00	X100- X103	Control Unit CU320-2	≤ 70 m (230 ft)		
		≤ 70 m (230 ft)	X100- X103	Control Unit SIMOTION CX32-2			
Motor encoder			X100- X105 <sup>1)</sup>	Control Unit SIMOTION D4x5-2	6SL3060-4A0-0AA0		
interface via SMC			X400- X402	Motor Module	≤ 5 m (16 ft) 6FX2002-1DC00	X400- X402	Motor Module
(Sensor Module Cabinet-Mounted) for motors without					≤ 70 m (230 ft)		
DRIVE-CLiQ interface	X400-	<b>6SL3060-4A0-0AA0</b> ≤ 5 m (16 ft)				- X500	SMC10 <sup>2)</sup>
	X402	<b>6FX2002-1DC00</b> ≤ 70 m (230 ft)				X500	SMC20 <sup>2)</sup>
Motor encoder interface for motors with		2 70 m (200 k)				<b>X</b> 500	SMC30 <sup>2)</sup>
DRIVE-CLiQ interface	X400-	<b>6FX5002- 2DC10-</b> ≤ 100 m (328 ft)					ncoder with iQ interface 5.D
	X402	<b>6FX8002- 2DC10</b> ≤ 75 m (246 ft)					oder in SIMOTICS n DRIVE-CLiQ
Motor	U2 V2	Pre-assembled power ca				Motors	
connection	W2	(max. cable length, see teo	cnnical specifica	ations of Motor Modu	ies)		G_D211_EN_00037

<sup>1)</sup> For SIMOTION D425-2: X100-X103 For SIMOTION D435-2/D445-2/D455-2: X100-X105

<sup>2)</sup> See connection overviews SMC10/SMC20/SMC30

Connection system

# Signal cables

# **Integration** (continued)

# **Connection overview for Power Modules**

A DRIVE-CLiQ cable of type 6SL3060-4A..0-0AA0 for connection to the chassis-mounted CU310-2 Control Unit is already included in the scope of supply.

J1/L1 /1/L2 - V1/L3		X100 SINAMICS S120 Control Unit CU310-2
/1/L2		X100 SINAMICS S120
	Power supply cables, see power cables for motors (by the meter)	X103 Control Unit CU320-2
		X100 Control Unit SIMOTION D410-2
400- 402	6SL3060-4A0-0AA0 ≤ 5 m (16 ft) 6FX2002-1DC00 € 70 m (200 ft)	X100- X105 <sup>1)</sup> SIMOTION D4x5-2
	≤ 70 m (230 ft)	X100- X103 X103 CX32-2
		X500- X501 Terminal Module
		X400- X402 Power Module
	6SL3060-4A0-0AA0	×500 SMC10 <sup>2)</sup>
X402	6FX2002-1DC00	X500 SMC20 <sup>2)</sup>
	≤ 70 m (230 ft)	X500 SMC30 <sup>2)</sup>
X402 -	6FX5002-2DC10 ≤ 100 m (328 ft)	Absolute encoder with DRIVE-CLiQ interface 6FX2001-5.D
	<b>6FX8002-2DC10</b> ≤ 75 m (246 ft)	Motor encoder for SIMOTICS motors with DRIVE-CLiQ interface
U2 V2 W2	Pre-assembled power cables, see power cables for motors (max. cable length, see technical specifications of Motor Modules)	Motors
_	<pre>&lt;402 - U2 V2 -</pre>	$(402  \frac{6SL3060-4A0-0AA0}{\leq 5 \text{ m (16 ft)}}$ $(402  \frac{6FX2002-1DC00}{\leq 70 \text{ m (230 ft)}}$ $(402  \frac{6FX5002-2DC10}{\leq 100 \text{ m (328 ft)}}$ $(402  \frac{6FX8002-2DC10}{\leq 75 \text{ m (246 ft)}}$ $\frac{U2}{V2}  \frac{\text{Pre-assembled power cables, see power cables for motors}{(\text{max cable length, see technical specifications of Motor Modules)}}$

<sup>1)</sup> For SIMOTION D425-2: X100-X103 For SIMOTION D435-2/D445-2/D455-2: X100-X10<sup>5</sup>

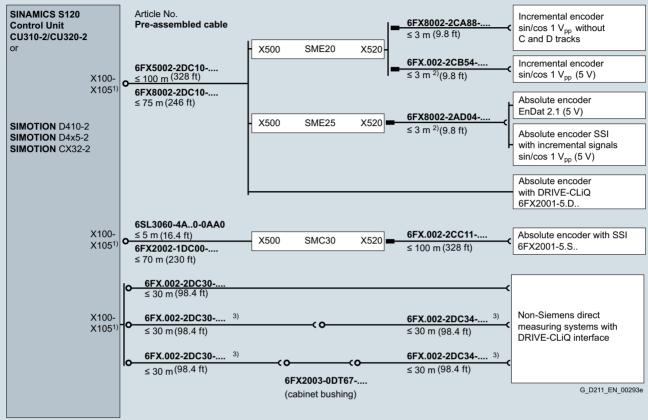
<sup>2)</sup>See connection overviews SMC10/SMC20/SMC30

Connection system

Signal cables

# Integration (continued)

Connection of a machine encoder (direct measuring system)



<sup>1)</sup> For Control Unit CU310-2/SIMOTION D410-2: X100

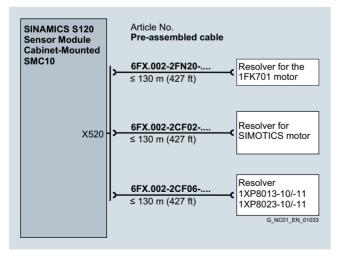
For Control Unit CU320-2/SIMOTION D425-2/SIMOTION CX32-2: X100-X103

For SIMOTION D435-2/D445-2/D455-2: X100-X105

<sup>2)</sup> Up to 10 m (32.8 ft) possible, dependent on encoder current consumption.

<sup>3)</sup> The total cable length (basic cable and extension cable) must not exceed 30 m (98.4 ft).

#### Connection overview of SINAMICS S120 Sensor Module Cabinet Mounted SMC10



Connection system

### Signal cables

# Integration (continued)

Connection overview of SINAMICS S120 Sensor Module Cabinet-Mounted SMC20

SINAMICS S120 Sensor Module Cabinet-Mounted	Article No. <b>Pre-assembled cable</b>	
SMC20	6FX.002-2CN20 ≤ 50 m (164 ft)	Incremental encoder sin/cos 1 V <sub>pp</sub> in 1FK701 motor
	<b>6FX.002-2CQ31</b> ≤ 100 m (328 ft)	Incremental encoder sin/cos 1 V <sub>pp</sub> with C/D tracks in 1FT7 motor
	<b>6FX.002-2CA31</b> ≤ 100 m (328 ft)	Incremental encoder sin/cos 1 V <sub>pp</sub> with C/D tracks in 1FT7/1FK7/1PH8/ 1FW3 motors <sup>1)</sup>
	<b>6FX8002-2CQ80</b> ≤ 50 m (164 ft)	Incremental encoder sin/cos 1 V <sub>pp</sub> without C/D tracks in 1PH8 motor <sup>2)</sup>
	→ 6FX8002-2CA80 ≤ 50 m (164 ft)	Incremental encoder sin/cos 1 V <sub>pp</sub> without C/D tracks in 1PH8 motor <sup>3)</sup>
X520	6FX.002-2CG00	Incremental encoder sin/cos 1 V <sub>pp</sub> 6FX2001-3
	Adapter cable <sup>4)</sup>	Direct linear increm. encoder sin/cos 1 V <sub>pp</sub> LS 187(C)/LF 183(C) LB 382(C) LS 487(C)/LF 481(C)
	6FX.002-2EN20 ≤ 50 m (164 ft)	Absolute encoder with EnDat 2.1 in 1FK701 motor
	> 6FX.002-2EQ31 ≤ 100 m (328 ft)	Absolute encoder with EnDat 2.1 in 1FT7/ 1PH8 <sup>5)</sup> motors
	> 6FX.002-2EQ10 ≤ 100 m (328 ft)	Absolute encoder with EnDat 2.1 in 1FK7/1PH8/1FW3 motors <sup>1)</sup>
	Adapter cable <sup>4)</sup>	Direct linear absolute encoder EnDat 2.1 LC 183/LC 483
		Absolute encoder with EnDat 2.1 6FX2001-5.E.
	6FX.002-2CH00	Absolute encoder with EnDat 2.1 1XP8014-10 1XP8024-10

1) 1FW3 motor not suitable for machine tools.
 2) Possible for 1PH808/1PH810/1PH813/1PH816 motors for encoders with 512 S/R and 256 S/R.

 $^{3)}$  Possible for 1PH8 motors for encoders with 512 S/R and 256 S/R.

<sup>4)</sup> Adapter cable available from measuring system manufacturer.

<sup>5)</sup> Possible for 1PH808/1PH810/1PH813/1PH816 motors.

SINAMICS S120 Sensor Module Cabinet-Mounted	Article No. <b>Pre-assembled cable</b>	
SMC30	<b>6FX.002-2CC11</b> ≤ 100 m (328 ft)	Absolute encoder with SSI (24 V DC) 6FX2001-5.S.
	<b>6FX.002-2CC06</b> ≤ 100 m (328 ft)	Absolute encoder with SSI (24 V DC) 1XP8014-20 1XP8024-20/-21 <sup>1)</sup>
X520	- 6FX.002-2CR00	Incremental encoder TTL RS 422 (5 V DC) 6FX2001-2
	≤ 100 m (328 ft)	Incremental encoder TTL RS 422 (5 V DC) 1XP8012-20/-21/-22 1XP8032-20/-21/-22
	<b>6FX.002-2CD24</b> ≤ 100 m (328 ft)	Incremental encoder TTL RS 422 (24 V DC) 6FX2001-2
	6FX5002-2CA12	Incremental encoder HTL (24 V DC) 6FX2001-4
X521 X531	OF A SU02-2CA 12  ≤ 100 m (328 ft)	Incremental encoder HTL (24 V DC) 1XP8012-10/-11 1XP8032-10/-11/-12
	6FX.002-2AH00 ≤ 300 m <sup>2</sup> ) (984 ft)	Incremental encoder HTL in 1PH8 motor G_D211_EN_00269d

#### Connection overview of SINAMICS S120 Sensor Module Cabinet-Mounted SMC30

<sup>1)</sup>For position control only.

<sup>2)</sup>Applies to HTL encoders with bipolar signal evaluation or for evaluation of difference signals A\*, A and B\*, B; for HTL encoders with unipolar signal evaluation the permissible cable length is reduced to 100 m (328 ft).

Connection system

Signal cables

Signal cables	MOTION-CONNECT 500	MOTION-CONNECT 800PLUS
	6FX50	6FX80
Certificates of suitability, according to		
• cURus or UR/CSA	UL758-CSA-C22.2-N.210.2-M90	UL758-CSA-C22.2-N.210.2-M90
UR-CSA File No. 1)	Yes	Yes
RoHS conformity	Yes	Yes
Rated voltage according to EN 50395	30 V	30 V
Test voltage, rms	500 V	500 V
Operating temperature on the surface		
<ul> <li>Permanently installed</li> </ul>	-20 +80 °C	-50 +80 °C
<ul> <li>Flexible installation</li> </ul>	0 60 °C	-20 +60 °C
Tensile stress, max.		
<ul> <li>Permanently installed</li> </ul>	50 N/mm <sup>2</sup>	50 N/mm <sup>2</sup>
<ul> <li>Flexible installation</li> </ul>	20 N/mm <sup>2</sup>	20 N/mm <sup>2</sup>
Smallest bending radius		
<ul> <li>Permanently installed</li> </ul>	60 mm	$4 \times D_{\text{max}}$
<ul> <li>Flexible installation</li> </ul>	100 mm	70 mm <sup>2)</sup>
Torsional stress	Absolute 30°/m	Absolute 30°/m
Bending operations	2 million	10 million
Traversing speed	180 m/min	Up to 300 m/min
Acceleration	5 m/s <sup>2</sup>	Up to 50 m/s <sup>2</sup>
Insulation material, incl. jacket	CFC/silicone-free	CFC/halogen/silicone-free IEC 60754-1/DIN VDE 0472-815
Oil resistance	EN 60811-2-1 (mineral oil only)	EN 60811-2-1
Jacket	PVC	PUR, HD22.10 S2 (VDE 0282, Part 10)
	DESINA color green RAL 6018	DESINA color green RAL 6018
Flame-retardant	EN 60332-1-1 to 1-3	EN 60332-1-1 to 1-3

Degree of protection of the pre-assembled signal cables and their extensions when closed and inserted: IP67.

Technical specifications

<sup>1)</sup> The File No. is printed on the cable jacket.

<sup>&</sup>lt;sup>2)</sup> Exception: 6FX8002-2SL..-...; smallest bending radius (flexible): 85 mm.

Connection system

# Signal cables

# Technical specifications (continued)

DRIVE-CLiQ signal cables	DRIVE-CLIQ	DRIVE-CLIQ MOTION-CONNECT 500	DRIVE-CLIQ MOTION-CONNECT 800PLUS	
	6FX21DC	6FX5DC	6FX8DC	
Certificates of suitability, according to				
cURus or UR/CSA	UL STYLE 2502/CSA-N.210.2-M90	UL STYLE 2502/CSA-N.210.2-M90	UL STYLE 2502/CSA-N.210.2-M90	
UR-CSA File No. 1)	Yes	Yes	Yes	
<ul> <li>RoHS conformity</li> </ul>	Yes	Yes	Yes	
Rated voltage according to EN 50395	30 V	30 V	30 V	
Test voltage, rms	500 V	500 V	500 V	
Operating temperature on the surface				
<ul> <li>Permanently installed</li> </ul>	-20 +80 °C	-20 +80 °C	-20 +80 °C	
<ul> <li>Flexible installation</li> </ul>	-	0 60 °C	-20 +60 °C	
Tensile stress, max.				
<ul> <li>Permanently installed</li> </ul>	45 N/mm <sup>2</sup>	80 N/mm <sup>2</sup>	50 N/mm <sup>2</sup>	
<ul> <li>Flexible installation</li> </ul>	-	30 N/mm <sup>2</sup>	20 N/mm <sup>2</sup>	
Smallest bending radius				
<ul> <li>Permanently installed</li> </ul>	50 mm	35 mm	35 mm	
<ul> <li>Flexible installation</li> </ul>	-	125 mm	75 mm	
Torsional stress	-	Absolute 30°/m	Absolute 30°/m	
Bending operations	-	100000	10 million	
Traversing speed	-	30 m/min	300 m/min	
Acceleration	-	2 m/s <sup>2</sup>	Up to 50 m/s <sup>2</sup>	
Insulation material, incl. jacket	CFC/silicone-free	CFC/silicone-free	CFC/halogen/silicone-free IEC 60754-1/DIN VDE 0472-815	
Oil resistance	EN 60811-2-1	EN 60811-2-1 (mineral oil only)	EN 60811-2-1	
Jacket	PVC	PVC	PUR, HD22.10 S2 (VDE 0282, Part 10)	
	Gray RAL 7032	DESINA color green RAL 6018	DESINA color green RAL 6018	
Flame-retardant	EN 60332-1-1 to 1-3	EN 60332-1-1 to 1-3	EN 60332-1-1 to 1-3	

Degree of protection of the pre-assembled signal cables and their extensions when closed and inserted: IP67.

3



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4/27	Smart Line Modules
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### Overview



SINAMICS S120 Cabinet Modules, air-cooled and liquid-cooled

SINAMICS S120 Cabinet Modules are the components of a modular cabinet system for multi-motor drives with a central supply infeed and a common DC link busbar, as used, for example, in the process industry, automotive industry, metal processing industry as well as in the crane and mining domains. They are available in air-cooled or liquid-cooled versions. As standard, they are installed side by side in a row. Other installation types (e.g. back to back) are possible on request.

SINAMICS S120 Cabinet Modules include the chassis units from the SINAMICS S120 series in booksize format (Motor Modules) and chassis format, thus making the range an ideal supplement to the SINAMICS G150 and SINAMICS S150 cabinet converter series for single-motor drives. All drive components, from the supply infeed to the motor-side converters, are configured in a clear, compact layout in the individual Cabinet Modules. They can be flexibly combined and optimally adapted to customer-specific requirements thanks to a comprehensive array of options.

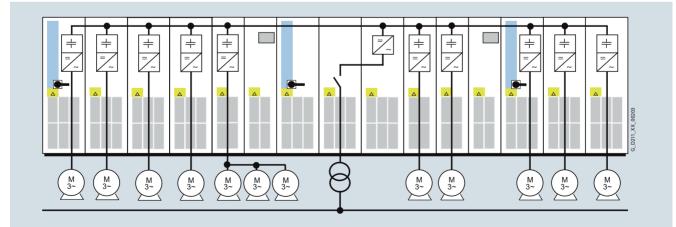
The main components of the air-cooled system are as follows:

- Line Connection Modules with line-side components such as contactors, fuses and circuit breakers, as well as line reactors for Basic Line Modules
- The following types of infeed Line Modules:
  - Basic Line Modules for two-quadrant operation
  - Smart Line Modules for four-quadrant operation
- Active Line Modules for four-quadrant operation with negligible line harmonics
- · Central Braking Modules for braking operation
- The following types of Motor Modules:
   Booksize Cabinet Kit
- Chassis
- Control Units
- Auxiliary Power Supply Modules to supply the auxiliary power supply system

The main components of the liquid-cooled system are as follows:

- Active Line Connection Modules as a combination of Line Connection Module and Active Line Module with an Active Interface Module
- Basic Line Connection Modules as a combination of Line Connection Module and Basic Line Module
- Motor Modules
- Control Units
- Auxiliary Power Supply Modules to supply the auxiliary power supply system
- Heat Exchanger Modules with pumps, closed-loop control and a heat exchanger between the deionized water and raw water circuits

Standardized interfaces for both the power and the control connections facilitate engineering and installation. Communication between the power units and the central Control Unit takes place via DRIVE-CLiQ, the internal drive serial interface.



Example of a drive line-up with SINAMICS S120 Cabinet Modules for a multi-motor drive

### **Overview** (continued)

The following tables provide an overview of the voltage ranges and power ratings of the available SINAMICS S120 Cabinet Modules.

### Voltage ranges and powers for air-cooled SINAMICS S120 Cabinet Modules

	Line voltage	Input current	DC link voltage	DC link current	Output current	Power range of single modules
Line Connection Modules <sup>1)</sup>	380 480 V 3 AC	250 3200 A	-	-	-	-
	500 690 V 3 AC	280 3200 A	-	-	-	-
Basic Line Modules <sup>1)</sup>	380 480 V 3 AC	365 1630 A	510 650 V	420 1880 A	-	200 900 kW
	500 690 V 3 AC	260 1580 A	675 930 V	300 1880 A	-	250 1500 kW
Smart Line Modules <sup>1)</sup>	380 480 V 3 AC	463 1430 A	510 650 V	550 1700 A	-	250 800 kW
	500 690 V 3 AC	463 1430 A	675 930 V	550 1700 A	-	450 1400 kW
Active Line Modules <sup>1)</sup>	380 480 V 3 AC	210 1405 A	570 720 V	235 1574 A	-	132 900 kW
	500 690 V 3 AC	575 1270 A	750 1035 V	644 1422 A	-	630 1400 kW
Motor Modules booksize	380 480 V 3 AC	-	510 720 V	-	9 132 A	4.8 71 kW
Motor Modules chassis <sup>1)</sup>	380 480 V 3 AC	-	510 720 V	-	210 1405 A	110 800 kW
	500 690 V 3 AC	-	675 1035 V	-	85 1270 A	75 1200 kW
Central Braking Modules <sup>1)</sup>	380 480 V 3 AC	-	510 720 V	-	-	500 1000 kW
	500 600 V 3 AC	-	675 900 V	-	-	550 1100 kW
	660 690 V 3 AC	-	890 1035 V	-	-	630 1200 kW
Auxiliary Power Supply Modules	380 690 V 3 AC	125 250 A	-	-	-	-

#### Voltage ranges and power ratings for liquid-cooled SINAMICS S120 Cabinet Modules

	Line voltage	Input current	DC link voltage	DC link current	Output current	Power range of single modules
Basic Line Connection	380 480 V 3 AC	610 1420 A	510 650 V	740 1730 A	-	360 830 kW
Modules <sup>1)</sup>	500 690 V 3 AC	340 1350 A	675 930 V	420 1650 A	-	355 1370 kW
Active Line Connection	380 480 V 3 AC	605 1405 A	570 720 V	677 1573 A	-	380 900 kW
Modules <sup>1)</sup>	500 690 V 3 AC	735 1560 A	750 1035 V	823 1740 A	-	800 1700 kW
Motor Modules <sup>1)</sup>	380 480 V 3 AC	-	510 720 V	-	210 1405 A	110 800 kW
	500 690 V 3 AC	-	675 1035 V	-	100 1560 A	90 1500 kW
Auxiliary Power Supply Modules	380 690 V 3 AC	25 A	-	-	-	-

### Benefits

The outstanding system features of the SINAMICS S120 Cabinet Modules provide the following advantages:

- · Process optimization with minimum outlav
  - A standard PROFIBUS or PROFINET interface and various analog and digital interfaces enable easy integration into automation solutions
- Vector and servo control ensures that they fulfill the most exacting requirements regarding the accuracy and dynamic response of drives
- High level of reliability and availability
- Individual modules and power components can be replaced quickly and easily, which ensures a higher level of plant availability
- Energy saving during operation
- The motor-side converters are coupled via the common DC link and allow energy to be exchanged between motors that are motoring and generating. This means that energy is saved, there is less load on the supply infeed and line harmonics are reduced
- Generally the line infeed is only dimensioned for the maximum energy required when motoring or the maximum current required when motoring and not the sum of the energy requirements of the Motor Modules connected to the DC link. As a consequence, for example, for conveyor belts or motor test bays with Motor Modules that are simultane-ously operated in motoring and generating modes, a significantly smaller line infeed unit can be selected
- Minimal operative, maintenance, and servicing costs
   Simple commissioning thanks to the menu-driven STARTER commissioning tool
  - Optional, menu-navigated AOP30 advanced operator panel with plain text display and bar-type display of process variables
  - All modules are easily accessible, making them extremely service friendly
- Space-saving design
- Environmentally-friendly operation
- The converters are exceptionally quiet and compact thanks to state-of-the-art IGBT power semiconductors and an innovative cooling concept

<sup>1)</sup> The power can be increased by connecting up to four identical modules in parallel.

4/3

### System overview

### Application

SINAMICS S120 Cabinet Modules have been specially developed to allow simple configuration of multi-motor systems. They are used for applications where several motors must be coordinated to realize a drive task as multi-motor drives in a drive line-up. Examples of such applications include:

- · Packaging machines
- · Plastics processing machines
- Textile machines
- Presses and punches
- Rolling mill drives

- · Hoists and cranes
- Printing and paper machines
- Vehicle and gearbox test bays
- Test bay applications
- Machines used in the woodworking, glass and ceramics industries
- · Handling and assembly systems
- Machine tools

High-power single-motor drives (parallel connection) can also be implemented with Cabinet Modules.

### Design

The devices have been designed according to the zone concept principle and therefore offer the highest possible level of operational reliability. EMC measures have been rigorously implemented. With the help of simulated conditions, partitions have been designed to act as air guides and heat dissipation units.

Special measures used in the construction of the cabinets ensure that they remain mechanically durable over their entire life cycle.

Attention has been paid to providing a wide range of cable routing options and special design concepts are applied consistently to broaden the scope of application and simplify service. The units have all the necessary connections and connecting elements. Thanks to their carefully considered configuration concept, cabinets are shipped in a ready-to-connect state or, in the case of multiple transport units, have been prepared for quick assembly. An extensive spectrum of options designed to adapt the units to a variety of different applications facilitates the selection process.

All components, from individual parts to the ready-to-connect cabinet, undergo rigorous testing throughout the entire production process. This guarantees a high level of functional reliability during installation and commissioning, as well as in operation.

Replaceable components have been designed so that they can be quickly and easily replaced. In addition, the "Spares On Web" Internet tool makes it easy to view the spare parts that are available for the particular order at all times <sup>1)</sup>.

### System design

Line Modules are coupled with the various Motor Modules by means of prefabricated busbar sets with different current carrying capacities.

All standard busbars, as well as electronics components, are protected against environmental influences. This is achieved through the use of nickel-plated copper bars and painted modules throughout.

#### Auxiliary power supply system

A special, standard auxiliary power supply system supplies the individual Cabinet Modules with the required auxiliary voltages for the power components, fans and 24 V loads.

These voltages are preferably generated using an Auxiliary Power Supply Module. Additional supply possibilities are available using the **K76** option (auxiliary power supply generation in the Line Connection Module) or using an external supply in the auxiliary power supply system. The auxiliary power supply system comprises one Auxiliary Power Supply Module with two terminal blocks (air cooling) and one connecting terminal with two terminal blocks (liquid cooling) and a 24 V DC fuse as well as the required connecting cables. It is supplied completely assembled and ready to operate. Only the cable connections to the adjacent Cabinet Module must be established on-site.

### **DRIVE-CLiQ** communication

Communication between the Control Unit, power units and other active SINAMICS components is realized via DRIVE-CLiQ connections.

DRIVE-CLiQ is an internal serial interface of the drive that enables fast and easy configuration of the complete drive line-up with prefabricated cables in varying lengths.

#### Transport units

The Cabinet Modules can be optionally supplied in pre-configured transport units up to a total length of 2400 mm. This option is particularly recommended in air-cooled Cabinet Modules for Line Modules together with Line Connection Modules since, in this case, the Line Connection Module must be equipped with a pre-charging DC link or line reactors (depending on the type of Line Module), in addition to the electrical interface (busbar). For liquid-cooled Cabinet Modules, delivery in transport units has the advantage that the tube system of the cooling system can be implemented completely without couplings. Transport units thus enable the various devices to be quickly and easily assembled on-site.

#### **Coated modules**

The following devices are equipped as standard with coated modules:

- Booksize format units
- · Chassis format units
- Control Units
- Sensor Modules
- Terminal Modules
- Advanced Operator Panel (AOP30)

The coating on the modules protects the sensitive SMD components against corrosive gases, chemically active dust and moisture.

#### Nickel-plated busbars

All of the copper busbars used in the converter cabinets are nickel-plated to achieve the best possible immunity to environmental effects. Furthermore, there is no need to clean the contacts on the customer terminals as otherwise required for bare copper connections.

### Note:

With some options, parts of the copper busbars cannot be nickel-plated for technical reasons.

<sup>1)</sup> The properties of the SINAMICS S120 Cabinet Modules described in this catalog are not transferable to cabinet units constructed to meet the requirements of specific applications.

### Design (continued)

### PE bars

The Cabinet Modules are delivered with a PE bar as standard. It is used to connect and fasten PE conductors.

#### **Degrees of protection of Cabinet Modules**

The EN 60529 standard covers the protection of electrical equipment by means of housings, covers or equivalent, and includes:

- Protection of persons against accidental contact with live or moving parts within the housing and protection of the equipment against the ingress of solid foreign bodies (touch protection and protection against ingress of solid foreign bodies)
- Protection of the equipment against the ingress of water (water protection)
- Abbreviations for the internationally agreed degrees of protection

The degrees of protection are specified by abbreviations comprising the code letters IP and two digits.

Degree of protection	First code number (touch protection and protection against solid foreign bodies)	Second code number (protection of the equipment against the ingress of water)
IP20 (Standard for air-cooled version)	Protected against solid foreign bodies Diameter ≥ 12.5 mm	No water protection
IP21 (Standard for liquid-cooled version, option M21 for air-cooled version)	Protected against solid foreign bodies Diameter ≥ 12.5 mm	Protected against drip water Vertically falling water drops shall not have a harmful effect.
IP23 (Option M23)	Protected against solid foreign bodies Diameter ≥ 12.5 mm	Protected against spray water Water sprayed on both sides of the vertical at an angle of up to 60° shall not have a harmful effect.
IP43 (Option M43)	Protected against solid foreign bodies Diameter ≥ 1 mm	Protected against spray water Water sprayed on both sides of the vertical at an angle of up to 60° shall not have a harmful effect.
IP54 (Air-cooled version only) (Option M54)	Dust protected Ingress of dust is not totally prevented, but dust must not be allowed to enter in such quantities that the functioning or safety of the equipment is impaired. Complete touch protection	Protected against splash water Water splashing onto the enclosure from any direction shall not have a harmful effect.
IP55 (Liquid-cooled version only) (Option M55)	Dust protected Ingress of dust is not totally prevented, but dust must not be allowed to enter in such quantities that the functioning or safety of the equipment is impaired. Complete touch protection	Protected against water jet (nozzle) Water projected by a nozzle against the enclosure from any direction shall not have a harmful effect.

Air-cooled Cabinet Modules meet degree of protection IP20, liquid-cooled Cabinet Modules degree of protection IP21, as standard. Heat Exchanger Modules have degree of protection IP55 as standard.

### Function

#### Communication with higher-level controller and customer terminal block

As the customer interface to the control system, a PROFIBUS interface is available on the CU320-2 DP Control Unit or a PROFINET interface on the CU320-2 PN Control Unit as standard.

In the case of the air-cooled Cabinet Modules, the inputs and outputs available as standard on the customer terminal block - X55, which are easy to access and easy to connect up, can be provided.

In the case of the liquid-cooled Cabinet Modules, the components are directly connected.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### **Open-loop and closed-loop control functions**

SINAMICS S120 can use a dynamic, high-precision closed-loop vector control (drive object type VECTOR), or a highly dynamic closed-loop servo control (drive object type SERVO).

### System overview

# Function (continued)

### Software and protective functions

The software functions available as standard are described

below:

Software and protective functions	Description
Setpoint input	The setpoint can be specified both internally and externally; internally as a fixed setpoint, motorized potentiometer setpoint or jog set- point, externally via the communications interface or an analog input. The internal fixed setpoint and the motorized potentiometer set- point can be switched or adjusted via control commands from any interface.
Motor identification	The automatic motor identification function makes commissioning faster and easier and optimizes closed-loop control of the drive.
Ramp-function generator	A user-friendly ramp-function generator with separately adjustable ramp-up and ramp-down times, together with adjustable rounding times in the lower and upper speed ranges, allows the drive to be smoothly accelerated and braked. This results in a good speed control response and plays its role in reducing the stress on the mechanical system. The down ramp can be parameterized separately for a quick stop.
V <sub>dc max</sub> controller	The $V_{dc max}$ controller automatically prevents overvoltages in the DC link, if the set down ramp is too short, for example. This may also extend the set ramp-down time.
	Note: This function only makes sense for single-axis applications.
Kinetic buffering (KIP)	For brief line supply failures, the kinetic energy of the rotating drive is used to buffer the DC link and therefore prevents fault trips. The drive converter remains operational as long as the drive can provide regenerative energy as a result of its motion and the DC link voltage does not drop below the shutdown threshold. When the line supply recovers within this time, the drive is again seamlessly accelerated up to its setpoint speed.
Automatic restart	The automatic restart switches the drive on again when the power is restored after a power failure, and ramps up to the current speed setpoint.
Flying restart	The flying restart function allows the converter to be switched to a motor that is still turning. With the voltage sensing capability provided by the optional VSM10, the flying restart time for large induction motors can be significantly reduced because the motor does not need to be de-magnetized.
Technology controller	Using the technology controller (PID controller) function module, level or flow controls and complex tension controls can be imple- mented, for example. The existing D component can act both on the system deviation as well as on the actual value (factory setting). The P, I, and D components are set separately.
Free function blocks	Using the freely programmable function blocks, it is easy to implement logic and arithmetic functions for controlling the SINAMICS drive. The blocks can be programmed via the operator panel or the STARTER commissioning tool.
Drive Control Chart (DCC)	Drive Control Chart (DCC) is an additional tool for the easy configuration of technological functions for SINAMICS. The block library con tains a large selection of control, arithmetic and logic blocks as well as extensive open-loop and closed-loop control functions. The user friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of charts that have already been created. DCC is an add-on for the STARTER commissioning tool ( $\rightarrow$ Tools and Engineering).
$f^{t}$ sensing for motor protection	A motor model stored in the converter software calculates the motor temperature based on the current speed and load. More exact measurement of the temperature, which also takes into account the influence of the ambient temperature, is possible by means of direct temperature measurement using KTY84 sensors in the motor winding.
Motor temperature evaluation	Motor protection by evaluating a KTY84, PTC or Pt100 temperature sensor. When a KTY84 temperature sensor is connected, the limit values can be set for alarm or shutdown. When a PTC thermistor is connected, the system reaction to triggering of the thermistor (alarm or trip) can be defined.
Motor blocking protection	A blocked motor is detected and protected against thermal overloading by a fault trip.
Brake control	"Simple brake control" for controlling holding brakes: The holding brake is used to secure drives against unwanted motion when deactivated.
	The "extended braking control" function module allows complex braking control, for example, for motor holding brakes and operational brakes. In the case of brakes with feedback signal, the brake control reacts to the feedback contacts of the brake.
Write protection	Write protection to prevent unintentional changing of the setting parameters (without password function).
Know-how protection	Know-how protection for encrypting stored data, e.g. to protect expert configuring knowledge, and to protect against modification and duplication (with password function).
Web server	The integrated web server provides information about the drive unit via its web pages. The web server is accessed using a web browser via unsecured (http) or secured transfer protocol (https).

### Power unit protection

 
 Power unit protection
 Description

 Ground fault monitoring at the output
 A ground fault at the output is detected by a total current monitor and results in shutdown in grounded systems.

 Electronic shortcircuit protection at the output
 A short-circuit at the output (e.g. at the converter output terminals, in the motor cable or in the motor terminal box) is detected and the converter shuts down with a "fault".

 Thermal overload protection
 An alarm is issued first when the overtemperature threshold responds. If the temperature continues to rise, the unit either shuts down or independently adjusts the pulse frequency or output current so that thermal load is reduced. Once the cause of the fault has been eliminated (e.g. cooling has been improved), the original operating values are automatically resumed.

# Technical specifications

The most important directives and standards are listed below. These are used as the basis for the SINAMICS S120 Cabinet Modules and they must be carefully observed to achieve an EMC-compliant configuration that is safe both in terms of function and operation.

European directive	S S S S S S S S S S S S S S S S S S S
2014/35/EU	Low Voltage Directive: Directive of the European Parliament and Council of February 26, 2014 on the harmonization of the laws of the member states relating to the making available on the market of electrical equipment designed for use within certain voltage limits (recast)
2014/30/EU	EMC Directive: Directive of the European Parliament and Council of February 26, 2014 on the harmonization of the laws of the member states relating to electromagnetic compatibility (recast)
2006/42/EC	Machinery Directive: Directive of the European Parliament and Council of May 17, 2006 on machinery and amending Directive 95/16/EC (recast)
European standard	is
EN ISO 3744	Acoustics - Determination of sound power levels and sound energy levels of noise sources using sound pressure – Engineering methods for an essentially free field over a reflecting plane
EN ISO 13849-1	Safety of machinery – safety-related parts of control systems Part 1: General principles for design (EN ISO 13849-1: 2006)
EN 60146-1-1	Semiconductor converters – General requirements and line-commutated converters Part 1-1: Specification of basic requirements
EN 60204-1	Safety of machinery – Electrical equipment of machines Part 1: General requirements
EN 60529	Degrees of protection provided by enclosures (IP Code)
EN 61508-1	Functional safety of electrical/electronic/programmable electronic safety-related systems Part 1: General requirements
EN 61800-2	Adjustable speed electrical power drive systems Part 2: General requirements – Rating specifications for low voltage adjustable frequency AC power drive systems
EN 61800-3	Adjustable speed electrical power drive systems Part 3: EMC requirements and specific test methods
EN 61800-5-1	Adjustable speed electrical power drive systems Part 5: Safety requirements Main section 1: Electrical and thermal requirements
EN 61800-5-2	Adjustable speed electrical power drive systems Part 5-2: Safety requirements – Functional safety (IEC 61800-5-2: 2007)

Air-cooled units

### Air-cooled units

### Overview

#### Line Modules

Power is fed to the drive line-up via Line Modules, which generate a DC voltage from the line voltage and, therefore, supply energy to the Motor Modules connected to the DC link. They are suitable for connection to grounded TN/TT and non-grounded IT systems.

The Line Modules are connected to the line supply system via Line Connection Modules and are equipped as standard according to Category C3. Category C3 is part of the "second environment" (in accordance with EN 61800-3). The "second environment" constitutes locations outside residential areas or industrial sites which are supplied from the medium-voltage network via a separate transformer.

The range of Line Modules has power ratings from 132 kW to 900 kW (380 V to 480 V) and from 250 kW to 1500 kW (500 V to 690 V). Furthermore, up to four identical Line Modules can be connected in parallel in order to increase the power rating.

For a compact configuration, Line Connection Modules up to input currents of 3200 A are available. Two Line Modules can be operated in parallel on these Line Connection Modules.

The following types of Line Module are available:

- Basic Line Modules
- Smart Line Modules
- Active Line Modules

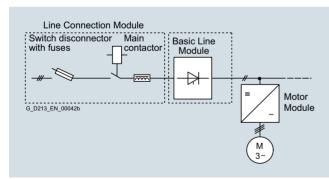
#### **Basic Line Modules**

Basic Line Modules are designed only for infeed operation, i.e. they are not capable of recovering energy to the line supply.

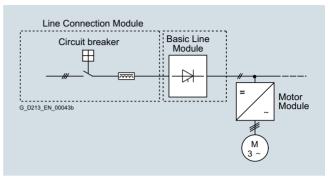
If regenerative energy is produced, e.g. when the drives brake, then it must be converted to heat by means of a Braking Module and a braking resistor.

When a Basic Line Module is used as the infeed, a line reactor appropriate to the supply conditions must be installed. Line reactors are generally required if two or more Basic Line Modules are operated in parallel on a common supply system in order to increase power.

For this reason, line reactors are installed in the appropriate Line Connection Module as standard.



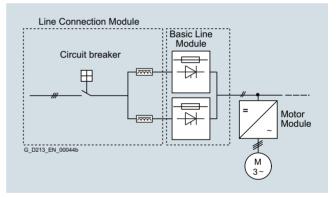
Line Connection Module with Basic Line Module ≤800 A



Line Connection Module with Basic Line Module >800 A

If, for example, a converter transformer is used to connect to the line supply (12-pulse operation), it may be possible to omit line reactors (depending on the supply conditions on site) and they can be optionally deselected (option **L22** for a Line Connection Module combined with a Basic Line Module).

For a compact configuration, Line Connection Modules with input currents of up to 3200 A are available. Two Basic Line Modules can be operated in parallel on these Line Connection Modules. Versions with line-side fuses are available for parallel connections in order to provide selective protection of the individual Basic Line Modules.



Line Connection Module with Basic Line Modules connected in parallel

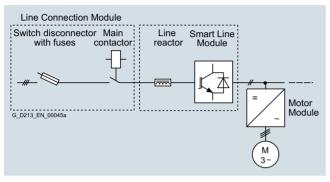
Air-cooled units

Air-cooled units

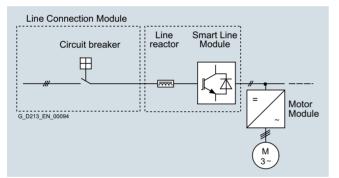
### Overview (continued)

# Smart Line Modules

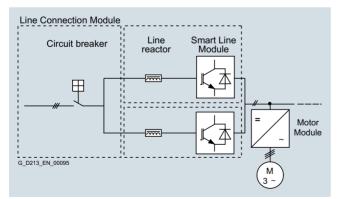
Smart Line Modules can supply energy to the DC link and return regenerative energy to the supply system. A Braking Module and braking resistor are required only if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be recovered to the supply). When a Smart Line Module is used as the infeed, the necessary line reactor is included in the device as standard and can be optionally deselected (option **L22**).



Line Connection Module with Smart Line Module ≤ 800 A



Line Connection Module with Smart Line Module > 800 A



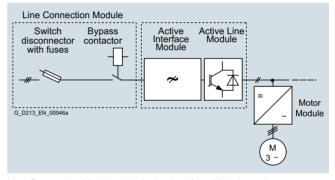
Line Connection Module with Smart Line Modules connected in parallel

### Active Line Modules

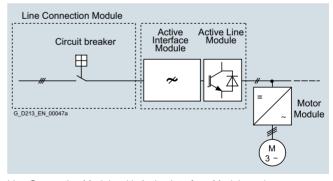
Active Line Modules can supply energy to the DC link and return regenerative energy to the supply system. A Braking Module and braking resistor are required only if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be recovered to the supply).

In contrast to Basic Line Modules and Smart Line Modules, however, Active Line Modules generate a regulated DC voltage which remains constant despite fluctuations in the line voltage. However, in this case, the line voltage must remain within the permissible tolerance range. Active Line Modules in combination with an Active Interface Module draw a virtually sinusoidal current from the supply system. Almost no harmonics occur. The total harmonic distortion factors of current THD(I) and voltage THD(U) are typically in the range of approx. 3 %. The stringent limit values of IEEE 519 (2014) are complied with.

Active Line Modules must always be used in conjunction with an Active Interface Module. Active Interface Modules include the required pre-charging circuit for the Active Line Module in addition to a Clean Power Filter. For SINAMICS S120 Cabinet Modules, these two components are always regarded as a single unit.



Line Connection Module with Active Interface Module and Active Line Module  $\leq$  800 A (example frame size HX + HI)



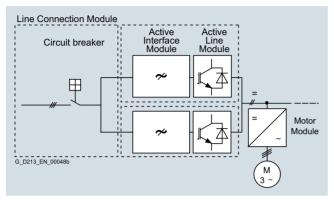
Line Connection Module with Active Interface Module and Active Line Module > 800 A

Air-cooled units

### Air-cooled units

#### Overview (continued)

In the example, two units comprising an Active Interface Module and Active Line Module are connected in parallel to jointly supply the DC link.



Line Connection Module with Active Interface Modules and Active Line Modules connected in parallel

#### DC link components

Braking Modules enable braking resistors to absorb the regenerative energy produced during drive deceleration, which is then converted into heat. Using a Braking Module and a braking resistor, it is possible to brake motors even when the power fails.

Braking Modules as a Line Module or Motor Module option

For lower braking powers, Braking Modules are available with continuous braking powers up to 50 kW. These Braking Modules are ordered as an option for the Line Modules and Motor Modules (order codes L61/L64 (25 kW) or L62/L65 (50 kW), refer to the Description of the options).

### Central Braking Modules

For higher continuous braking powers, separate Central Braking Modules are available. These modules are used centrally in the drive line-up. To increase the braking power, up to four Central Braking Modules can be connected in parallel.

#### Motor Modules

There are two different types of Motor Module available with the SINAMICS S120 Cabinet Modules drive system.

Booksize Base Cabinets with Booksize Cabinet Kits

Motor Modules at the low end of the power range from 4.8 kW to 71 kW (380 V to 480 V) can be implemented as Booksize Cabinet Kits installed in Booksize Base Cabinets.

### Chassis Cabinets

Each Chassis Cabinet is fitted with one SINAMICS S120 Motor Module in chassis format and covers the power range from 75 kW to 1200 kW (380 V to 480 V or 500 V to 690 V). The power rating can be extended up to approx. 4500 kW by connecting up to four Motor Modules in chassis format in parallel.

SINAMICS S120 Motor Modules in chassis format can also be used as a Braking Module (braking chopper) if a 3-phase braking resistor is connected instead of a motor. For more information on this topic, please refer to the SINAMICS Low Voltage Engineering Manual.

#### **Auxiliary Power Supply Modules**

Auxiliary Power Supply Modules supply power to the auxiliary power supply system of the SINAMICS S120 Cabinet Modules.

Units connected to this auxiliary power supply system include the fans of the SINAMICS S120 devices installed in the Cabinet Modules. In addition, the auxiliary power supply system supplies the electronic modules with an external 24 V DC voltage. This is required when the DC link is not charged, for instance, in order to maintain PROFIBUS or PROFINET communication.

Air-cooled units

Air-cooled units

# Technical specifications

# General technical specifications

Electrical specifications								
Line voltages	380 480 V 3 AC, ±10 % (-15 % <1	min)						
	500 690 V 3 AC, ±10 % (-15 % <1	min)						
Line supply types	Grounded TN/TT systems and non-gr	rounded IT systems						
Line frequency	47 63 Hz	47 63 Hz						
Output frequency 1)								
<ul><li>Control type Servo</li><li>Control type Vector</li></ul>	0 550 Hz 0 550 Hz							
Control mode V/f	0 550 Hz							
Line power factor								
Fundamental     Basic Line Module	>0.96							
Smart Line Module	>0.96							
Active Line Module	Adjustable (factory-set to $\cos \varphi = 1$ )							
Efficiency								
<ul> <li>Basic Line Module</li> <li>Smart Line Module</li> </ul>	>99 % >98.5 %							
Active Line Module	>97.5 % (including Active Interface N	Aodule)						
Motor Module	>98.5 %							
Overvoltage category	III acc. to EN 61800-5-1							
Control method	Vector/Servo control with and without							
Fixed speeds	15 fixed speeds plus 1 minimum spe are selectable using terminal block/P	ed, parameterizable (in the default setti ROFIBUS/PROFINET)	ng, 3 fixed setpoints plus 1 minimum speed					
Skippable speed ranges	4, parameterizable							
Setpoint resolution	0.001 rpm digital (14 bits + sign)							
•	12 bits analog							
Braking operation	With Active Line Modules and Smart Line Modules, four-quadrant operation as standard (energy recovery) With Basic Line Modules, two-quadrant operation as standard, braking by means of an optional braking chopper, or alternatively by a Motor Module							
Cabinet system								
Cabinet system	Rittal TS 8, doors with double-bit key,	three-section base plates for cable ent	ry					
Paint finish	RAL 7035 (indoor requirements)		,					
Mechanical specifications								
Degree of protection	IP20 (higher degrees of protection up	to IP54 optional)						
Protection class	l acc. to EN 61800-5-1							
Touch protection	EN 50274/DGUV regulation 3 when u	sed as intended						
Cooling method	Forced air cooling AF according to E							
Ambient conditions	Storage <sup>2)</sup>	Transport <sup>2)</sup>	Operation					
Ambient temperature	-25 +55 °C	-25 +70 °C from -40 °C for 24 hours	$0 \dots +40 \ ^{\circ}C$ to +50 $^{\circ}C$ see derating data					
Relative humidity	5 95 %	5 95 % at 40 °C	5 95 %					
(condensation not permissible)	Class 1K4 acc. to IEC 60721-3-1	Class 2K3 acc. to IEC 60721-3-2	Class 3K3 acc. to IEC 60721-3-3					
Environmental class/harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3					
Organic/biological influences	Class 1B1	Class 2B1	Class 3B1					
3 3	acc. to EN 60721-3-1	acc. to EN 60721-3-2	acc. to EN 60721-3-3					
Degree of pollution	2 acc. to IEC/EN 61800-5-1							
Installation altitude	Cabinet Modules chassis format: ≤ 2000 m above sea level - no deratin	ng; >2000 m, see characteristic curves/	derating data					
	≤ 1000 m above sea level without de	or Modules as well as Central Braking M rating, > 1000 m, see characteristic cur	ves/derating data					
Mechanical stability	Storage <sup>2)</sup>	Transport <sup>2)</sup>	Operation					
Vibratory load	Class 1M2 acc. to EN 60721-3-1	Class 2M2 acc. to EN 60721-3-2	-					
Deflection	1.5 mm at <u>5</u> 9 Hz	3.1 mm at <u>5</u> 9 Hz	0.075 mm at 10 58 Hz					
Acceleration	5 m/s² at >9 200 Hz	10 m/s <sup>2</sup> at >9 200 Hz	9.8 m/s² at >58 200 Hz					
Acceleration	Class 1M2 acc. to EN 60721-3-1 40 m/s² at 22 ms	Class 2M2 acc. to EN 60721-3-2 100 m/s <sup>2</sup> at 11 ms	Class 3M4 acc. to EN 60721-3-3 100 m/s² at 11 ms					
Compliance with standards	TO 11/0 AL 22 110							
			hinery Directive 2000/40/50 for furst					
Conformances/certificates of suitability, according to	CE (EMC Directive 2014/30/EU, Low safety), RCM	voltage Directive 2014/35/EU, and Mac	hinery Directive 2006/42/EC for functional					
Radio interference suppression	ence suppression is compliant with the ment" (industrial networks). EMC dist							

Deviations from the specified class are <u>underlined</u>.

4

Air-cooled units

### Air-cooled units

# Characteristic curves

### Derating data for the chassis format

SINAMICS S120 Cabinet Modules and the associated system components are rated for an ambient temperature of 40 °C and installation altitudes up to 2000 m above sea level.

At ambient temperatures > 40 °C, the output current must be reduced. Ambient temperatures above 50 °C are not permissible.

At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease.

Due to the reduced cooling efficiency, it is necessary to both reduce the ambient temperature and lower heat loss in the Cabinet Module by reducing the output current, whereby ambient temperatures lower than 40 °C may be offset to compensate.

The following table specifies the permissible output currents as a function of the installation altitude and ambient temperature for the various degrees of protection. (The permissible compensation between installation altitude and ambient temperatures <  $40 \,^{\circ}\text{C}$  – air intake temperature at the entry to the

Cabinet Module – has been taken into account in the specified values.)

The values apply under the precondition that it is guaranteed that the cooling air, as specified in the technical specifications, flows through the units as a result of the cabinet arrangement.

As an additional measure for installation altitudes from 2000 m up to 5000 m, an isolating transformer is required in order to reduce transient overvoltages according to EN 60664-1. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Current derating factors for Cabinet Modules as a function of the ambient/air intake temperature, the installation altitude and the degree of protection

Degree of protection	Installation altitude above sea level	<b>Current derating factor</b> (as a percentage of the rated current) for an ambient / air intake temperature of						
	m	20 °C	25 °C	30 °C	35 °C	40 °C	45 °C	50 °C
IP20, IP21,	0 2000						93.3 %	86.7 %
IP23, IP43	2001 2500					96.3 %		
	2501 3000		100 %		98.7 %			
	3001 3500							
3	3501 4000			96.3 %				
	4001 4500		97.5 %					
	4501 5000	98.2 %						
IP54	0 2000		T.			93.3 %	86.7 %	80 %
	2001 2500		100 %		96.3 %	89.8 %		
	2501 3000		100 %	98.7 %	92.5 %			
	3001 3500			94.7 %				
	3501 4000		96.3 %	90.7 %				
	4001 4500	97.5 %	92.1 %					
	4501 5000	93 %						

Air-cooled units

Air-cooled units

# Characteristic curves (continued)

Current derating for SINAMICS S120 Motor Modules, chassis format as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased,

the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 2 kHz

Motor Module in chassis format	Type rating at 400 V	Output current at 2 kHz	Derating factor at pulse frequency				
6SL3720	kW	А	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC	;						
1TE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %
1TE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %
1TE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %
1TE33-8AA3	200	380	96 %	87 %	77 %	54 %	50 %
1TE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 1.25 kHz

Motor Module in chassis format	Type rating at 400 V or 690 V	Output current at 1.25 kHz	Derating factor at pulse freque					
6SL3720	kW	A	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 AC								
1TE36-1AA3	315	605	83 %	72 %	64 %	60 %	40 %	36%
1TE37-5AA3	400	745	83 %	72 %	64 %	60 %	40 %	36%
1TE38-4AA3	450	840	87 %	79 %	64 %	55 %	40 %	37 %
1TE41-0AA3	560	985	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-2AA3	710	1260	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-4AA3	800	1405	97 %	95 %	74 %	60 %	50 %	47 %
500 690 V 3 AC	;							
1TG28-5AA3	75	85	93 %	89 %	71 %	60 %	40 %	-
1TG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %	-
1TG31-2AA3	110	120	92 %	88 %	71 %	60 %	40 %	-
1TG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %	-
1TG31-8AA3	160	175	92 %	87 %	70 %	60 %	40 %	-
1TG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %	-
1TG32-6AA3	250	260	92 %	88 %	71 %	60 %	40 %	-
1TG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %	-
1TG34-1AA3	400	410	89 %	82 %	65 %	55 %	35 %	-
1TG34-7AA3	450	465	92 %	87 %	67 %	55 %	35 %	-
1TG35-8AA3	560	575	91 %	85 %	64 %	50 %	35 %	-
1TG37-4AA3	710	735	87 %	79 %	64 %	55 %	25 %	-
1TG38-1AA3	800	810	97 %	95 %	71 %	55 %	35 %	-
1TG38-8AA3	900	910	92 %	87 %	67 %	55 %	33 %	-
1TG41-0AA3	1000	1025	91 %	86 %	64 %	50 %	30 %	-
1TG41-3AA3	1200	1270	87 %	79 %	55 %	40 %	25 %	-

The following tables list the maximum achievable output frequency as a function of the pulse frequency:

Maximum output frequencies achieved by increasing the

pulse frequency in Vector mode

Pulse frequency	Max. achievable output frequency
1.25 kHz	100 Hz
2 kHz	160 Hz
2.5 kHz	200 Hz
4 kHz	300 Hz

Pulse frequency	Max. achievable output frequency
2 kHz	300 Hz
4 kHz	300/550 Hz <sup>1)</sup>

Maximum output frequencies achieved by increasing the

pulse frequency in Servo mode

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Air-cooled units

#### **Air-cooled units**

### Characteristic curves (continued)

#### Derating data for the booksize format

SINAMICS S120 Cabinet Modules with power units in booksize format and the associated system components are rated for an ambient temperature of 40 °C and installation altitudes up to 1000 m above sea level. If SINAMICS S120 Cabinet Modules with power units in booksize format are operated at ambient temperatures higher than 40 °C and/or installation altitudes higher than 1000 m above sea level, then the corresponding derating factors must be taken into account as a function of the ambient temperature and/or the installation altitude. These derating factors are different from the derating factors for the chassis format power units and are listed in Catalog PM 21.

#### **Overload capability**

SINAMICS S120 Cabinet Modules have an overload reserve, e.g. to handle breakaway torques. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base-load current must therefore be used as a basis for the required load.

Permissible overload assumes that the drive converter is operated at its base-load current before and after the overload occurs, based on a duty cycle duration of 300 s.

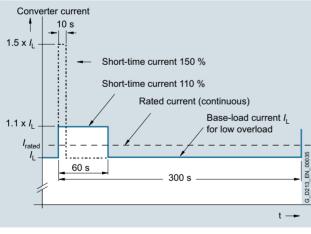
Another precondition is that the Motor Modules are operated at their factory-set pulse frequency at output frequencies >10 Hz.

For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

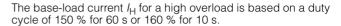
#### Motor Modules in chassis format

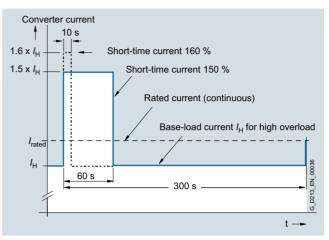
Motor Modules with power units in chassis format can be configured on the basis of different base-load currents.

The base-load current for a low overload  $I_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s.



Low overload

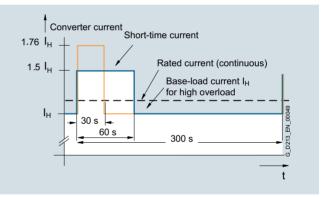




High overload

Motor Modules in booksize format

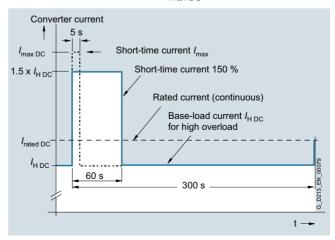
Motor Modules with power units in booksize format have the following overload capabilities:



#### High overload

Line Modules in chassis format

The base-load current for a high overload  $I_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s.



Air-cooled units

**Line Connection Modules** 

### Overview



Line Connection Modules (LCM) contain the line-side infeed via main circuit breaker with fuse switch disconnector or circuit breaker and provide the connection between the plant power system and the Line Modules.

Line Connection Modules are available for the following voltages and currents:

Line voltage	Rated infeed/ regenerative feedback current
380 480 V 3 AC	250 3200 A
500 690 V 3 AC	280 3200 A

# Design

Different versions exist depending on the input current:

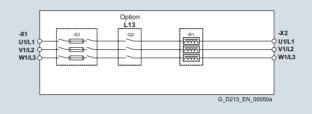
- Units ≤ 800 A are equipped with a main circuit breaker with a fuse switch disconnector
- Units > 800 A are equipped with a fixed-mounted circuit breaker (draw-out circuit breaker is available as an option)

When Line Connection Modules are ordered, the type of Line Module used must be specified:

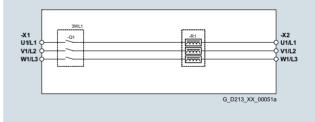
- For Basic Line Modules: Option L43
- For Smart Line Modules: Option L44
- For Active Line Modules: Option L42

When using a Basic Line Module, a reactor is included in the scope of delivery of the Line Connection Module, and when required, can be deselected (option L22).

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.



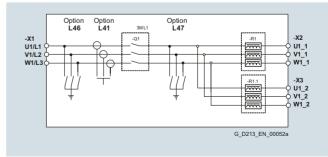
Connection example: Line Connection Module for units  $\leq$  800 A to connect to Basic Line Modules, option L43, option main contactor, order code L13



Connection example: Line Connection Module for units > 800 A, < 2000 A to connect to Basic Line Modules, option  ${\bf L43}$ 

For input currents  $\geq$  2000 A, additional options are available:

- Grounding switch upstream of main circuit breaker: Option L46
- Current transformer upstream of main circuit breaker: Option L41
- Grounding switch downstream of main circuit breaker: Option L47



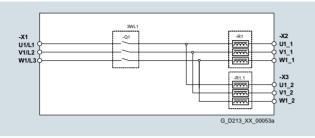
Connection example: Line Connection Module ≥ 2000 A

Air-cooled units

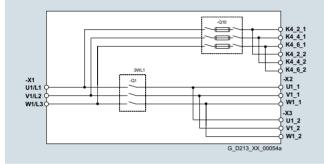
### **Line Connection Modules**

### Design (continued)

When Basic Line Modules that are fed via a common Line Connection Module are connected in parallel, line reactors are generally required. These are installed in the Line Connection Module.



Connection example: Line Connection Module  $\geq$  2000 A for connection to Basic Line Modules, option **L43** 



Connection example: Line Connection Module  $\geq$  2000 A for connection to Active Line Modules in parallel connection, option L42

### Selection and ordering data

Rated infeed/ regenerative feedback current <sup>1)</sup>	Line Connection Module
A	Article No.
Line voltage 380 480 V 3 AC	
250	6SL3700-0LE32-5AA3
380	6SL3700-0LE34-0AA3
600	6SL3700-0LE36-3AA3
770	6SL3700-0LE38-0AA3
1000	6SL3700-0LE41-0AA3
1250	6SL3700-0LE41-3AA3
1600	6SL3700-0LE41-6AA3
2000	6SL3700-0LE42-0AA3
2000	6SL3700-0LE42-0BA3
2500	6SL3700-0LE42-5BA3
3200	6SL3700-0LE43-2BA3
Line voltage 500 690 V 3 AC	
280	6SL3700-0LG32-8AA3
380	6SL3700-0LG34-0AA3
600	6SL3700-0LG36-3AA3
770	6SL3700-0LG38-0AA3
1000	6SL3700-0LG41-0AA3
1250	6SL3700-0LG41-3AA3
1600	6SL3700-0LG41-6AA3
2000	6SL3700-0LG42-0BA3
2500	6SL3700-0LG42-5BA3
3200	6SL3700-0LG43-2BA3

### Note:

When ordering Line Connection Modules, the option order code must be appended to the article number to indicate whether the Line Connection Module is to be connected to a Basic Line Module (option L43), a Smart Line Module (option L44) or an Active Line Module (option L42).

This information is required to ensure that the Line Connection Module is correctly equipped at the factory. This particularly applies to the busbar connection at the 3-phase end (3 AC), to any pre-charging circuits required and to the specified line reactors for Basic Line Modules.

When Cabinet Modules are selected and combined, the specified equipping and preparation of the Line Connection Modules is performed at the factory in accordance with the assignment table in the Integration section. For all other combinations deviating from this, this is not the case. In such cases, the 3-AC busbar connections will have to be engineered and installed on site.

 The current values stated are based on an ambient temperature (air intake temperature) of 40 °C.

Air-cooled units

Line Connection Modules

Line Conr	nection Module	Basic Line	Module	Smart Lin	e Module	Active Lin	e Module
Rated infeed/ regenera- tive feed- back current <sup>1)</sup>		Rated input current		Rated infeed/ regenera- tive feed- back current		Rated infeed/ regenera- tive feed- back current	
А		A		А		А	
Line volta	age 380 480 V 3 AC						
250	6SL3700-0LE32-5AA3	-	-	-	-	210	6SL3730-7TE32-1BA3
380	6SL3700-0LE34-0AA3	-	-	-	-	260	6SL3730-7TE32-6BA3
600	6SL3700-0LE36-3AA3	365	6SL3730-1TE34-2AA3	463	6SL3730-6TE35-5AA3	380	6SL3730-7TE33-8BA3
		460	6SL3730-1TE35-3AA3			490	6SL3730-7TE35-0BA3
770	6SL3700-0LE38-0AA3	710	6SL3730-1TE38-2AA3	614	6SL3730-6TE37-3AA3	605	6SL3730-7TE36-1BA3
1000	6SL3700-0LE41-0AA3	-	-	883	6SL3730-6TE41-1AA3	840	6SL3730-7TE38-4BA3
1250	6SL3700-0LE41-3AA3	1010	6SL3730-1TE41-2AA3	1093	6SL3730-6TE41-3AA3	985	6SL3730-7TE41-0BA3
1600	6SL3700-0LE41-6AA3	1265	6SL3730-1TE41-5AA3	1430	6SL3730-6TE41-7AA3	1405	6SL3730-7TE41-4BA3
2000	6SL3700-0LE42-0AA3	1630	6SL3730-1TE41-8AA3	-	-	-	-
2000	6SL3700-0LE42-0BA3	2 × 935	6SL3730-1TE41-2BA3	2 × 817	6SL3730-6TE41-1BA3	2 × 936	6SL3730-7TE41-0BA3
			6SL3730-1TE41-2BC3	_	6SL3730-6TE41-1BC3	-	6SL3730-7TE41-0BC3
2500	6SL3700-0LE42-5BA3	2 × 1170	6SL3730-1TE41-5BA3	2 × 1011	6SL3730-6TE41-3BA3	-	-
			6SL3730-1TE41-5BC3	_	6SL3730-6TE41-3BC3	-	
3200	6SL3700-0LE43-2BA3	2 × 1508	6SL3730-1TE41-8BA3	2 × 1323	6SL3730-6TE41-7BA3	2 × 1335	6SL3730-7TE41-4BA3
			6SL3730-1TE41-8BC3	_	6SL3730-6TE41-7BC3	-	6SL3730-7TE41-4BC3
Line volta	ige 500 690 V 3 AC						
280	6SL3700-0LG32-8AA3	260	6SL3730-1TG33-0AA3	-	-	-	-
380	6SL3700-0LG34-0AA3	375	6SL3730-1TG34-3AA3	-	-	-	-
600	6SL3700-0LG36-3AA3	575	6SL3730-1TG36-8AA3	463	6SL3730-6TG35-5AA3	575	6SL3730-7TG35-8BA3
770	6SL3700-0LG38-0AA3	-	-	757	6SL3730-6TG38-8AA3	735	6SL3730-7TG37-4BA3
1000	6SL3700-0LG41-0AA3	925	6SL3730-1TG41-1AA3	-	-	-	-
1250	6SL3700-0LG41-3AA3	1180	6SL3730-1TG41-4AA3	1009	6SL3730-6TG41-2AA3	1025	6SL3730-7TG41-0BA3
1600	6SL3700-0LG41-6AA3	1580	6SL3730-1TG41-8AA3	1430	6SL3730-6TG41-7AA3	1270	6SL3730-7TG41-3BA3
2000	6SL3700-0LG42-0BA3	2 × 855	6SL3730-1TG41-1BA3	2 × 700	6SL3730-6TG38-8BA3	2 × 698	6SL3730-7TG37-4BA3
			6SL3730-1TG41-1BC3		6SL3730-6TG38-8BC3		6SL3730-7TG37-4BC3
		-	-	2 × 934	6SL3730-6TG41-2BA3	2 × 974	6SL3730-7TG41-0BA3
					6SL3730-6TG41-2BC3		6SL3730-7TG41-0BC3
2500	6SL3700-0LG42-5BA3	2 × 1092	6SL3730-1TG41-4BA3	-	-	2 × 1206	6SL3730-7TG41-3BA3
			6SL3730-1TG41-4BC3				6SL3730-7TG41-3BC3
3200	6SL3700-0LG43-2BA3	2 × 1462	6SL3730-1TG41-8BA3	2 × 1323	6SL3730-6TG41-7BA3	-	-
			6SL3730-1TG41-8BC3		6SL3730-6TG41-7BC3		
Entries in	Parallel circuit of two Line	e Modules co	nnected to a Line Connecti	on Module.			

Entries in Parallel circuit of two Line Modules connected to a Line Connection Module. italics: The required derating factors listed below are already included in the current

S: The required derating factors listed below are already included in the current values given above:

• 7.5% for Basic Line Modules

Integration

• 7.5% for Smart Line Modules

• 5% for Active Line Modules

 $^{1)}$  The current values stated are based on an ambient temperature (air intake temperature) of 40  $^{\circ}\mathrm{C}.$ 

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Air-cooled units

### **Line Connection Modules**

# Technical specifications

Line voltage 380 480 V 3 AC		Line Connection Modules							
		6SL3700- 0LE32-5AA3	6SL3700- 0LE34-0AA3	6SL3700- 0LE36-3AA3	6SL3700- 0LE38-0AA3	6SL3700- 0LE41-0AA3	6SL3700- 0LE41-3AA3		
Infeed/regenerative feedback current									
Rated current I <sub>rated I</sub>	А	250	380	600	770	1000	1250		
Current demand									
Fan power supply 230 V AC	A	-	-	-	-	1.07	1.07		
• 230 V AC <sup>1)</sup>									
- Inrush current	А	3.6	3.6	3.6	10.8	0.5	0.5		
- Holding current	А	0.04	0.04	0.04	0.12	0.06	0.06		
Power loss, max. <sup>2)</sup>									
• At 50 Hz 400 V									
- Option <b>L42/L44</b>	kW	0.115	0.19	0.31	0.39	0.18	0.29		
- Option L43	kW	-	-	0.675	0.74	-	0.787		
• At 60 Hz 460 V									
- Option <b>L42/L44</b>	kW	0.115	0.19	0.31	0.39	0.18	0.29		
- Option <b>L43</b>	kW	-	-	0.675	0.74	-	0.787		
Cooling air requirement <sup>3)</sup>	m <sup>3</sup> /s	-	-	-	-	0.36	0.36		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	-	-	-	-	68/70	68/70		
Line supply connection L1, L2, L3		2/M12	2/M12	2/M12	4/M12	5/M12 + 4/M16	5/M12 + 4/M16		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 150	2 × 150	4 × 240	8 × 240	8 × 240	8 × 240		
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar	PE bar		
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600	600		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	240		
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20		
Dimensions									
• Width	mm	400	400	600	600	600	600		
• Height <sup>4)</sup>	mm	2200	2200	2200	2200	2200	2200		
• Depth	mm	600	600	600	600	600	600		
Weight, approx.									
• Option <b>L42/L44</b>	kg	210	230	310	340	450	470		
Option L43	kg	-	-	360	420	-	570		
Frame size		FL	FL	GL	HL	JL	JL		
Short-circuit current rating according to IEC	kA	50	50	50	50	50	50		
Minimum short-circuit current <sup>5)</sup>	А	3000	3000	8000	12000	2000	2500		

<sup>1)</sup> Current demand of contactors/circuit breakers and fans with degree of protection IP23, IP43, IP54 (in combination with Basic Line Modules).

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> For IP23, IP43 or IP54 degree of protection only (in combination with Basic Line Modules). <sup>4)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

<sup>5)</sup> Current required to ensure reliable tripping of installed protective devices.

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Air-cooled units

**Line Connection Modules** 

Line voltage 380 480 V 3 AC		Line Connection Modules						
		6SL3700- 0LE41-6AA3	6SL3700- 0LE42-0AA3	6SL3700- 0LE42-0BA3	6SL3700- 0LE42-5BA3	6SL3700- 0LE43-2BA3		
				Prepared for connection to Line Mod		ules connected in parallel		
Infeed/regenerative feedback current								
Rated current I <sub>rated I</sub>	А	1600	2000	2000	2500	3200		
Current demand								
<ul> <li>Fan power supply 230 V AC</li> </ul>	A	1.07	2.14	2.14	2.14	2.14		
• 230 V AC <sup>1)</sup>								
- Inrush current	А	0.5	0.5	0.5	0.5	0.5		
- Holding current	А	0.06	0.06	0.06	0.06	0.04		
Power loss, max. <sup>2)</sup>								
• At 50 Hz 400 V								
- Option <b>L42/L44</b>	kW	0.41	0.6	0.6	0.95	0.95		
- Option <b>L43</b>	kW	1.186	1.366	1.594	2.502	2.482		
• At 60 Hz 460 V								
- Option <b>L42/L44</b>	kW	0.41	0.6	0.6	0.95	0.95		
- Option <b>L43</b>	kW	1.186	1.366	1.594	2.502	2.482		
Cooling air requirement <sup>3)</sup>	m <sup>3</sup> /s	0.36	0.72	0.72	0.72	0.72		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	68/70	70/72	70/72	70/72	70/72		
Line supply connection L1, L2, L3		5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	8 × 240	10 × 240	10 × 240	10 × 240	10 × 300		
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar		
Busbar cross-section	mm <sup>2</sup>	600	600	600	600	600		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240		
Degree of protection		IP20	IP20	IP20	IP20	IP20		
Dimensions								
• Width	mm	600	1000	1000	1000	1000		
• Height <sup>4)</sup>	mm	2200	2200	2200	2200	2200		
• Depth	mm	600	600	600	600	600		
Weight, approx.								
• Option <b>L42/L44</b>	kg	490	600	620	620	720		
Option L43	kg	650	760	820	900	1000		
Frame size		JL	KL	KL	KL	LL		
Short-circuit current rating according to IEC	kA	100	100	100	100	100		
Minimum short-circuit current <sup>5)</sup>	А	3200	4000	4000	5000	6400		

 Current demand of contactors/circuit breakers and fans with degree of protection IP23, IP43, IP54 (in combination with Basic Line Modules).

Technical specifications (continued)

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> For IP23, IP43 or IP54 degree of protection only (in combination with Basic Line Modules). <sup>4)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

<sup>5)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

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### **Line Connection Modules**

# Technical specifications (continued)

Line voltage 500 690 V 3 AC		Line Connection Modules						
			6SL3700- 0LG34-0AA3	6SL3700- 0LG36-3AA3	6SL3700- 0LG38-0AA3	6SL3700- 0LG41-0AA3		
Infeed/regenerative feedback current								
Rated current I <sub>rated I</sub>	А	280	380	600	770	1000		
Current demand								
<ul> <li>Fan power supply 230 V AC</li> </ul>	A	-	-	-	-	1.07		
• 230 V AC <sup>1)</sup>								
- Inrush current	А	3.6	3.6	3.6	10.8	0.5		
- Holding current	А	0.04	0.04	0.04	0.12	0.06		
Power loss, max. <sup>2)</sup>								
• At 50 Hz 500/690 V								
- Option <b>L42/L44</b>	kW	0.125	0.19	0.31	0.39	0.18		
- Option <b>L43</b>	kW	0.402	0.668	0.794	-	0.963		
• At 60 Hz 575 V								
- Option <b>L42/L44</b>	kW	0.125	0.19	0.31	0.39	0.18		
- Option <b>L43</b>	kW	0.402	0.668	0.794	-	0.963		
Cooling air requirement <sup>3)</sup>	m <sup>3</sup> /s	-	-	-	-	0.36		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	-	-	-	-	68/70		
Line supply connection L1, L2, L3		2/M12	2/M12	2/M12	2/M12	5/M12 + 4/M16		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 150	2 × 150	4 × 240	8 × 240	8 × 240		
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar		
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240		
Degree of protection		IP20	IP20	IP20	IP20	IP20		
Dimensions								
• Width	mm	400	600	600	600	600		
• Height <sup>4)</sup>	mm	2200	2200	2200	2200	2200		
• Depth	mm	600	600	600	600	600		
Weight, approx.								
• Option <b>L42/L44</b>	kg	220	230	310	340	450		
Option L43	kg	260	310	400	-	650		
Frame size		FL	FL	GL	HL	JL		
Short-circuit current rating according to IEC	kA	50	50	50	50	85		
Minimum short-circuit current <sup>5)</sup>	А	3200	3500	9000	15000	2000		

 Current demand of contactors/circuit breakers and fans with degree of protection IP23, IP43, IP54 (in combination with Basic Line Modules).

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

 For IP23, IP43 or IP54 degree of protection only (in combination with Basic Line Modules). <sup>5)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

Line Connection Modules

Line voltage 500 690 V 3 AC		Line Connection Modules						
		6SL3700- 0LG41-3AA3	6SL3700- 0LG41-6AA3	6SL3700- 0LG42-0BA3	6SL3700- 0LG42-5BA3	6SL3700- 0LG43-2BA3		
				Prepared for connection to Line Modu		s connected in parallel		
Infeed/regenerative feedback current								
Rated current I <sub>rated I</sub>	А	1250	1600	2000	2500	3200		
Current demand								
<ul> <li>Fan power supply 230 V AC</li> </ul>	А	1.07	1.07	2.14	2.14	2.14		
• 230 V AC <sup>1)</sup>								
- Inrush current	А	0.5	0.5	0.5	0.5	0.5		
- Holding current	А	0.06	0.06	0.06	0.06	0.06		
Power loss, max. <sup>2)</sup>								
• At 50 Hz 500/690 V								
- Option <b>L42/L44</b>	kW	0.29	0.41	0.6	0.6	0.95		
- Option <b>L43</b>	kW	1.073	1.387	2.166	2.166	2.894		
• At 60 Hz 575 V								
- Option <b>L42/L44</b>	kW	0.29	0.41	0.6	0.6	0.95		
- Option <b>L43</b>	kW	1.073	1.387	2.166	2.166	2.894		
Cooling air requirement <sup>3)</sup>	m <sup>3</sup> /s	0.36	0.36	0.72	0.72	0.72		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	68/70	68/70	70/72	70/72	70/72		
Line supply connection L1, L2, L3		5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16	5/M12 + 4/M16		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	8 × 240	8 × 240	10 × 240	10 × 240	10 × 300		
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar		
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240		
Degree of protection		IP20	IP20	IP20	IP20	IP20		
Dimensions								
• Width	mm	600	600	1000	1000	1000		
• Height <sup>4)</sup>	mm	2200	2200	2200	2200	2200		
• Depth	mm	600	600	600	600	600		
Weight, approx.								
• Option <b>L42/L44</b>	kg	470	490	600	620	720		
Option L43	kg	670	680	980	1000	1080		
Frame size		JL	JL	KL	KL	LL		
Short-circuit current rating according to IEC	kA	85	85	85	85	85		
Minimum short-circuit current <sup>5)</sup>	А	2500	3200	4000	5000	6400		

<sup>1)</sup> Current demand of contactors/circuit breakers and fans with degree of protection IP23, IP43, IP54 (in combination with Basic Line Modules).

Technical specifications (continued)

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> For IP23, IP43 or IP54 degree of protection only (in combination with Basic Line Modules).

<sup>4)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

<sup>5)</sup> Current required to ensure reliable tripping of installed protective devices.

4

Air-cooled units

### Overview



Basic Line Modules (BLM) are compact line infeeds for two-quadrant operation, i.e. no regenerative feedback.

They are used when energy need not be fed back into the network.

If regenerative conditions occur in the drive line-up, Braking Modules must be used because they convert the excess energy into heat in braking resistors.

### Design

The Basic Line Modules are available in different frame sizes.

With frame sizes FB and GB, a fully controlled thyristor bridge is used to pre-charge the Basic Line Modules and connected Motor Modules. The thyristors normally operate with a trigger delay angle of 0°.

Basic Line Modules, frame size GD for 900 kW (400 V) or 1500 kW (690 V) include a diode bridge, and the DC link is precharged via a separate line-side pre-charging device that is located in the Line Connection Module (option **L43**, Line Connection Module for Basic Line Module). Basic Line Modules are suitable for connection to grounded TN/TT and non-grounded IT systems. The following voltages and power ratings are available:

Line voltage	Rated power
380 480 V 3 AC	200 900 kW
500 690 V 3 AC	250 1500 kW

The power ratings can be increased by connecting up to four identical Basic Line Modules in parallel.

For an infeed with the Basic Line Modules, depending on the line short-circuit power, a line reactor should be provided at the connection point. This reactor is available as standard in the Line Connection Module. However, it can be omitted if it is not required (option **L22**).

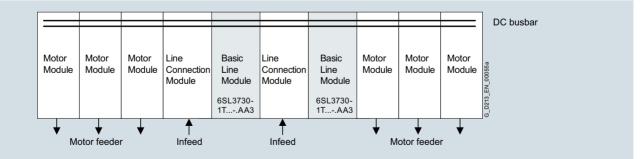
For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Parallel connection of Basic Line Modules to increase power rating

Line Modules can be connected in parallel (relative to the line supply) in two ways for the purpose of creating drive line-ups with a higher power rating.

Two Basic Line Modules supplied with power via two separate Line Connection Modules

With this arrangement, each Basic Line Module is supplied via a Line Connection Module and the Basic Line Modules are protected by fuses or circuit breakers (at *I* > 800 A) in the Line Connection Module. A Basic Line Module is assigned to a Line Connection Module and is mechanically coupled. It is not necessary to mechanically directly couple both "groups" comprising Line Connection Module and Basic Line Module. Other modules can also be inserted in between.



Air-cooled units

**Basic Line Modules** 

#### **Design** (continued)

Two Basic Line Modules supplied with power via a single Line Connection Module

Basic Line Modules are available that can be operated on a single Line Connection Module. These can be connected to the left and right of the Line Connection Module. The power connections on the Basic Line Module on the left of the Line Connection Module are a mirror image (article no. with "C" in the next to last position, example: 6SL3730-1T.41-.BC3), which results in a very compact design for the line infeed.

# For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

These module versions feature integrated line-side fuses which are required because the circuit breaker in the Line Connection Module is not capable of providing selective protection for the Basic Line Modules. They are therefore 200 mm wider in each case than version 6SL3730-1T...-.AA3.

7.5 % applies and this must be taken into account when the

A connection of the Basic Line Modules connected in parallel

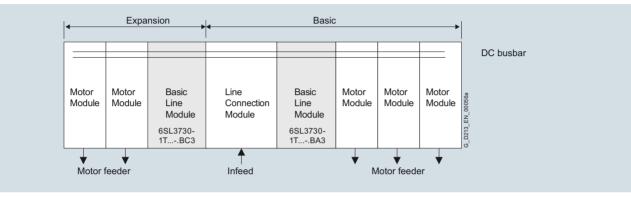
For additional information, please refer to the SINAMICS Low

using DRIVE-CLiQ must be taken into consideration during the

modules are dimensioned.

Voltage Engineering Manual.

engineering phase.



#### Note:

If the Basic Line Modules are supplied with power via the same circuit breaker, line-side fuses are provided to ensure selective individual protection of the modules. This arrangement increases the cabinet width by 200 mm (dimension data in selection tables includes extra width).

Please note that only Basic Line Modules with exactly the same output rating may be connected in parallel. The potential for imbalances in current distribution means that current derating of

#### Selection and ordering data

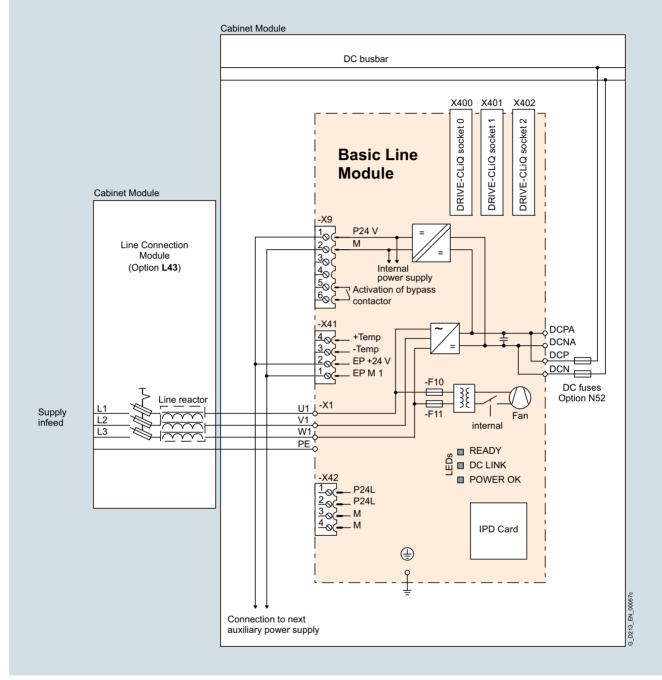
Rated power at 400 V	Rated DC link current	Note for a parallel connection	Basic Line Module
kW	A	Mounting onto a Line Connection Module	Article No.
	380 480 V 3 / ge 510 650 \		
200	420	-	6SL3730-1TE34-2AA3
250	530	-	6SL3730-1TE35-3AA3
400	820	-	6SL3730-1TE38-2AA3
560	1200	_	6SL3730-1TE41-2AA3
		Right	6SL3730-1TE41-2BA3
		Left	6SL3730-1TE41-2BC3
710	1500	-	6SL3730-1TE41-5AA3
		Right	6SL3730-1TE41-5BA3
		Left	6SL3730-1TE41-5BC3
900	1880	_	6SL3730-1TE41-8AA3
		Right	6SL3730-1TE41-8BA3
		Left	6SL3730-1TE41-8BC3

Rated power at 690 V	Rated DC link current	Note for a parallel connection	Basic Line Module
kW	A	Mounting onto a Line Connection Module	Article No.
	500 690 V 3 A ge 675 930 \		
250	300	-	6SL3730-1TG33-0AA3
355	430	-	6SL3730-1TG34-3AA3
500	680	_	6SL3730-1TG36-8AA3
900	1100	-	6SL3730-1TG41-1AA3
		Right	6SL3730-1TG41-1BA3
		Left	6SL3730-1TG41-1BC3
1100	1400	_	6SL3730-1TG41-4AA3
		Right	6SL3730-1TG41-4BA3
		Left	6SL3730-1TG41-4BC3
1500	1880	_	6SL3730-1TG41-8AA3
		Right	6SL3730-1TG41-8BA3
		Left	6SL3730-1TG41-8BC3

Air-cooled units

# **Basic Line Modules**

# Integration



Connection example: Basic Line Module

Air-cooled units

**Basic Line Modules** 

# Technical specifications

Line voltage 380 480 V 3 AC		Basic Line Mod	lules				
-		6SL3730-	6SL3730-	6SL3730-	6SL3730-	6SL3730-	6SL3730-
		1TE34-2AA3	1TE35-3AA3	1TE38-2AA3	1TE41-2AA3	1TE41-5AA3	1TE41-8AA3
For a parallel circuit configuration, mounted to the <u>right</u> of the Line Connec Module	ction				6SL3730- 1TE41-2BA3	6SL3730- 1TE41-5BA3	6SL3730- 1TE41-8BA3
For a parallel circuit configuration, mounted to the <u>left</u> of the Line Connect Module	ion				6SL3730- 1TE41-2BC3	6SL3730- 1TE41-5BC3	6SL3730- 1TE41-8BC3
Rated power							
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	200	250	400	560	710	900
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	160	200	315	450	560	705
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	305	385	615	860	1090	1390
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	245	305	485	690	860	1090
DC link current							
Rated current Irated DC	А	420	530	820	1200	1500	1880
• Base-load current $I_{\rm H DC}^{(1)}$	А	328	413	640	936	1170	1467
Maximum current Imax DC	А	630	795	1230	1800	2250	2820
Input current							
Rated current Irated I	А	365	460	710	1010	1265	1630
Maximum current I <sub>max I</sub>	А	547	690	1065	1515	1897	2380
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.1	1.1	1.1	1.1	1.1	1.1
• 400 V AC <sup>2)</sup>	А	Internal	Internal	Internal	Internal	Internal	Internal
DC link capacitance							
Basic Line Module	μF	7200	9600	14600	23200	29000	34800
• Drive line-up, max.	μF	57600	76800	116800	185600	232000	139200
Power loss, max. <sup>3)</sup>	-						
• At 50 Hz 400 V	kW	1.9	2.1	3.2	4.6	5.5	6.9
• At 60 Hz 460 V	kW	1.9	2.1	3.2	4.6	5.5	6.9
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.36	0.36	0.36
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	66/68	66/68	66/68	71/73	71/73	71/73
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar	PE bar
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600	600
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	240
Cable length, max. 4)							
Shielded	m	2600	2600	2600	4000	4000	4800
Unshielded	m	3900	3900	3900	6000	6000	7200
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
Dimensions							
• Width	mm	400	400	400	400/ <i>600/600</i>	400/ <i>600/600</i>	400/ <i>600/600</i>
• Height <sup>5)</sup>	mm	2200	2200	2200	2200	2200	2200
• Depth	mm	600	600	600	600	600	600
Weight, approx.	kg	166	166	166	320/ <i>440/480</i>	320/440/480	320/ <i>440/480</i>
Frame size		FB	FB	FB	GB	GB	GD
Short-circuit current rating according to IEC	kA	65	65	65	84	100	100
Minimum short-circuit current <sup>6)</sup>	А	4400	5200	10000	2500	3200	4000
<ul> <li>For connection in parallel</li> </ul>	А	-	-	-	4000	5000	6400

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

<sup>2)</sup> The current demand for the 400 V AC auxiliary power supply is drawn from the line input voltage.

 The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions. <sup>5)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>6)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

# **Basic Line Modules**

# **Technical specifications** (continued)

Line voltage 500 690 V 3 AC		Basic Line Modules						
		6SL3730- 1TG33-0AA3	6SL3730- 1TG34-3AA3	6SL3730- 1TG36-8AA3	6SL3730- 1TG41-1AA3	6SL3730- 1TG41-4AA3	6SL3730- 1TG41-8AA3	
For a parallel circuit configuration, mounted to the <u>right</u> of the Line Connec Module	ction				6SL3730- 1TG41-1BA3	6SL3730- 1TG41-4BA3	6SL3730- 1TG41-8BA3	
For a parallel circuit configuration, mounted to the <u>left</u> of the Line Connect Module	tion				6SL3730- 1TG41-1BC3	6SL3730- 1TG41-4BC3	6SL3730- 1TG41-8BC3	
Rated power								
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	250	355	560	900	1100	1500	
• At / <sub>H DC</sub> (50 Hz 690 V)	kW	195	280	440	710	910	1220	
• At I <sub>rated DC</sub> (50 Hz 500 V)	kW	175	250	390	635	810	1085	
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	165	235	365	595	755	1015	
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	250	350	600	900	1250	1500	
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	200	300	450	800	1000	1250	
DC link current								
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	300	430	680	1100	1400	1880	
• Base-load current / <sub>H DC</sub> <sup>1)</sup>	А	234	335	530	858	1092	1467	
Maximum current Imax DC	А	450	645	1020	1650	2100	2820	
Input current								
Rated current Irated I	А	260	375	575	925	1180	1580	
• Maximum current Imax I	А	390	563	863	1388	1770	2370	
Current demand								
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.1	1.1	1.1	1.1	1.1	1.1	
• 500 V/690 V AC <sup>2)</sup>	A	Internal	Internal	Internal	Internal	Internal	Internal	
DC link capacitance								
Basic Line Module	μF	3200	4800	7300	11600	15470	19500	
• Drive line-up, max.	μF	25600	38400	58400	92800	123760	78000	
Power loss, max. <sup>3)</sup>	P**							
• At 50 Hz 690 V	kW	1.5	2.1	3	5.4	5.8	7.3	
• At 60 Hz 575 V	kW	1.5	2.1	3	5.4	5.8	7.3	
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.36	0.36	0.36	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	66/68	66/68	66/68	71/73	71/73	71/73	
PE/GND connection		PE bar						
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600	600	
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	240	
Cable length, max. <sup>4)</sup>								
Shielded	m	1500	1500	1500	2250	2250	2750	
Unshielded	m	2250	2250	2250	3375	3375	4125	
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20	
Dimensions								
Width	mm	400	400	400	400/ <i>600/600</i>	400/ <i>600/600</i>	400/ <i>600/600</i>	
• Height <sup>5)</sup>	mm	2200	2200	2200	2200	2200	2200	
• Depth	mm	600	600	600	600	600	600	
Weight, approx.	kg	166	166	166	320/440/480	320/440/480	320/440/480	
Frame size	-	FB	FB	FB	GB	GB	GD	
Short-circuit current rating according to IEC	kA	65	65	84	100	100	100	
Minimum short-circuit current <sup>6)</sup>	A	3000	4400	8000	2000	2500	3200	
<ul> <li>For connection in parallel</li> </ul>	А	-	-	_	4000	5000	6400	
•								

 $^{1)}$  The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

<sup>2)</sup> The current demand for the 500 V/690 V AC auxiliary power supply is drawn from the line input voltage.

<sup>3)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

<sup>5)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>6)</sup> Current required to ensure reliable tripping of installed protective devices.

Smart Line Modules

### Overview



#### Design

IGBTs (fundamental frequency-switched) serve as Smart Line Module power semiconductors. As this reduces switching losses, a high percentage of the power unit current can be utilized.

The current flows in the direction of the infeed via the freewheeling diodes of the IGBTs. This means that the Smart Line Module behaves in a similar way to the Basic Line Module. If the DC link voltage increases due to regenerative operation of the drives, the IGBTs conduct the current, thus feeding the energy back into the supply system.

In contrast to Active Line Modules, Smart Line Modules do not require a line-side filter; all they require is a line reactor (4 %  $u_k$ ). The unit has a built-in pre-charging circuit for the DC link capacitors. For this reason, a main contactor or a motor-driven circuit breaker is absolutely essential. By specifying the option with order code **L44** for the Line Connection Modules, these components are appropriately accommodated in the Line Connection Module.

Smart Line Modules are non-regulated rectifier/regenerative units. The infeed occurs over a diode jumper, while stable, line-commutated regenerative feedback takes place via IGBTs with 100 % continuous energy regeneration. An autotransformer is not required for regenerative feedback.

The regenerative capability can be deactivated.

Smart Line Modules are suitable for connection to grounded TN/TT and non-grounded IT systems. The following voltages and power ratings are available:

Line voltage	Rated power
380 480 V 3 AC	250 800 kW
500 690 V 3 AC	450 1400 kW

The power ratings can be increased by connecting up to four identical Smart Line Modules in parallel. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Parallel connection of Smart Line Modules to increase power rating

Up to four Smart Line Modules with the same power rating can be connected in parallel in order to increase power. Current derating of 7.5% with respect to the rated current of each Smart Line Module must be taken into account when the system is dimensioned.

A connection of the Smart Line Modules connected in parallel using DRIVE-CLiQ must be taken into consideration during the engineering phase.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

A 4% reactor is always required upstream of each Smart Line Module for the purpose of current symmetrization. This is integrated as standard. Just as with the Basic Line Modules, "mirrorimage" power connections are available for Smart Line Modules, which enable parallel circuits to be realized in a compact design. Units that are arranged to the left of the Line Connection Module have the letter "**C**" in the penultimate position of the article number.

Example: 6SL3730-6TE41-1BC3 (see also the corresponding diagram for the Basic Line Modules).

#### Selection and ordering data

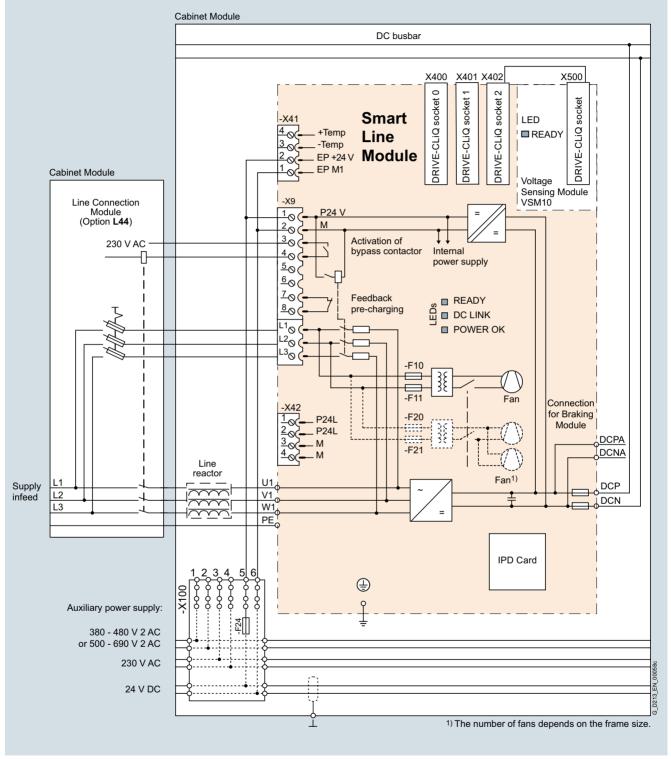
Rated power at 400 V	Rated infeed/ regenerative feedback current	Note for a parallel connection	Smart Line Module
kW	A	Mounting onto a Line Connection Module	Article No.
	80 480 V 3 / ge 510 650 \		
250	463	-	6SL3730-6TE35-5AA3
355	614	-	6SL3730-6TE37-3AA3
500	883	-	6SL3730-6TE41-1AA3
		Right	6SL3730-6TE41-1BA3
		Left	6SL3730-6TE41-1BC3
630	1093	-	6SL3730-6TE41-3AA3
		Right	6SL3730-6TE41-3BA3
		Left	6SL3730-6TE41-3BC3
800	1430		6SL3730-6TE41-7AA3
		Right	6SL3730-6TE41-7BA3
		Left	6SL3730-6TE41-7BC3

Rated power at 690 V	Rated infeed/ regenerative feedback current	Note for a parallel connection	Smart Line Module
kW	A	Mounting onto a Line Connection Module	Article No.
	500 690 V 3 / ge 675 930 \		
	ge 0/5 550 (		
450	463	-	6SL3730-6TG35-5AA3
710	757	-	6SL3730-6TG38-8AA3
		Right	6SL3730-6TG38-8BA3
		Left	6SL3730-6TG38-8BC3
1000	1009	-	6SL3730-6TG41-2AA3
		Right	6SL3730-6TG41-2BA3
		Left	6SL3730-6TG41-2BC3
1400	1430	-	6SL3730-6TG41-7AA3
		Right	6SL3730-6TG41-7BA3
		Left	6SL3730-6TG41-7BC3

Air-cooled units

### **Smart Line Modules**

# Integration



Connection example: Smart Line Module

Air-cooled units

Smart Line Modules

# Technical specifications

Line voltage 380 480 V 3 AC		Smart Line Modules					
		6SL3730-	6SL3730-	6SL3730-	6SL3730-	6SL3730-	
		6TE35-5AA3	6TE37-3AA3	6TE41-1AA3	6TE41-3AA3	6TE41-7AA3	
For a parallel circuit configuration, mounted to the <u>right</u> of the Line Connec Module	otion			6SL3730- 6TE41-1BA3	6SL3730- 6TE41-3BA3	6SL3730- 6TE41-7BA3	
For a parallel circuit configuration, mounted to the <u>left</u> of the Line Connect Module	ion			6SL3730- 6TE41-1BC3	6SL3730- 6TE41-3BC3	6SL3730- 6TE41-7BC3	
Rated power							
• At I <sub>rated DC</sub> (50 Hz 400 V)	kW	250	355	500	630	800	
• At I <sub>H DC</sub> (50 Hz 400 V)	kW	235	315	450	555	730	
• At I <sub>rated DC</sub> (60 Hz 460 V)	hp	395	545	770	970	1230	
• At I <sub>H DC</sub> (60 Hz 460 V)	hp	360	485	695	855	1125	
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>	А	550	730	1050	1300	1700	
<ul> <li>Base-load current I<sub>H DC</sub><sup>1)</sup></li> </ul>	А	490	650	934	1157	1513	
<ul> <li>Maximum current I<sub>max DC</sub></li> </ul>	А	825	1095	1575	1950	2550	
Infeed/regenerative feedback current							
Rated current I <sub>rated I</sub>	А	463	614	883	1093	1430	
<ul> <li>Maximum current I<sub>max I</sub></li> </ul>	А	694	921	1324	1639	2145	
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.35	1.35	1.4	1.5	1.7	
• 400 V AC <sup>2)</sup>	А	1.8	1.8	3.6	5.4	5.4	
DC link capacitance							
Smart Line Module	μF	8400	12000	16800	18900	28800	
Drive line-up, max.	μF	42000	60000	67200	75600	115200	
Power loss, max. <sup>3)</sup>							
• At 50 Hz 400 V	kW	3.7	4.7	7.1	11.0	11.5	
• At 60 Hz 460 V	kW	3.7	4.7	7.1	11.0	11.5	
Cooling air requirement	m <sup>3</sup> /s	0.36	0.36	0.78	1.08	1.08	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69/73	69/73	70/73	70/73	70/73	
PE/GND connection	0	PE bar	PE bar	PE bar	PE bar	PE bar	
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	
Cable length, max. <sup>4)</sup>							
Shielded	m	4000	4000	4800	4800	4800	
Unshielded	m	6000	6000	7200	7200	7200	
Degree of protection		IP20	IP20	IP20	IP20	IP20	
Dimensions		400	100		000		
• Width	mm	400	400	600	800	800	
• Height <sup>5)</sup>	mm	2200	2200	2200	2200	2200	
Depth	mm	600	600	600	600	600	
Weight, approx.	kg	270	270	490	775	775	
Frame size	LA	GX	GX	HX	JX	JX	
Short-circuit current rating according to IEC	kA	65	65	84	84	100	
Minimum short-circuit current <sup>6)</sup>	А	6200	9200	2000	2500	3200	

 $^{1)}$  The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

 <sup>2)</sup> The current demand for the 400 V AC auxiliary power supply is drawn from the line input voltage.

<sup>3)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. <sup>5)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>6)</sup> Current required to ensure reliable tripping of installed protective devices.

4

Air-cooled units

# Smart Line Modules

# **Technical specifications** (continued)

Line voltage 500 690 V 3 AC		Smart Line Modules			
Ū.		6SL3730-6TG35-5AA3	6SL3730-6TG38-8AA3	6SL3730-6TG41-2AA3	6SL3730-6TG41-7AA3
For a parallel circuit configuration, mounted to the <u>right</u> of the Line Connec Module	ction		6SL3730-6TG38-8BA3	6SL3730-6TG41-2BA3	6SL3730-6TG41-7BA3
For a parallel circuit configuration, mounted to the <u>left</u> of the Line Connecti Module	on		6SL3730-6TG38-8BC3	6SL3730-6TG41-2BC3	6SL3730-6TG41-7BC3
Rated power					
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	450	710	1000	1400
• At I <sub>H DC</sub> (50 Hz 690 V)	kW	405	665	885	1255
• At / <sub>rated DC</sub> (50 Hz 500 V)	kW	320	525	705	995
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	295	480	640	910
• At / <sub>rated DC</sub> (60 Hz 575 V)	hp	500	790	1115	1465
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	450	740	990	1400
DC link current					
Rated current Irated DC	А	550	900	1200	1700
• Base-load current $I_{H DC}$ <sup>1)</sup>	A	490	800	1068	1513
Maximum current Imax DC	A	825	1350	1800	2550
Infeed/regenerative feedback current					
Rated current Irated I	А	463	757	1009	1430
Maximum current Imax I	A	694	1135	1513	2145
Current demand					
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	1.35	1.4	1.5	1.7
• 500 V AC <sup>2)</sup>	А	1.3	2.9	4.3	4.3
• 690 V AC	А	1	2.1	3.1	3.1
DC link capacitance					
Smart Line Module	μF	5600	7400	11100	14400
• Drive line-up, max.	μF	28000	29600	44400	57600
Power loss, max. <sup>3)</sup>					
• At 50 Hz 690 V	kW	4.3	6.5	12.0	13.8
• At 60 Hz 575 V	kW	4.3	6.5	12.0	13.8
Cooling air requirement	m <sup>3</sup> /s	0.36	0.78	1.08	1.08
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69/73	70/73	70/73	70/73
PE/GND connection		PE bar	PE bar	PE bar	PE bar
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240
Cable length, max. 4)					
Shielded	m	2250	2750	2750	2750
Unshielded	m	3375	4125	4125	4125
Degree of protection		IP20	IP20	IP20	IP20
Dimensions					
• Width	mm	400	600	800	800
• Height <sup>5)</sup>	mm	2200	2200	2200	2200
Depth	mm	600	600	600	600
Weight, approx.	kg	270	550	795	795
Frame size	kΛ	GX	HX	JX	JX
Short-circuit current rating according to IEC	kA	65	84	100	100
Minimum short-circuit current <sup>6)</sup>	А	6200	10500	2500	3200

 $^{1)}$  The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>4)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

 $^{2)}$  The current demand for the 500 V / 690 V AC auxiliary power supply is drawn from the line input voltage.

<sup>3)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions. <sup>5)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>6)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

Active Line Modules incl. Active Interface Modules

#### Overview



Active Line Modules are regulated rectifier/regenerative units. They can supply energy to the DC link and return regenerative energy to the supply system.

In contrast to Basic Line Modules and Smart Line Modules, Active Line Modules generate a stabilized DC voltage that is kept constant despite fluctuations in the line voltage (the line voltage must remain within the permissible tolerance range). Active Line Modules in combination with an Active Interface Module draw a virtually sinusoidal current from the supply system. Almost no harmonics occur.

A Braking Module and braking resistor are required only if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be recovered to the supply).

Active Line Modules are suitable for connection to grounded TN/TT and non-grounded IT systems. The following voltages and power ratings are available:

Line voltage	Rated power
380 480 V 3 AC	132 900 kW
500 690 V 3 AC	630 1400 kW

#### Design

Active Line Modules are always operated together with an Active Interface Module that contains the associated Clean Power Filter and pre-charging circuit. The integrated line filter ensures compliance with the EMC requirements for the "second environment".

The Active Line Module and Active Interface Module are supplied as a complete, fully wired unit, i.e. the customer does not need to supply any further cables or carry out any other wiring tasks.

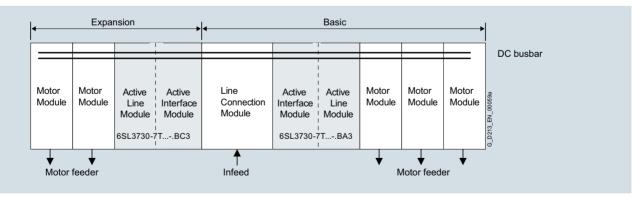
#### Parallel connection of Active Line Modules to increase power rating

Active Line Modules are available for creating drive line-ups with more power. These modules can be operated in parallel on a common Line Connection Module and are arranged to the right and left of the Line Connection Module. The power connections on the Active Line Module on the left of the Line Connection Module are a mirror image (article no. with "**C**" in the next to last position, example: 6SL3730-7T.41.-.B**C**3), which results in a very compact design for the line infeed.

Please note that only Active Line Modules with exactly the same power rating may be connected in parallel. The potential for imbalances in current distribution means that a current derating of 5 % applies; this must be taken into account when the modules are dimensioned.

A connection of the Active Line Modules connected in parallel using DRIVE-CLiQ must be taken into consideration during the engineering phase.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.



Air-cooled units

# Active Line Modules incl. Active Interface Modules

# Selection and ordering data

Rated power at 400 V	Rated infeed/ regenerative feedback current	Note for a parallel connection	Active Line Module (incl. Active Interface Module)
kW	A	Mounting onto a Line Connection Module	Article No.
Line voltage 3 (DC link volta	380 480 V 3 / ge 570 720 \	AC / DC)	
132	210	-	6SL3730-7TE32-1BA3
160	260	-	6SL3730-7TE32-6BA3
235	380	-	6SL3730-7TE33-8BA3
300	490	-	6SL3730-7TE35-0BA3
380	605	-	6SL3730-7TE36-1BA3
500	840	-	6SL3730-7TE38-4BA3
630	985	-	6SL3730-7TE41-0BA3
		Left	6SL3730-7TE41-0BC3
900	1405	-	6SL3730-7TE41-4BA3
		Left	6SL3730-7TE41-4BC3

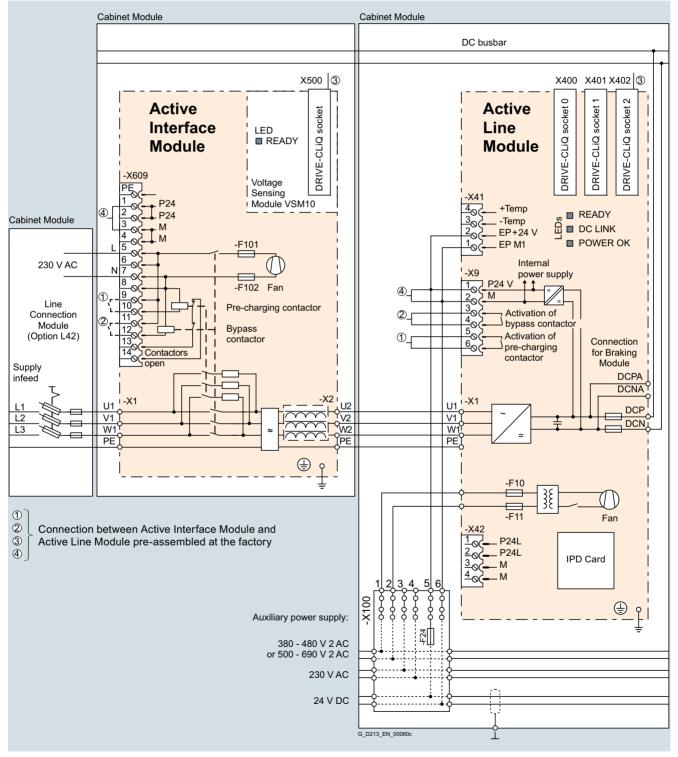
Rated power at 690 V	Rated infeed/ regenerative feedback current	Note for a parallel connection	Active Line Module (incl. Active Interface Module)
kW	A	Mounting onto a Line Connection Module	Article No.
	500 690 V 3 / ge 750 1035		
630	575	-	6SL3730-7TG35-8BA3
800	735	-	6SL3730-7TG37-4BA3
		Left	6SL3730-7TG37-4BC3
1100	1025	-	6SL3730-7TG41-0BA3
		Left	6SL3730-7TG41-0BC3
1400	1270	-	6SL3730-7TG41-3BA3
		Left	6SL3730-7TG41-3BC3

Air-cooled units

Active Line Modules incl. Active Interface Modules

# Integration

The Active Line Module is controlled by the CU320-2 Control Unit. Communication between the Control Unit and module is established via DRIVE-CLiQ connections. The Active Interface Module is included in the scope of delivery for the Active Line Module.

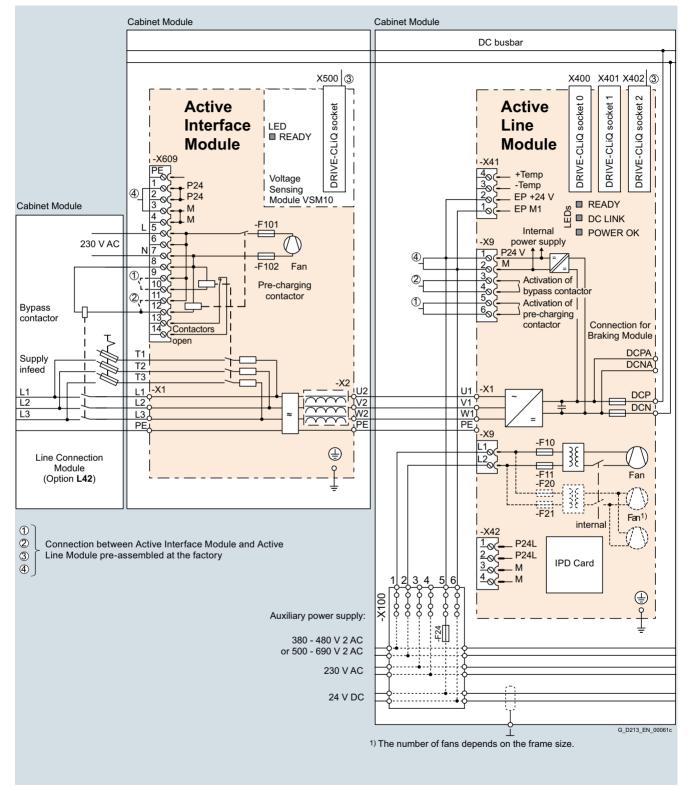


Connection example: Active Line Module (frame size FI/FX and GI/GX)

Air-cooled units

#### Active Line Modules incl. Active Interface Modules

#### Integration (continued)



Connection example: Active Line Module (frame size HI/HX and JI/JX)

Air-cooled units

Active Line Modules incl. Active Interface Modules

#### Line voltage 380 ... 480 V 3 AC Active Line Modules 6SL3730-6SL3730-7TE33-8BA3 6SL3730-7TE35-0BA3 7TE36-1BA3 6SL3730-7TE38-4BA3 6SL3730- 6SL3730-7TE41-0BA3 7TE41-4BA3 6SL3730-7TE32-1BA3 7TE32-6BA3 6SL3730-7TE41-0BC3 6SL3730-7TE41-4BC3 For a parallel circuit configuration, mounted to the left of the Line Connection Module Rated power At I<sub>rated DC</sub> (50 Hz 400 V) kW 132 160 235 300 380 500 630 900 • At I<sub>H DC</sub> (50 Hz 400 V) kΜ 115 210 270 335 465 545 780 145 • At I<sub>rated DC</sub> (60 Hz 460 V) hp 200 250 400 500 600 700 900 1250 • At I<sub>H DC</sub> (60 Hz 460 V) hp 150 200 300 400 500 700 800 1000 **DC** link current Rated current Irated DC 235 291 425 549 678 940 1103 1574 А Base-load current I<sub>H DC</sub><sup>1)</sup> 209 378 1404 Δ 259 489 603 837 982 Maximum current Imax DC 352 436 637 1017 1410 2361 А 823 1654 Infeed/regenerative feedback current Rated current Irated I 260 380 490 605 840 985 1405 А 210 • Maximum current Imax I А 315 390 570 735 907 1260 1477 2107 Current demand · 24 V DC auxiliary power supply А 1.27 1.27 1.52 1.52 1.57 1.57 1.67 1.67 • 230 V AC auxiliary power supply А 0.6 06 12 12 46 46 49 49 400 V AC <sup>2)</sup> A 0.63 1.13 1.8 1.8 3.6 3.6 5.4 5.4 **DC** link capacitance Active Line Module μF 4200 5200 7800 9600 12600 16800 18900 28800 • Drive line-up, max μF 41600 41600 76800 76800 134400 134400 230400 230400 Power loss, max, 3) • At 50 Hz 400 V kW 4.3 4.9 6.9 8.7 11.7 13.8 17.6 21.8 • At 60 Hz 460 V 4.4 kW 9.0 12.1 5.1 7.2 14.3 18.3 22.7 Cooling air requirement m<sup>3</sup>/s 0.47 0.47 0.83 0.83 1.18 1.18 1.48 1.48 Sound pressure level $L_{nA}^{4}$ dB 71/73 71/73 72/74 72/74 77/79 77/79 78/80 78/80 (1 m) at 50/60 Hz **PE/GND** connection PE bar Busbar cross-section mm<sup>2</sup> 600 600 600 600 600 600 600 600 mm<sup>2</sup> 240 240 240 240 240 240 240 240 Conductor cross-section, max. (IEC) Cable length, max. 5) Shielded 2700 2700 2700 3900 3900 3900 2700 3900 m Unshielded 4050 4050 4050 4050 5850 5850 5850 5850 m Degree of protection IP20 IP20 IP20 IP20 IP20 IP20 IP20 IP20 Dimensions • Width mm 800 800 800 800 1000 1000 1400 1400 Height <sup>6)</sup> 2200 2200 2200 2200 2200 2200 2200 2200 mm Depth 600 600 600 600 600 600 600 600 mm 380 380 530 530 930 930 1360 1360 Weight, approx. kg Frame size FX + FI FX + FI GX + GI GX + GI HX + HI HX + HI JX + JI JX + JI Short-circuit current rating kΑ 65 65 65 65 65 84 84 100 according to IEC Minimum short-circuit current 7) А 6200 10500 10500 10500 12000 2000 4000 6400

 $^{1)}$  The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

Technical specifications

<sup>5)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.
 <sup>6)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>2)</sup> The current demand for the 400 V AC auxiliary power supply is drawn from the line input voltage.

- <sup>3)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.
- <sup>4)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

<sup>7)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

#### Active Line Modules incl. Active Interface Modules

# Technical specifications (continued)

Line voltage 500 690 V 3 AC		Active Line Modules					
		6SL3730-7TG35-8BA3	6SL3730-7TG37-4BA3	6SL3730-7TG41-0BA3	6SL3730-7TG41-3BA3		
For a parallel circuit configuration, mounted to the left of the Line Connect Module	ion		6SL3730-7TG37-4BC3	6SL3730-7TG41-0BC3	6SL3730-7TG41-3BC3		
Rated power							
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	630	800	1100	1400		
• At / <sub>H DC</sub> (50 Hz 690 V)	kW	620	705	980	1215		
• At I <sub>rated DC</sub> (50 Hz 500 V)	kW	447	560	780	965		
• At I <sub>H DC</sub> (50 Hz 500 V)	kW	450	510	710	880		
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	675	900	1250	1500		
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	506	600	1000	1250		
DC link current							
Rated current I <sub>rated DC</sub>	А	644	823	1148	1422		
• Base-load current $I_{\rm H DC}^{(1)}$	А	573	732	1022	1266		
Maximum current Imax DC	А	966	1234	1722	2133		
Infeed/regenerative feedback current							
Rated current I <sub>rated I</sub>	A	575	735	1025	1270		
Maximum current Imax I	А	862	1102	1537	1905		
Current demand <sup>2)</sup>							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	A	1.57	1.67	1.87	1.87		
230 V AC auxiliary power supply	A	4.6	4.9	4.9	4.9		
• 500 V AC	A	3.0	4.4	4.4	4.4		
• 690 V AC	А	2.1	3.1	3.1	3.1		
DC link capacitance							
Active Line Module	μF	7400	11100	14400	19200		
• Drive line-up, max.	μF	59200	153600	153600	153600		
Power loss, max. <sup>3)</sup>	r.						
• At 50 Hz 500/690 V	kW	13.6	19.2	22.8	26.1		
• At 60 Hz 575 V	kW	13.0	18.6	22.1	24.9		
Cooling air requirement	m <sup>3</sup> /s	1.18	1.48	1.48	1.48		
Sound pressure level L <sub>pA</sub> <sup>4)</sup> (1 m) at 50/60 Hz	dB	77/79	77/79	77/79	77/79		
PE/GND connection		PE bar	PE bar	PE bar	PE bar		
Busbar cross-section	mm <sup>2</sup>	600	600	600	600		
• Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240		
Cable length, max. <sup>5)</sup>							
• Shielded	m	2250	2250	2250	2250		
Unshielded	m	3375	3375	3375	3375		
Degree of protection		IP20	IP20	IP20	IP20		
Dimensions							
• Width	mm	1000	1400	1400	1400		
• Height <sup>6)</sup>	mm	2200	2200	2200	2200		
• Depth	mm	600	600	600	600		
Weight, approx.	kg	930	1360	1360	1360		
Frame size		HX + HI	JX + JI	JX + JI	JX + JI		
Short-circuit current rating according to IEC	kA	65	84	100	100		
Minimum short-circuit current 7)	А	9000	10500	2500	3200		
<ul> <li>For connection in parallel</li> </ul>	А	-	4000	4000	5000		

 $^{1)}$  The base-load current  $\mathit{I}_{H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $\mathit{I}_{max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The current demand for the 500 V/690 V AC auxiliary power supply is drawn from the line input voltage.

<sup>3)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

<sup>4)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

<sup>5)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

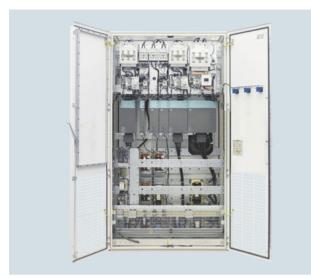
<sup>6)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 or IP54.

<sup>7)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

#### Motor Modules in booksize format

### Overview



Motor Modules Booksize format are also available as Booksize Cabinet Kits in voltage class 380 V to 480 V (DC link voltage 510 V to 720 V).

Motor Modules are also available as Single Motor Modules for power ratings of 4.8 kW to 71 kW for connection of a motor.

#### Design

Motor Modules Booksize format are installed in the factory as Booksize Cabinet Kits in Booksize Base Cabinets. This complete unit contains all of the components necessary for operation.

Several Booksize Cabinet Kits can be installed in one Booksize Base Cabinet, depending on the installation width requirements, which in turn depend on the power rating. The number of Booksize Cabinet Kits that can be installed in a Booksize Base Cabinet is determined solely on the basis of the available cabinet width. By changing the way in which the cabinet width is used (i.e. the equipment that is installed), it can be adapted to suit system requirements.

Each Motor Module is connected separately to the DC busbar of the SINAMICS S120 Cabinet Module via a separate fuse switch disconnector with integrated fuses. The DC connecting busbar integrated in the units is not used.

The basic version of the Booksize Cabinet Kit comprises the following components:

- Motor Module in booksize format
- Fuse switch disconnector for each Motor Module installed
- Customer interface -X55.1 located in the connection area of the Booksize Base Cabinet
- · Shield connection plate
- Complete electrical connection to the Booksize Base Cabinet interfaces

The Booksize Base Cabinets can be operated up to and including IP54 degree of protection without additional temperature derating. However, some values need to be taken into account that differ from those of the chassis format. For derating data, see System overview  $\rightarrow$  Characteristic curves.

# Selection and ordering data

Type rating at 400 V	Rated output current <i>I</i> <sub>rated</sub>	Width	Single Motor Module Booksize Cabinet Kit
kW	А	mm	Article No.
	380 480 V 3 . age 510 720 V		
4.8	9	100	6SL3720-1TE21-0AB3
9.7	18	100	6SL3720-1TE21-8AB3
16	30	100	6SL3720-1TE23-0AB3
24	45	200	6SL3720-1TE24-5AB3
32	60	200	6SL3720-1TE26-0AB3
46	85	200	6SL3720-1TE28-5AB3
71	132	300	6SL3720-1TE31-3AB3

Booksize Cabinet Kits must always be ordered in combination with at least one Booksize Base Cabinet (cannot be supplied as a single unit).

The required number of Booksize Cabinet Kits installed in a Booksize Base Cabinet must be stated in plain text in the order. The number of possible kits is limited only by the usable installation width of the Booksize Base Cabinet.

Booksize Base Cabinets ready to be installed in the Booksize Cabinet Kits:

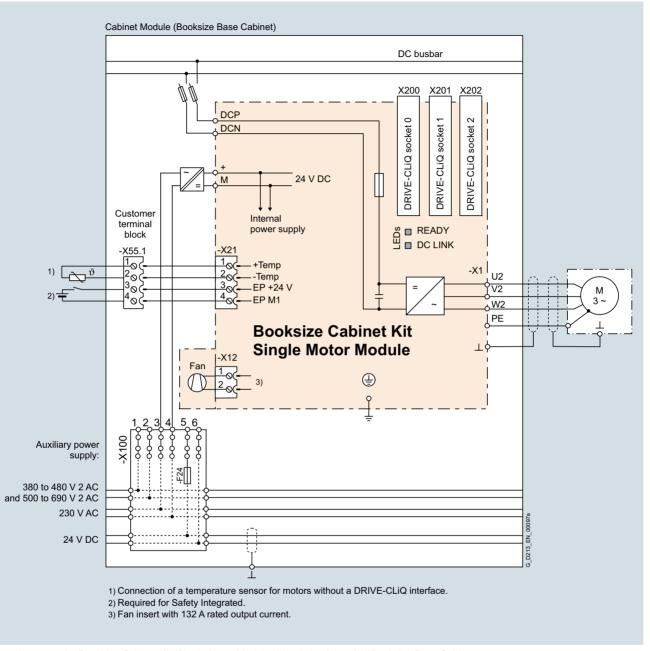
Usable installa- tion width	Weight, approx.	Dimensions with degree of protection IP20 <sup>1)</sup> $(W \times D \times H)$	Booksize Base Cabinet
mm	kg	mm	Article No.
600	170	$800 \times 600 \times 2200$	6SL3720-1TX38-0AA3
1000	240	$1200\times600\times2200$	6SL3720-1TX41-2AA3

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Air-cooled units

### Motor Modules in booksize format

# Integration



Connection example: Booksize Cabinet Kit (Single Motor Module in booksize format) in Booksize Base Cabinet

Air-cooled units

Motor Modules in booksize format

# Technical specifications

Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Single Motor Modules Booksize Cabinet Kit					
		6SL3720-1TE21-0AB3	6SL3720-1TE21-8AB3	6SL3720-1TE23-0AB3	6SL3720-1TE24-5AB3		
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	4.8	9.7	16	24		
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	4.1	8.2	13.7	21		
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	5	10	20	30		
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	5	10	15	25		
Output current							
Rated current I <sub>rated O</sub>	А	9	18	30	45		
<ul> <li>Base-load current I<sub>H</sub><sup>3)</sup></li> </ul>	А	7.7	15.3	25.5	38		
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	18	36	56	85		
DC link current <i>I</i> d <sup>4)</sup>	А	11	22	36	54		
Current demand							
• 24 V DC, max.	А	0.85	0.85	0.9	1.2		
DC link capacitance	μF	110	220	710	1175		
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	4	4	4	4		
<ul> <li>Pulse frequency, max.</li> </ul>							
- With current derating	kHz	16	16	16	16		
Power loss, max. <sup>6)</sup>							
• At 50 Hz 400 V	kW	0.08	0.165	0.29	0.43		
• At 60 Hz 460 V	kW	0.08	0.165	0.29	0.43		
Cooling air requirement	m <sup>3</sup> /s	0.008	0.008	0.016	0.031		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	<60	<60	<60	<65		
Motor connection U2, V2, W2		Terminal	Terminal	Terminal	Terminal		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	6	6	6	16		
Cable length, max. <sup>7)</sup>							
Shielded	m	50	70	100	100		
Unshielded	m	75	100	150	150		
PE/GND connection		PE bar	PE bar	PE bar	PE bar		
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240		
Degree of protection		IP20	IP20	IP20	IP20		
Weight, approx.	kg	20	20	21.9	27		
Width	mm	100	100	100	200		
Short-circuit current rating according to IEC	kA	65	65	65	65		

- $^{\rm 1)}\,$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 460 V 3 AC 60 Hz.
- <sup>3)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>4)</sup> For a DC link voltage of 600 V DC.

- <sup>5)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>6)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request.

Air-cooled units

### Motor Modules in booksize format

Technical specifications (contin	nued)						
Line voltage 380 480 V 3 AC DC link voltage 510 720 V DC		Single Motor Modules Booksize Cabinet Kit					
		6SL3720-1TE26-0AB3	6SL3720-1TE28-5AB3	6SL3720-1TE31-3AB3			
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	32	46	71			
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	28	37	57			
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	40	60	100			
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	40	50	75			
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	60	85	132			
<ul> <li>Base-load current I<sub>H</sub><sup>3)</sup></li> </ul>	А	52	68	105			
Maximum current I <sub>max O</sub>	А	113	141	210			
DC link current <i>I</i> d <sup>4)</sup>	А	72	102	158			
Current demand							
• 24 V DC, max.	А	1.2	1.5	1.5			
DC link capacitance	μF	1410	1880	2820			
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	4	4	4			
<ul> <li>Pulse frequency, max.</li> </ul>							
- With current derating	kHz	16	16	16			
Power loss, max. <sup>6)</sup>							
• At 50 Hz 400 V	kW	0.59	0.75	1.25			
• At 60 Hz 460 V	kW	0.59	0.75	1.25			
Cooling air requirement	m <sup>3</sup> /s	0.031	0.044	0.144			
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	<65	<60	<73			
Motor connection U2, V2, W2		Terminal	Terminal	Terminal			
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	16	35	70			
Cable length, max. 7)							
Shielded	m	100	100	100			
Unshielded	m	150	150	150			
PE/GND connection		PE bar	PE bar	PE bar			
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600			
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240			
Degree of protection		IP20	IP20	IP20			
Weight, approx.	kg	27	33	41			
Width	mm	200	200	300			

65

 Width
 mm
 200

 Short-circuit current rating according to IEC
 kA
 65

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- <sup>3)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>4)</sup> For a DC link voltage of 600 V DC.
  - 4/40 Siemens D 21.3 · 2017

<sup>5)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

65

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- <sup>6)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.
- <sup>7)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request.

Selection and ordering data

# **SINAMICS S120 Cabinet Modules**

Air-cooled units

#### Motor Modules in chassis format

#### Overview



Motor Modules in chassis format are available in the power range from 75 kW to 1200 kW.

Line voltage	DC link voltage	Type rating
380 480 V 3 AC	510 720 V DC	110 800 kW
500 690 V 3 AC	675 1035 V DC	75 1200 kW

By connecting in parallel up to four Motor Modules operated on one Control Unit and which supply one motor, it is possible to increase the available shaft power to a maximum of approx. 4500 kW (taking into account the derating factors according to the SINAMICS Low Voltage Engineering Manual).

SINAMICS S120 Motor Modules in chassis format can also be used as a Braking Module if, instead of a motor, a 3-phase braking resistor is connected.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Design

Motor Modules in chassis format contain the following components as standard:

- Retaining device for the DC busbar, including the connection to the DC connections of the Motor Module
- Nickel-plated connection busbars for motor cables for Motor Modules, frame sizes FX and GX; for Motor Modules, frame sizes HX and JX, the connection is made directly on the unit
- · Cable retaining bar for the power cables
- DRIVE-CLiQ interface (3 DRIVE-CLiQ sockets), without Control Unit
- Customer interface -X55
- Auxiliary power supply system (6-pole) for the auxiliary power supply, including cable connections for looping through to the next Cabinet Module
- Nickel-plated PE bar (60 x 10 mm), including jumper for looping through to the next Cabinet Module
- EMC-compliant design thanks to additional shielding measures and appropriately routed cables

	Selection and ordering data								
Type rating at 400 V or 690 V	Rated output current I <sub>rated</sub>	Motor Module in chassis format							
kW	А	Article No.							
Line voltage 380 48 (DC link voltage 510 .									
110	210	6SL3720-1TE32-1AA3							
132	260	6SL3720-1TE32-6AA3							
160	310	6SL3720-1TE33-1AA3							
200	380	6SL3720-1TE33-8AA3							
250	490	6SL3720-1TE35-0AA3							
315	605	6SL3720-1TE36-1AA3							
400	745	6SL3720-1TE37-5AA3							
450	840	6SL3720-1TE38-4AA3							
560	985	6SL3720-1TE41-0AA3							
710	1260	6SL3720-1TE41-2AA3							
800	1405	6SL3720-1TE41-4AA3							
Line voltage 500 69 (DC link voltage 675 .	90 V 3 AC 1035 V DC)								
75	85	6SL3720-1TG28-5AA3							
90	100	6SL3720-1TG31-0AA3							
110	120	6SL3720-1TG31-2AA3							
132	150	6SL3720-1TG31-5AA3							
160	175	6SL3720-1TG31-8AA3							
200	215	6SL3720-1TG32-2AA3							
250	260	6SL3720-1TG32-6AA3							
315	330	6SL3720-1TG33-3AA3							
400	410	6SL3720-1TG34-1AA3							
450	465	6SL3720-1TG34-7AA3							
560	575	6SL3720-1TG35-8AA3							
710	735	6SL3720-1TG37-4AA3							
800	810	6SL3720-1TG38-1AA3							
900	910	6SL3720-1TG38-8AA3							
1000	1025	6SL3720-1TG41-0AA3							
1200	1270	6SL3720-1TG41-3AA3							

Air-cooled units

#### Motor Modules in chassis format

#### Integration

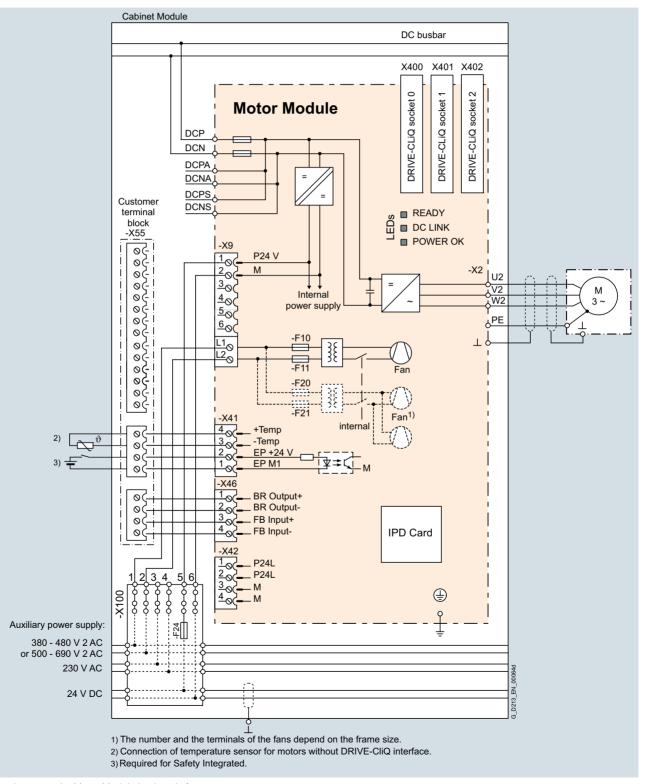
Motor Modules are controlled by the CU320-2 DP or CU320-2 PN Control Unit. Communication between the Control Unit and Modules is established via a DRIVE-CLiQ connection.

If the Control Unit is integrated in the same cabinet as an option with order code **K90** or **K95**, these communication cables will already be installed. If the Control Unit is to be mounted exter-

nally, the DRIVE-CLiQ cable will not be included in the scope of delivery and must be configured on site.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

For a description of the terminal block, see section Customer terminal block -X55.



Connection example: Motor Module in chassis format

Air-cooled units

Motor Modules in chassis format

# Technical specifications

Line voltage 380 480 V 3 AC		Motor Modules	in chassis forma	t			
DC link voltage 510 720 V DC		6SL3720- 1TE32-1AA3	6SL3720- 1TE32-6AA3	6SL3720- 1TE33-1AA3	6SL3720- 1TE33-8AA3	6SL3720- 1TE35-0AA3	6SL3720- 1TE36-1AA3
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	200	250	315
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	160	200	250
• At <i>I</i> <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	300	400	500
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	250	350	350
Output current							
Rated current I <sub>rated Q</sub>	A	210	260	310	380	490	605
<ul> <li>Base-load current I<sup>(3)</sup></li> <li>Base-load current I<sup>(4)</sup></li> </ul>	A	205	250	302	370	477	590
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	178	233	277	340	438	460
Maximum current I <sub>max O</sub>	А	307	375	453	555	715	885
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>							
when supplied via							
<ul> <li>Basic/Smart Line Module</li> </ul>	A	252	312	372	456	588	726
- Active Line Module	А	227	281	335	411	529	653
• Base-load current I <sub>L DC</sub> <sup>3)</sup>							
when supplied via	А	245	304	362	444	573	707
<ul> <li>Basic/Smart Line Module</li> <li>Active Line Module</li> </ul>	A	245 221	304 273	362	444 400	573 515	636
<ul> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> </ul>	A	221	215	520	400	515	000
when supplied via							
- Basic/Smart Line Module	А	224	277	331	405	523	646
- Active Line Module	А	202	250	298	365	470	581
Current demand							
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	0.8	0.8	0.9	0.9	0.9	1.0
• 400 V AC	A	0.63	1.13	1.8	1.8	1.8	3.6
DC link capacitance	μF	4200	5200	6300	7800	9600	12600
Pulse frequency <sup>5)</sup>	μι	4200	3200	0300	7800	9000	12000
		0	0	0	0	0	1.05
Rated frequency	kHz	2	2	2	2	2	1.25
Pulse frequency, max.     Without ourrept densiting	kHz	2	2	2	2	2	1.25
<ul> <li>Without current derating</li> <li>With current derating</li> </ul>	kHz	8	8	8	8	8	7.5
	KI IZ	0	0	0	0	0	1.5
Power loss, max. <sup>6)</sup>	1.14/	1 00	0.5	0.00	0.07	4.00	5.04
• At 50 Hz 400 V	kW	1.86	2.5	2.96	3.67	4.28	5.84
• At 60 Hz 460 V	kW	1.94	2.6	3.1	3.8	4.5	6.3
Cooling air requirement	m <sup>3</sup> /s	0.17	0.23	0.36	0.36	0.36	0.78
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	67	69	69	69	69	72
Motor connection		M12 screws					
<ul><li>U2, V2, W2</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup>	2 × 185	2 × 185	2 × 240	2 × 240	2 × 240	4 × 240
Cable length, max. <sup>7)</sup>							
Shielded	m	300	300	300	300	300	300
Unshielded	m	450	450	450	450	450	450
PE/GND connection	mm <sup>2</sup>	PE bar 600	PE bar				
<ul> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup>	600 240	600 240	600 240	600 240	600 240	600 240
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
		100	100	100	100	100	<u></u>
• Width <sup>8)</sup>	mm	400	400	400	400	400	600
• Height <sup>9)</sup>	mm	2200	2200	2200	2200	2200	2200
• Depth	mm	600	600	600	600	600	600
Weight, approx.	kg	145	145	286	286	286	490
Frame size		FX	FX	GX	GX	GX	HX
Short-circuit current rating according to IEC	kA	65	65	65	65	65	65

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.

- $^{3)}$  The base-load current  $\mathit{I}_{L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>4)</sup> The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- <sup>5)</sup> Information regarding the correlation between the pulse frequency and max, output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

<sup>7)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

 <sup>8)</sup> With option L10 (dv/dt filter plus VPL): - Frame sizes FX/GX/HX/JX: Additional cabinet 600 mm wide With option L34 (circuit breaker on the output side): - Frame size FX/GX: Additional cabinet 400 mm wide - Frame size HX/JX: Additional cabinet 600 mm wide.

Air-cooled units

#### Motor Modules in chassis format

#### Technical specifications (continued)

Line voltage 380 480 V 3 AC		Motor Modules	in chassis format			
DC link voltage 510 720 V DC		6SL3720-	6SL3720-	6SL3720-	6SL3720-	6SL3720-
		1TE37-5AA3	1TE38-4AA3	1TE41-0AA3	1TE41-2AA3	1TE41-4AA3
Type rating						
• At / <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	400	450	560	710	800
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	315	400	450	560	710
• At $I_{L}$ (60 Hz 460 V) <sup>2)</sup>	hp	600	700	800	1000	1150
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	450	600	700	900	1000
Output current	•	745	0.40	005	1000	1 105
Rated current I <sub>rated Q</sub> Base load current ( <sup>3</sup> )	A	745	840	985	1260	1405
	A	725	820	960	1230	1370
• Base-load current <i>I</i> <sub>H</sub> <sup>4)</sup>	A	570	700	860	1127	1257
Maximum current I <sub>max O</sub>	А	1087	1230	1440	1845	2055
DC link current						
Rated current Irated DC						
when supplied via		004	1000	1100	1510	1000
- Basic/Smart Line Module	A	894	1008	1182	1512	1686
- Active Line Module	A	805	907	1064	1361	1517
• Base-load current $I_{\rm L DC}^{(3)}$						
when supplied via	^	071	000	1150	1474	1040
- Basic/Smart Line Module	A	871	982	1152	1474	1643
- Active Line Module	A	784	884	1037	1326	1479
Base-load current I <sub>H DC</sub> <sup>4)</sup>						
when supplied via	٨	705	907	1051	1945	1500
- Basic/Smart Line Module	A	795	897	1051	1345	1500
- Active Line Module	A	716	807	946	1211	1350
Current demand	•	1.0	1.0	1.05		
• 24 V DC auxiliary power supply	A	1.0	1.0	1.25	1.4	1.4
• 400 V AC	A	3.6	3.6	5.4	5.4	5.4
DC link capacitance	μF	15600	16800	18900	26100	28800
Pulse frequency <sup>5)</sup>						
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>						
<ul> <li>Without current derating</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25
<ul> <li>With current derating</li> </ul>	kHz	7.5	7.5	7.5	7.5	7.5
Power loss, max. <sup>6)</sup>						
• At 50 Hz 400 V	kW	6.68	7.15	9.5	11.1	12.0
• At 60 Hz 460 V	kW	7.3	7.8	10.2	12.0	13.0
Cooling air requirement	m <sup>3</sup> /s	0.78	0.78	1.08	1.08	1.08
Sound pressure level L <sub>pA</sub>	dB	72	72	72	72	72
(1 m) at 50/60 Hz	uв	12	12			12
Motor connection		M12 screws	M12 screws	M12 screws	M12 screws	M12 screws
U2, V2, W2	2					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	6 × 240	6 × 240	6 × 240
Cable length, max. <sup>7)</sup>						
Shielded	m	300	300	300	300	300
Unshielded	m	450	450	450	450	450
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240
Degree of protection		IP20	IP20	IP20	IP20	IP20
Dimensions						
• Width <sup>8)</sup>	mm	600	600	800	800	800
• Height <sup>9)</sup>	mm	2200	2200	2200	2200	2200
• Depth	mm	600	600	600	600	600
Weight, approx.	kg	490	490	700	700	700
Frame size		HX	HX	JX	JX	JX
	L.A					
Short-circuit current rating according to IEC	kA	65	84	84	100	100

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.

<sup>6)</sup> The specified power loss represents the maximum value at 100% utili-zation. The value is lower under normal operating conditions.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.

<sup>3)</sup> The base-load current  $l_1$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

<sup>5)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual. <sup>8)</sup> With option L10 (dv/dt filter plus VPL): Frame sizes FX/GX/HX/JX: Additional cabinet 600 mm wide
With option L34 (circuit breaker on the output side):
Frame size FX/GX: Additional cabinet 400 mm wide
Frame size HX/JX: Additional cabinet 600 mm wide.

Air-cooled units

Motor Modules in chassis format

# Technical specifications (continued)

Line voltage 500 690 V 3 AC			in chassis format		1		
DC link voltage 675 1035 V DC		6SL3720- 1TG28-5AA3	6SL3720- 1TG31-0AA3	6SL3720- 1TG31-2AA3	6SL3720- 1TG31-5AA3	6SL3720- 1TG31-8AA3	6SL3720- 1TG32-2AA3
Type rating							
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	75	90	110	132	160	200
• At $I_{H}$ (50 Hz 690 V) <sup>1)</sup>	kW	55	75	90 75	110	132	160
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup> • At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	55	75 75	90	110	132
• At / <sub>H</sub> (50 Hz 500 V) <sup>2</sup> • At / <sub>L</sub> (60 Hz 575 V) <sup>2</sup>	kW hp	45 75	55 75	75 100	90 150	90 150	110 200
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	75	100	125	150	200
Output current	ΠP			100	120	100	200
Bated current later o	А	85	100	120	150	175	215
<ul> <li>Rated current l<sub>rated Q</sub></li> <li>Base-load current l<sup>3</sup><sub>L</sub></li> </ul>	A	80	95	115	142	170	208
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	76	89	107	134	157	192
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	120	142	172	213	255	312
DC link current							
<ul> <li>Rated current I<sub>rated DC</sub></li> </ul>							
when supplied via		100	100				050
<ul> <li>Basic/Smart Line Module</li> <li>Active Line Module</li> </ul>	A A	102 92	120 108	144 130	180 162	210 189	258 232
• Base-load current $I_{L DC}^{3}$	~	92	100	150	102	109	202
when supplied via							
- Basic/Smart Line Module	А	99	117	140	175	204	251
<ul> <li>Active Line Module</li> </ul>	А	89	105	126	157	184	226
Base-load current / <sub>H DC</sub> <sup>4)</sup>							
when supplied via	٨	00	100	100	100	100	000
<ul> <li>Basic/Smart Line Module</li> <li>Active Line Module</li> </ul>	A A	90 81	106 96	128 115	160 144	186 168	229 206
	A	01	50	115	144	100	200
<ul> <li>Current demand</li> <li>24 V DC auxiliary power supply</li> </ul>	А	0.8	0.8	0.8	0.8	0.9	0.9
<ul> <li>690 V AC</li> </ul>	Â	0.4	0.4	0.4	0.4	1.0	1.0
DC link capacitance	μF	1200	1200	1600	2800	2800	2800
Pulse frequency <sup>5)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	7.5
<ul> <li>Power loss, max. <sup>6)</sup></li> <li>At 50 Hz 690 V</li> </ul>	1.0.07	1 17	1 40	1.00	1.0	0.67	2.00
• At 50 Hz 590 V • At 60 Hz 575 V	kW kW	1.17 1.1	1.43 1.3	1.89 1.77	1.8 1.62	2.67 2.5	3.09 2.91
Cooling air requirement	m <sup>3</sup> /s	0.17	0.17	0.17	0.17	0.36	0.36
Sound pressure level L <sub>pA</sub>	dB	67	67	67	67	69	69
(1 m) at 50/60 Hz	uр	07	07	01	01	00	00
Motor connection U2, V2, W2		M12 screws					
<ul> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup>	2 × 185	2 × 185	2 × 185	2 × 185	2 × 240	2 × 240
Cable length, max. 7)							
Shielded	m	300	300	300	300	300	300
Unshielded	m	450	450	450	450	450	450
PE/GND connection	0	PE bar					
Busbar cross-section	mm <sup>2</sup>	600	600	600	600	600	600
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	240
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
Dimensions		100	100	100	100	100	100
<ul> <li>Width <sup>8)</sup></li> <li>Height <sup>9)</sup></li> </ul>	mm	400	400	400	400	400	400
Depth	mm mm	2200 600	2200 600	2200 600	2200 600	2200 600	2200 600
Weight, approx.	kg	145	145	145	145	286	286
Frame size		FX	FX	FX	FX	GX	GX
	kΛ	65	65	65	65		65
Short-circuit current rating according to IEC	kA	00	00	00	00	65	00

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{\rm 4)}$  The base-load current  ${\it I}_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

7) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>8)</sup> With option **L10** (dv/dt filter plus VPL): - Frame sizes FX/GX/HX/JX: Additional cabinet 600 mm wide With option L34 (circuit breaker on the output side): Frame size FX/GX: Additional cabinet 400 mm wide
 Frame size HX/JX: Additional cabinet 600 mm wide.

Air-cooled units

#### Motor Modules in chassis format

#### Technical specifications (continued)

Line voltage 500 690 V 3 AC		Motor Modules in chassis format						
DC link voltage 675 1035 V DC		6SL3720- 1TG32-6AA3	6SL3720- 1TG33-3AA3	6SL3720- 1TG34-1AA3	6SL3720- 1TG34-7AA3	6SL3720- 1TG35-8AA3	6SL3720- 1TG37-4AA3	
Type rating           • At $I_L$ (50 Hz 690 V) <sup>1</sup> )           • At $I_H$ (50 Hz 690 V) <sup>1</sup> )           • At $I_H$ (50 Hz 500 V) <sup>1</sup> )           • At $I_H$ (50 Hz 500 V) <sup>1</sup> )           • At $I_H$ (50 Hz 500 V) <sup>2</sup> )           • At $I_H$ (60 Hz 575 V) <sup>2</sup> )	kW kW kW kW hp hp	<b>250</b> 200 160 132 250 200	<b>315</b> 250 200 160 300 250	<b>400</b> 315 250 200 400 350	<b>450</b> 400 315 250 450 450	<b>560</b> 450 400 315 600 500	<b>710</b> 630 500 450 700 700	
Output current • Rated current I <sub>rated Q</sub> • Base-load current I <sub>L</sub> <sup>3)</sup> • Base-load current I <sub>H</sub> <sup>4)</sup> • Maximum current I <sub>max Q</sub>	A A A	260 250 233 375	330 320 280 480	410 400 367 600	465 452 416 678	575 560 514 840	735 710 657 1065	
DC link current         • Rated current I <sub>rated DC</sub> when supplied via         • Basic/Smart Line Module         • Active Line Module         • Base-load current I <sub>LDC</sub> <sup>3)</sup> when supplied via         • Basic/Smart Line Module         • Basic/Smart Line Module	A A A A A	312 281 304 273 277 250	396 356 386 347 352 316	492 443 479 431 437 394	558 502 544 489 496 446	690 621 672 605 614 552	882 794 859 774 784 706	
Current demand     24 V DC auxiliary power supply     690 V AC	A A	0.9	0.9 1.0	1.0 2.1	1.0 2.1	1.0 2.1	1.25 3.1	
DC link capacitance	μF	3900	4200	7400	7400	7400	11100	
Pulse frequency <sup>5)</sup> • Rated frequency         • Pulse frequency, max.         • Without current derating         • With current derating         • Power loss, max. <sup>6)</sup> • At 50 Hz 690 V	kHz kHz kHz kW	1.25 1.25 7.5 3.62	1.25 1.25 7.5 4.34	1.25 1.25 7.5 6.13	1.25 1.25 7.5 6.8	1.25 1.25 7.5 10.3	1.25 1.25 7.5 10.9	
• At 60 Hz 575 V	kW	3.38	3.98	5.71	6.32	9.7	10.0	
Cooling air requirement	m <sup>3</sup> /s	0.36	0.36	0.78	0.78	0.78	1.08	
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	69	69	72	72	72	72	
Motor connection U2, V2, W2	<u>_</u>	M12 screws						
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	4 × 240	4 × 240	4 × 240	6 × 240	
Cable length, max. <sup>7)</sup> • Shielded • Unshielded	m m	300 450	300 450	300 450	300 450	300 450	300 450	
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240						
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20	
Dimensions • Width <sup>8)</sup> • Height <sup>9)</sup> • Depth	mm mm mm	400 2200 600	400 2200 600	600 2200 600	600 2200 600	600 2200 600	800 2200 600	
Weight, approx.	kg	286	286	490	490	490	700	
Frame size		GX	GX	HX	HX	HX	JX	
Short-circuit current rating according to IEC	kA	65	65	65	84	84	100	

 $^{\rm 1)}\,$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 500 V or 690 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{\rm 4)}$  The base-load current  ${\it I}_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

<sup>5)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

7) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>8)</sup> With option **L10** (dv/dt filter plus VPL): - Frame sizes FX/GX/HX/JX: Additional cabinet 600 mm wide With option L34 (circuit breaker on the output side): Frame size FX/GX: Additional cabinet 400 mm wide
 Frame size HX/JX: Additional cabinet 600 mm wide.

Air-cooled units

Motor Modules in chassis format

Line voltage 500 690 V 3 AC		Motor Modules in chassis format					
DC link voltage 675 1035 V DC		6SL3720-1TG38-1AA3	6SL3720-1TG38-8AA3	6SL3720-1TG41-0AA3	6SL3720-1TG41-3AA3		
Type rating           • At $I_L$ (50 Hz 690 V) <sup>1</sup> )           • At $I_H$ (50 Hz 690 V) <sup>1</sup> )           • At $I_L$ (50 Hz 500 V) <sup>1</sup> )           • At $I_H$ (50 Hz 500 V) <sup>1</sup> )           • At $I_L$ (60 Hz 575 V) <sup>2</sup> )           • At $I_L$ (60 Hz 575 V) <sup>2</sup> )	kW kW kW kW hp hp	<b>800</b> 710 560 500 800 700	<b>900</b> 800 630 560 900 800	<b>1000</b> 900 710 630 1000 900	<b>1200</b> 1000 900 800 1250 1000		
Output current         • Rated current l <sub>rated Q</sub> • Base-load current l <sub>i</sub> <sup>3)</sup> • Base-load current l <sub>i</sub> <sup>4)</sup> • Maximum current l <sub>max Q</sub>	A A A	810 790 724 1185	910 880 814 1320	1025 1000 917 1500	1270 1230 1136 1845		
DC link current         • Rated current I <sub>rated DC</sub> when supplied via         • Basic/Smart Line Module         • Base-load current I <sub>L DC</sub> <sup>3)</sup> when supplied via         • Basic/Smart Line Module         • Base-load current I <sub>L DC</sub> <sup>3)</sup> when supplied via         • Base-load current I <sub>H DC</sub> <sup>4)</sup> when supplied via         • Basic/Smart Line Module         • Basic/Smart Line Module         • Active Line Module         • Active Line Module         • Active Line Module         • Basic/Smart Line Module         • Basic/Smart Line Module         • Current demand         • 24 V DC auxiliary power supply         • 690 V AC         DC link capacitance         Pulse frequency <sup>5</sup> • Rated frequency	Α Α Α Α Α Α Α Α Α Α Α Α Α Α	972 875 947 853 865 778 1.25 3.1 11100 1.25	1092 983 1064 958 971 874 1.4 3.1 14400 1.25	1230 1107 1199 1079 1094 985 1.4 3.1 14400 1.25	1524 1372 1485 1337 1356 1221 1.4 3.1 19200 1.25		
<ul> <li>Pulse frequency, max.</li> <li>Without current derating</li> <li>With current derating</li> </ul>	kHz kHz kHz	1.25 1.25 7.5	1.25 1.25 7.5	1.25 1.25 7.5	1.25 1.25 7.5		
Power loss, max. <sup>6</sup> ) • At 50 Hz 690 V • At 60 Hz 575 V	kW kW	11.5 10.5	11.7 10.6	13.2 12.0	16.0 14.2		
Cooling air requirement	m <sup>3</sup> /s	1.08	1.08	1.08	1.08		
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	72	72	72	72		
Motor connection U2, V2, W2 • Conductor cross-section, max. (IEC)	mm <sup>2</sup>	M12 screws 6 x 240	M12 screws 6 x 240	M12 screws 6 x 240	M12 screws 6 x 240		
Cable length, max. <sup>7</sup> ) • Shielded • Unshielded PE/GND connection • Busbar cross-section	m m	300 450 PE bar 600	300 450 PE bar 600	300 450 PE bar 600	300 450 PE bar 600		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240		
Degree of protection Dimensions • Width <sup>8)</sup> • Height <sup>9)</sup> • Depth Weight, approx.	mm mm mm kg	IP20 800 2200 600 700	IP20 800 2200 600 700	IP20           800           2200           600           700	IP20 800 2200 600 700		
Frame size		JX	JX	JX	JX		
Short-circuit current rating according to IEC	kA	100	100	100	100		
<ol> <li>Rated output of a typical 6-pole stand for 500 V or 690 V 3 AC 50 Hz.</li> </ol>	lard indu	ction motor based on $I_{\rm L}$ or $I_{\rm P}$	<sup>6)</sup> The specified pow zation. The value is	er loss represents the maxi s lower under normal opera	mum value at 100% utili- ting conditions.		

for 500 V or 690 V 3 AC 50 Hz.  $^{2)}\,$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$ 

for 575 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

Technical specifications (continued)

 $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

<sup>5)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

7) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

 <sup>8)</sup> With option L10 (dv/dt filter plus VPL):
 - Frame sizes FX/GX/HX/JX: Additional cabinet 600 mm wide With option L34 (circuit breaker on the output side): - Frame size FX/GX: Additional cabinet 400 mm wide

- Frame size HX/JX: Additional cabinet 600 mm wide.

<sup>9)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

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Air-cooled units

#### **Central Braking Modules**

#### Overview



Central Braking Modules limit the DC link voltage at a central location in the drive line-up when the motors are operating in generator mode and energy recovery to the supply system is not possible. If, in regenerative mode, the voltage of the DC busbar exceeds a limit value, an externally installed braking resistor is switched in, thus restricting the voltage from increasing further. The regenerative energy is converted into heat. The braking resistor is switched in by the Braking Unit integrated in the Cabinet Module, which is equipped with state-of-the-art MOSFET/IGBT semiconductors.

Central Braking Modules are an alternative to the optional Braking Modules (options **L61/L62** or **L64/L65**) and are particularly suitable when high braking powers are required in a drive line-up. The required braking power can also be increased by connecting units in parallel.

Line voltage	DC link voltage	Braking power P <sub>150</sub>
380 480 V 3 AC	510 720 V DC	500 kW/1000 kW
500 600 V 3 AC	675 900 V DC	550 kW/1100 kW
660 690 V 3 AC	890 1035 V DC	630 kW/1200 kW

The built-in fan means that Central Braking Modules are also suitable for high continuous power levels.

#### Design

The Central Braking Module is a cabinet unit with integrated braking chopper. Using state-of-the-art MOSFET/IGBT semiconductors, the power unit controls when the braking resistor is switched in.

Central Braking Modules are designed as a 400 mm wide cabinet module. Its connection to the DC link is protected by fuses.

Central Braking Modules require braking resistors that must be externally mounted and which can be ordered separately. The cables to the resistors can be connected to lugs which are specially prepared for plant application and which are located in the connection area of the cabinet.

The power units have diagnostics LEDs for the display of faults and also a control output for the communication of faults. The Central Braking Module can be disabled externally via a control input.

The arrangement in the DC link system is subject to specific configuring rules.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Selection and ordering data

Braking p	owers			Central Braking Module
P <sub>15</sub>	P <sub>150</sub>	P <sub>270</sub>	$P_{\rm DB}$	
kW	kW	kW	kW	Article No.
DC link v	oltage 510	) 720 V	DC	
730	500	300	200	6SL3700-1AE35-0AA3
1380	1000	580	370	6SL3700-1AE41-0AA3
DC link v	oltage 675	5 900 V	DC	
830	550	340	220	6SL3700-1AF35-5AA3
1580	1100	650	420	6SL3700-1AF41-1AA3
DC link v	oltage 890	) 1035 V	DC	
920	630	380	240	6SL3700-1AH36-3AA3
1700	1200	720	460	6SL3700-1AH41-2AA3

Note:

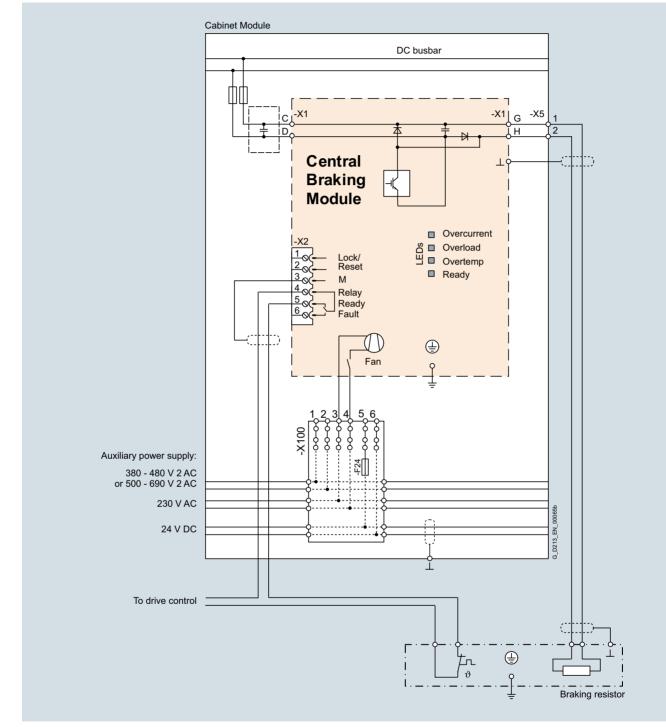
In contrast to the optional Braking Modules (options **L61**, **L62** or **L64**, **L65**), the braking resistors for the Central Braking Modules must be ordered separately.

Braking power P <sub>150</sub>	Dimensions $(W \times D \times H)$	Braking resistor in degree of protection IP21
kW	mm	Article No.
DC link voltage 510	720 V DC	
500	$960 \times 620 \times 790$	6SL3000-1BE35-0AA0
1000	$960 \times 620 \times 1430$	6SL3000-1BE41-0AA0
DC link voltage 675	900 V DC	
550	$960 \times 620 \times 1110$	6SL3000-1BF35-5AA0
1100	$960 \times 620 \times 1430$	6SL3000-1BF41-1AA0
DC link voltage 890	1035 V DC	
630	$960 \times 620 \times 1110$	6SL3000-1BH36-3AA0
1200	960 × 620 × 1430	6SL3000-1BH41-2AA0

Air-cooled units

**Central Braking Modules** 

# Integration



Connection example: Central Braking Module

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Air-cooled units

# **Central Braking Modules**

# Technical specifications

		Central Braking Modules					
		6SL3700- 1AE35-0AA3	6SL3700- 1AE41-0AA3	6SL3700- 1AF35-5AA3	6SL3700- 1AF41-1AA3	6SL3700- 1AH36-3AA3	6SL3700- 1AH41-2AA3
Line voltage		380 480 V		500 600 V		660 690 V	
Braking power P <sub>150</sub>	kW	500	1000	550	1100	630	1200
Continuous braking power P <sub>DB</sub>	kW	200	370	220	420	240	460
Braking current for P <sub>150</sub>	А	650	1200	580	1100	520	1000
Current demand <sup>1)</sup>							
• 230 V 2 AC	А	0.4	0.4	0.4	0.4	0.4	0.4
<b>Power loss, max. <sup>2)</sup></b> At 50 Hz 400/500/690 V	kW	0.8	1.5	0.8	1.5	0.8	1.5
DC link capacitance	μF	8160	9720	7640	8680	7640	8680
Cooling air requirement	m <sup>3</sup> /s	0.14	0.14	0.14	0.14	0.14	0.14
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	55	55	55	55	55	55
Braking resistor connection		M12 screws	M12 screws	M12 screws	M12 screws	M12 screws	M12 screws
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 240	2 × 240	2 × 240	2 × 240	2 × 240	2 × 240
PE/GND connection		PE bar	PE bar	PE bar	PE bar	PE bar	PE bar
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	600	600
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	240	240
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
Dimensions							
• Width	mm	400	400	400	400	400	400
• Height <sup>3)</sup>	mm	2200	2200	2200	2200	2200	2200
• Depth	mm	600	600	600	600	600	600
Weight, approx.	kg	230	230	230	230	230	230
Frame size	mm	400	400	400	400	400	400

	Braking resistor	Braking resistors					
		6SL3000- 1BE35-0AA0	6SL3000- 1BE41-0AA0	6SL3000- 1BF35-5AA0	6SL3000- 1BF41-1AA0	6SL3000- 1BH36-3AA0	6SL3000- 1BH41-2AA0
Line voltage		380 480 V		500 600 V		660 690 V	
Braking power P <sub>BR</sub>	kW	500	1000	550	1100	630	1200
Continuous braking power P <sub>DB</sub>	kW	23	58	34	62	42	75
Resistance value	Ω	0.95	0.49	1.35	0.69	1.8	0.95
Degree of protection		IP21	IP21	IP21	IP21	IP21	IP21
Dimensions							
• Width	mm	960	960	960	960	960	960
Height	mm	620	620	620	620	620	620
• Depth	mm	790	1430	1110	1430	1110	1430
Weight, approx.	kg	82	170	110	180	124	196

1) Current demand of the fans.

<sup>2)</sup> The specified power loss represents the maximum value at 100% utilization. The value is lower under normal operating conditions.

<sup>3)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

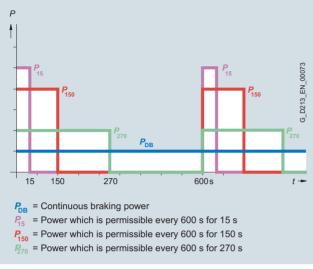
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Air-cooled units

**Central Braking Modules** 

# Characteristic curves

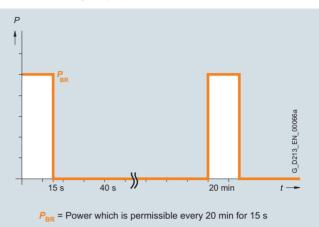
Central Braking Modules are dimensioned for braking powers with the following duty cycles:



Braking powers of the Central Braking Modules

The braking powers are subject to a cycle time of 600 s.  $P_{150}$  is assumed to be the rated braking power. The braking resistors can be assigned according to these power ratings.

In most applications, Central Braking Modules are only used for occasional braking operations, e.g. stopping a drive in an emergency. Low-cost braking resistors in degree of protection IP21 are specifically offered for these types of applications; these braking resistors are dimensioned for braking powers  $P_{\rm BR}$  with the following duty cycle:



Duty cycle for braking resistors

Braking resistors with a higher braking power and shorter cycle times are available on request.

Air-cooled units

### **Auxiliary Power Supply Modules**

# Overview



Auxiliary Power Supply Modules supply the auxiliary power supply for the SINAMICS S120 Cabinet Modules. Units connected to this auxiliary power supply system include the fans of the SINAMICS S120 devices installed in the Cabinet Modules. In addition, the auxiliary power supply system supplies the electronic modules with an external voltage of 24 V DC. This is required when the DC link is not charged, for instance, in order to maintain PROFIBUS/PROFINET communication.

#### Design

The Auxiliary Power Supply Module is connected in the customer's plant to a voltage corresponding to the respective rated unit voltage.

The standard version contains the following components:

- Fuse switch disconnector with fuse monitoring for external evaluation
- Supply of the auxiliary power supply system with 3 fused auxiliary voltages:
  - 24 V DC for the electronics power supply
  - 230 V 2 AC to supply 230 V loads
- 380 V to 690 V 2 AC to supply the equipment fans
- Transformer with 230 V output voltage
- SITOP 24 V DC power supply
- 6-pole auxiliary power supply system (ready-wired), including connections for looping through to the next Cabinet Module
- Nickel-plated PE bar (60 mm × 10 mm), including jumper for looping through to the next Cabinet Module

#### Selection and ordering data

System-side power supply (380 690 V 3 AC)	Auxiliary Power Supply Module
A	Article No.
125	6SL3700-0MX14-0AA3
160	6SL3700-0MX16-3AA3
200	6SL3700-0MX21-0AA3
250	6SL3700-0MX21-4AA3

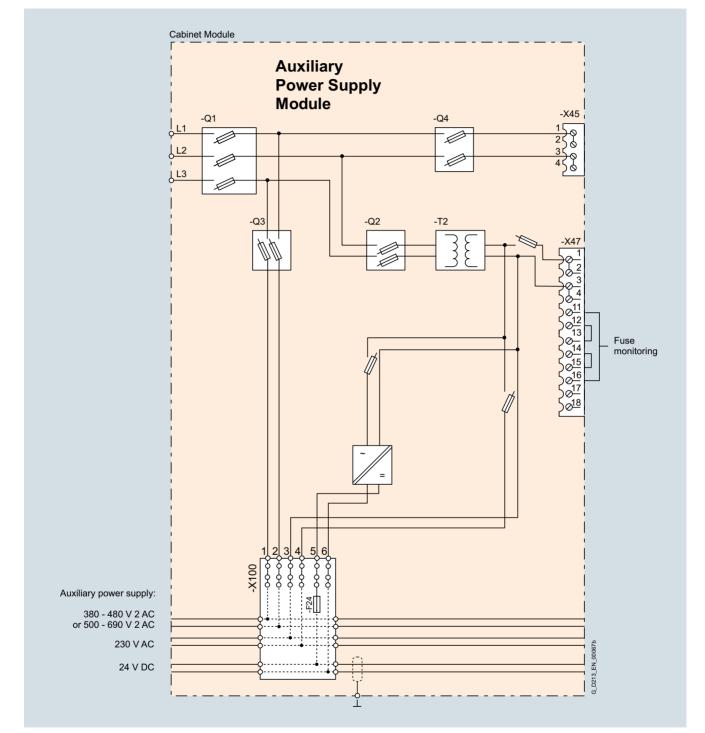
#### Note:

In smaller systems, there is often no need for an additional Cabinet Module for the auxiliary power supply. In such cases, the infeed for the auxiliary power supply system can also be supplied by the Line Connection Module. This must then be separately ordered (option **K76**).

Air-cooled units

**Auxiliary Power Supply Modules** 

# Integration



Connection example: Auxiliary Power Supply Module

Air-cooled units

# Auxiliary Power Supply Modules

# Technical specifications

		Auxiliary Power Supply Modules				
		6SL3700-0MX14-0AA3	6SL3700-0MX16-3AA3	6SL3700-0MX21-0AA3	6SL3700-0MX21-4AA3	
Plant-side power supply 380 690 V 3 AC	A	125	160	200	250	
Line supply connection						
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	150	150	150	150	
Current carrying capacity, max.						
Load connection     380 V 690 V AC						
- To auxiliary power supply	А	63	80	100	100	
- To customer terminal -X45	А	50	63	80	80	
Load connection     230 V 2 AC						
- To auxiliary power supply	А	6	10	10	20	
- To customer terminal -X47	А	8	10	10	20	
<ul> <li>Load connection 24 V DC</li> </ul>						
- To auxiliary power supply	А	20	40	80	80	
Cable cross-section, max.						
Connection -X45	mm <sup>2</sup>	16	16	16	16	
Connection -X47	mm <sup>2</sup>	2.5	2.5	2.5	2.5	
Cooling air requirement	m <sup>3</sup> /s	Natural convection	Natural convection	Natural convection	Natural convection	
PE/GND connection		PE bar	PE bar	PE bar	PE bar	
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600	600	600	600	
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240	240	240	240	
Degree of protection		IP20	IP20	IP20	IP20	
Dimensions						
• Width	mm	600	600	600	600	
• Height <sup>1)</sup>	mm	2200	2200	2200	2200	
• Depth	mm	600	600	600	600	
Weight, approx.	kg	170	180	210	240	
Minimum short-circuit current <sup>2)</sup>	А	3200	4000	5000	7000	

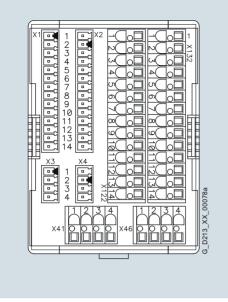
<sup>1)</sup> The cabinet height increases by 250 mm with degree of protection IP21, and by 400 mm with degrees of protection IP23, IP43 and IP54.

<sup>2)</sup> Current required to ensure reliable tripping of installed protective devices.

Air-cooled units

Customer terminal strip -X55

# Overview



Customer terminal block -X55 is the interface with the

 $\ensuremath{\text{I/O}}$  devices and marshals a range of cabinet-internal signals to a central terminal block module mounted in the lower part of the cabinet.

It can be used for Motor Modules in the chassis format as well as together with options **K90** (Control Unit CU320-2 DP) or **K95** (Control Unit CU320-2 PN) for Basic Line Modules, Smart Line Modules, Active Line Modules and Booksize Cabinet Kits.

# Design

To connect signal cables on the customer side, terminal block -X55 includes terminals -X122, -X132, -X41 and -X46 (terminals -X1 to -X4 are used inside the cabinet and are not available). As a consequence, depending on the version (with/without option **K90**) the following digital inputs/outputs and/or signals are available:

The customer terminal strip -X55 includes:	Motor Modules in chassis format		Line Module	5
	Without	With	Without	With
	CU320-2 <b>(K</b> §	90/K95)	CU320-2 (KS	90/K95)
-X122, -X132				
12 digital inputs DI	-	√	-	√
8 bidirectional inputs/ outputs (DI/DO)	-	~	-	~
-X41				
Connection safety function Safe Torque Off / Safe Stop 1	√	✓	_ 1)	_ 1)
Connection temperature sensor KTY84/PTC/Pt100	~	~	_ 1)	_ 1)
-X46				
Connection, Safe Brake Adapter	~	✓	-	-

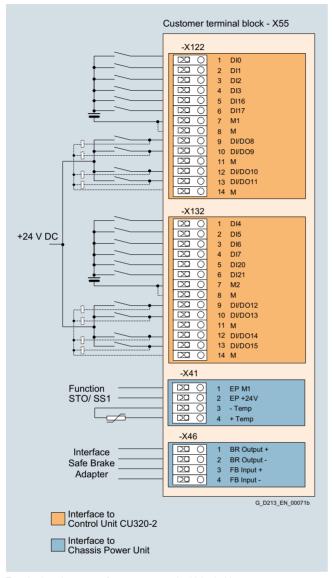
 For Booksize Cabinet Kits, a connection is provided at the separate customer terminal block -X55.1.

Air-cooled units

# Customer terminal strip -X55

# Design (continued)

Pin assignment



Terminal blo	ock -X55-X122 dig	ital inputs/outputs
Terminal	Designation 1)	Technical data
1	DI 0	Voltage -30 V to +30 V DC
2	DI 1	Current consumption, typical: 9 mA at 24 V DC
3	DI 2	Electrical isolation: The reference potential
4	DI 3	is terminal M1
5	DI 16	-Level (incl. ripple): High level: 15 V 30 V
6	DI 17	Low level: -30 V +5 V
		Input delay (typ.): at $0 \rightarrow 1: 50 \ \mu s$ at $1 \rightarrow 0: 150 \ \mu s$
7	M1	Reference potential for terminals 1 to 6
8	Μ	Ground
9	DI/DO 8	As input:
10	DI/DO 9	Voltage -30 V +30 V DC -Current consumption, typical: 9 mA at
11	Μ	24 V DC
12	DI/DO 10	Level (incl. ripple):
13	DI/DO 11	-High level: 15 V 30 V Low level: -30 V +5 V
14	М	Fast inputs: <sup>2)</sup> DI/DO 8, 9, 10 and 11
		Input delay (typ.): at $0 \rightarrow 1:5 \ \mu s$ at $1 \rightarrow 0:50 \ \mu s$
		As output: Voltage 24 V DC Max. load current per output: 500 mA Continuously short-circuit proof Output delay (typ./max.): <sup>3)</sup> at 0 $\rightarrow$ 1: 150 µs/400 µs at 1 $\rightarrow$ 0: 75 µs/100 µs Switching frequency: For resistive load: max. 100 Hz For inductive load: max. 0.5 Hz For lamp load: max. 10 Hz Max. lamp load: 5 W

Max. connectable cross-section: 2.5 mm<sup>2</sup>

Terminal assignment of customer terminal block -X55

 DI: Digital input DI/DO: Bidirectional digital input/output M: Electronics ground M1: Reference ground.

 $^{2)}\,$  Can be used as measuring probe input or input for the external zero mark.

 $^{3)}$  Data for:  $U_{\rm CC}$  = 24 V; load 48  $\Omega;$  High (1) = 90 %  $U_{\rm out};$  Low (0) = 10 %  $U_{\rm out}.$ 

Air-cooled units

# Customer terminal strip -X55

# Design (continued)

Terminal blo	ock -X55-X132 dig	ital inputs/outputs			
Terminal	Designation 1)	Technical data			
1	DI 4	Voltage -30 V to +30 V DC			
2	DI 5	Current consumption, typical: 9 mA at 24 V DC			
3	DI 6	Electrical isolation: The reference potential			
4	DI 7	is terminal M2			
5	DI 20	-Level (incl. ripple): High level: 15 V 30 V			
6	DI 21	Low level: -30 V +5 V			
		Input delay (typ.): at $0 \rightarrow 1: 50 \ \mu s$ at $1 \rightarrow 0: 150 \ \mu s$			
7	M2	Reference potential for terminals 1 to 6			
8	М	Ground			
9	DI/DO 12	As input:			
10	DI/DO 13	Voltage -30 V +30 V DC -Current consumption, typical: 9 mA at			
11	М	24 V DC			
12	DI/DO 14	Level (incl. ripple): -High level: 15 V 30 V			
13	DI/DO 15	Low level: -30 V +5 V			
14	М	Fast inputs: <sup>2)</sup> DI/DO 12, 13, 14 and 15			
		Input delay (typ.): at $0 \rightarrow 1:5 \ \mu s$ at $1 \rightarrow 0:50 \ \mu s$			
		As output:			
		Voltage 24 V DC Max. load current per output: 500 mA Continuously short-circuit proof			
		Output delay (typ./max.): <sup>3)</sup> at 0 $\rightarrow$ 1: 150 µs/400 µs at 1 $\rightarrow$ 0: 75 µs/100 µs			
		Switching frequency: For resistive load: max. 100 Hz For inductive load: max. 0.5 Hz For lamp load: max. 10 Hz Max. lamp load: 5 W			
		0			

Terminal blo	Terminal block -X55-X41 temperature sensor connection				
Terminal	Function	Technical data			
1	EP M1 (enable pulses)	Supply voltage 24 V DC (20.4 28.8 V DC)			
2	EP +24 V (enable pulses)	-Current consumption: 10 mA Signal propagation times: $L \rightarrow H: 100 \ \mu s$ $H \rightarrow L: 1000 \ \mu s$ The pulse inhibit function is only available when Safety Integrated Basic Functions are enabled			
3	-Temp	Temperature sensor connection for -motor temperature sensing:			
4	+Temp	KTY84-1C130, PTC, Pt100			

Max. connectable cross-section: 2.5 mm<sup>2</sup>

#### Terminal block -X55-X46 brake control and monitoring

Terminal	Function	Technical data
1	BR output +	The interface is used to connect the Safe
2	BR output -	-Brake Adapter
3	FB input +	_
4	FB input -	_

Max. connectable cross-section: 2.5 mm<sup>2</sup>

Max. connectable cross-section: 2.5 mm<sup>2</sup>

 DI: Digital input DI/DO: Bidirectional digital input/output M: Electronics ground M2: Reference ground.

 $^{2)}\,$  Can be used as measuring probe input or input for the external zero mark.

<sup>3)</sup> Data for:  $U_{\rm cc}$  = 24 V; load 48  $\Omega$ ; High (1) = 90 %  $U_{\rm out}$ ; Low (0) = 10 %  $U_{\rm out}$ .

Liquid-cooled units

#### Liquid-cooled units

#### Overview

To comply with high requirements regarding installation and ambient conditions, SINAMICS S120 Cabinet Modules are also available in a liquid-cooled version.

The power loss of the units is transferred to the cooling liquid and dissipated, without noticeably increasing the temperature of the surrounding environment. As a consequence it is possible to save the expense of controlling the climate of the electrical room.

The system consists of liquid-cooled Basic Line Connection Modules, Active Line Connection Modules, Motor Modules, an Auxiliary Power Supply Module, and a suitably selected cooling unit (Heat Exchanger Module).

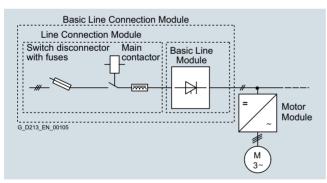
#### **Basic Line Connection Modules**

Basic Line Connection Modules comprise a Line Connection Module and a liquid-cooled Basic Line Module. Basic Line Connection Modules are only suitable for infeed operation, i.e. they are not capable of feeding regenerative energy back into the supply system.

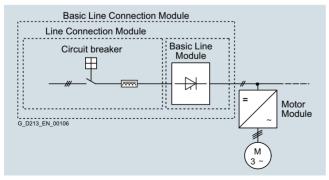
If regenerative energy is produced, e.g. when the drives brake, it must be converted into heat in external braking resistors using a supplementary Motor Module, which is used as a Braking Module.

When a Basic Line Connection Module is used as the infeed, a line reactor appropriate for the supply conditions must be installed. If the infeed is realized via a transformer with an appropriate rating in 6-pulse operation with a Basic Line Connection Module or in 12-pulse operation with two Basic Line Connection Modules, the line reactor is optional and can be omitted.

If two or more Basic Line Connection Modules are operated in parallel on a common supply system in order to increase power, then line reactors must also be used.



Basic Line Connection Module ≤ 800 A



Basic Line Connection Module > 800 A

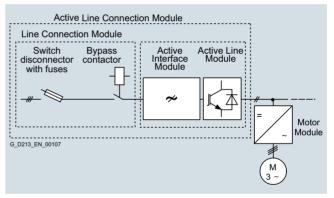
#### Active Line Connection Modules

Active Line Connection Modules comprise a Line Connection Module, a liquid-cooled Active Interface Module and a liquidcooled Active Line Module. Active Line Connection Modules can supply energy to the DC link and return regenerative energy to the line supply (energy recovery). The use of an additional Motor Module as a Braking Module is only required if the drives need to be decelerated in a controlled manner after a power failure (i.e. when energy cannot be fed back into the line supply).

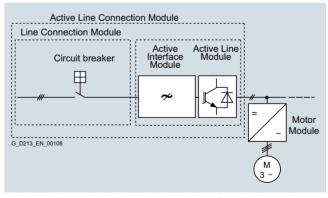
In contrast to Basic Line Connection Modules, Active Line Connection Modules generate a regulated DC voltage which remains constant irrespective of fluctuations in the line voltage. However, in this case, the line voltage must remain within the permissible tolerance range. Active Line Connection Modules draw a virtually sinusoidal current from the supply system. Almost no harmonics occur.

The total harmonic distortion factors of current THD(I) and voltage THD(U) are typically in the range of approx. 3 %. The stringent limit values of IEEE 519 (2014) are complied with.

Active Line Connection Modules always contain an Active Interface Module which, in addition to a Clean Power Filter, also includes the necessary pre-charging circuit for the Active Line Module.



Active Line Connection Module with Active Interface Module and Active Line Module  $\leq 800~\text{A}$ 



Active Line Connection Module with Active Interface Module and Active Line Module > 800 A

Liquid-cooled units

Liquid-cooled units

### **Overview** (continued)

#### **Motor Modules**

Each Cabinet Module is fitted with one SINAMICS S120 Motor Module in chassis format and covers the power range from 90 kW to 1500 kW (380 V to 480 V or 500 V to 690 V). The power rating can be extended up to approx. 5700 kW by connection in parallel.

The Motor Modules can also be used as Braking Modules (braking chopper) if a 3-phase braking resistor is connected instead of a motor.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### **Auxiliary Power Supply Modules**

Auxiliary Power Supply Modules supply power to the auxiliary power supply system of the SINAMICS S120 Cabinet Modules.

The heat exchangers, which are installed in the SINAMICS S120 Cabinet Modules with degree of protection IP55, are one of the connections to the auxiliary power supply system. In addition, the auxiliary power supply system supplies the electronic modules with an external 24 V DC voltage. This is required when the DC link is not charged, for instance, in order to maintain PROFIBUS or PROFINET communication.

The installation is analogous to the air-cooled Auxiliary Power Supply Modules with an additional water pipe system.

The Auxiliary Power Supply Modules provide an expansion to the option **K76** (auxiliary voltage generating unit) if higher power ratings are required.

Liquid-cooled units

# Liquid-cooled units

# Technical specifications

## General technical specifications

Electrical specifications	
Line voltages	380 480 V 3 AC, ±10 % (-15 % <1 min)
Line voltages	500 690 V 3 AC, ±10 % (-15 % <1 min)
Line supply types	Grounded TN/TT systems and non-grounded IT systems
Line frequency	47 63 Hz
Output frequency <sup>1)</sup>	
<ul> <li>Control type Servo</li> </ul>	0 550 Hz
Control type Vector	0 550 Hz
Control mode V/f	0 550 Hz
Line power factor Fundamental	
Basic Line Module	>0.96
<ul> <li>Active Line Module</li> </ul>	Adjustable (factory-set to $\cos \varphi = 1$ )
Efficiency	
Basic Line Module	>99 %
Active Line Module	>97.5 % (including Active Interface Module)
Motor Module	>98.5 %
Overvoltage category	III acc. to EN 61800-5-1
Control method	Vector/Servo control with and without encoder or V/f control
Fixed speeds	15 fixed speeds plus 1 minimum speed, parameterizable (in the default setting, 3 fixed setpoints plus 1 minimum speed are selectable using terminal block/PROFIBUS/PROFINET)
Skippable speed ranges	4, parameterizable
Setpoint resolution	0.001 rpm digital (14 bits + sign) 12 bits analog
Braking operation	With Active Line Modules, four-quadrant operation as standard (energy recovery). With Basic Line Modules, two-quadrant operation as standard, braking by means of a Motor Module
Cabinet system	
Cabinet system	Rittal TS 8, doors with double-barb lock, base plate with cable entry options
Paint finish	RAL 7035 (indoor requirements)
Mechanical specifications	
Degree of protection	IP21 (higher degrees of protection up to IP55 optional)
Protection class	l acc. to EN 61800-5-1
Touch protection	EN 50274/DGUV regulation 3 when used as intended
Cooling method	Cooling in compliance with EN 60146:
	Basic Line Connection Modules, Active Line Connection Modules, Motor Modules: WE - W: Liquid cooling - E: Forced air cooling, drive device outside the equipment
	Line reactors, motor reactors, dv/dt filters with Voltage Peak Limiter: AN - A: Air cooling - N: Natural cooling (convection)

- N: Natural cooling (convection)

1) Higher output frequencies available on request.

Liquid-cooled units

Liquid-cooled units

Ambient conditions	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation		
Ambient temperature	-25 +55 °C	-25 +70 °C from <u>-40 °C</u> for 24 hours	0 +45 °C to +50 °C see derating data		
Relative humidity (condensation not permissible)	5 95 % Class 1K4 acc. to IEC 60721-3-1	5 95 % at 40 °C Class 2K3 acc. to IEC 60721-3-2	5 <u>95 %</u> Class 3K3 acc. to IEC 60721-3-3		
Environmental class/harmful chemical substances	Class 1C2 acc. to EN 60721-3-1	Class 2C2 acc. to EN 60721-3-2	Class 3C2 acc. to EN 60721-3-3		
Organic/biological influences	Class 1B1 acc. to EN 60721-3-1	Class 2B1 acc. to EN 60721-3-2	Class 3B1 acc. to EN 60721-3-3		
Degree of pollution	2 acc. to IEC/EN 61800-5-1				
Installation altitude	≤ 2000 m above sea level without de				
Mechanical stability	Storage <sup>1)</sup>	Transport <sup>1)</sup>	Operation -		
Vibratory load	Class 1M2 acc. to EN 60721-3-1	Class 2M2 acc. to EN 60721-3-2			
Deflection	1.5 mm at <u>5</u> 9 Hz	3.1 mm at <u>5</u> 9 Hz	0.075 mm at 10 58 Hz 9.8 m/s² at >58 200 Hz		
<ul> <li>Acceleration</li> </ul>	5 m/s² at >9 200 Hz	10 m/s² at >9 200 Hz			
Shock load	Class 1M2 acc. to EN 60721-3-1	Class 2M2 acc. to EN 60721-3-2	Class 3M4 acc. to EN 60721-3-3		
<ul> <li>Acceleration</li> </ul>	40 m/s <sup>2</sup> at 22 ms	100 m/s <sup>2</sup> at 11 ms	100 m/s² at 11 ms		
Compliance with standards					
Conformances/certificates of suitability, according to	CE (EMC Directive 2014/30/EU, Low functional safety), RCM	Voltage Directive 2014/35/EU, and Mach	inery Directive 2006/42/EC for		
Radio interference suppression	ence suppression is compliant with the	re not designed for connection to the pu ne EMC product standard for variable-sp urbances can occur when connected to	eed drives EN 61800-3, "second enviro		

Deviations from the specified class are underlined.

Liquid-cooled units

#### Liquid-cooled units

### Technical specifications (continued)

### Cooling circuit and coolant quality

The following tables and sections describe the coolant quality requirements for the raw water circuit on the plant side and the deionized water circuit of the liquid-cooled SINAMICS S120 Cabinet Modules on the converter side.

#### Plant-side raw water circuit (based on VDI 3803)

<ul> <li>System pressure with reference to atmospheric pressure, max.</li> </ul>	600 kPa
<ul> <li>Inlet temperature of liquid coolant</li> </ul>	Antifreeze essential for temperature range between 0 °C and 5 °C
<ul> <li>Degree of protection &lt; IP55</li> </ul>	0 38 °C without derating > 38 43 °C, see derating data
- Degree of protection IP55	0 33 °C without derating > 33 38 °C, see derating data
Coolant quality	
<ul> <li>Electrical conductivity</li> </ul>	< 2200 µS/cm
• pH value	7.5 9
Chloride ions	< 180 mg/l
<ul> <li>Sulfate ions</li> </ul>	< 200 mg/l
<ul> <li>Orthophosphate</li> </ul>	< 50 mg/l
<ul> <li>Dissolved iron</li> </ul>	< 3 mg/l
<ul> <li>Dissolved copper</li> </ul>	< 0.2 mg/l
<ul> <li>Biological load</li> </ul>	< 50 CFU/ml
<ul> <li>SiO2 as silicic acid</li> </ul>	< 47 mg/l
Aluminum	< 2.65 mg/l

< 20 (< 40 °C) °dH

≤ 0.5 mm

# < 4 mg/l

- Fluoride Total hardness
- Size of entrained particles
- SK 4.3 (upper limit value of < 10 mmol/l polymer phosphates for untreated additional water)
- Permissible limit values for suspended particles in the coolant

No deposits of solid particles at  $\ge 0.5$  m/s

#### Converter-side deionized water circuit

<ul> <li>System pressure with reference to atmospheric pressure, max.</li> </ul>	600 kPa
<ul> <li>Pressure drop at rated volumetric flow</li> </ul>	70 kPa
<ul> <li>Recommended pressure range</li> </ul>	80 150 kPa (applicable for water as coolant)
<ul> <li>Inlet temperature of liquid coolant</li> </ul>	Depending on ambient temperature; no condensation permitted
	Antifreeze essential for temperature range between 0 °C and 5 °C
<ul> <li>Degree of protection &lt; IP55</li> </ul>	0 45 °C without derating > 45 50 °C, see derating data
- Degree of protection IP55	0 40 °C without derating > 40 45 °C, see derating data
Coolant quality	
Coolant basis	Distilled, demineralized, completely desalinated water or deionized water with reduced electrical conductivity in acc. with ISO 3696, quality 3 or based on IEC 60993
Electrical conductivity when	< 30 µS/cm (3 mS/m)

- filling pH value 5 ... 8
- Components that can be < 30 mg/l oxidized as oxygen content
- Residue after vaporization < 10 mg/kg and drying at 110 °C

The coolant definition specified here should only be considered as a recommendation. For units that have been shipped, the information and data provided in the equipment manual supplied should be observed!

Liquid-cooled units

Liquid-cooled units

# Technical specifications (continued)

Antifreeze and inhibitors

Antifreeze	Antifrogen N	Antifrogen L	DOWCAL 100
Manufacturer	Clariant	Clariant	DOW
Chemical base	Ethylene glycol Propylene gly- col		Ethylene glycol
Minimum concentration	25 %	25 %	25 %
Antifreeze agent with minimum concentration	-10 °C	-10 °C	-10 °C
Maximum concentration	45 %	48 %	45 %
Antifreeze agent with maximum concentration	-30 °C	-30 °C	-30 °C
Inhibitor content	Contains inhibitors with nitrites	Contains inhib- itors that are free of nitrates, amines, borates, and phosphate	Contains inhib- itors that are free of nitrates, amines, and phosphate
Biocide action with a concentration of	> 25 %	> 25 %	> 25 %

Biocides prevent corrosion that is caused by slime-forming, corrosive or iron-depositing bacteria. These can occur in closed cooling circuits with low water hardness and in open cooling circuits. Biocides must always be selected according to the relevant bacterial risks. Compatibility with inhibitors or antifreeze used with them must be checked on a case-by-case basis.

Inhibitors	Antifrogen N	ANTICORIT S 200 A		
Manufacturer	Clariant	Fuchs		
Chemical base	Ethylene glycol	-		
Minimum concentration	25 %	4 %		
Maximum concentration	45 %	5 %		

#### Recommended service

The manufacturer of the antifreeze/inhibitor should analyze the coolant at least once per annum. The concentration and boundary conditions of the antifreeze/inhibitor should be checked. It may be necessary to correct the concentration on the plant side.

Liquid-cooled units

#### Liquid-cooled units

### Technical specifications (continued)

#### Protection against condensation

With liquid-cooled units, warm air can condense on the cold surfaces of heat sinks, pipes and hoses. This condensation depends on the air humidity and the temperature difference between the ambient air and the coolant.

The water which is produced as a result of condensation can cause corrosion as well as electrical damage such as creepage shorts and flashovers. As the SINAMICS units cannot prevent condensation if it is caused by the prevailing climatic conditions, any potential risk of condensation must be prevented by appropriate engineering or by precautionary measures implemented by the customer. These measures include the following:

- a fixed coolant temperature that has been adjusted to the expected air humidity or ambient temperature ensures that critical differences between the coolant and ambient air temperatures do not develop or
- temperature regulation of the coolant as a function of the ambient air temperature

. . . . . . . . .

The temperature at which water vapor contained in the air condenses into water is known as the dew point. In order to reliably prevent condensation, the coolant temperature must always be higher than the dew point.

The table below specifies the dew point as a function of room temperature T and relative air humidity  $\Phi$  for an atmospheric pressure of 100 kPa (1 bar). This corresponds to an installation altitude of 0 to approximately 500 m above sea level. Since the dew point drops as the air pressure decreases, the dew point values at higher installation altitudes are lower than the specified table values. It is therefore the safest approach to engineer the coolant temperature according to the table values for an installation altitude of zero.

Room temperature	Relative air humidity $\Phi$										
Т	20 %	30 %	40 %	50 %	60 %	70 %	80 %	85 %	90 %	95 %	100 %
10 °C	< 0 °C	< 0 °C	< 0 °C	0.2 °C	2.7 °C	4.8 °C	6.7 °C	7.6 °C	8.4 °C	9.2 °C	10 °C
20 °C	< 0 °C	2 °C	6 °C	9.3 °C	12 °C	14.3 °C	16.4 °C	17.4 °C	18.3 °C	19.1 °C	20 °C
25 °C	0.6 °C	6.3 °C	10.5 °C	13.8 °C	16.7 °C	19.1 °C	21.2 °C	22.2 °C	23.2 °C	24.1 °C	24.9 °C
30 °C	4.7 °C	10.5 °C	14.9 °C	18.4 °C	21.3 °C	23.8 °C	26.1 °C	27.1 °C	28.1 °C	29 °C	29.9 °C
35 °C	8.7 °C	14.8 °C	19.3 °C	22.9 °C	26 °C	28.6 °C	30.9 °C	32 °C	33 °C	34 °C	34.9 °C
40 °C	12.8 °C	19.1 °C	23.7 °C	27.5 °C	30.6 °C	33.4 °C	35.8 °C	36.9 °C	37.9 °C	38.9 °C	39.9 °C
45 °C	16.8 °C	23.3 °C	28.2 °C	32 °C	35.3 °C	38.1 °C	40.6 °C	41.8 °C	42.9 °C	43.9 °C	44.9 °C
50 °C	20.8 °C	27.5 °C	32.6 °C	36.6 °C	40 °C	42.9 °C	45.5 °C	46.6 °C	47.8 °C	48.9 °C	49.9 °C

A detailed description of the cooling circuits and the recommended coolant is given in the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

Liquid-cooled units

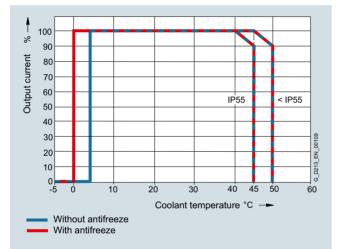
### Characteristic curves

#### Derating

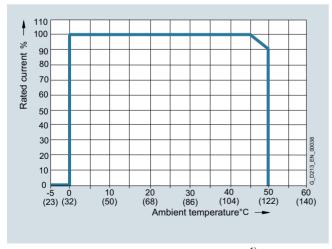
Liquid-cooled SINAMICS S120 Cabinet Modules are rated for an ambient temperature of 45 °C and installation altitudes up to 2000 m above sea level and a plant-side raw water temperature of 38 °C (< IP55) or 33 °C (IP55). At ambient temperatures > 45 °C and a plant-side raw water temperature > 38 °C (< IP55) or 33 °C (IP55), the output current must be reduced. Ambient temperatures above 50 °C are not permissible. At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease.

The intake temperatures in the plant/system-side raw water circuit must always be at least 7 K below the intake temperatures in the converter-side deionized water circuit. This ensures that the cooling power of the Heat Exchanger Module of the deionized water circuit, specified in the technical specifications, can be dissipated to the raw water circuit.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

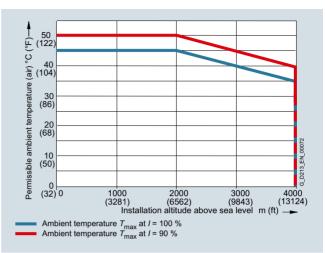


Current derating as a function of the temperature of the cooling liquid in the converter-side deionized water circuit  $^{1)}\,$ 

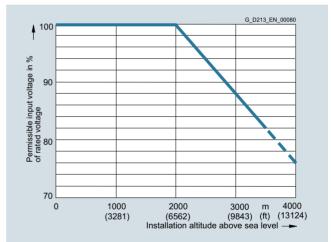


Current derating as a function of ambient temperature 1)

<sup>1)</sup> The factors of the two derating curves must not be multiplied. The highest value in each case must be assumed for the purposes of calculation, so that the derating factor in the worst-case scenario is 0.9.



Permissible ambient temperature as a function of installation altitude



Voltage derating as a function of installation altitude

Liquid-cooled units

#### Liquid-cooled units

### Characteristic curves (continued)

Current derating as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased, the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

The following table lists the rated output currents of the Motor Modules with pulse frequency set at the factory, as well as the current derating factors (permissible output currents referred to the rated output current) for higher pulse frequencies.

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 2 kHz

Motor Module	Type rating at 400 V	Output current at 2 kHz	Derating factor at pulse frequen	Derating factor at pulse frequency			
6SL3725	kW	А	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 A	380 480 V 3 AC / 510 720 V DC						
1TE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %
1TE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %
1TE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %
1TE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %
1TE41-4AS3 1)	800	1330	88 %	55 %	_	_	-

Derating factor of the output current as a function of the pulse frequency for units with a rated pulse frequency of 1.25 kHz
---

Motor Module	Type rating at 400 V or 690 V	Output current at 1.25 kHz	Derating factor at pulse frequer					
6SL3725	kW	А	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz
380 480 V 3 /	AC / 510 720 V D	c						
1TE36-1AA3	315	605	83 %	72 %	64 %	60 %	40 %	-
1TE37-5AA3	400	745	83 %	72 %	64 %	60 %	40 %	-
1TE38-4AA3	450	840	87 %	79 %	64 %	60 %	40 %	-
1TE41-0AA3	560	985	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-2AA3	710	1260	92 %	87 %	70 %	60 %	50 %	47 %
1TE41-4AA3	800	1405	97 %	95 %	74 %	60 %	50 %	47 %
500 690 V 3 /	AC / 675 1035 V [	oc						
1TG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %	-
1TG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %	-
1TG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %	-
1TG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %	-
1TG34-7AA3	450	465	92 %	87 %	67 %	55 %	35 %	-
1TG35-8AA3	560	575	91 %	85 %	64 %	50 %	35 %	-
1TG37-4AA3	710	735	84 %	74 %	53 %	40 %	25 %	-
1TG38-0AA3	800 <sup>2)</sup>	810	82 %	71 %	52 %	40 %	25 %	-
1TG38-1AA3	800	810	97 %	95 %	71 %	55 %	35 %	-
1TG41-0AA3	1000	1025	91 %	86 %	64 %	50 %	30 %	-
1TG41-3AA3	1200	1270	87 %	79 %	55 %	40 %	25 %	-
1TG41-6AA3	1500	1560	87 %	79 %	55 %	40 %	25 %	-

The following tables list the maximum achievable output frequency as a function of the pulse frequency:

Maximum output frequencies achieved by increasing the pulse frequency in Vector mode

Pulse frequency		Max. achievable output frequency			
	1.25 kHz	100 Hz			
	2 kHz	160 Hz			
	2.5 kHz	200 Hz			
	4 kHz	320 Hz			
	5 kHz	400 Hz			
	2 kHz 2.5 kHz 4 kHz	160 Hz 200 Hz 320 Hz			

Maximum output frequencies achieved by increasing the pulse
frequency in Servo mode

Pulse frequency	Max. achievable output frequency		
2 kHz	300 Hz		
4 kHz	300/550 Hz <sup>3)</sup>		

<sup>1)</sup> This Motor Module has been specifically designed for loads demanding a high dynamic performance. The derating factor k<sub>IGBT</sub> and the derating characteristics can be ignored (see section "Duty cycles" in the SINAMICS Low Voltage Engineering Manual).

- <sup>2)</sup> The Motor Module 6SL3725-1TG38-0AA3 is optimized for low overload; with an increased pulse frequency, the derating factor is higher than for the Motor Module 6SL3725-1TG38-1AA3.
- <sup>3)</sup> Higher frequencies on request.

Liquid-cooled units

#### Liquid-cooled units

### Characteristic curves (continued)

#### **Overload capability**

SINAMICS S120 Cabinet Modules have an overload reserve, e.g. to handle breakaway torques. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base-load current must, therefore, be used as a basis for the required load.

Permissible overload assumes that the drive converter is operated at its base-load current before and after the overload occurs, based on a duty cycle duration of 300 s.

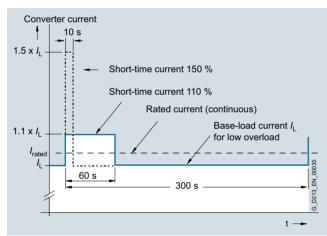
Another precondition is that the Motor Modules are operated at their factory-set pulse frequency at output frequencies >10 Hz.

For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

#### Motor Modules

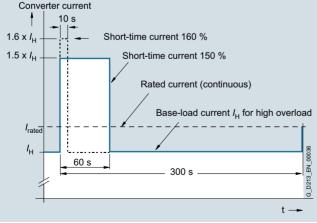
Motor Modules can be configured on the basis of different base-load currents.

The base-load current for a low overload  $I_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s.



#### Low overload

The base-load current  $I_{\rm H}$  for a high overload is based on a duty cycle of 150 % for 60 s or 160 % for 10 s.

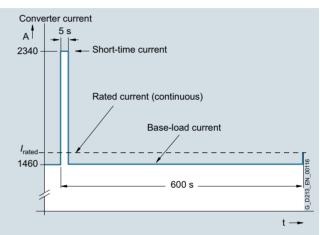


High overload

# The following applies to the Motor Module 6SL3725-1TG41-6AP3:

This Motor Module is particularly suited to high breakaway torques with applications such as drilling, mixers, centrifuges, and test bays. An **additional** duty cycle is required at output frequencies of 5 Hz to 10 Hz.

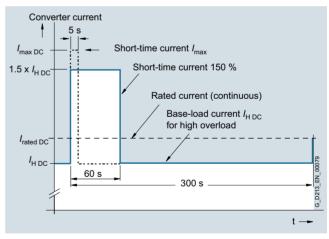
At output frequencies of 1 Hz to 5 Hz, the short-time current is 1900 Å for 5 s.



High overload for Motor Module 6SL3725-1TG41-6AP3

Basic Line Connection Modules and Active Line Connection Modules

The base-load current for a high overload  $I_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s.



High overload

Liquid-cooled units

#### **Basic Line Connection Modules**

#### Overview



Basic Line Connection Modules are compact line infeeds for two-quadrant operation, i.e. no regenerative feedback. They are used when energy need not be fed back into the network.

Basic Line Connection Modules comprise a Line Connection Module and a liquid-cooled Basic Line Module.

As standard, the Basic Line Connection Module is positioned in the drive line-up so that the Motor Modules are arranged to the right. If Motor Modules are to be arranged to the left of the Basic Line Connection Module, option **M88** (DC bus system for lineside Cabinet Modules) must be ordered.

Line Connection Modules contain the line-side infeed via main circuit breaker with fuse switch disconnector or circuit breaker and establish the connection between the plant power system and the Basic Line Modules. They are equipped as standard with a radio interference suppression filter according to EN 61800-3 Category C3.

Under full load, the DC link voltage is higher than the rms value of the rated line voltage by a factor of 1.32, and under partial load by a factor of 1.35.

If regenerative conditions occur in the drive line-up, a Motor Module can be used as a braking chopper, which then converts excess energy to heat in a braking resistor.

Basic Line Connection Modules are suitable for connection to grounded TN/TT and non-grounded IT systems. The following voltages and power ratings are available:

Line voltage	Rated input current	Rated power
380 480 V 3 AC	610 1420 A	360 830 kW
500 690 V 3 AC	340 1350 A	355 1370 kW

For a Basic Line Connection Module a line reactor should be provided at the connection point depending on the line shortcircuit power. This reactor is available as standard. However, it can be omitted if it is not required (option **L22**).

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

# Design

Depending on the input current, the following versions are available:

- ≤ 800 A: Main circuit breaker with fuse switch disconnector
- > 800 A: Circuit breaker, type 3WL, with option L25 as withdrawable circuit breaker

A fully controlled thyristor bridge is used to pre-charge the Basic Line Connection Module and the connected DC link. The thyristors normally operate with a trigger delay angle of 0°.

The power rating can be increased by connecting Basic Line Connection Modules in parallel. You must observe the following rules:

- Up to four identical Active Line Connection Modules can be connected in parallel.
- A common Control Unit is required whenever the modules are connected in parallel.
- The parallel connection must be supplied from a common infeed point (i.e. the modules cannot be operated on different line supplies). For information on using line reactors, see section Basic Line Connection Modules → Overview.
- A derating factor of 7.5 % must be taken into consideration, regardless of the number of modules connected in parallel.
- The main contactors or circuit breakers of the respective Line Connection Modules must close together and simultaneously. Monitoring is performed via the -X50 terminals of the respective Line Connection Module.
- Option M88 must be ordered.

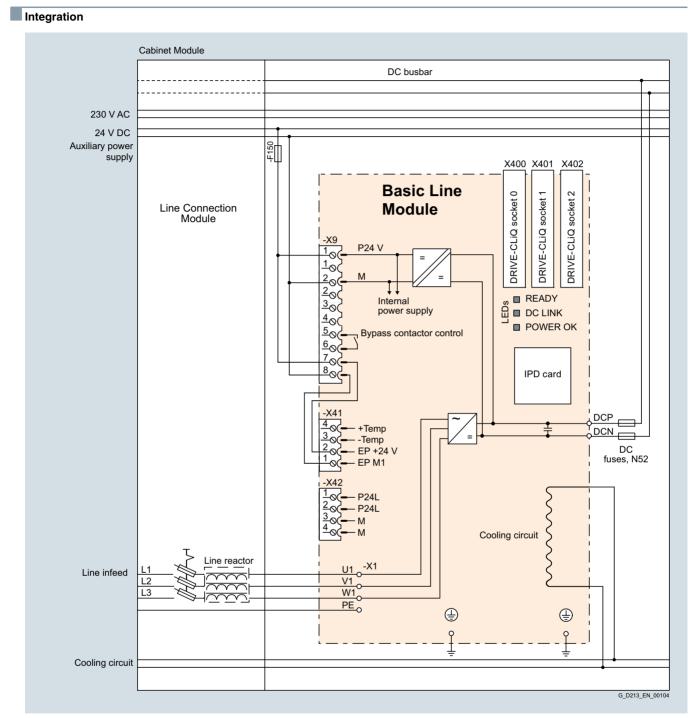
For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Selection and ordering data

Rated power at 400 V or 690 V kW	Rated DC link current A	Basic Line Connection Module Article No.
Line voltage 380 4 (DC link voltage 510		
360	740	6SL3735-1TE37-4LA3
600	1220	6SL3735-1TE41-2LA3
830	1730	6SL3735-1TE41-7LA3
Line voltage 500 6 (DC link voltage 675		
355	420	6SL3735-1TG34-2LA3
630	730	6SL3735-1TG37-3LA3
1100	1300	6SL3735-1TG41-3LA3
1370	1650	6SL3735-1TG41-7LA3

Liquid-cooled units

**Basic Line Connection Modules** 



Connection example: Basic Line Connection Module, liquid-cooled

Liquid-cooled units

### **Basic Line Connection Modules**

# Technical specifications

Line voltage 380 480 V 3 AC		Basic Line Connection Modules		
		6SL3735-1TE37-4LA3	6SL3735-1TE41-2LA3	6SL3735-1TE41-7LA3
Rated power           • At I <sub>rated DC</sub> (50 Hz 400 V)           • At I <sub>H DC</sub> (50 Hz 400 V)	kW kW	<b>360</b> 280	<b>600</b> 450	<b>830</b> 650
• At I <sub>rated DC</sub> (60 Hz 460 V) • At I <sub>H DC</sub> (60 Hz 460 V)	hp hp	555 430	925 690	1280 1000
DC link current			1000	1700
<ul> <li>Rated current l<sub>rated DC</sub></li> <li>Base-load current l<sub>H DC</sub> <sup>1)</sup></li> <li>Maximum current l<sub>max DC</sub></li> </ul>	A A A	740 578 1110	1220 936 1830	1730 1350 2595
Input current			1000	
<ul> <li>Rated current I<sub>rated I</sub></li> <li>Maximum current I<sub>max I</sub></li> </ul>	A A	610 915	1000 1500	1420 2130
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	0.7 1.2	0.7 1.2	0.7 1.2
DC link capacitance • Basic Line Module • Drive line-up, max.	μF μF	12000 96000	20300 162400	26100 208800
Power loss, max. <sup>2)</sup> At 50 Hz 400 V	μ			
<ul> <li>Degree of protection <ip55< li=""> <li>Dissipated to coolant</li> <li>Dissipated to ambient air</li> </ip55<></li></ul>	kW kW	2.7 2.7	4.4 3.5	5.8 4.2
<ul> <li>Degree of protection IP55</li> <li>Dissipated to coolant</li> <li>Dissipated to ambient air</li> </ul>	kW kW	4.9 0.5	7.4 0.5	9.5 0.5
Coolant volume flow <sup>3)</sup> Degree of protection <ip55 ip55<="" td=""><td>l/min</td><td>9/36</td><td>9/36</td><td>12/39</td></ip55>	l/min	9/36	9/36	12/39
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>6.6/10.2</td><td>6.6/10.2</td><td>6.9/10.5</td></ip55>	dm <sup>3</sup>	6.6/10.2	6.6/10.2	6.9/10.5
Pressure drop, max. <sup>4)</sup> For volume flow	Pa	150000	150000	150000
Heat exchanger material		Aluminum	Aluminum	Aluminum
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	56	56
Line supply connection L1, L2, L3		4/M12	5/M12 + 4/M16	5/M12 + 4/M16
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	8 × 240	10 × 240
<ul><li>PE/GND connection</li><li>Busbar cross-section</li><li>Conductor cross-section, max. (IEC)</li></ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>5)</sup> Shielded/unshielded	m	2600/3900	4000/6000	4800/7200
Degree of protection (standard version)		IP21	IP21	IP21
Dimensions • Width	mm	1000	1000	1000
<ul><li>Height</li><li>Depth</li></ul>	mm mm	2200 600	2200 600	2200 600
Weight, approx. (standard version)	kg	688	838	995
Frame size <ul> <li>Line Connection Module</li> <li>Basic Line Module</li> </ul>		HL FBL	JL FBL	JL GBL
Short-circuit current rating according to IEC	kA	65	84	100
Minimum short-circuit current <sup>6)</sup>	А	8800	2000	3200

<sup>1)</sup> The base-load current  $l_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

 The value applies to coolants comprising water and a mixture of water and antifreeze agent. <sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>5)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

<sup>6)</sup> Current required for reliably triggering protective devices.

Δ

Liquid-cooled units

Basic Line Connection Module							
Technical specifications (cor	ntinued)						
Line voltage 500 690 V 3 AC Basic Line Connection Modules							
<b>.</b>		6SL3735-1TG34-2LA3 6SL3735-1TG37-3LA3 6SL3735-1TG41-3LA3 6SL3735-1TG41-7LA3					
Rated power							
• At I <sub>rated DC</sub> (50 Hz 690 V)	kW	355	630	1100	1370		
• At I <sub>H DC</sub> (50 Hz 690 V)	kW	275	475	840	1070		
<ul> <li>At I<sub>rated DC</sub> (50 Hz 500 V)</li> <li>At I<sub>H DC</sub> (50 Hz 500 V)</li> </ul>	kW kW	245 200	420 345	750 610	950 775		
• At I <sub>rated DC</sub> (60 Hz 575 V)	hp	395	705	1230	1530		
• At I <sub>H DC</sub> (60 Hz 575 V)	hp	305	530	940	1195		
DC link current							
Rated current I <sub>rated DC</sub>	А	420	730	1300	1650		
• Base-load current I <sub>H DC</sub> <sup>1)</sup>	A	328	570	1014	1287		
Maximum current Imax DC	A	630	1095	1950	2475		
Input current	•	0.40	000	4070	1050		
<ul> <li>Rated current I<sub>rated I</sub></li> <li>Maximum current I<sub>max I</sub></li> </ul>	A A	340 510	600 900	1070 1605	1350 2025		
	A	510	900	1005	2023		
<ul> <li>Current demand</li> <li>24 V DC auxiliary power supply</li> </ul>	A	0.7	0.7	0.7	0.7		
• 230 V 1 AC	A	1.2	1.2	1.2	1.2		
DC link capacitance							
Basic Line Module	μF	4800	7700	15500	19300		
<ul> <li>Drive line-up, max.</li> </ul>	μF	38400	61600	124000	154400		
Power loss, max. <sup>2)</sup>							
at 50 Hz 690 V • Degree of protection <ip55< td=""><td></td><td></td><td></td><td></td><td></td></ip55<>							
- Dissipated to coolant	kW	1.8	2.7	4.7	5.7		
- Dissipated to ambient air	kW	2.3	2.7	3.3	5.1		
<ul> <li>Degree of protection IP55</li> </ul>							
- Dissipated to coolant	kW	3.3	4.9	7.5	10.3		
- Dissipated to ambient air	kW	0.5	0.5	0.5	0.5		
Coolant volume flow <sup>3)</sup> Degree of protection <ip55 ip55<="" td=""><td>I/min</td><td>9/36</td><td>9/36</td><td>12/39</td><td>12/39</td></ip55>	I/min	9/36	9/36	12/39	12/39		
Liquid volume	.,	6,00	0,00	12,00	.2,00		
Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>6.6/10.2</td><td>6.6/10.2</td><td>6.9/10.5</td><td>6.9/10.5</td></ip55>	dm <sup>3</sup>	6.6/10.2	6.6/10.2	6.9/10.5	6.9/10.5		
Pressure drop, max. <sup>4)</sup> For volume flow	Pa	150000	150000	150000	150000		
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum		
Sound pressure level L <sub>pA</sub>	dB	54	54	56	56		
(1 m) at 50/60 Hz		0/1440	10.110				
Line supply connection L1, L2, L3		2/M12	4/M12	5/M12 + 4/M16	5/M12 + 4/M16		
Conductor cross-section, max.	mm <sup>2</sup>	2 × 150	4 × 240	8 × 240	8 × 240		
(IEC)							
PE/GND connection	mm <sup>2</sup>	PE bar	PE bar	PE bar	PE bar		
<ul> <li>Busbar cross-section</li> <li>Conductor cross-section, max.</li> </ul>	mm <sup>-</sup> mm <sup>2</sup>	600 240	600 240	600 240	600 240		
(IEC)		240	240	240	240		
Cable length, max. <sup>5)</sup> Shielded/unshielded	m	1500/2250	1500/2250	2250/3375	2250/3375		
	111						
Degree of protection (standard version)		IP21	IP21	IP21	IP21		
Dimensions							
• Width	mm	1000	1000	1000	1000		
Height     Depth	mm	2200	2200	2200 600	2200 600		
Depth	mm	600	600				
Weight, approx. (standard version)	kg	578	668	995	1025		
Frame size							
<ul> <li>Line Connection Module</li> <li>Basic Line Module</li> </ul>		GL FBL	HL FBL	JL GBL	JL GBL		
	kA		84		100		
Short-circuit current rating according to IEC	K/A	65	04	100	100		
Minimum short-circuit current <sup>6)</sup>	А	4400	7200	2500	3200		

 $^{1)}$  The base-load current  $\mathit{I}_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $\mathit{I}_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

<sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

 $^{\rm 5)}$  Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

<sup>6)</sup> Current required for reliably triggering protective devices.

4

Liquid-cooled units

#### **Active Line Connection Modules**

#### Overview



Active Line Connection Modules comprise a Line Connection Module, a liquid-cooled Active Interface Module and a liquidcooled Active Line Module. They can supply motoring energy to the DC link and return regenerative energy to the line supply.

As standard, the Active Line Connection Module is positioned in the drive line-up so that the Motor Modules are arranged to the right. If Motor Modules are to be arranged to the left of the Active Line Connection Module, option **M88** (DC bus system for lineside Cabinet Modules) must be ordered.

Line Connection Modules contain the line-side infeed via main circuit breaker with fuse switch disconnector or circuit breaker and establish the connection between the plant power system and the Active Line Modules. They are equipped as standard with a radio interference suppression filter according to EN 61800-3 Category C3.

Active Line Connection Modules produce a stabilized DC voltage that remains constant regardless of fluctuations in the line voltage (the line voltage must remain within the permissible tolerances).

In the factory setting, the DC voltage is regulated to 1.5 times the rms value of the rated line voltage.

Active Line Connection Modules draw a virtually sinusoidal current from the supply system and cause virtually no line harmonics.

Active Line Connection Modules are suitable for connection to supply systems grounded at the neutral point (TN, TT) and non-grounded (IT) supply systems. The following voltages and currents are available:

Line voltage	Rated infeed/ regenerative feedback current	Rated power
380 480 V 3 AC	605 1405 A	380 900 kW
500 690 V 3 AC	735 1560 A	800 1700 kW

### Design

Active Line ConnectionModules always include an Active Interface Module, which contains the associated Clean Power Filter and pre-charging circuit. The line filter that is included ensures compliance with the EMC requirements for the "second environment".

Depending on the input current, the following versions are available:

- ≤ 800 A: Main circuit breaker with fuse switch disconnector
- > 800 A: Circuit breaker, type 3WL, with option L25 as withdrawable circuit breaker

The power rating can be increased by connecting Active Line Connection Modules in parallel. You must observe the following rules:

- Up to four identical Active Line Connection Modules can be connected in parallel.
- A common Control Unit is required whenever the modules are connected in parallel.
- The parallel connection must be supplied from a common infeed point (i.e. the modules cannot be operated on different line supplies).
- A derating factor of 5% must be taken into consideration, regardless of the number of modules connected in parallel.
- The main contactors or circuit breakers of the respective Line Connection Modules must close together and simultaneously. Monitoring is performed via the -X50 terminals of the respective Line Connection Module.
- Option M88 must be ordered.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

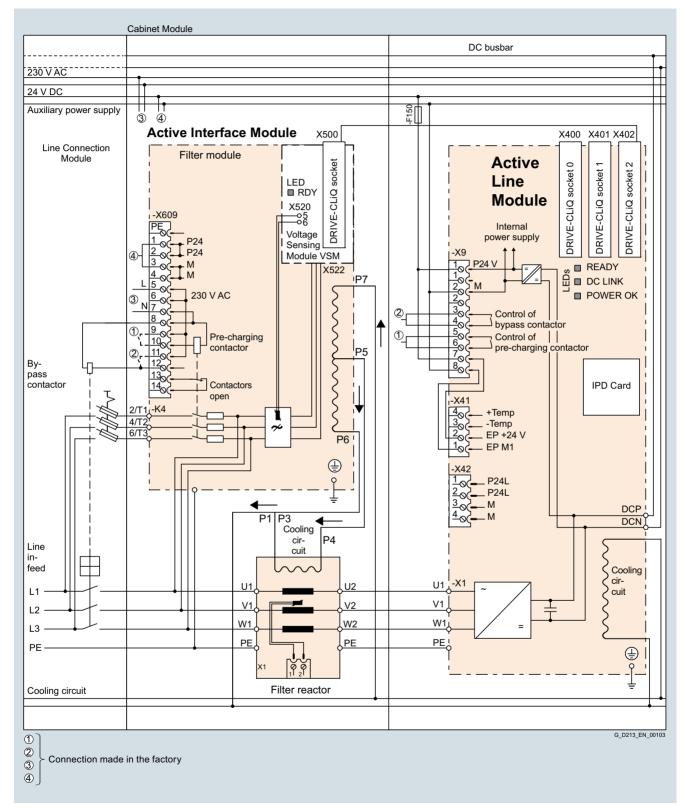
### Selection and ordering data

Rated power at 400 V or 690 V	Rated DC link current	Active Line Connection Module
kW	А	Article No.
Line voltage 380 4 (DC link voltage 570		
380	677	6SL3735-7TE36-1LA3
500	941	6SL3735-7TE38-4LA3
630	1100	6SL3735-7TE41-0LA3
900	1573	6SL3735-7TE41-4LA3
Line voltage 500 ( (DC link voltage 750		
800	823	6SL3735-7TG37-4LA3
900	907	6SL3735-7TG38-1LA3
1100	1147	6SL3735-7TG41-0LA3
1400	1422	6SL3735-7TG41-3LA3
1700	1740	6SL3735-7TG41-6LA3

Liquid-cooled units

**Active Line Connection Modules** 

## Integration



Connection example: Active Line Connection Module, liquid-cooled

Liquid-cooled units

### **Active Line Connection Modules**

### Technical specifications

Line voltage 380 480 V 3 AC		Active Line Connection Modules				
		6SL3735-7TE36-1LA3	6SL3735-7TE38-4LA3	6SL3735-7TE41-0LA3	6SL3735-7TE41-4LA3	
Rated power           • At Irated DC (50 Hz 400 V)           • At IH DC (50 Hz 400 V)           • At IH DC (50 Hz 400 V)           • At Irated DC (60 Hz 460 V)           • At IH DC (60 Hz 460 V)	kW kW hp hp	<b>380</b> 335 600 500	<b>500</b> 465 700 700	<b>630</b> 545 900 800	<b>900</b> 780 1250 1000	
A I H DC (00 H 2 400 V)     DC link current     Rated current I <sub>rated DC</sub> Base-load current I <sub>H DC</sub> Maximum current I <sub>max DC</sub>	A A A	677 603 1017	941 837 1410	1100 982 1654	1573 1401 2361	
Infeed/regenerative feedback current Rated current l <sub>rated 1</sub> • Maximum current l <sub>max 1</sub>		605 907	840 1260	985 1477	1405 2055	
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.77 1.2	1.77 1.2	1.77 1.2	1.77 1.2	
DC link capacitance • Active Line Module • Drive line-up, max.	μF μF	12600 134400	17400 134400	18900 230400	28800 230400	
Power loss, max. <sup>2)</sup> at 50 Hz 400 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant - Dissipated to ambient air</ip55 	kW kW kW kW	10.9 2.4 12.2 0.9	11.7 2.3 13.1 0.9	19.6 3.1 21.8 0.9	21.8 3.8 24.7 0.9	
Coolant volume flow <sup>3)</sup> Degree of protection <ip55 ip55<="" td=""><td>l/min</td><td>32/59</td><td>32/59</td><td>43/70</td><td>43/70</td></ip55>	l/min	32/59	32/59	43/70	43/70	
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>13/16.6</td><td>13/16.6</td><td>14/17.6</td><td>14/17.6</td></ip55>	dm <sup>3</sup>	13/16.6	13/16.6	14/17.6	14/17.6	
Pressure drop, max. <sup>4)</sup> For volume flow	Pa	150000	150000	150000	150000	
Heat exchanger material • Active Line Module • Active Interface Module		Aluminum Aluminum	Aluminum Aluminum	Aluminum Aluminum	Aluminum Aluminum	
Sound pressure level L <sub>pA</sub> <sup>5)</sup> (1 m) at 50/60 Hz	dB	65/65	65/65	65/65	65/65	
Line supply connection L1, L2, L3 • Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 x M12 4 x 240	4 x M12 4 x 240	5 x M12 + 4 x M16 8 x 240	5 x M12 + 4 x M16 10 x 240	
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240	
Cable length, max. <sup>6)</sup> Shielded/unshielded	m	3900/5850	3900/5850	3900/5850	3900/5850	
Degree of protection (standard version)		IP21	IP21	IP21	IP21	
Dimensions • Width • Height • Depth	mm mm mm	1600 2200 600	1600 2200 600	1600 2200 600	1600 2200 600	
Weight, approx. (standard version)	kg	1134	1244	1430	1470	
Frame size <ul> <li>Line Connection Module</li> <li>Active Interface Module</li> <li>Active Line Module</li> </ul>		HL JIL HXL	JL JIL HXL	JL JIL JXL	JL JIL JXL	
Short-circuit current rating according to IEC	kA	65	84	84	100	
Minimum short-circuit current <sup>7)</sup>	А	9200	2000	2000	3200	

<sup>1)</sup> The base-load current  $l_{H DC}$  is based on a duty cycle of 150 % for 60 s or  $l_{max DC}$  for 5 s with a duty cycle duration of 300 s. <sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

 $^{3)}\,$  The value applies to coolants comprising water and a mixture of water and antifreeze agent.

<sup>4)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

 $^{\rm 5)}$  Total sound pressure level of Active Interface Module and Active Line Module.

<sup>6)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

<sup>7)</sup> Current required for reliably triggering protective devices.

Liquid-cooled units

**Active Line Connection Modules** 

# Technical specifications (continued)

Line voltage 500 690 V 3 AC		Active Line Connection Modules					
		6SL3735- 7TG37-4LA3	6SL3735- 7TG38-1LA3	6SL3735- 7TG41-0LA3	6SL3735- 7TG41-3LA3	6SL3735- 7TG41-6LA3	
Rated power           • At I <sub>rated DC</sub> (50 Hz 690 V)           • At I <sub>H DC</sub> (50 Hz 690 V)           • At I <sub>rated DC</sub> (50 Hz 500 V)           • At I <sub>H DC</sub> (50 Hz 500 V)           • At I <sub>H DC</sub> (60 Hz 575 V)           • At I <sub>H DC</sub> (60 Hz 575 V)	kW kW kW kW hp hp	<b>800</b> 705 560 510 900 600	<b>900</b> 670 620 485 975 765	<b>1100</b> 1000 780 710 1250 1000	<b>1400</b> 1215 965 880 1500 1250	<b>1700</b> 1490 1180 1080 1855 1530	
<ul> <li>DC link current</li> <li>Rated current l<sub>rated DC</sub></li> <li>Base-load current l<sub>H DC</sub><sup>1)</sup></li> <li>Maximum current l<sub>max DC</sub></li> </ul>	A A A	823 732 1235	907 808 1360	1147 936 1722	1422 1266 2133	1740 1550 2620	
Infeed/regenerative feedback current • Rated current l <sub>rated 1</sub> • Maximum current l <sub>max 1</sub>	A A	735 1100	810 1214	1025 1537	1270 1905	1560 2055	
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.77 1.2	1.77 1.2	1.77 1.2	1.63 1.2	1.67 1.2	
DC link capacitance • Active Line Module • Drive line-up, max.	μF μF	10500 153600	10500 153600	16000 153600	19330 153600	21000 210000	
Power loss, max. <sup>2)</sup> at 50 Hz 400 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant - Dissipated to ambient air</ip55 	kW kW kW	17.0 2.4 18.4 0.9	19.5 2.4 20.9 0.9	21.6 3.1 23.7 0.9	27.3 3.7 30.1 0.9	37.7 4.4 39.2 0.9	
Coolant volume flow <sup>3)</sup> Degree of protection <ip55 ip55<="" td=""><td>l/min</td><td>32/59</td><td>43/70</td><td>43/70</td><td>43/70</td><td>43/70</td></ip55>	l/min	32/59	43/70	43/70	43/70	43/70	
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>13/16.6</td><td>14/17.6</td><td>14/17.6</td><td>14/17.6</td><td>14/17.6</td></ip55>	dm <sup>3</sup>	13/16.6	14/17.6	14/17.6	14/17.6	14/17.6	
Pressure drop, max. <sup>4)</sup> For volume flow	Pa	150000	150000	150000	150000	150000	
Heat exchanger material • Active Line Module • Active Interface Module		Aluminum Aluminum	Aluminum Aluminum	Aluminum Aluminum	Aluminum Aluminum	Aluminum Aluminum	
Sound pressure level L <sub>pA</sub> <sup>5)</sup> (1 m) at 50/60 Hz	dB	65/65	65/65	65/65	65/65	65/65	
Line supply connection		4 x M12	4 x M12	5 x M12 + 4 x M16	5 x M12 + 4 x M16	5 x M12 + 4 x M16	
Conductor cross-section, max. (IEC)     PE/GND connection     Busbar cross-section	mm <sup>2</sup>	8 × 240 PE bar 600	8 × 240 PE bar 600	8 × 240 PE bar 600	8 × 240 PE bar 600	8 × 240 PE bar 600	
Conductor cross-section, max. (IEC)     Cable length, max. <sup>6)</sup>	mm <sup>2</sup> m	240 2250/3375	240 2250/3375	240 2250/3375	240 2250/3375	240 2250/3375	
Shielded/unshielded Degree of protection (standard usraiae)		IP21	IP21	IP21	IP21	IP21	
(standard version) <b>Dimensions</b> • Width • Height • Depth	mm mm mm	1600 2200 600	1600 2200 600	1600 2200 600	1600 2200 600	1600 2200 600	
Weight, approx. (standard version)	kg	1150	1365	1520	1540	1640	
Frame size <ul> <li>Line Connection Module</li> <li>Active Interface Module</li> <li>Active Line Module</li> </ul>		HL JIL HXL	JL JIL HXL	JL JIL JXL	JL JIL JXL	JL JIL JXL	
Short-circuit current rating according to IEC	kA	84	100	100	100	100	
Minimum short-circuit current <sup>7)</sup>	А	10500	2000	2000	3200	3200	

 $^{1)}$  The base-load current  $I_{\rm H\,DC}$  is based on a duty cycle of 150 % for 60 s or  $I_{\rm max\,DC}$  for 5 s with a duty cycle duration of 300 s.

<sup>2)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>3)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

4) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual. <sup>5)</sup> Total sound pressure level of Active Interface Module and Active Line Module.

<sup>6)</sup> Total of all motor cables and DC link. Longer cable lengths for specific configurations are available on request.

7) Current required for reliably triggering protective devices.

Liquid-cooled units

### **Motor Modules**

## Overview



Motor Modules are available in the power range from 90 kW to 1500 kW.

Line voltage	DC link voltage	Type rating
380 480 V 3 AC	510 720 V DC	110 800 kW
500 690 V 3 AC	675 1035 V DC	90 1500 kW

By connecting in parallel up to four Motor Modules, which are operated on one Control Unit and supply one motor, it is possible to increase the available shaft power to max. approx. 5700 kW (taking into account the derating factors according to the SINAMICS Low Voltage Engineering Manual).

The Motor Modules can also be used as Braking Modules (braking chopper) if a 3-phase braking resistor is connected instead of a motor.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

# Design

Motor Modules contain the following components as standard:

- Retaining device for the DC busbar, including the connection to the DC connections of the Motor Module
- Connection busbars, nickel-plated
  - on Motor Modules, frame size JXL, the connection for the motor cables is routed to the right of the device
  - on Motor Modules, frame size HXL, the connection is underneath the device
- Cable retaining bar for the power cables
- DRIVE-CLiQ interface (three DRIVE-CLiQ sockets), without Control Unit
- Auxiliary power supply system (4-pole) for the auxiliary power supply, including cable connections for looping through to the next Cabinet Module
- Nickel-plated PE bar (60 x 10 mm), including jumper for looping through to the next Cabinet Module
- EMC-compliant design thanks to additional shielding measures and appropriately routed cables

#### Selection and ordering data

Type rating at 400 V or 690 V	Rated output current Irated	Motor Module
kW	A	Article No.
Line voltage 380 44 (DC link voltage 510	80 V 3 AC 720 V DC)	
110	210	6SL3725-1TE32-1AA3
132	260	6SL3725-1TE32-6AA3
160	310	6SL3725-1TE33-1AA3
250	490	6SL3725-1TE35-0AA3
315	605	6SL3725-1TE36-1AA3
400	745	6SL3725-1TE37-5AA3
450	840	6SL3725-1TE38-4AA3
560	985	6SL3725-1TE41-0AA3
710	1260	6SL3725-1TE41-2AA3
800	1405	6SL3725-1TE41-4AA3
800	1330	6SL3725-1TE41-4AS3
Line voltage 500 69 (DC link voltage 675	90 V 3 AC 1035 V DC)	
90	100	6SL3725-1TG31-0AA3
132	150	6SL3725-1TG31-5AA3
200	215	6SL3725-1TG32-2AA3
315	330	6SL3725-1TG33-3AA3
450	465	6SL3725-1TG34-7AA3
560	575	6SL3725-1TG35-8AA3
710	735	6SL3725-1TG37-4AA3
800	810	6SL3725-1TG38-0AA3
800	810	6SL3725-1TG38-1AA3
1000	1025	6SL3725-1TG41-0AA3
1200	1270	6SL3725-1TG41-3AA3
1500	1560	6SL3725-1TG41-6AP3

Liquid-cooled units

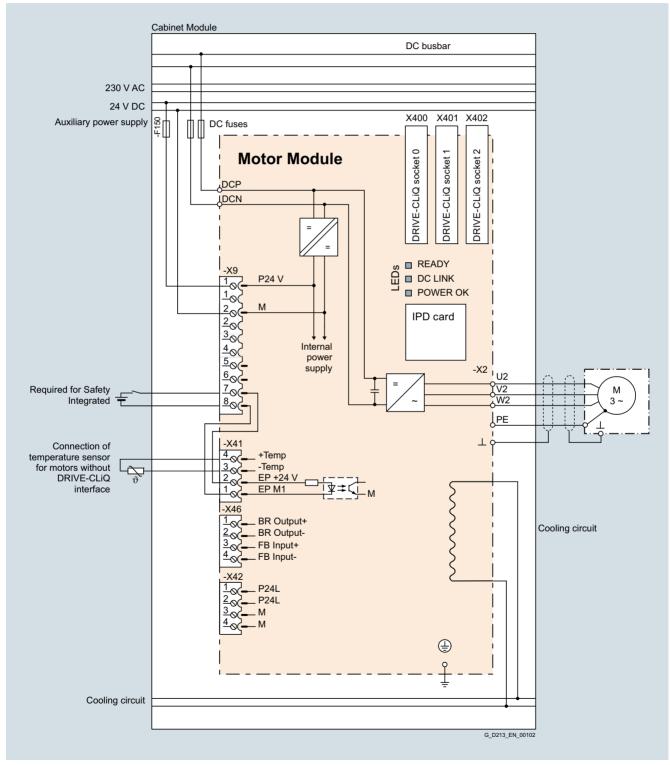
## Integration

Motor Modules are controlled by the CU320-2 DP or CU320-2 PN Control Unit. Communication between the Control Unit and Modules is established via a DRIVE-CLiQ connection.

If the Control Unit is integrated in the same cabinet as an option with order code **K90** or **K95**, these communication cables will

already be installed. If the Control Unit is to be mounted externally, the DRIVE-CLiQ cable will not be included in the scope of delivery and must be configured on site.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.



Connection example: Motor Module, liquid-cooled

Liquid-cooled units

### **Motor Modules**

### Technical specifications

Line voltage 380 480 V 3 AC		Motor Modules			
DC link voltage 510 720 V DC		6SL3725-1TE32-1AA3	6SL3725-1TE32-6AA3	6SL3725-1TE33-1AA3	6SL3725-1TE35-0AA3
<b>Type rating</b> • At <i>l<sub>L</sub></i> (50 Hz 400 V) <sup>1)</sup> • At <i>l<sub>H</sub></i> (50 Hz 400 V) <sup>1)</sup> • At <i>l<sub>H</sub></i> (60 Hz 460 V) <sup>2)</sup> • At <i>l<sub>H</sub></i> (60 Hz 460 V) <sup>2)</sup>	kW kW hp hp	<b>110</b> 90 150 150	<b>132</b> 110 200 200	<b>160</b> 132 250 200	<b>250</b> 200 400 350
Output current • Rated current I <sub>rated Q</sub> • Base-load current I <sub>L</sub> <sup>3</sup> ) • Base-load current I <sub>H</sub> <sup>4</sup> • Maximum current I <sub>max O</sub>	A A A A	210 205 178 307	260 250 233 375	310 302 277 453	490 477 438 715
<ul> <li>DC link current</li> <li>Rated current I<sub>rated DC</sub> when supplied via</li> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current I<sub>L DC</sub><sup>3)</sup> when supplied via</li> <li>Basic Line Module</li> </ul>	A A	256 230 250	317 287 305	380 340 368	600 538 581
<ul> <li>Active Line Module</li> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> <li>Basic Line Module</li> <li>Active Line Module</li> </ul>	A A A	225 227 195	274 284 255	331 338 303	522 534 480
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.3 0.6	1.3 0.6	1.3 0.6	1.3 0.6
DC link capacitance	μF	4800	5800	8400	9600
Pulse frequency <sup>5)</sup> • Rated frequency • Pulse frequency, max. - Without current derating - With current derating	kHz kHz kHz	2 2 8	2 2 8	2 2 8	2 2 8
Power loss, max. <sup>6)</sup>	KIIZ	0	0	0	0
at 50 Hz 400 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant - Dissipated to ambient air</ip55 	kW kW kW	1.6 0.2 1.7 0.2	1.9 0.2 2.1 0.2	2.2 0.2 2.4 0.2	3.4 0.3 3.8 0.2
Coolant volume flow <sup>7)</sup> All degrees of protection	l/min	9	9	12	12
Liquid volume Degree of protection <ip55 ip55<="" th=""><th>dm<sup>3</sup></th><th>2.9/4.7</th><th>2.9/4.7</th><th>3.5/5.3</th><th>3.5/5.3</th></ip55>	dm <sup>3</sup>	2.9/4.7	2.9/4.7	3.5/5.3	3.5/5.3
Pressure drop, max. <sup>8)</sup> For volume flow	Pa	150000	150000	150000	150000
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52
Motor connection U2, V2, W2		M12	M12	M12	M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	2 × 95	2 × 95	2 × 240	2 × 240
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m	300/450	300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21	IP21
Dimensions • Width • Height • Depth	mm mm mm	400 2200 600	400 2200 600	400 2200 600	400 2200 600
Weight, approx.	kg	280	280	320	320
Frame size		FXL	FXL	GXL	GXL
Short-circuit current rating acc. to IEC	kA	65	65	65	65

 $^{\rm 1)}\,$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 460 V 3 AC 60 Hz.

3) The base-load current *I*<sub>L</sub> is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

<sup>4)</sup> The base-load current  $I_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

<sup>8)</sup> The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

**Motor Modules** 

Line voltage 380 480 V 3 AC		Motor Modules		
DC link voltage 510 720 V DC		6SL3725-1TE36-1AA3	6SL3725-1TE37-5AA3	6SL3725-1TE38-4AA3
<b>Type rating</b> At <i>I</i> <sub>L</sub> (50 Hz 400 V) <sup>1</sup> ) At <i>I</i> <sub>H</sub> (50 Hz 400 V) <sup>1</sup> ) At <i>I</i> <sub>L</sub> (60 Hz 460 V) <sup>2</sup> ) At <i>I</i> <sub>L</sub> (60 Hz 460 V) <sup>2</sup> )	kW kW hp hp	<b>315</b> 250 500 350	<b>400</b> 315 600 450	<b>450</b> 400 700 600
Dutput current / Rated current /rated G Base-load current /L <sup>3</sup> ) Base-load current /H <sup>4</sup> ) Maximum current /max O	A A A	605 590 460 885	745 725 570 1087	840 820 700 1230
DC link current / <sub>max O</sub> DC link current / <sub>rated DC</sub> when supplied via - Basic Line Module - Active Line Module Base-load current / <sub>L DC</sub> <sup>3)</sup> when supplied via	A A	738 664	894 805	1025 922
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current l<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> </ul>	A A	719 646	871 784	1000 898
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> </ul>	A A	561 504	795 716	853 767
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.6 0.6	1.6 0.6	1.6 0.6
DC link capacitance	μF	12600	17400	17400
Pulse frequency <sup>5)</sup> Rated frequency	kHz	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> <li>Without current derating</li> <li>With current derating</li> </ul>	kHz kHz	1.25 7.5	1.25 7.5	1.25 7.5
Power loss, max. <sup>6)</sup> at 50 Hz 400 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant - Dissipated to ambient air</ip55 	kW kW kW	4.6 0.6 5.0 0.2	5.2 0.7 5.7 0.2	5.5 0.8 6.2 0.2
Coolant volume flow <sup>7)</sup> All degrees of protection	l/min	16	16	16
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>3.3/5.1</td><td>3.3/5.1</td><td>3.3/5.1</td></ip55>	dm <sup>3</sup>	3.3/5.1	3.3/5.1	3.3/5.1
Pressure drop, max. <sup>8)</sup> For volume flow	Pa	150000	150000	150000
Heat exchanger material		Aluminum	Aluminum	Aluminum
Sound pressure level L <sub>pA</sub> 1 m) at 50/60 Hz	dB	54	54	54
Motor connection J2, V2, W2	0	2/M12	2/M12	2/M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 185	4 × 185	4 × 185
PE/GND connection <ul> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m	300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21
Dimensions				
• Width • Height	mm mm	400 2200 600	400 2200 600	400 2200 600
Depth     Weight, approx.	mm kg	350	350	350
Frame size	1.9	HXL	HXL	HXL
Short-circuit current rating	kA	65	65	84

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 460 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $\mathit{I}_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

#### **Motor Modules**

#### Technical specifications (continued)

Line voltage 380 480 V 3 AC		Motor Modules			
DC link voltage 510 720 V DC		6SL3725-1TE41-0AA3	6SL3725-1TE41-2AA3	6SL3725-1TE41-4AA3	6SL3725-1TE41-4AS3 10)
Type rating           • At $I_{i}$ (50 Hz 400 V) <sup>1</sup> )           • At $I_{i}$ (50 Hz 400 V) <sup>1</sup> )           • At $I_{i}$ (60 Hz 460 V) <sup>2</sup> )           • At $I_{i}$ (60 Hz 460 V) <sup>2</sup> )	kW kW hp hp	<b>560</b> 450 800 700	<b>710</b> 630 1000 900	<b>800</b> 710 1150 1000	<b>800</b> 630 1000 900
Output current • Rated current I <sub>rated</sub> (G) • Base-load current I <sub>L</sub> (4) • Maximum current I <sub>max O</sub>	A A A A	985 960 860 1440	1260 1230 1127 1845	1405 1370 1257 2055	1330 1310 1150 2055
<ul> <li>DC link current</li> <li>Rated current l<sub>rated</sub> DC when supplied via</li> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current l<sub>L</sub> DC <sup>3</sup>) when supplied via</li> </ul>	A A	1202 1080	1512 1361	1714 1544	1550 1403
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current I<sub>H DC</sub><sup>4)</sup> when supplied via</li> </ul>	AA	1170 1051	1474 1326	1670 1500	1525 1405
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> </ul>	A A	1048 942	1345 1211	1532 1377	1676 1403
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.46 0.6	1.46 0.6	1.46 0.6	1.46 0.6
DC link capacitance	μF	21000	29000	29000	21000
Pulse frequency <sup>5)</sup> • Rated frequency • Pulse frequency, max. • Without current derating	kHz kHz	1.25 1.25	1.25	1.25 1.25	2
- With current derating	kHz	7.5	7.5	7.5	2 4
Power loss, max. <sup>6)</sup> at 50 Hz 400 V • Degree of protection <ip55 • Dissipated to coolant • Dissipated to ambient air • Degree of protection IP55 • Dissipated to coolant</ip55 	kW kW	7.5 1.0 8.3 0.2	8.6 1.3 9.6	9.5 1.5 10.7	10.2 1.4 11.3
- Dissipated to ambient air Coolant volume flow <sup>7)</sup>	kW I/min	27	0.3	0.3	0.3
All degrees of protection					
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>5.2/7</td><td>5.2/7</td><td>5.2/7</td><td>5.2/7</td></ip55>	dm <sup>3</sup>	5.2/7	5.2/7	5.2/7	5.2/7
<b>Pressure drop, max.</b> <sup>8)</sup> For volume flow	Pa	150000	150000	150000	150000
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	56	56	56	56
Motor connection U2, V2, W2		2/M12	2/M12	2/M12	2/M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	4 × 240
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m	300/450	300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21	IP21
Dimensions • Width • Height • Depth	mm mm mm	600 2200 600	600 2200 600	600 2200 600	600 2200 600
Weight, approx.	kg	460	460	460	470
Frame size		JXL	JXL	JXL	JXL
Short-circuit current rating according to IEC	kA	84	100	100	100

according to IEC

1) Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 400 V 3 AC 50 Hz.

<sup>2)</sup> Rated output of a typical 6-pole standard induction motor based on  $l_{\rm L}$  or  $l_{\rm H}$  for 460 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $I_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual

<sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

7) The value applies to coolants comprising water and a mixture of water and antifreeze agent.

The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request.For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>This Motor Module has been specifically designed for loads demanding a high dynamic performance. The derating factor  $k_{\text{IGBT}}$  and the derating characteristics can be ignored (see section "Duty cycles" in the SINAMICS Low Voltage Engineering Manual).

Liquid-cooled units

**Motor Modules** 

	,	Mater Madulas			
Line voltage 500 690 V 3 AC DC link voltage 675 1035 V DC		Motor Modules 6SL3725-1TG31-0AA3	6SL3725-1TG31-5AA3	6SL3725-1TG32-2AA3	6SL3725-1TG33-3AA3
		03L3723-11031-0AA3	03L3723-11031-JAA3	03L3723-11032-2AA3	03L3723-11033-3AA3
Type rating           • At $h_1$ (50 Hz 690 V) <sup>1</sup> )           • At $h_2$ (50 Hz 690 V) <sup>1</sup> )           • At $h_2$ (50 Hz 500 V) <sup>1</sup> )           • At $h_2$ (50 Hz 500 V) <sup>1</sup> )           • At $h_4$ (50 Hz 500 V) <sup>1</sup> )           • At $h_4$ (60 Hz 575 V) <sup>2</sup> )           • At $h_4$ (60 Hz 575 V) <sup>2</sup> )	kW kW kW kW hp hp	<b>90</b> 75 55 55 75 75	<b>132</b> 110 90 150 125	<b>200</b> 160 132 132 200 200	<b>315</b> 250 200 200 300 250
Output current • Rated current / <sub>rated</sub> G • Base-load current / <sub>L</sub> • Base-load current / <sub>H</sub> • Maximum current / <sub>max O</sub>	A A A A	100 95 89 142	150 142 134 213	215 208 192 312	330 320 280 480
DC link current • Rated current / <sub>rated DC</sub> when supplied via - Basic Line Module - Active Line Module • Base-load current l <sub>L DC</sub> <sup>3</sup> ) when supplied via	A A	122 110	183 165	263 237	403 363
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current I<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> <li>Basic Line Module</li> </ul>	A A A	116 105 108	173 156 163	253 229 234	390 352 341
- Active Line Module Current demand	Â	98	147	211	308
<ul> <li>24 V DC auxiliary power supply</li> <li>230 V 1 AC</li> </ul>	A	1.0 0.6	1.0 0.6	1.5 0.6	1.5 0.6
DC link capacitance	μF	2800	2800	4200	5800
<ul> <li>Pulse frequency <sup>5)</sup></li> <li>Rated frequency</li> <li>Pulse frequency, max.</li> </ul>	kHz	1.25	1.25	1.25	1.25
<ul> <li>Without current derating</li> <li>With current derating</li> <li>Power loss, max. <sup>6</sup>)</li> </ul>	kHz kHz	1.25 7.5	1.25 7.5	1.25 7.5	1.25 7.5
at 50 Hz 690 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant</ip55 	kW kW	1.1 0.1 1.2	1.6 0.1 1.7	2.3 0.2 2.4	3.3 0.3 3.5
- Dissipated to ambient air	kW	0.1	0.1 9	0.2	0.2
Coolant volume flow 7) All degrees of protection Liquid volume	l/min dm <sup>3</sup>	9 2.9/4.7	2.9/4.7	12 3.5/5.3	12 3.5/5.3
Degree of protection <ip55 ip55<br="">Pressure drop, max.<sup>8)</sup></ip55>	Pa				
For volume flow	Ра	150000	150000	150000	150000
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	52	52	52	52
Motor connection U2, V2, W2	0	M12	M12	M12	M12
Conductor cross-section, max. (IEC)	mm∠	2 × 95	2 × 95	2 × 240	2 × 240
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m	300/450	300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21	IP21
Dimensions	20.07	100	400	400	100
<ul><li>Width</li><li>Height</li><li>Depth</li></ul>	mm mm mm	400 2200 600	400 2200 600	400 2200 600	400 2200 600
Weight, approx.	kg	280	280	320	320
Frame size	Ŭ	FXL	FXL	GXL	GXL
Short-circuit current rating according to IEC	kA	65	65	65	65

<sup>1)</sup> Rated output of a typical 6-pole standard induction motor based on  $I_{\rm L}$  or  $I_{\rm H}$  for 500 V or 690 V 3 AC 50 Hz.

Technical specifications (continued)

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $I_{\rm L}$  or  $I_{\rm H}$  for 575 V 3 AC 60 Hz.

<sup>3)</sup> The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $\mathit{I}_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

9) Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Liquid-cooled units

#### **Motor Modules**

#### Technical specifications (continued)

Line voltage 500 690 V 3 AC		Motor Modules			201 2725 (TO22 244 5 10)
DC link voltage 675 1035 V DC		6SL3725-1TG34-7AA3	6SL3725-1TG35-8AA3	6SL3725-1TG37-4AA3	6SL3725-1TG38-0AA3 <sup>10)</sup>
Type rating           • At $h_{1}$ (50 Hz 690 V) <sup>1</sup> )           • At $h_{2}$ (50 Hz 690 V) <sup>1</sup> )           • At $h_{1}$ (50 Hz 690 V) <sup>1</sup> )           • At $h_{2}$ (50 Hz 500 V) <sup>1</sup> )           • At $h_{1}$ (50 Hz 500 V) <sup>1</sup> )           • At $h_{2}$ (60 Hz 575 V) <sup>2</sup> )           • At $h_{1}$ (60 Hz 575 V) <sup>2</sup> )	kW kW kW hp hp	<b>450</b> 400 315 250 450 450	<b>560</b> 450 400 315 600 500	<b>710</b> 630 500 450 700 700	800 710 560 500 800 700
Output current • Rated current <i>I</i> <sub>rated</sub> (G) • Base-load current <i>I</i> <sub>H</sub> <sup>(4)</sup> • Base-load current <i>I</i> <sub>H</sub> <sup>(4)</sup> • Maximum current <i>I</i> <sub>max O</sub>	A A A A	465 452 416 678	575 560 514 840	735 710 657 1065	810 790 724 1185
DC link current • Rated current I <sub>rated DC</sub> when supplied via - Basic Line Module - Active Line Module • Base-load current I <sub>L DC</sub> <sup>3</sup> when supplied via	A A	558 502	702 632	903 808	990 891
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current /<sub>H DC</sub><sup>4)</sup></li> <li>when supplied via</li> <li>Basic Line Module</li> </ul>	A A	544 489 496	683 616	870 781 795	948 870
- Active Line Module Current demand	A	446	627 565	732	885 808
<ul> <li>24 V DC auxiliary power supply</li> <li>230 V 1 AC</li> </ul>	A A	1.6 0.6	1.6 0.6	1.6 0.6	1.6 0.6
DC link capacitance	μF	9670	9670	10500	10500
Pulse frequency <sup>5)</sup> • Rated frequency • Pulse frequency, max. - Without current derating	kHz kHz	1.25 1.25	1.25 1.25	1.25 1.25	1.25 1.25
<ul> <li>With current derating</li> </ul>	kHz	7.5	7.5	7.5	7.5
Power loss, max. <sup>6)</sup> at 50 Hz 690 V • Degree of protection <ip55 • Dissipated to coolant • Dissipated to ambient air • Degree of protection IP55</ip55 	kW kW	5.3 0.4	5.5 0.5	7.5 0.6	8.3 0.7
<ul> <li>Dissipated to coolant</li> <li>Dissipated to ambient air</li> </ul>	kW kW	5.6 0.2	5.8 0.2	7.9 0.2	8.8 0.2
Coolant volume flow <sup>7)</sup> All degrees of protection	l/min	16	16	16	16
Liquid volume Degree of protection <ip55 ip55<="" th=""><th>dm<sup>3</sup></th><th>3.3/5.1</th><th>3.3/5.1</th><th>3.3/5.1</th><th>3.3/5.1</th></ip55>	dm <sup>3</sup>	3.3/5.1	3.3/5.1	3.3/5.1	3.3/5.1
<b>Pressure drop, max.</b> <sup>8)</sup> For volume flow	Pa	150000	150000	150000	150000
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	54	54	54	54
Motor connection U2, V2, W2		2/M12	2/M12	2/M12	2/M12
<ul> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup>	4 × 185	4 × 185	4 × 185	4 × 185
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m	300/450	300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21	IP21
Dimensions • Width • Height • Depth	mm mm mm	400 2200 600	400 2200 600	400 2200 600	400 2200 600
Weight, approx.	kg	350	350	350	350
Frame size		HXL	HXL	HXL	HXL
Short-circuit current rating according to IEC	kA	84	84	100	100

according to IEC

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 500 V or 690 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual. <sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>The device is optimized for a base pulse frequency of 1.25 kHz. For an increased pulse frequency or for certain overloads, the derating factor is higher than that for the device with article number 6SL3325-1TG38-1AAx.

Liquid-cooled units

**Motor Modules** 

	1000)				
Line voltage 500 690 V 3 AC		Motor Modules			COL 0705 1TO 41 CAPO 10)
DC link voltage 675 1035 V DC		6SL3725-1TG38-1AA3	6SL3725-1TG41-0AA3	6SL3725-1TG41-3AA3	6SL3725-1TG41-6AP3 10)
Type rating           • At $I_{L}$ (50 Hz 690 V) <sup>1</sup> )           • At $f_{L}$ (50 Hz 690 V) <sup>1</sup> )           • At $f_{L}$ (50 Hz 500 V) <sup>1</sup> )           • At $f_{L}$ (50 Hz 500 V) <sup>1</sup> )           • At $f_{L}$ (50 Hz 500 V) <sup>1</sup> )           • At $f_{L}$ (60 Hz 575 V) <sup>2</sup> )           • At $f_{H}$ (60 Hz 575 V) <sup>2</sup> )	kW kW kW hp hp	<b>800</b> 710 560 560 800 700	<b>1000</b> 900 710 630 1000 900	<b>1200</b> 1000 900 800 1250 1000	<b>1500</b> 1260 1000 900 1500 1250
Output current • Rated current / <sub>rated</sub> (G) • Base-load current / <sub>L</sub> 4) • Maximum current / <sub>max O</sub>	A A A A	810 790 724 1185	1025 1000 917 1500	1270 1230 1136 1845	1560 1500 1370 2250
DC link current • Rated current l <sub>rated DC</sub> when supplied via - Basic Line Module - Active Line Module • Base-load current l <sub>L DC</sub> <sup>3</sup> when supplied via	A A	990 891	1250 1125	1550 1395	1903 1714
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> <li>Base-load current (<sub>H DC</sub><sup>4</sup>) when supplied via</li> </ul>	A A	963 869	1219 1100	1500 1353	1800 1650
<ul> <li>Basic Line Module</li> <li>Active Line Module</li> </ul>	A A	883 796	1118 1009	1384 1250	1680 1550
Current demand • 24 V DC auxiliary power supply • 230 V 1 AC	A A	1.46 0.6	1.46 0.6	1.46 0.6	1.46 0.6
DC link capacitance	μF	14000	16000	19330	21000
Pulse frequency <sup>5)</sup> • Rated frequency • Pulse frequency, max.	kHz	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> <li>Without current derating</li> <li>With current derating</li> </ul>	kHz kHz	1.25 7.5	1.25 7.5	1.25 7.5	1.25 7.5
Power loss, max. <sup>6)</sup> At 50 Hz 690 V • Degree of protection <ip55 - Dissipated to coolant - Dissipated to ambient air • Degree of protection IP55 - Dissipated to coolant</ip55 	kW kW kW	9.0 1.1 9.8	10.0 1.2 11.2	12.9 1.4 14.0	17.1 1.6 18.4
- Dissipated to ambient air Coolant volume flow <sup>7)</sup>	kW I/min	0.3 27	0.3 27	0.3	0.3
All degrees of protection					
Liquid volume Degree of protection <ip55 ip55<="" td=""><td>dm<sup>3</sup></td><td>5.2/7</td><td>5.2/7</td><td>5.2/7</td><td>5.2/7</td></ip55>	dm <sup>3</sup>	5.2/7	5.2/7	5.2/7	5.2/7
<b>Pressure drop, max.</b> <sup>8)</sup> For volume flow	Pa	150000	150000	150000	150000
Heat exchanger material		Aluminum	Aluminum	Aluminum	Aluminum
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	56	56	56	56
Motor connection U2, V2, W2	0	2/M12	2/M12	2/M12	2/M12
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4 × 240	4 × 240	4 × 240	4 × 240
<ul> <li>PE/GND connection</li> <li>Busbar cross-section</li> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup> mm <sup>2</sup>	PE bar 600 240	PE bar 600 240	PE bar 600 240	PE bar 600 240
Cable length, max. <sup>9)</sup> Shielded/unshielded	m 300/450 300/450		300/450	300/450	300/450
Degree of protection (standard version)		IP21	IP21	IP21	IP21
Dimensions • Width • Height • Depth	mm mm mm	600 2200 600	600 2200 600	600 2200 600	600 2200 600
Weight, approx.	kg	460	460	460	480
Frame size		JXL	JXL	JXL	JXL
Short-circuit current rating according to IEC	kA	100	100	100	100

#### according to IEC

Technical specifications (continued)

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 500 V or 690 V 3 AC 50 Hz.

 $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.

 $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

5) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

<sup>6)</sup> The specified power loss represents the maximum value at 100 % utilization. The value is lower under normal operating conditions.

<sup>7)</sup> The value applies to coolants comprising water and a mixture of water and antifreeze agent.

8) The value is valid for water as coolant. Additional information and notes on other coolants are provided in the SINAMICS Low Voltage Engineering Manual.

<sup>9)</sup> Total of all motor cables. Longer cable lengths for specific configurations are available on request. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

<sup>10)</sup>Additional duty cycle for output frequencies from 5 Hz to 10 Hz: Base-load current = 1460 A, short-time current = 2340 A for 5 s with a duty cycle duration of 600 s. For output frequencies from 1 Hz to 5 Hz, the short-time current is 1900 A for 5 s.

Liquid-cooled units

### **Auxiliary Power Supply Modules**

## Overview



Auxiliary Power Supply Modules supply the auxiliary power supply system for the SINAMICS S120 Cabinet Modules as well as additional external loads. The heat exchangers, which are installed in the Cabinet Modules with degree of protection IP55, are one of the connections to the auxiliary power supply system. In addition, the auxiliary power supply system supplies the electronic modules with an external voltage of 24 V DC. This is required when the DC link is not charged, for instance, in order to maintain PROFIBUS/PROFINET communication.

The Auxiliary Power Supply Module provides an expansion to the option K76 (auxiliary voltage generating unit in the Line Connection Module) if higher power ratings are required.

## Design

The Auxiliary Power Supply Module is connected in the customer's plant to a voltage corresponding to the respective rated unit voltage.

The standard version contains the following components:

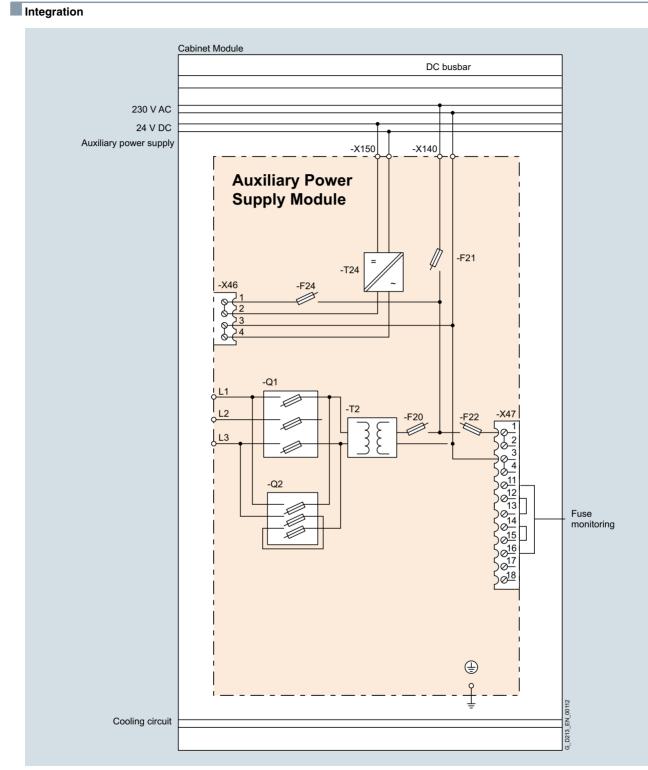
- Fuse switch disconnector with fuse monitoring for external evaluation
- Supply of auxiliary power supply system with 2 auxiliary voltages:
  - 24 V DC for the electronics power supply - 230 V 2 AC to supply 230 V loads
- Transformer with 230 V output voltage
- SITOP 24 V DC power supply
- Nickel-plated PE bar (60 mm × 10 mm), including jumper for looping through to the next Cabinet Module

#### Selection and ordering data

Plant-side power supply (380 690 V 3 AC)	Auxiliary Power Supply Module
A	Article No.
25	6SL3705-0MX22-0AA3

Liquid-cooled units

Auxiliary Power Supply Modules



Connection example: Auxiliary Power Supply Module, liquid-cooled

Liquid-cooled units

# Auxiliary Power Supply Modules

# Technical specifications

		Auxiliary Power Supply Module
		6SL3705-0MX22-0AA3
Plant-side power supply 380 690 V 3 AC	A	25
Line supply connection		
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	70
<ul> <li>Recommended conductor cross-section</li> </ul>	mm <sup>2</sup>	6
Current carrying capacity, max.		
Load connection     230 V 2 AC		
- To auxiliary power supply	А	10
- To customer terminal -X47	А	10
Load connection     24 V DC		
- To auxiliary power supply	А	20
Cable cross-section, max.		
Connection -X47	mm <sup>2</sup>	2.5
Cooling air requirement		Natural convection
PE/GND connection		PE bar
<ul> <li>Busbar cross-section</li> </ul>	mm <sup>2</sup>	600
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	240
Degree of protection		IP21
Dimensions		
• Width	mm	600
• Height	mm	2200
• Depth	mm	600
Weight, approx.	kg	160
Short-circuit current rating acc. to IEC	kA	80
Minimum short-circuit current <sup>1)</sup>	А	400

4

<sup>1)</sup> Current required to ensure reliable tripping of installed protective devices.

Liquid-cooled units

#### **Heat Exchanger Modules**

### Overview



Heat Exchanger Modules are used to dissipate the power loss from the converter. They comprise a deionized water circuit on the converter side and a raw water circuit on the plant side.

The hot deionized water in the circuit on the converter side passes through a low-maintenance circulating pump (2 redundant pumps with option **W01**) into the water/water plate-type heat exchanger. This is made of stainless steel and connected to the raw water circuit on the plant side. The deionized water is cooled there by the raw water of the outer circuit and flows back into the drive.

The closed converter-side deionized water circuit is filled with coolant in accordance with the requirements in section "Cooling circuit and coolant quality" and deaerated before commissioning. The pressure is maintained by means of an expansion chamber. Any residual air that arises in the circuit during operation is removed via automatic vents.

To avoid condensation at excessively low coolant temperatures, a 3-way valve for controlling the coolant temperature is installed.

The Heat Exchanger Modules are controlled and monitored in the external CU320-2 Control Unit as "Technology Extension HEM". This means that the Heat Exchanger Modules are controlled and monitored in a drive-related manner which therefore increases usability. The system parameters of the Heat Exchanger Modules can be accessed using the familiar tools (STARTER). The current LOGO! modules are being replaced by the SINAMICS product range (TM31, TM150 Terminal Modules). New functionalities for avoiding condensation are integrated and can be parameterized together with further settings. Integration into the drive system means that integration into higher-level control systems to visualize signals and messages is considerably easier.

Heat Exchanger Modules are available for the following voltages and cooling power ratings:

Line voltage	Cooling power
380 415 V 3 AC, 50 Hz	32 120 kW
660 690 V 3 AC, 50 Hz	32 120 kW

Heat Exchanger Modules for the line voltages 440 V to 480 V, 60 Hz as well as 660 V to 690 V, 60 Hz are available with options **C95** and **C97**.

### Design

The deionized water is monitored by the drive itself to ensure intrinsic protection. The operating status is signaled to the drive.

Heat Exchanger Modules contain the following components as standard:

- 1 pump
- 1 stainless steel plate-type heat exchanger
- 1 3-way valve
- Filter, expansion chamber, vent, safety valve, pressure sensors, pressure display, temperature sensor, TM31 and TM150 Terminal Modules

#### Scope of delivery:

The pipe connections (couplings) for connection to the deionized water circuit on the converter side are included in the scope of delivery. The pipe connections (couplings) for connection to the raw water circuit on the plant/system side are not components of the scope of delivery. For this connection, a connecting pipe and a pipe coupling with the appropriate diameter must be used. The respective data is given in the Technical specifications.

#### Note:

Heat Exchanger Modules can only be located at the beginning or end of a cabinet row for technical reasons.

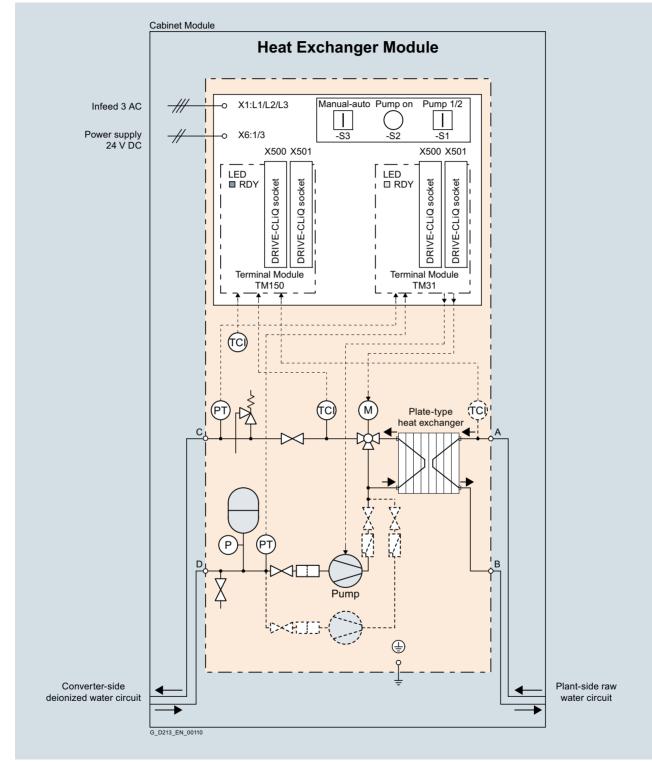
#### Selection and ordering data

Cooling power	Heat Exchanger Module
kW	Article No.
Line voltage 380 415 V 3 AC, 50 Hz; 440	480 V 3 AC, 60 Hz
32	6SL3705-0RE23-2AA4
48	6SL3705-0RE24-8AA4
72	6SL3705-0RE27-2AA4
120	6SL3705-0RE31-1AA4
Line voltage 660 690 V 3 AC, 50/60 Hz	
32	6SL3705-0RG23-2AA4
48	6SL3705-0RG24-8AA4
72	6SL3705-0RG27-2AA4
120	6SL3705-0RG31-1AA4

Liquid-cooled units

### **Heat Exchanger Modules**

# Integration



Connection example: Heat Exchanger Module, liquid-cooled

Liquid-cooled units

# Technical specifications

The Heat Exchanger Modules must be selected appropriately for the required cooling power and the required volume flow of coolant in the converter-side deionized water circuit. The values stated in the technical specifications of the Cabinet Modules for the heat loss dissipated into the coolant must be summated. The total value is then the required cooling power.

The volume flow of coolant stated in the technical specifications of the Cabinet Modules must also be added.

If either of the two total values exceeds the values defined in the technical specifications of the Heat Exchanger Module (cooling power and volume flow of coolant for converter-side deionized water), the next larger Heat Exchanger Module must be selected.

Line voltage 380 415 V 3 AC 50 Hz		Heat Exchanger Mo	dules		
Line voltage 440 480 V 3 AC 60 Hz	1)	6SL3705-0RE23-2AA	4 6SL3705-0RE24-8AA4	6SL3705-0RE27-2AA4	6SL3705-0RE31-1AA4
Cooling power	kW	32	48	72	120
Deionized water circuit (on the conve	rter side	e)			
Inlet temperature					
• Min.	°C		nbient temperature and humic et Modules $\rightarrow$ Protection agai		he dew point in section
• Max.					
<ul> <li>Drive line-up degree of protection <ip55< li=""> </ip55<></li></ul>	°C	45	45	45	45
<ul> <li>Drive line-up degree of protection IP55</li> </ul>	°C	40	40	40	40
Intake pressure					
• Min.	bar	1.7	1.7	1.7	1.7
• Max.	bar	6	6	6	6
Coolant volume flow <sup>2)</sup>	l/min	88	132	197	267
Liquid volume	I	20.4	21.4	30.5	32.5
Intake/return connection					
<ul> <li>External diameter x wall thickness</li> </ul>	mm	76.1 x 2	76.1 x 2	76.1 x 2	76.1 x 2
Raw water circuit (on the plant side)					
Inlet temperature					
• Min.	°C	5 <sup>3)</sup>	5 <sup>3)</sup>	5 <sup>3)</sup>	5 <sup>3)</sup>
• Max.					
<ul> <li>Drive line-up degree of protection <ip55< li=""> </ip55<></li></ul>	°C	38	38	38	38
- Drive line-up degree of protection IP55	°C	33	33	33	33
Intake pressure, max.	bar	6	6	6	6
Coolant volume flow <sup>2)</sup>	l/min	132	198	263	445
Intake/return connection					
<ul> <li>External diameter x wall thickness</li> </ul>	mm	42 x 1.5	42 x 1.5	76.1 x 2	76.1 x 2
General data					
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel
Current consumption					
Operating current, total at 50/60 Hz 400 V	А	7.5/7.0	7.5/7.0	11.0/12.0	11.0/12.0
<ul> <li>Electronics current (24 V DC)</li> </ul>	А	1.0	1.0	1.0	1.0
Power consumption, max. at 50/60 Hz 400 V	kW	3.5/4.7	3.5/4.7	5.5/6.4	5.5/6.4
Sound pressure level L <sub>pA</sub> (1 m) at 50 Hz	dB	60	60	60	60
Line supply connection		Terminal	Terminal	Terminal	Terminal
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4	4	4	4
PE/GND connection		Terminal	Terminal	Terminal	Terminal
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4	4	4	4
Degree of protection (standard version)		IP55	IP55	IP55	IP55
Dimensions					
• Width <sup>4)</sup>	mm	600	600	600	600
• Height	mm	2200	2200	2200	2200
• Depth	mm	600	600	600	600
Weight, approx. <sup>5)</sup> (standard version)	kg	310	310	320	320

<sup>2)</sup> The value is valid for water as coolant. For other coolants,

 $^{\rm 4)}$  With option W01, the cabinet width increases to 1000 mm.

see section Cooling circuit and coolant properties.

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Liquid-cooled units

### Heat Exchanger Modules

### **Technical specifications** (continued)

With Heat Exchanger Modules for line voltages of 660 ... 690 V 3 AC, the voltage is adapted to the 400 V 3 AC/50 Hz or 460 V/3 AC 60 Hz supply voltage of the pump using a transformer.

Line voltage 660 690 V 3 AC 50 Hz		Heat Exchanger Modules								
Line voltage 660 690 V 3 AC 60 Hz	z <sup>1)</sup>	6SL3705-0RG23-2AA4	6SL3705-0RG27-2AA4	6SL3705-0RG31-1AA4						
Cooling power	kW	32	48	72	120					
Deionized water circuit (on the conv	verter side)									
Inlet temperature										
• Min.	°C		Depending on the ambient temperature and humidi Liquid-cooled Cabinet Modules $\rightarrow$ Protection again		the dew point in section					
<ul> <li>Max.</li> <li>Drive line-up degree of protection <ip55< li=""> </ip55<></li></ul>	°C	45	45	45	45					
<ul> <li>Drive line-up degree of protection IP55</li> </ul>	°C	40	40	40	40					
Intake pressure										
• Min.	bar	1.7	1.7	1.7	1.7					
• Max.	bar	6	6	6	6					
Coolant volume flow <sup>2)</sup>	l/min	88	132	197	267					
Liquid volume	1	20.4	21.4	30.5	32.5					
Intake/return connection • External diameter x wall thickness	mm	76.1 × 2	76.1 x 2	76.1 x 2	76.1 x 2					
Raw water circuit (on the plant side	)									
Inlet temperature										
• Min.	°C	5 <sup>3)</sup>	5 <sup>3)</sup>	5 <sup>3)</sup>	5 <sup>3)</sup>					
• Max.										
- Drive line-up degree of protection <ip55< td=""><td>°C</td><td>38</td><td>38</td><td>38</td><td colspan="2">38</td></ip55<>	°C	38	38	38	38					
- Drive line-up degree of protection IP55	°C	33	33	33	33					
Intake pressure, max.	bar	6	6	6	6					
Coolant volume flow <sup>2)</sup>	l/min	132	198	263	445					
Intake/return connection										
External diameter x wall thickness	mm	42 x 1.5	42 x 1.5	76.1 x 2	76.1 x 2					
General data										
Heat exchanger material		Stainless steel	Stainless steel	Stainless steel	Stainless steel					
Current consumption     Operating current, total	A	4.4/4.1	4.4/4.1	6.4/7.0	6.4/7.0					
at 50/60 Hz 690 V	A	1.0	1.0	1.0	1.0					
• Electronics current (24 V DC)				-	-					
Power consumption, max. at 50/60 Hz 690 V	kW	3.5/4.7	3.5/4.7	5.5/6.4	5.5/6.4					
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	60	60	60	60					
Line supply connection		Terminal	Terminal	Terminal	Terminal					
<ul> <li>Conductor cross-section, max. (IEC)</li> </ul>	mm <sup>2</sup>	4	4	4	4					
PE/GND connection		Terminal	Terminal	Terminal	Terminal					
Conductor cross-section, max. (IEC)	mm <sup>2</sup>	4	4	4	4					
Degree of protection (standard version)		IP55	IP55	IP55	IP55					
Dimensions										
• Width <sup>4)</sup>	mm	600	600	600	600					
• Height	mm	2200	2200	2200	2200					
• Depth	mm	600	600	600	600					
Weight, approx. <sup>5)</sup> (standard version)	kg	310	310	320	320					

<sup>1)</sup> Heat Exchanger Modules 660 V to 690 V, 60 Hz available with option **C97**.

<sup>2)</sup> The value is valid for water as coolant. For other coolants, see section Cooling circuit and coolant properties. <sup>3)</sup> 0 °C with antifreeze (see derating characteristics).

 $^{\rm 4)}$  With option W01, the cabinet width increases to 1000 mm.

 $^{5)}\,$  With option W01, the cabinet weight increases by approximately 110 kg.

Liquid-cooled units

4

**Heat Exchanger Modules** 

### Accessories

Components for filling the cooling circuit with liquid-cooled SINAMICS S120 Cabinet Modules

For commissioning and filling the deionized water circuit on the converter side with the corresponding cooling medium, the following components are needed:

- 1 pump
- 1 vessel with capacity of 100 I
- 1 hose (1/2")
- 1 ball valve

The coolant base must be mixed before filling the cooling circuit with the coolant additive. 100+ liter drums are suitable for this purpose, for example.

We recommend that a drum pump is used that can produce a pressure of 3 bar. The following pumps are recommended for filling:

- Drum and container pumps for emptying the drum, RE-PP, for corrosive and neutral liquids from Lutz Pumpen GmbH, www.lutz-pumpen.com or
- Chemical pumps, electrical drum pumps from Sinntec Schmiersysteme GmbH, www.sinntec.de

Note:

When placing an order, please state that a hose (1/2"), a ball valve, and a terminal piece are required for a connection with 1/2" on the pump outlet.

# Options

## Overview

The following table provides an overview of all of the available options and their assignment to the individual Cabinet Modules.

SINAMICS S120 Cabinet Modules			ooled net Mo	dules			Liquid-cooled Cabinet Modules								
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module
C95	Supply voltage for the Heat Exchanger Module, 440480 V/60 Hz	-	-	-	-	-	-	-	-	-	-	-	-	-	✓
C97	Supply voltage for the Heat Exchanger Module, 660 690 V/60 Hz	-	-	-	-	-	-	-	-	-	-	-	-	-	~
G20 <sup>1)</sup>	CBC10 Communication Board	_	√	√	√	√	_	✓	_	_	√	√	✓	_	_
G33 <sup>1)</sup>	CBE20 Communication Board	_			~		_		_	_			 ✓	_	_
G51	1 x TM150 temperature sensor evaluation unit	✓	_	_	_	_	_	_	_	_	✓	✓	✓	_	_
G52	2 x TM150 temperature sensor evaluation units	✓	_	_	_	_	_	_	_	_	✓	✓	✓	_	_
G53	3 x TM150 temperature sensor evaluation units	~	-	_	_	_	_	_	_	_	~	~	_	_	_
G54	4 x TM150 temperature sensor evaluation units	✓	-	_	_	_	_	_	_	_	✓	✓	_	_	_
G56	Contactor monitoring	-	✓	✓	<b>√</b> 2)	-	-	-	-	-	-	-	-	-	-
G60 <sup>1)</sup>	TM31 Terminal Module	-	-	-	-	-	-	-	-	-	✓	✓	✓	-	-
G61 <sup>1)</sup>	Additional TM31 Terminal Module	-	-	-	-	-	-	_	-	_	~	~	~	-	-
G62 <sup>1)</sup>	TB30 Terminal Board	-	✓	✓	✓	✓	-	✓	-	-	~	✓	✓	-	-
K01 to K05	Safety license for 1 to 5 axes	-	-	-	-	✓	-	✓	-	-	-	-	✓	-	-
K08 <sup>1)</sup>	AOP30 Advanced Operator Panel installed in the cabinet door	-	~	~	~	~	-	~	-	-	~	~	~	-	-
K46	SMC10 Sensor Module Cabinet-Mounted	-	-	-	-	~	-	~	-	-	-	-	~	-	-
K48	SMC20 Sensor Module Cabinet-Mounted	-	-	-	-	✓	-	✓	-	-	-	-	✓	-	-
K50	SMC30 Sensor Module Cabinet-Mounted	-	-	-	-	~	-	~	-	-	-	-	~	-	-
K51	VSM10 Voltage Sensing Module	-	-	-	-	✓	-	~	-	-	-	-	~	-	-
K52	Second SMC30 Sensor Module Cabinet-Mounted	-	-	-	-	~	-	~	-	-	-	-	~	-	-
K70	Fan power supply	~	-	-	-	-	-	-	-	-	-	-	-	-	-
K73	SITOP power supply 24 V DC	-	-	-	-	-	✓	-	-	-	-	-	-	-	-
K76	Auxiliary power generation (in the Line Connection Module)	~	-	-	-	-	-	-	-	-	~	~	-	-	-
K82	Terminal module for controlling the Safe Torque Off and Safe Stop 1 safety functions	-	-	-	-	~	-	~	-	-	-	-	~	-	-
K87	TM54F Terminal Module	—	-	-	—	~	-	~	-	—	-	—	~	-	-
K88	Safe Brake Adapter 230 V AC	-	-	-	-	-	-	~	-	_	-	-	~	-	-
K90	CU320-2 DP Control Unit	-	✓	~	~	~	-	~	-	-	~	~	~	-	-
K94 <sup>1)</sup>	Performance expansion for CU320-2 Control Unit	-	~	~	~	~	-	✓	-	-	~	~	✓	-	-
K95	CU320-2 PN Control Unit	_	✓	✓	✓	✓		✓			✓	✓	✓		

Option cannot be ordered for this Cabinet Module

# Options

Overview (continued)

SINAMICS S120 Cabinet Modules			Air-cooled Cabinet Modules										Liquid-cooled Cabinet Modules					
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module			
L00 <sup>3)</sup>	Use in the "first environment" according to EN 61800-3, Category C2 (TN/TT supply systems with grounded neutral point)	<u>→</u>	-	-	-	-	-	-	-	-	-	-	-	-	-			
L07	dv/dt filter compact plus Voltage Peak Limiter	-	-	-	-	-	-	✓	-	-	-	-	-	-	-			
L08	Motor reactor	-	-	-	-	✓	-	~	-	-	-	-	-	-	-			
L09	2 motor reactors connected in series	-	-	-	-	~	-	-	-	-	-	-	-	-	-			
L10	dv/dt filter plus Voltage Peak Limiter	-	-	-	-	-	-	~	-	-	-	-	-	-	-			
L13	Main contactor (for supply currents of $\leq$ 800 A)	✓ <sup>4)</sup>	-	-	-	-	-	-	-	-	✓ <sup>4)</sup>	-	-	-	-			
L21	Surge suppression	✓	-	-	-	-	-	-	-	-	~	~	-	-	-			
L22	Scope of delivery without line reactor	✓ <sup>5)</sup>	-	~	-	-	-	-	-	-	✓ ()	-	-	-	-			
L25	Withdrawable circuit breaker in place of a fixed- mounted circuit breaker	✓ <sup>6)</sup>	-	-	-	-	-	-	-	-	<b>√</b> <sup>6)</sup>	✓ <sup>6)</sup>	-	-	-			
L34	Output-side circuit breaker (motor-driven)	-	-	-	-	-	-	<ul> <li>✓</li> </ul>	-	-	-	-	-	-	-			
L37	DC interface incl. pre-charging circuit of the associated DC link capacitance	-	-	-	-	~	-	✓	-	-	-	-	-	-	-			
L40	Line filter monitoring	-	-	-	~	-	-	-	-	-	-	✓ 	-	-	-			
L41	Current transformer upstream of main circuit breaker	✓ 	-	-	-	-	-	-	-	-	✓	✓	-	-	-			
L42	Line Connection Module for Active Line Modules	✓ ✓	-	-	-	-	-	-	-	-	-	-	-	-	-			
L43	Line Connection Module for Basic Line Modules	✓ ✓	-	-	-	-	-	-	-	-	-	-	-	-	-			
L44 L45	Line Connection Module for Smart Line Modules EMERGENCY OFF pushbutton installed in the cabinet door	<ul> <li>✓</li> </ul>	-	-	-	-	-	-	-	-		-	-	-	-			
L46	Grounding switch upstream of main circuit breaker	<b>√</b> 7)	_	_	_	_	_	_	_	_	_	_	_	_	_			
L47	Grounding switch downstream of main circuit breaker	✓ 7)	-	-	-	-	-	-	-	-	-	-	-	-	-			
L50	Cabinet lighting with service socket	✓	-	-	-	-	-	-	-	-	✓	✓	-	-	-			
L55	Cabinet anti-condensation heating	~	~	✓	✓	-	~	~	~	~	~	~	~	~	~			
L61	25/125 kW braking unit (can be used for frame size FB) for line voltages of 380 480 V and 660 690 V	-	√	-	•	-	-	~	-	-	-	-	-	-	-			
L62	50/250 kW braking unit (can be used for frame size GB/GD) for line voltages of 380 480 V and 660 690 V	-	✓ 8)	*	~	-	-	~	-	-	-	-	-	-	-			
L64	25/125 kW braking unit (can be used for frame size FB) for line voltages of 500 600 V	-	~	-	~	-	-	~	-	-	-	-	-	-	-			
L65	50/250 kW braking unit (can be used for frame size GB/GD) for line voltages of 500 600 V	-	~	*	~	-	-	~	-	-	-	-	-	-	-			
L87	Insulation monitoring	~	-	-	-	-	-	-	-	-	✓	✓	-	-	-			
✓ -	Option can be ordered for this Cabinet Module Option cannot be ordered for this Cabinet Module																	

# Options

# **Overview** (continued)

SINAMICS S	SINAMICS S120 Cabinet Modules			dules			Liquid-cooled Cabinet Modules								
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module
M06	Base 100 mm high, RAL 7022	✓	✓	1	1	-	✓	✓	~	<ul> <li>✓</li> </ul>	✓	✓	✓	✓	✓
M07	Cable marshaling compartment 200 mm high, RAL 7035	✓	✓	~	~	-	~	✓	~	~	~	~	~	~	~
M21	Degree of protection IP21	✓	✓	✓	✓	-	✓	✓	✓	✓	-	-	-	-	-
M23	Degree of protection IP23 (includes M60)	~	✓	✓	~	-	~	✓	✓	~	✓	✓	~	✓	_ 9)
M26	Side panel mounted to the right	-	✓	✓	~	-	~	✓	✓	✓	✓	~	✓	~	✓
M27	Side panel mounted to the left	~	~	✓	~	-	~	~	✓	~	✓	~	~	~	~
M43	Degree of protection IP43 (includes M60)	~	✓	✓	~	-	~	~	✓	~	✓	~	~	~	_ 9)
M51	Motor connection wired to customer terminal	-	-	-	-	✓	-	-	-	-	-	-	-	-	-
M54	Degree of protection IP54 (includes M60)	~	✓	✓	~	-	✓	~	✓	~	-	-	-	-	-
M55	Degree of protection IP55	-	-	-	-	-	-	-	-	-	✓	~	✓	~	_ 9)
M56	Reinforced mechanical design	~	~	✓	~	-	~	~	~	~	-	-	-	-	-
M59	Closed cabinet door, air intake from below through floor opening	~	~	~	1	-	~	~	~	~	-	-	-	-	-
M60 <sup>10)</sup>	Additional touch protection (included in M23, M43, and M54)	~	~	~	~	-	-	~	-	-	-	-	-	-	_
M70	EMC shield bus	✓	-	-	-	-	~	~	-	~	✓	~	✓	~	-
M72	Quick-release couplings for water hoses	-	-	-	-	-	-	-	-	-	~	~	~	-	-
M77	Version without component support plates and without additional control components	-	-	-	-	-	~	-	-	-	-	-	-	-	-
M90	Crane transport assembly (top-mounted)	✓	✓	~	~	-	~	~	~	~	~	~	✓	~	✓
M91	Marking of all control cable wire ends (including customer-specific cables)	~	~	~	~	-	~	~	~	~	~	~	~	~	~
N52	DC link fuses	-	✓	-	-	-	-	-	-	-	✓	✓	-	-	-
P10	Measuring instrument for line supply values; mounted in cabinet door (includes L41)	~	-	-	-	-	-	-	-		~	~	-	_	-
P11	Measuring instrument for line supply values like option <b>P10</b> , with PROFIBUS connection	~	-	-	-	-	-	-	-	-	~	~	-	-	-
W01	Heat Exchanger Module, partially redundant with 2 pumps	-	-	-	-	-	-	-	-	-	-	-	-	-	~
W10	Pipe insulation in the raw water circuit	-	-	-	-	-	-	-	-	-	-	-	-	-	~
W20	Raw-water connection from the bottom	-	-	-	-	-	-	-	-	-	-	-	-	-	~
W34	Heat Exchanger Module for installation on the left	-	-	-	-	-	-	-	-	-	-	-	-	-	~
W36	Heat Exchanger Module for installation on the right	-	-	-	-	-	-	-	-	-	-	-	-	-	<ul> <li>✓</li> </ul>
W43	Release valve in the deionized water circuit	-	-	-	-	-	-	-	-	-	-	-	-	-	<ul> <li>✓</li> </ul>
W49	Leakage sensor in the Heat Exchanger Module	-	-	-	-	-	-	-	-	-	-	-	-	-	<ul> <li>✓</li> </ul>
W62	Sensors in the raw water circuit on the plant/ system side	-	-	-	-	-	-	-	-	-	-	-	-	-	~
Y09	Special paint finish for cabinet	~	~	✓	✓	-	~	~	~	✓	✓	~	~	✓	~
Y11	Factory-assembled transport units	~	✓	1	~	-	~	~	~	~	✓	~	✓	✓	-
~	Option can be ordered for this Cabinet Module														

Option cannot be ordered for this Cabinet Module

# Options

Overview (continued)

SINAMICS S	120 Cabinet Modules	Air-ce Cabii	ooled net Mo	dules								d-cool net Mo			
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module
Production f	lowcharts														
B43	Document - Production flowchart: one issue	~	~	~	~	-	~	~	~	~	~	~	~	~	~
B44	Document - Production flowchart: updated every two weeks	~	~	~	~	-	~	~	~	~	~	~	~	~	~
B45	Document - Production flowchart: updated every month	~	~	~	~	-	~	~	~	~	~	~	~	~	~
Packaging o	ptions														
B55	Generation of a preliminary and a final packing list (shipping)	~	~	~	~	-	~	~	~	~	~	~	~	~	~
B56	Packed items labeled with a customized label	~	~	~	~	-	~	~	~	~	~	~	~	~	~
B57	Photo documentation of the ordered units	~	~	~	~	-	~	~	~	~	~	~	~	~	~
Mechanical	options for DC busbar system														
M80	DC busbar system ( $I_d = 1170 \text{ A}, 1 \times 60 \times 10 \text{ mm}$ )	~	~	~	~	-	~	~	~	~	~	~	~	~	-
M81	DC busbar system ( $I_d = 1500 \text{ A}, 1 \times 80 \times 10 \text{ mm}$ )	~	~	~	~	-	~	~	~	~	~	~	~	~	-
M82	DC busbar system ( $I_d$ = 1840 A, 1 × 100 × 10 mm)	~	~	~	~	-	~	~	~	~	~	~	~	~	-
M83	DC busbar system ( $I_d = 2150 \text{ A}, 2 \times 60 \times 10 \text{ mm}$ )	~	~	~	~	-	~	~	~	~	~	~	~	~	-
M84	DC busbar system ( $I_d = 2730 \text{ A}, 2 \times 80 \times 10 \text{ mm}$ )	~	~	~	~	-	✓	1	~	~	~	~	~	~	-
M85	DC busbar system ( $I_d = 3320 \text{ A}, 2 \times 100 \times 10 \text{ mm}$ )	~	~	~	~	-	✓	1	~	~	~	~	~	~	-
M86	DC busbar system ( $I_{\rm d}=3720$ A, 3 × 80 × 10 mm)	~	1	~	~	-	✓	1	✓	~	~	~	~	~	-
M87	DC busbar system ( $I_{\rm d}=4480$ A, 3 × 100 × 10 mm)	✓	1	~	~	-	~	1	1	~	~	~	~	~	-
M88	DC busbar system for line-side Cabinet Modules	-	-	-	-	-	-	-	-	-	✓	✓	-	-	-
	Option and he contend for this Ophic at Medule														

Option can be ordered for this Cabinet Module

Option cannot be ordered for this Cabinet Module

# Options

# **Overview** (continued)

SINAMICS S	120 Cabinet Modules		ooled net Mo	dules							Liquid-cooled Cabinet Modules				
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module
Documentati										_			_		
D00 D02	Documentation in German Customer documentation (circuit diagram, terminal diagram, layout diagram) in DXF format	✓ ✓	✓ ✓	✓ ✓	✓ ✓	-	✓ ✓	✓ ✓	✓ ✓	✓ ✓	✓ ✓	✓ ✓	✓ ✓	✓ ✓	✓ ✓
D14	Preliminary version of customer documentation in PDF format	~	~	~	~	-	~	~	<b>√</b>	✓	~	~	<b>√</b>	~	√
D56	Documentation in Russian	✓	✓	✓	✓	-	✓	✓	✓	~	✓	✓	✓	✓	✓
D58	Documentation in English/French	✓	✓	✓	✓	-	✓	✓	✓	~	✓	✓	✓	✓	✓
D60	Documentation in English/Spanish	~	✓	✓	~	-	✓	✓	✓	✓	✓	✓	✓	~	✓
D72	Documentation in Italian	~	✓	✓	~	-	✓	✓	✓	✓	✓	✓	✓	~	✓
D76	Documentation in English	~	✓	~	~	-	~	✓	~	~	✓	~	~	✓	~
D77	Documentation in French	✓	✓	✓	~	-	~	✓	✓	✓	✓	~	✓	<b>√</b>	~
D78	Documentation in Spanish	✓	✓	✓	~	-	~	✓	✓	✓	✓	~	✓	<b>√</b>	~
D80	Documentation in English/Italian	~	~	~	~	-	~	~	~	~	~	~	~	~	~
D84	Documentation in Chinese	✓	✓	✓	~	-	~	~	~	~	~	~	~	✓	~
D91	Documentation in English/Chinese	~	~	~	~	-	~	~	~	~	~	~	~	~	~
D93	Documentation in English/Portuguese (Brazil)	~	~	~	~	-	~	~	~	~	-	-	-	-	-
D94	Documentation in English/Russian	~	✓	~	~	-	~	~	~	~	~	~	~	~	~
D99	Without operating instructions	~	✓	✓	~	-	~	✓	~	~	✓	~	~	~	~
Labeling plat	tes														
Т58	Rating plate data in English/French	✓	✓	✓	~	-	~	~	~	~	✓	~	~	✓	~
Т60	Rating plate data in English/Spanish	~	~	~	~	-	~	~	~	~	~	~	~	~	~
Т80	Rating plate data in English/Italian	~	✓	✓	~	-	~	✓	~	~	~	~	~	~	~
Т83	Rating plate data in English/Portuguese (Brazil)	~	~	✓	~	-	~	~	~	~	-	-	-	-	-
Т85	Rating plate data in English/Russian	~	~	~	✓	-	~	~	~	~	~	~	~	~	~
T91	Rating plate data in English/Chinese	~	~	✓	~	-	~	~	~	~	✓	~	~	~	~
Y31	One-line label for system identification, 40 × 80 mm	<b>v</b>	~	~	✓	-	~	~	~	~	~	~	~	~	✓
Y32	Two-line label for system identification, $40 \times 180 \text{ mm}$	~	~	~	~	-	~	~	~	~	~	~	~	~	✓
Y33	Four-line label for system identification, 40 × 180 mm	✓	~	~	~	-	~	1	✓	✓	~	~	✓	~	✓
✓	Option can be ordered for this Cabinet Module														

- Option cannot be ordered for this Cabinet Module

4

## Options

Overview (continued)

SINAMICS S	Air-co Cabir	ooled net Mo	dules								d-cool net Mo				
Order code	Options	Line Connection Module	Basic Line Module	Smart Line Module	Active Line Module with Active Interface Module	Motor Module Booksize (Cabinet Kit)	Motor Module Booksize (Base Cabinet)	Motor Module Chassis	Central Braking Module	Auxiliary Power Supply Module	Basic Line Connection Module	Active Line Connection Module	Motor Module	Auxiliary Power Supply Module	Heat Exchanger Module
Converter ac	cceptance inspection														
F03	Visual acceptance	~	✓	✓	~	-	~	✓	✓	✓	✓	✓	✓	✓	✓
F71	Function test without motor (witnessed by customer)	✓	✓	✓	✓	-	✓	✓	✓	✓	✓	✓	✓	✓	✓
F72	Function test without motor (not witnessed by customer)	~	~	~	~	-	~	~	~	~	~	~	~	~	~
F74	Function test with test bay motor in no-load operation (not witnessed by customer) <sup>11)</sup>	~	~	~	~	-	~	~	-	-	~	~	~	-	-
F75	Function test with test bay motor in no-load operation (witnessed by customer) <sup>11)</sup>	~	~	~	~	-	~	~	-	-	~	~	~	-	-
F76	Insulation test (not witnessed by customer)	✓	✓	✓	✓	-	✓	✓	✓	✓	✓	✓	✓	✓	✓
F77	Insulation test (witnessed by customer)	~	✓	✓	✓	-	~	✓	✓	~	✓	~	✓	~	✓
F97	Customer-specific acceptance inspections (on request)	~	~	~	~	-	~	~	~	~	~	~	~	~	~
✓	Option can be ordered for this Cabinet Module														

Option cannot be ordered for this Cabinet Module

<sup>1)</sup> Only in conjunction with option **K90** or **K95**.

- $^{2)}\,$  Option G56 cannot be selected for Active Line Modules in frame sizes FX and GX.
- <sup>3)</sup> For Basic Line Modules for cable lengths < 100 m. Not for a parallel connection of Line Modules to a common Line Connection Module.

<sup>4)</sup> For rated currents  $\leq$  800 A.

<sup>5)</sup> Only with option L43 (for Basic Line Modules) and for rated currents  $\leq$  2000 A.

<sup>6)</sup> For rated currents  $\ge$  800 A.

<sup>7)</sup> For rated currents  $\geq$  2000 A.

- <sup>8)</sup> When Basic Line Modules are connected in parallel with a Line Connection Module, there is only space to fit a braking unit in the right-hand Basic Line Module.
- $^{9)}\,$  Heat Exchanger Modules have degree of protection IP55 as standard.
- <sup>10)</sup>Can only be ordered for air-cooled Cabinet Modules. Liquid-cooled Cabinet Modules incorporate additional touch protection as a standard feature.
- <sup>11)</sup>For a function test with test bay motor, the motor is connected to Motor Modules in chassis format and/or Motor Modules in booksize format in the Base Cabinet.

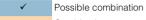
4

# Options

# Overview (continued)

**Option selection matrix** 

Certain options are mutually exclusive. Options that are not affected are not shown.



Combination not possible

# Electrical options

	G20	G33	G62	K90	K95
G20		-	-	~	✓
G33	-		-	~	~
G62	-	-		~	✓
K90	~	~	~		-
K95	~	~	~	I	

	L61/64	L62/65
L61/64		-
L62/65	-	

	K46	K48	K50	K51	K52	K88	L07	L08	L09 <sup>1)</sup>	L10	L34	L37
K46		-	-	-	-	~	~	~	~	~	~	~
K48	-		-	-	-	~	~	~	~	~	~	~
K50	-	-		-	~	~	~	~	~	~	~	~
K51	-	-	-		-	~	~	~	✓	~	✓	~
K52	-	-	~	-		~	~	~	~	~	~	✓
K88	~	~	~	~	~		~	~	✓	~	✓	~
L07	~	✓	~	~	~	~		-	-	-	-	~
L08	~	~	~	~	~	~	-		-	-	~	~
L09 <sup>1)</sup>	~	~	~	~	~	~	-	-		-	-	~
L10	~	✓	~	~	~	~	-	-	-		-	✓
L34	~	✓	~	✓	✓	✓	-	✓	-	-		~
L37	~	✓	~	~	~	~	~	~	~	~	~	

1) Option for Booksize Cabinet Kit only.

# Electrical options (Line Connection Module)

	K76	L13 <sup>1)</sup>	L25 <sup>2)</sup>	L41	L46 <sup>3)</sup>	L47 <sup>3)</sup>	P10	P11
K76		~	✓	~	-	~	~	~
L13 <sup>1)</sup>	~		-	~	-	-	~	~
L25 <sup>2)</sup>	~	-		~	~	~	~	✓
L41	~	~	✓		~	~	-	-
L46 <sup>3)</sup>	-	-	~	~		~	~	~
L47 <sup>3)</sup>	~	-	✓	~	~		~	~
P10	~	~	~	-	~	~		-
P11	~	~	✓	-	~	✓	-	

<sup>1)</sup> Option for rated currents of  $\leq$  800 A only.

<sup>2)</sup> Option for rated currents of > 800 A only.

<sup>3)</sup> Option for rated currents of  $\ge$  2000 A only.

Options

	L22	L42	L43	L44	M06	M07	M21	M23	M26	M27	M43	M54	M55	M60	M90	Y11	Y31	Y32	Y33
L22		-	✓	-	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
L42	-		-	-	✓	~	✓	✓	~	✓	~	~	-	~	✓	✓	✓	~	✓
L43	✓	-		-	~	~	~	~	~	✓	~	~	-	✓	✓	~	~	~	✓
L44	-	-	-		✓	✓	✓	✓	✓	✓	✓	✓	-	✓	✓	✓	✓	✓	✓
M06	✓	✓	✓	✓		-	~	✓	✓	✓	✓	✓	~	✓	✓	~	✓	✓	✓
M07	✓	✓	✓	✓	-		~	✓	✓	✓	✓	✓	✓	✓	✓	~	✓	✓	✓
M21	✓	✓	✓	✓	✓	✓		-	✓	✓	-	-	-	✓	✓	~	✓	✓	✓
M23	✓	✓	✓	✓	✓	✓	-		✓	✓	-	-	-	_ 1)	✓	✓	✓	✓	✓
M26	✓	✓	✓	✓	✓	✓	~	✓		-	✓	✓	~	✓	✓	~	✓	✓	✓
M27	~	✓	✓	✓	✓	✓	✓	✓	-		✓	✓	~	✓	✓	✓	✓	✓	✓
M43	✓	✓	✓	✓	✓	✓	-	-	✓	~		-	-	_ 1)	✓	✓	✓	✓	✓
M54	✓	✓	✓	✓	✓	✓	-	-	✓	✓	-		-	_ 1)	✓	✓	✓	✓	✓
M55	✓	-	-	-	✓	✓	-	-	✓	✓	-	-		-	✓	✓	✓	✓	✓
M60	✓	✓	✓	✓	✓	✓	✓	_ 1)	✓	✓	_ 1)	_ 1)	-		✓	✓	✓	✓	✓
M90	✓	✓	✓	✓	✓	✓	~	✓	✓	✓	✓	✓	~	✓		-	✓	✓	✓
Y11	✓	✓	~	~	~	~	~	~	~	~	~	~	✓	✓	-		✓	~	✓
Y31	✓	✓	~	~	~	~	~	~	~	✓	~	~	✓	✓	✓	~		-	-
Y32	✓	✓	~	~	✓	~	✓	✓	~	✓	~	~	✓	~	✓	✓	-		-
Y33	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	-	-	

Overview (continued)

Mechanical/electrical options

<sup>1)</sup> Option **M60** is already included in **M23**, **M43**, and **M54** for all Line Modules and Motor Modules in chassis format.

# DC busbar system mechanical options (busbars between individual Cabinet Modules)

	M80	M81	M82	M83	M84	M85	M86	M87
M80		-	-	✓	-	-	-	-
M81	-		-	-	✓	-	~	-
M82	-	-		-	-	~	-	~
M83	~	-	-		-	-	-	-
M84	-	~	-	-		-	~	-
M85	-	-	~	-	-		-	~
M86	-	~	-	-	~	-		-
M87	-	-	~	-	-	~	-	

# Documentation

	D00	D02	D14	D56	D58	D60	D72	D76	D77	D78	D80	D84	D91	D93	D94	D99
D00		✓	✓	~	~	~	~	✓	✓	~	~	√	✓	✓	~	-
D02	✓		✓	~	~	~	~	✓	✓	~	~	√	✓	✓	~	-
D14	✓	✓		~	~	~	~	✓	~	~	~	✓	~	✓	~	-
D56	✓	~	✓		~	~	~	~	√	~	~	√	✓	~	-	-
D58	✓	~	✓	~		-	~	-	-	~	-	✓	-	-	-	-
D60	✓	~	~	~	-		~	-	✓	-	-	✓	-	-	-	-
D72	✓	~	✓	~	~	~		~	~	✓	-	✓	~	✓	~	-
D76	✓	~	~	~	-	-	~		✓	~	-	✓	-	-	-	-
D77	✓	~	~	~	-	~	~	~		~	~	✓	~	~	~	-
D78	✓	~	~	~	~	-	~	~	✓		~	✓	✓	~	~	-
D80	✓	~	~	~	-	-	-	-	~	~		~	-	-	-	-
D84	✓	~	~	~	~	~	~	~	✓	~	~		-	~	~	-
D91	✓	~	~	~	-	-	~	-	~	~	-	-		-	-	-
D93	~	~	~	√	-	-	✓	-	√	✓	-	√	-		-	-
D94	✓	~	~	-	-	-	~	-	✓	~	-	✓	-	-		-
D99	-	-	-	-	-	-	-	-	-	-	-	Ι	-	-	-	

# Options

### Options

#### *B43, B44, B45 Production flowcharts*

Production flowcharts are provided with options **B43** to **B45**. After the order has been clarified, these are emailed as a dual-language (English/German) PDF file.

Option	Description
B43	Documentation - Production flowchart: one issue
B44	Documentation - Production flowchart: updated every two weeks
B45	Documentation - Production flowchart: updated every month
DEE	

#### **B55**

# Generation of a preliminary and a final packing list (shipping)

This option provides an electronically editable packing list (possibly predefined from the factory) with the following information in Excel format:

- Number of individual packages
- Type of package (pallet, crate, etc.)
- Weight (unpacked and packed)
- Dimensions (unpacked and packed)
- Delivery location
- Label for package item (when option B56 is ordered)
- · Description of what is in the package

An initial packing list is generated after complete technical clarification with preliminary data. When shipped, a final packing list is provided with the actual data.

## **B**56

# Packed items labeled with a customized label

With this option, customized labels are attached to the unpacked and packed packaged units. Internal customers must provide two labels at least 2 weeks before the shipping date (printout to the factory logistics department, specifying the article number).

## **B**57

#### Photographic documentation of the ordered units

This option provides digital photographic documentation with the following content:

- 1 photo diagonally from the front
- 1 photo diagonally from the rear (opposite)
- 1 photo with the packed item on which the label is legible

The listed photos of the packed items are taken in both an unpacked and a packed state in each position (a total of 6 photos per packed item).

#### *C95, C97 Power supply voltage for the Heat Exchanger Module with 60 Hz*

With option **C95**, Heat Exchanger Modules are provided for power supply voltages of 440 V to 480 V 3 AC at 60 Hz.

With option **C97** for line voltages of 660 to 690 V 3 AC/60 Hz, the voltage is adapted to the 440 V to 480 V 3 AC/60 Hz supply voltage of the pump using a transformer.

# D02

# Customer documentation (circuit diagram, terminal diagram, layout diagram) in DXF format

Option **D02** can be used to order documents such as circuit diagrams, terminal diagrams, layout diagrams, and dimension drawings in DXF format, e.g. for further processing in CAD systems.

#### D14

# Preliminary version of customer documentation in PDF format

If documents such as circuit diagrams, terminal diagrams, layout diagrams and dimension drawings are required in advance for the purpose of system engineering (integration of drive into higher-level systems, interface definition, installation, building planning, etc.), it is possible to order a draft copy of the documentation when ordering the Cabinet Modules. These documents are then supplied electronically a few working days following receipt of the order. If the order includes options that fall outside the scope of standard delivery, these will not be covered by the documentation due to the obvious time constraints.

The client is sent the documentation relating to the order by email. The recipient's email address must be specified with the order for this purpose. In the email, the recipient will also receive a link for downloading order-specific documentation. With option **D02**, the documents are also delivered in DXF format.

#### *D58, D60, D80, D91, D93, D94 Documentation as language package*

If a documentation option is not selected, the relevant documentation is supplied as standard in English/German. When one of the options specified in the table is selected, the standard documentation language will be changed from English/German to the language combination provided by the option.

Order code	Language
D58	English/French
D60	English/Spanish
D80	English/Italian
D91	English/Chinese
D93	English/Portuguese (Brazil)
D94	English/Russian

#### D00, D56, D72, D76, D77, D78, D84 Documentation in a single language

The documentation is also available in a single language, for example, to be able to order other language combinations.

If a further language is required for standard documentation in English/German, the option **D74** (documentation in English/German) must also be ordered in addition to that language.

Order code	Language
D00	German
D56	Russian
D72	Italian
D76	English
D77	French
D78	Spanish
D84	Chinese

## Options

# Options (continued)

D99

## Without operating instructions

The Cabinet Modules or Booksize Cabinet Kit are shipped without a documentation CD.

#### F03, F71, F72, F74, F75, F76, F77, F97 Converter acceptance inspections

#### Order code Description

Oldel code	Description
F03	Visual acceptance
	The inspection includes the following:
	Check of degree of protection
	<ul> <li>Check of equipment (components)</li> </ul>
	Check of equipment identifiers
	Check of clearance and creepage distances
	Check of cables
	Check of customer documentation
	<ul> <li>Submission of the acceptance report</li> </ul>
	All the above checks are performed with the equipment in a no-voltage condition.
F71 (wit-	Function test without motor
nessed by customer) F72 (not witnessed	After the visual acceptance with the converter switched off, the converter is connected to rated voltage. No current at the converter output end.
by cus-	The inspection includes the following:
tomer)	<ul> <li>Visual acceptance as described for option F03</li> </ul>
	Check of power supply
	Check of protective and monitoring devices (simulation)
	Check of fans
	Pre-charging test
	<ul> <li>Function test without connected motor</li> </ul>
	<ul> <li>Submission of the acceptance report</li> </ul>
F74 (not	Function test with test bay motor under no-load conditions
witnessed by cus- tomer) <b>F75</b> (wit- nessed by	After the visual acceptance with the converter switched off, the converter is connected to rated voltage. A small current flows at the converter output end in order to operate the test bay motor under no-load conditions.
customer)	The inspection includes the following:
	<ul> <li>Visual acceptance as described for option F03</li> </ul>
	Check of power supply
	<ul> <li>Check of protective and monitoring devices (simulation)</li> </ul>
	Check of fans
	Function test with test bay motor under no-load conditions
	<ul> <li>Submission of the acceptance report</li> </ul>
F76 (not	Insulation test of the equipment
witnessed by cus-	The inspection includes the following:
tomer)	High-voltage test
F77 (wit-	<ul> <li>Measurement of the insulation resistance</li> </ul>
nessed by customer)	<ul> <li>Submission of the acceptance report</li> </ul>
F97	Customer-specific acceptance inspections (on request)
	If acceptance inspections that are not covered by the options F03, F71/F72, F74/F75 or F76/F77 are required, then cus- tomer-specific acceptance inspections/supplementary tests can be ordered using order code F97 on request and following technical clarification.

#### Note:

The options for converter acceptance must be ordered separately for each Cabinet Module and each order position.

# G20

# CBC10 Communication Board

The CBC10 Communication Board is used to interface the CU320-2 Control Unit and thus the SINAMICS S120 Cabinet Modules to the CAN (Controller Area Network) protocol. The associated driver software fulfills the standards of the following CANopen specification of the CiA organization (CAN in Automation):

- Communication profiles in accordance with DS 301
- Drive profile in accordance with DSP 402 (in this case Profile Velocity Mode)
- EDS (Electronic Data Sheet) in accordance with DSP 306
- Operational state signaling in accordance with DSP 305

The CBC10 Communication Board plugs into the option slot on the CU320-2 Control Unit. The CAN interface on the CBC10 has 2 SUB-D connections each for input and output.

The CBC10 Communication Board can only be ordered in conjunction with a CU320-2 Control Unit (option **K90** or **K95**). A combination with options **G33** and **G62** is not possible.

Description of the CBC10 Communication Board  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### G33

**CBE20** Communication Board

The CBE20 Communication Board can be used to connect the SINAMICS S120 Cabinet Modules to a PROFINET-IO or EtherNet/IP network via a CU320-2 Control Unit. The CBE20 Communication Board plugs into the option slot on the CU320-2 Control Unit.

The CBE20 Communication Board can only be ordered as option **G33** in conjunction with a CU320-2 Control Unit (option **K90** or **K95**) and is supplied in an accessories pack for possible configuration. A combination with options **G20** and **G62** is not possible.

#### Note:

Only one communication interface can be used in isochronous operation when operating the CBE20 Communication Board in a Control Unit CU320-2.

- CU320-2 DP: Either the DP interface of the Control Unit or the PN interfaces of the CBE20
- CU320-2 PN: Either the internal PN interfaces or the external PN interfaces of the CBE20

Description of the CBE20 Communication Board  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

4

# Options

# Options (continued)

#### G51 to G54

#### TM150 temperature sensor evaluation unit

Options **G51** to **G54** can be used to order between one and four TM150 Terminal Modules for sensing and evaluating several temperature sensors.

Order code	Option
G51	1 x TM150 temperature sensor evaluation unit
G52	2 x TM150 temperature sensor evaluation units
G53	3 x TM150 temperature sensor evaluation units
G54	4 x TM150 temperature sensor evaluation units

The TM150 Terminal Module is a DRIVE-CLiQ component for temperature evaluation. The temperature is measured in a temperature range from -99 °C to +250 °C for the following temperature sensors:

- Pt100 (with monitoring for wire breakage and short-circuit)
- Pt1000 (with monitoring for wire breakage and short-circuit)
- KTY84 (with monitoring for wire breakage and short-circuits)
- PTC (with monitoring for short-circuit)
- Bimetallic NC contact (without monitoring)

For the temperature sensor inputs, the evaluation can be parameterized for 1x2-wire, 2x2-wire, 3-wire or 4-wire for each terminal block. There is no electrical isolation in the TM150.

A maximum of 12 temperature sensors can be connected to the TM150 Terminal Module.

Description of the TM150 Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### G56

## **Contactor monitoring**

The option is used for monitoring the pre-charging and bypass contactors of the Line Modules, mainly for infeeds connected in parallel.

## Note:

Option  ${\bf G56}$  cannot be selected for Active Line Modules in frame sizes FX and GX.

### G60 TM31 Terminal Module

The TM31 Terminal Module is used to expand the customer terminal.

The following additional interfaces are available:

- 8 digital inputs
- 4 bidirectional digital inputs/outputs
- · 2 relay outputs with changeover contact
- 2 analog inputs
- · 2 analog outputs
- 1 temperature sensor input (KTY84-130/PTC)
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE connection

To simplify configuration and commissioning of the drive, the optional TM31 Terminal Module can be preset with various factory settings, which can then be selected when commissioning the system.

Description of the TM31 Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### G61

Additional TM31 Terminal Module

With option **G61**, the number of digital inputs/outputs, as well as the number of analog inputs/outputs in the drive system can be expanded using a second TM31 Terminal Module (in addition to the TM31 Terminal Module that can be selected using option **G60**).

## Note:

Option G61 requires option G60.

#### G62

## **TB30 Terminal Board**

The TB30 Terminal Board provides a way of adding digital inputs/digital outputs and analog inputs/analog outputs to the Control Unit. The TB30 Terminal Board plugs into the option slot on the Control Unit.

The following are located on the TB30 Terminal Board:

- Power supply for digital inputs/digital outputs
- · 4 digital inputs
- 4 digital outputs
- 2 analog inputs
- · 2 analog outputs

The **TB30** Terminal Board can only be ordered in conjunction with a CU320-2 Control Unit (option **K90** or **K95**). A combination with options **G20** and **G33** is not possible.

Description of the TB30 Terminal Board  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

## Options

## Options (continued)

### K01 to K05 Safety license for 1 to 5 axes

The Safety Integrated Basic Functions do not require a license. However, the Safety Integrated Extended Functions require a license for each axis equipped with safety functions. It is irrelevant which safety functions are used and how many.

Option K01 includes the license for 1 axis, K02 for 2 axes, etc. up to option K05 for 5 axes.

The required licenses can be optionally ordered with the CompactFlash card.

Subsequent licensing is possible online via the WEB License Manager by generating a license key:

www.siemens.com/automation/license

#### K08

AOP30 Advanced Operator Panel installed in the cabinet door

The AOP30 Advanced Operator Panel is an optional input/output device for the Cabinet Modules. If, for the Cabinet Module or the Booksize Cabinet Kit, an autonomous closed-loop control (option **K90** or **K95**) is selected, this module can be assigned to its own operator panel with option **K08**.

The AOP30 Advanced Operator Panel is installed in the cabinet door of each Cabinet Module.

Description of the AOP30  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K46

SMC10 Sensor Module Cabinet-Mounted

The SMC10 Sensor Module Cabinet-Mounted can be used to simultaneously sense the speed and the rotor position angle. The signals received from the resolver are converted here and made available to the closed-loop controller via the DRIVE-CLiQ interface for evaluation purposes.

The following encoder signals can be evaluated:

- · 2-pole resolver
- Multi-pole resolver

The motor temperature can also be measured using KTY84-130 or PTC thermistors.

Description of the SMC10 Sensor Module Cabinet-Mounted  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

# K48

## SMC20 Sensor Module Cabinet-Mounted

The SMC20 Sensor Module Cabinet-Mounted can be used to simultaneously sense the speed and position. The signals received from the incremental encoder are converted here and made available to the closed-loop controller via the DRIVE-CLiQ interface for evaluation purposes.

The following encoder signals can be evaluated:

- Incremental encoder sin/cos 1 Vpp
- Absolute encoder EnDat 2.1
- SSI encoder with incremental signals sin/cos 1 V<sub>pp</sub>

The motor temperature can also be measured using KTY84-130 or PTC thermistors.

Description of the SMC20 Sensor Module  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

# K50

SMC30 Sensor Module Cabinet-Mounted

The SMC30 Sensor Module Cabinet-Mounted can be used to evaluate the encoders of motors without a DRIVE-CLiQ interface. External encoders can also be connected via the SMC30.

The following encoder signals can be evaluated:

- Incremental encoders TTL/HTL with and without open-circuit detection (open-circuit detection is only available with bipolar signals)
- SSI encoders with TTL/HTL incremental signals
- SSI encoders without incremental signals

The motor temperature can also be measured using KTY84-130 or PTC thermistors.

Description of the SMC30 Sensor Module  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K51

# VSM10 Voltage Sensing Module

The VSM10 Voltage Sensing Module is used to measure the voltage characteristic on the motor side, so that the following functions can be implemented:

- Operation of a permanent-magnet synchronous motor without encoder with the requirement to be able to connect to a motor that is already running (flying restart function)
- Quick flying restart of large induction motors: The voltage sensing function eliminates the delay incurred by demagnetization of the motor

Description of the VSM10 Voltage Sensing Module  $\rightarrow$  Chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K52

### Second SMC30 Sensor Module Cabinet-Mounted

With option **K50**, the cabinet unit contains an SMC30 Sensor Module Cabinet-Mounted. An additional SMC30 (option **K52**) enables reliable actual-value acquisition when Safety Integrated extended functions are used (requires a license: options **K01** to **K05**).

Detailed and comprehensive instructions and information for the Safety Integrated functions can be found in the associated Function Manual.

### Options

# Options (continued)

#### K70

## Fan power supply

With option **K70**, the line voltage supply for the 400 V 3 AC auxiliary power supply system is tapped downstream of the circuit breaker and protected by a motor starter protector.

The voltages 230 V 1 AC and 24 V DC of the auxiliary power supply system are supplied externally on the plant side.

#### K73

#### SITOP power supply 24 V DC

The 24 V DC supply for standard Booksize Cabinet Kits is tapped from the auxiliary power supply.

With option  $\mathbf{K73}$ , the 24 V DC supply is provided by a dedicated SITOP power supply unit.

#### K76

# Auxiliary voltage generation in the Line Connection Module

Cabinet Modules require an auxiliary energy supply to function properly. This current demand must be included in the configuration and supplied from an external source. If an external supply is not possible, the required auxiliary voltages can be supplied by means of an Auxiliary Power Supply Module.

Alternatively, option **K76** can be selected. This provides for generation of auxiliary voltages in the Line Connection Module. This is particularly advisable for smaller device configurations.

With option **K76**, the following auxiliary voltages are provided:

	Air-cooled Cabinet Modules	Liquid-cooled Cabinet Modules
380 480 V or 500 690 V 2 AC	Possible tap for the following Line Connection Modules:	-
	Line Connection Module with rated current up to 800 A: 35 A	
	Line Connection Module with rated current of 1000 to 1600 A: 50 A	
	Line Connection Module 6SL3700-0LE42-0AA3: 50 A	
	Line Connection Module with rated current of 2000 to 3200 A: 80 A	
230 V 1 AC	Possible tap for the Line Connection Modules: • < 800 A: approx. 4 A • > 800 A: approx. 6 A	Possible tap for Basic Line Connection Modules / Active Line Connection Modules • 4 10 A
24 V DC	Possible tap for the Line Connection Modules: • < 800 A: approx. 20 A • > 800 A: approx. 40 A	Possible tap for Basic Line Connection Modules / Active Line Connection Modules • 5 20 A

The supply for the auxiliary power supply system is connected at the auxiliary voltage module of the Line Connection Module.

#### K82

# Terminal Module for controlling the Safe Torque Off and Safe Stop 1 safety functions

The terminal module controls the Safety Integrated Basic Functions Safe Torque Off (STO) and Safe Stop 1 (SS1) (time-controlled) over a wide voltage range from 24 V to 240 V DC/AC (terminology as defined in IEC 61800-5-2).

The integrated safety functions, starting from the Safety Integrated (SI) input terminals of the components (Control Unit and Motor Module), satisfy the requirements of EN 61800-5-2, EN 60204-1, EN ISO 13849-1 Category 3 for Performance Level (PL) d and IEC 61508 SIL 2.

With option **K82**, the requirements specified in EN 61800-5-2, EN 60204-1, EN ISO 13849-1 Category 3 for Performance Level (PL) d and IEC 61508 SIL 2 are fulfilled.

The Safety Integrated functions using option **K82** are only available in conjunction with certified components and software versions.

The Safety Integrated functions of SINAMICS are generally certified by independent institutes. An up-to-date list of certified components is available on request from your local Siemens office.

#### K87 TM54F Terminal Module

The TM54F Terminal Module is a terminal expansion module with safe digital inputs and outputs to control the Safety Integrated functions.

The TM54F is directly connected to a Control Unit via DRIVE-CLiQ. Each Control Unit can be assigned to precisely one TM54F.

Note:

It is not permissible to connect Motor Modules or Line Modules to a TM54F.

The TM54F provides 4 fail-safe digital outputs and 10 fail-safe digital inputs. A fail-safe digital output consists of one 24 V DC switching output, one output switching to ground and one digital input to check the switching state. A fail-safe digital input consists of two digital inputs.

Description of the TM54F Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

## Options

## Options (continued)

#### K88 SBA Safe Brake Adapter, 230 V AC

The Safe Brake Control (SBC) is a safety function that is used in safety-relevant applications, for example, in presses or rolling mills. In the no-current state, the brake acts on the drive motor using spring force. The brake is released when current flows in it (low active).

The Safe Brake Adapter is already installed in the cabinet unit in the factory. An infeed is connected to terminal -X12 on the Safe Brake Adapter for the power supply. For control, a connection is established between the Safe Brake Adapter and the Control Interface Module in the factory using a cable harness.

On the plant side, to control the brake, a connection must be established between terminal -X14 on the Safe Brake Adapter and the brake.

Description of the SBA Safe Brake Adapter  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K90

#### CU320-2 DP Control Unit (PROFIBUS)

Option **K90** assigns a CU320-2 DP Control Unit incl. CompactFlash card to the Line Modules and Motor Modules. This unit handles the communication and open-loop/closed-loop control functions. DRIVE-CLiQ is used to establish a connection to the various modules and, where required, to additional I/O modules. A PROFIBUS interface is available as standard for higher-level communication.

The computational performance required from the CU320-2 DP Control Unit increases with the number of connected Motor Modules and system components – as well as the dynamic performance demanded.

Without performance expansion, it is generally possible to operate two Motor Modules with one Line Module.

The full computational performance of the CU320-2 DP is only available on systems with performance expansion (option **K94**).

Description of the CU320-2 Control Unit  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Control Units.

#### K94

#### Performance expansion for CU320-2 Control Unit

With option **K94**, the CU320-2 Control Unit (option **K90** or **K95**) is supplied with a CompactFlash card with performance expansion. This therefore provides the full computational performance of the CU320-2 Control Unit.

In addition to the firmware, the CompactFlash card also contains licensing codes that are required to enable firmware options, for example, the performance expansion and the Safety Integrated Extended Functions.

# K95 CU320-2 PN Control Unit (PROFINET)

Option **K95** assigns a CU320-2 PN Control Unit, incl. Compact-Flash card, to the Line Modules and Motor Modules. This unit handles the communication and open-loop/closed-loop control functions. DRIVE-CLiQ is used to establish a connection to the various modules and, where required, to additional I/O modules. A PROFINET interface is available for higher-level communication.

The computational performance required from the CU320-2 PN Control Unit increases with the number of connected Motor Modules and system components – as well as the dynamic performance demanded.

Without performance expansion, it is generally possible to operate two Motor Modules with one Line Module.

The full computational performance of the CU320-2 PN is only available on systems with performance expansion (option **K94**).

Description of the CU320-2 Control Unit  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Control Units.

#### L00

Use in the first environment according to EN 61800-3, Category C2 (TN/TT supply systems with grounded neutral point)

With option **L00**, the Line Modules have a line filter as well as additional measures installed in the factory; this means that the Cabinet Modules can also comply with the limit values for use in the first environment (Category C2) according to EN 61800-3.

Notes on the measures to be implemented by the customer are provided in the SINAMICS Low Voltage Engineering Manual.

In order to achieve the full filter effect, the optional line filter must always be used in conjunction with a line reactor.

# Note:

Option **L00** is not available for Line Modules in a parallel connection.

4

# Options

# Options (continued)

L07

#### dv/dt filter compact plus Voltage Peak Limiter

dv/dt filters compact plus VPL (**V**oltage **P**eak Limiter) limit the voltage rate-of-rise dv/dt to values of < 1600 V/ $\mu$ s and the typical voltage peaks to the following values in accordance with the limit value curve A according to IEC 60034-25: 2007:

- < 1150 V at U<sub>line</sub> < 575 V</li>
- < 1400 V at 660 V <  $U_{\text{line}}$  < 690 V

The dv/dt filter compact plus VPL functionally consists of two components that are supplied as a compact mechanical unit, the dv/dt reactor and the voltage limiting network (VPL), which limits voltage peaks and feeds back the energy to the DC link.

It is so compact that it can be completely integrated into the cabinet, even for high power ratings. An additional cabinet is not required.

By using a dv/dt filter compact plus VPL, standard motors with standard insulation and without insulated bearings can be used with supply voltages up to 690 V in converter operation.

The power losses stated in section System components  $\rightarrow$ Motor-side components  $\rightarrow$  dv/dt filters compact plus VPL can be used to determine the total losses for engineering purposes. dv/dt filters compact plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables 100 m (e.g. Protodur NYCWY)
- Unshielded cables 150 m (e.g. Protodur NYY)

For longer cable lengths (> 100 m shielded, >150 m unshielded), the dv/dt filter plus VPL (option  $\mbox{L10})$  should be used.

## Notice:

- Operation with output frequencies <10 Hz is permissible for max. 5 min.
- The maximum permissible output frequency is 150 Hz.

When using dv/dt filters, restrictions regarding permissible pulse frequencies must be observed.

# Please also note the relevant information provided in the SINAMICS Low Voltage Engineering Manual.

# Note:

Option L07 cannot be combined with the following options:

- L08 (motor reactor)
- L10 (dv/dt filter plus VPL)

#### L08 Motor reactor

Motor reactors reduce the voltage load on the motor windings by reducing the voltage gradients at the motor terminals that occur during converter operation. At the same time, the capacitive charge/discharge currents that place an additional load at the Motor Module output when long motor cables are used are reduced.

Suitably dimensioned motor reactors or a series connection of several motor reactors make it possible to connect larger capacitances and thus allow the use of longer motor cables.

In the case of multi-motor drives, the use of motor reactors is recommended as a general principle.

The motor reactor is accommodated in the Cabinet Module. An additional 600-mm-wide cabinet located to the right of the Motor Module is only required for the chassis format in frame sizes HX and JX.

The power losses stated in the section System components  $\rightarrow$  Motor-side components  $\rightarrow$  Motor reactors can be used to determine the total losses for engineering purposes.

# Note:

The terminal lugs of the reactors are not nickel-plated.

For Motor Modules in chassis format, the maximum cable lengths when using motor reactors are 300 m (shielded) or 450 m (unshielded).

For Motor Modules in Booksize Cabinet Kit format, the maximum motor cables lengths specified in the following table can be reached by using motor reactors (option **L08**).

Booksize Cabinet Kit	Rated output current of Motor Module	Maximum motor cable length when using motor reactors for Booksize Cabinet Kits					
		Shielded cable			Unshielded cable		
		Without reactor	With one reactor (option <b>L08</b> )	With two reactors in series (option <b>L09</b> )	Without reactor	With one reactor (option <b>L08</b> )	With two reactors in series (option <b>L09</b> )
6SL3720	А	m	m	m	m	m	m
1TE21-0AB3	9	50	135	-	75	200	-
1TE21-8AB3	18	70	160	320	100	240	480
1TE23-0AB3	30	100	190	375	150	280	560
1TE24-5AB3	45	100	200	400	150	300	600
1TE26-0AB3	60	100	200	400	150	300	600
1TE28-5AB3	85	100	200	400	150	300	600
1TE31-3AB3	132	100	200	400	150	300	600

## Options (continued)

#### L09

#### Two motor reactors in series

With option **L09** for Booksize Cabinet Kits, two motor reactors are used in series that can be located within the standard width of the Cabinet Kit.

The maximum permissible motor cable lengths when using option L09 are specified in the table under option **L08**.

#### Note:

The terminal lugs of the reactors are not nickel-plated.

#### L10

## dv/dt filter plus Voltage Peak Limiter

A dv/dt filter plus VPL (**V**oltage **P**eak Limiter) limits the voltage rate-of-rise dv/dt to values <  $500 V/\mu s$  and the typical voltage peaks to the following values in accordance with the limit value curve according to IEC/TS 60034-17: 2006:

- < 1000 V at U<sub>line</sub> < 575 V</li>
- < 1250 V at 660 V < U<sub>line</sub> < 690 V</li>

The dv/dt filter plus VPL functionally consists of two components, the dv/dt reactor and the voltage limiting network (VPL), which limits voltage peaks and feeds the energy back to the DC link.

Option **L10** is installed in an additional cabinet with a width of 600 mm that is located on the right-hand side of the Motor Module.

By using a dv/dt filter plus VPL, standard motors with standard insulation and without insulated bearings can be used with supply voltages up to 690 V in converter operation.

dv/dt filters plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables (e.g. Protodur NYCWY)
  - Motor Modules, frame sizes FX to HX: 300 m
  - Motor Modules, frame size JX: 150 m
- Unshielded cables (e.g. Protodur NYY)
- Motor Modules, frame sizes FX to HX: 450 m
- Motor Modules, frame size JX: 225 m

For cable lengths < 100 m shielded or < 150 m unshielded, the dv/dt filter compact plus VPL (option **L07**) can be used advantageously.

The power losses stated in the section System components  $\rightarrow$  Motor-side components  $\rightarrow$  dv/dt filters plus VPL can be used to determine the total losses for engineering purposes.

#### Notice:

- Operation with output frequencies <10 Hz is permissible for max. 5 min.
- The maximum permissible output frequency is 150 Hz.

When using dv/dt filters, restrictions regarding permissible pulse frequencies must be observed.

Please also note the relevant information provided in the SINAMICS Low Voltage Engineering Manual.

# Note:

Parts of option **L10** do not have nickel-plated copper busbars. Option **L10** cannot be combined with the following options:

- **L07** (dv/dt filter compact plus VPL)
- L08 (motor reactor)

# L13 Main contactor (for supply currents ≤ 800 A)

Line Connection Modules for current ratings up to 800 A feature only a manually operated fuse switch disconnector as standard. Option **L13** is needed if a switching element is also required for disconnecting the cabinet from the supply (needed for EMERGENCY OFF). The contactor is controlled by the closedloop control in this case. Option **L13** can be ordered for Line Connection Modules together with Basic Line Modules (option **L43**). With Smart Line Modules and Active Line Modules, the main contactor is included as standard.

#### L21 Surge suppression

In ungrounded IT systems, the line voltage is not permanently connected to the ground potential because of the missing ground connection of the supply network. Therefore, when a ground fault occurs during operation, a voltage against ground increased by a factor of 2 can occur. For this reason, it is recommended that a surge suppression against ground be installed for operation on IT systems. The surge suppression option includes the installation of line-side surge arresters and upstream fuses for each system phase. The signaling contacts for monitoring the surge arresters are connected in series and connected to a customer interface.

### Note:

Option **L21** does not include the components required to install an insulation monitor for the IT system. An insulation monitor should always be ordered separately as option **L87** when the supplying IT system is not monitored at another position (e.g. at the transformer outgoing feeder). Only one insulation monitor should ever be used within the same electrically connected network.

Option **L21** also does not include removal in the factory of the metal bracket that makes the connection to ground of the radio interference suppression filter installed as standard. The metal bracket should therefore be removed during the installation or commissioning of the converter if the device is to be operated on an ungrounded IT system.

# L22

## Delivery scope without line reactor

The air-cooled Basic Line Modules and Smart Line Modules as well as the liquid-cooled Basic Line Connection Modules are supplied with line reactors as standard; the reason for this is that frequently, in practice, the line configuration at the connection point of the drive line-up and/or the line supply short-circuit power is not known.

If the supply is connected through a separate transformer or if the line has a suitably low short-circuit power or if the standard integrated line reactor does not need to be supplied for other reasons, then this can be indicated by selecting option **L22**.

In the case of air-cooled Cabinet Modules, option **L22** can be selected for Line Connection Modules (rated current < 2000 A) in conjunction with Basic Line Modules (option **L43**) and for Smart Line Modules. In the case of liquid-cooled Cabinet Modules, option **L22** can be selected for Basic Line Connection Modules.

For Basic Line Modules and Basic Line Connection Modules connected in parallel, a line reactor should always be used, i.e. option **L22** cannot be selected.

The power losses of each line reactor stated in section System components  $\rightarrow$  Line-side components  $\rightarrow$  Line reactors can be deducted from the total power loss for engineering purposes.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

# Options

# Options (continued)

L25

#### Withdrawable circuit breaker

Line Connection Modules (air-cooled), Active Line Connection Modules and Basic Line Connection Modules (liquid-cooled) with an input current of > 800 A are equipped with fixedmounted circuit breakers as standard. Where the customer requires a visible isolating distance, a withdrawable circuit breaker can be ordered as an option.

#### L34

#### Output-side circuit breaker

Option **L34** can be used to disconnect the motor terminals from the Motor Module Chassis.

A rotating permanent-magnet synchronous motor generates a voltage at its motor terminals proportional to the speed. The motor terminal voltage is also available at the converter output terminals as well as at the DC link and the components connected to it.

Option **L34** is available for disconnection in the case of a fault or if maintenance work is to be carried out.

Option **L34** is completely prewired and is accommodated in an additional cabinet, which is arranged on the right-hand side of the Motor Module (400 mm wide for frame sizes FX/GX, 600 mm wide for frame sizes HX/JX). It is controlled using a TM31 Terminal Module, which is included with this option. This means that the output switch is automatically controlled via the Motor Module.

Option L34 cannot be combined with the following options:

- L07 (dv/dt filter compact plus VPL)
- **L10** (dv/dt filter plus VPL)

#### L37

# DC interface incl. pre-charging circuit of the relevant DC link capacitance

If, for reasons relating to the process or availability,

the Motor Module needs to be disconnected from the common DC link for an entire drive line-up or connected to it during operation, a manually operated isolating distance can be ordered as an option. With chassis format power units, this takes the form of switch disconnectors, and with Booksize Cabinet Kits, a contactor combination.

Option **L37** is installed on the busbar between the Motor Module and the main DC busbar. To ensure that the module can be connected to a pre-charged DC link, the option also includes a precharging circuit for the DC link capacitors of the relevant Motor Module.

The switching operation is performed externally. The operating levers can be locked using a padlock (padlock not included in scope of delivery). The degree of protection of the cabinets is not influenced.

The air guidance contains option **L37** and also option **M60** (additional touch protection).

Options L61/L62 and L64/L65 (braking units) cannot be ordered together with option L37 for space reasons.

## L40 Line filter monitoring

With option **L40**, the filter in the Active Interface Module is monitored for effectiveness against harmonic effects on the system. The capacitance of the filter capacitors of the integrated filter is continuously calculated and compared with the installed nominal capacitance by measuring the current and voltage in the Active Interface Module. If the calculated capacity deviates by more than the set tolerance, an alarm is triggered.

# L41

#### Current transformer upstream of main circuit breaker

If additional current transformers are required for measuring or monitoring purposes, these can be ordered for (air-cooled) Line Connection Modules or (liquid-cooled) Active Line Connection Modules and Basic Line Connection Modules with option L41. The current transformers are installed upstream of the main circuit breaker in all three infeed phases.

The transformers have an accuracy class of 1.0. The secondary current is maximum 1 A.

The transformer measuring connections are routed to the terminal block in the Line Connection Module.

#### Note:

These current transformers are already included in options **P10** and **P11** (measuring instrument for the display of line values).

#### L42 Line Connection Module for Active Line Modules

Order code **L42** is specified in the order to indicate that the Line Connection Module will be connected to an Active Line Module. The Line Connection Module is then adapted accordingly (pre-charging circuit, connection busbars, etc.). See also the information for the Line Connection Modules and the overview of options.

#### L43

#### Line Connection Module for Basic Line Modules

Order code **L43** is specified in the order to indicate that the Line Connection Module will be connected to a Basic Line Module. The Line Connection Module is then adapted accordingly (line reactors, pre-charging circuit, connection busbars, etc.). See also the information for the Line Connection Modules and the overview of options.

#### L44

#### Line Connection Module for Smart Line Modules

Order code **L44** is specified in the order to indicate that the Line Connection Module will be connected to a Smart Line Module. The Line Connection Module is then adapted accordingly (pre-charging circuit, connection busbars, etc.). See also the assignment table for the Line Connection Modules and the overview of options.

#### L45

## EMERGENCY OFF pushbutton, installed in the cabinet door

The EMERGENCY OFF pushbutton with protective collar is installed in the cabinet door of the Line Connection Module and its contacts are connected to a terminal block. From here, the EMERGENCY OFF pushbutton can be integrated into the plant-side EMERGENCY OFF chain.

## Options

# Options (continued)

L46

#### Grounding switch upstream of main circuit breaker

The grounding switch is upstream of the circuit breaker in the Line Connection Module and short-circuits the incoming supply system to ground. The grounding switch is manually engaged using a rotary operating mechanism to ensure isolation from the line supply when maintenance is being carried out. Measures must be taken at the plant to ensure that the grounding switch cannot be engaged when voltage is applied.

It is also essential to ensure that the supply system cannot be connected when the grounding switch is engaged.

The signals required for mutual interlocking are available on the terminal block.

## L47

#### Grounding switch downstream of main circuit breaker

The grounding switch is installed downstream of the circuit breaker in the Line Connection Module and short-circuits the incoming supply system to ground downstream of the main circuit breaker. The grounding switch is manually engaged using a rotary operating mechanism to ensure isolation from the line supply when maintenance work is being carried out on the converter.

In this case, the grounding switch and the main circuit breaker for the Line Connection Module are interlocked with each other, which ensures that the grounding switch cannot be closed when the main circuit breaker is closed.

If the grounding switch is engaged, it is interconnected to ensure that the main circuit breaker cannot be closed.

#### L50

#### Cabinet lighting with service socket

With option **L50**, cabinet lighting is included with an additional service socket for a SCHUKO connector (connector type F) according to CEE 7/4. The power supply for the cabinet lighting and the service socket is external and must be fuse-protected for max. 10 A.

The cabinet lighting consists of an LED hand lamp with On/Off switch and with magnetic fasteners an approx. 3 m long connecting cable. The lamp is factory-positioned in the cabinet door at a defined marking, and the connecting cable is wound on the associated mount.

#### L55

## Cabinet anti-condensation heating

The anti-condensation heating is recommended at low ambient temperatures and high levels of humidity to prevent condensation. Depending on the cabinet width, a 100 W cabinet heater is installed for each Cabinet Module.

1 heating element for cabinet width up to 600 mm, 2 heating elements for cabinet width over 800 mm.

The power supply for the anti-condensation heating (110 V to 230 V AC, at terminal block -X240) must be provided externally and fused with max. 16 A.

#### L61, L62, L64, L65 Braking units

Braking units may be required for drives in which motors might operate in generator mode, but have no facility for feeding energy back into the supply system.

The braking unit comprises two components:

- A Braking Module that can be installed in the air discharge of the chassis format power units
- A braking resistor to be mounted externally (degree of protection IP20)

The braking unit functions as an autonomous unit and does not require an external power supply. During the braking process, the kinetic energy is converted into heat in the externally mounted braking resistor.

A max. cable length of 100 m is permissible between the Braking Module and the braking resistor. This allows the braking resistor to be mounted externally so that heat losses can be dissipated outside the converter enclosure. The braking resistor is directly connected to the Braking Module.

For SINAMICS S120 Cabinet Modules the following braking modules are available, depending on the frame size:

Option	Can be used with frame sizes	Braking Module				
		Rated power P <sub>DB</sub>	Braking power P <sub>20</sub>	Peak power P <sub>15</sub>		
		kW	kW	kW		
380 480 V	380 480 V 3 AC, 660 690 V 3 AC					
L61	FX	25	100	125		
L62	GX, HX, JX	50	200	250		
500 600 V 3 AC						
L64	FX	25	100	125		
L65	GX, HX, JX	50	200	250		

PDB: Rated power (continuous braking power)

 $P_{20}$ : 20 s power referred to a braking interval of 90 s

 $P_{15}$ : 15 s power referred to a braking interval of 90 s

If the braking units listed here do not provide adequate braking power, up to four braking units on a DC link busbar may be connected in parallel. Braking power can be shared among several Modules. In this case, a Braking Module is assigned to each braking resistor.

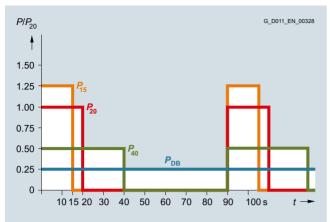
#### Note:

It is only possible to use a Braking Module if a DC interface (option **L37**) has not been selected for the Motor Module.

When engineering the system, it should be ensured that the module in which the Braking Module is installed is switched on during braking so that the Braking Module is properly cooled. Failure to follow this instruction means that the Braking Module could overheat and shut down, and the drive will no longer be able to operate in braking mode. In this case, the Braking Modules should preferably be located in the Line Modules.

#### Options

# Options (continued)



P<sub>DB</sub> = Rated power

 $\begin{array}{l} P_{15} = 5 \times P_{DB} = \text{Power which is permissible every 90 s for 15 s} \\ P_{20} = 4 \times P_{DB} = \text{Power which is permissible every 90 s for 20 s} \\ P_{40} = 2 \times P_{DB} = \text{Power which is permissible every 90 s for 40 s} \end{array}$ 

Load diagram for Braking Modules and braking resistors

Additional notes about possible duty cycles of the braking resistors and other engineering notes are included in the SINAMICS Low Voltage Engineering Manual.

## Insulation monitoring

An insulation monitor must be used if the converter is connected to an ungrounded line supply. The device monitors the entire galvanically coupled circuit for insulation faults.

An alarm is output in the event of a fault.

#### Notice:

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Only **one** insulation monitor can be used in each galvanically coupled network.

As there are different response strategies when a ground fault occurs in an ungrounded system, output relays of the insulation monitor are provided for integration in a plant-side control. It is also possible to integrate the outputs into the Cabinet Modules monitoring system on the plant side.

# M06

### Base 100 mm high, RAL 7022

The additional cabinet base allows larger bending radii for cables (cable inlet from below) and enables them to be routed within the cabinet base.

The cabinet base is supplied in RAL 7022 as standard. A special paint finish is not available for the base. It is delivered completely assembled with the cabinet. The height of the operator panel changes accordingly.

# *M07*

#### Cable marshaling compartment 200 mm high, RAL 7035

The cable marshaling compartment is made of strong sheet steel and allows cables to be connected more flexibly (entry from below). It also allows routing of cables within the cable marshaling compartment. It is delivered completely assembled with the cabinet. The height of the operator panel changes accordingly.

## Notice:

The cable marshaling compartment is painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the cable marshaling compartment is also painted in this color.

# M21

#### Degree of protection IP21 (for air cooling only)

Cabinet version in IP20, but with additional top covers or canopies. This increases the cabinet height by 250 mm. For transport reasons, the top covers or canopies are delivered separately and must be fitted on site.

#### Notice:

The top covers or canopies are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the top covers or canopies are also painted in this color.

Degree of protection IP21 is the standard version for liquidcooled Cabinet Modules.

#### M23

### **Degree of protection IP23**

Cabinet Modules with degree of protection IP23 are supplied with additional plastic ventilation grilles and a filter medium in the air inlet and outlet. The filter medium must be maintained according to the local environmental conditions. The covers provided with option **M60** are also included in the scope of supply.

The air-cooled Cabinet Modules are additionally supplied with a roof section. This increases the cabinet height by 400 mm. For transport reasons, the roof sections are delivered separately and must be fitted on site.

# Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

## M26

#### Side panel mounted to the right

For side-by-side installation of Cabinet Modules from left to right, cabinets can be ordered ready-prepared at the factory for assembly on-site. If option **M26** is ordered, the Cabinet Module is shipped with a side panel fitted on the right.

This side panel is essential for ensuring compliance with IP20 and higher degrees of protection.

# Options (continued)

#### M27 Side panel mounted to the left

For side-by-side installation of Cabinet Modules from right to left, cabinets can be ordered ready-prepared at the factory for assembly on-site. If option **M27** is ordered, the Cabinet Module is shipped with a side panel fitted on the left.

This side panel is essential for ensuring compliance with IP20 and higher degrees of protection.

## M43

## **Degree of protection IP43**

Cabinet Modules with degree of protection IP43 are supplied with additional plastic ventilation grilles and a filter medium in the air inlet and outlet. The filter medium must be maintained according to the local environmental conditions. The covers provided with option **M60** are also included in the scope of supply.

The air-cooled Cabinet Modules are additionally supplied with a roof section. This increases the cabinet height by 400 mm. For transport reasons, the roof sections are delivered separately and must be fitted on site.

#### Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option Y09), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

## M51

#### Motor connection wired to customer terminal

Option **M51** can only be selected in combination with option **M77** (version without component support plates or additional control components).

With option **M51**, the connection of the motor cable is wired to a customer terminal -X1 and thus makes the process of connecting motor cables easier.

Without option **M51**, the motor cable is connected directly to the Motor Module. In systems with one motor reactor or two series-connected motor reactors (option **L08/L09**), the motor cables are connected directly to the motor reactor.

#### M54

#### Degree of protection IP54 (for air cooling only)

Cabinet Modules with degree of protection IP54 are supplied with additional roof sections, plastic ventilation grilles, and a filter medium in the air inlet and outlet, which ensures compliance with degree of protection IP54. This increases the cabinet height by 400 mm. For transport reasons, the roof sections are delivered separately and must be fitted on site.

The filters must be maintained according to the local environmental conditions.

## Notice:

- The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.
- For units with degree of protection IP54, it is important to observe the derating factor for output currents in relation to ambient temperature and installation altitude.

### M55

## Degree of protection IP55 (for liquid cooling only)

Cabinet Modules with degree of protection IP55 are supplied with closed doors and roof sheets (without additional roof section). Water jets from any angle are permitted. Because the cabinets are completely enclosed and there is no exchange of air with the environment, it is not necessary to clean a filter medium.

The derating data are provided in the derating characteristics for the liquid-cooled Cabinet Modules.

Almost all heat losses are dissipated into the cooling liquid.

# M56

# Reinforced mechanical design

This option includes a strengthened mechanical version of the cabinet and mechanical locking of the cabinet doors. To secure the converter to the floor, a welding frame (5 mm high) is supplied separately. This option is available for all degrees of protection.

# Note:

Option **M56** cannot be combined with option **M70** (EMC shielding busbar).

#### M59

# Closed cabinet doors, air inlet from below through floor opening

If the Cabinet Modules are erected on a false floor or duct which forms part of a forced ventilation system, the modules can be ordered with closed cabinet doors. To ensure an adequate air inlet cross-section, the units are shipped without the standard base plates. In this case, the customer must ensure that no dirt/ dust or moisture can enter the Cabinet Module. Cables must not be routed in such a way that they impede the flow of air through the cabinet floor opening. If the area beneath the Cabinet Modules can be accessed, the customer must provide touch protection.

#### *M60*

#### Additional touch protection

The Cabinet Modules are designed in accordance with DGUV regulation 3 as standard. With option **M60**, additional covers (out of reach) at accessible operator control and switching elements are provided in the area of the AC and DC busbars and in front of the power unit.

Option **M60** is already included in **M23**, **M43**, and **M54** for the following Cabinet Modules.

- Line Connection Modules
- Basic Line Modules
- Smart Line Modules
- Active Line Modules with Active Interface Modules
- Motor Modules chassis
- Central Braking Modules
- Auxiliary Supply Modules

Liquid-cooled Cabinet Modules incorporate additional touch protection as a standard feature - it does not have to be ordered with option **M60**.

#### M70 EMC shield bus

The EMC shield bus is used to connect shielded line and motor supply cables. The shields can be applied over a large surface area with the supplied EMC shield clips.

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# Options

# Options (continued)

#### M72

Quick-release couplings for water hoses (for liquid cooling only)

With option **M72**, the ports for connecting the water hoses to the power modules and heat exchangers are fitted with quick-release couplings. The quick-release couplings ensure that no liquid escapes during uncoupling.

The use of quick-release couplings makes disassembly of the power units and heat exchangers considerably easier.

#### M77

# Version without component support plates and without additional control components

If electronic components (Control Unit, Terminal Modules, Sensor Modules) are not used in the Booksize Cabinet Kit, the mechanical component support plates are omitted with option **M77**, including the customer terminal blocks for connecting motor cables.

The motor cables are then connected directly to the Motor Module in booksize format.

When option **L08/L09** is used (motor reactor / 2 motor reactors in series), the motor cables are connected directly to the motor reactor.

The table below provides an overview of possible motor cable connection cross-sections for motor cables connected directly to a Motor Module in booksize format:

Booksize Cabinet Kit	Rated output current of Motor Module	Conductor cross-section
6SL3720	А	mm <sup>2</sup>
1TE21-0AB3	9	1.5 6
1TE21-8AB3	18	1.5 6
1TE23-0AB3	30	1.5 6
1TE24-5AB3	45	6 50
1TE26-0AB3	60	6 50
1TE28-5AB3	85	16 120
1TE31-3AB3	132	25 120

#### Note:

When combined with option **M51**, the motor connection is wired to a customer terminal.

#### *M80 to M87 DC busbar system*

The correct DC busbar for the Cabinet Module must be ordered. This is fitted in the upper section of the Cabinet Modules and connects the Line Modules to the Motor Modules.

The busbar is dimensioned according to the load requirements and demand factor associated with operation of the individual drives, and according to the specific Cabinet Module layout. For this reason, the DC busbar is not supplied as standard, but must be ordered as an option.

When selecting busbars, it is important to ensure that the systems of adjacent Cabinet Modules are compatible with one another (refer to the table below and option selection matrix for the Cabinet Modules in question).

Where Cabinet Modules are ordered as a factory-assembled transport unit with option **Y11**, all busbars in the transport unit must be identical.

Order code	DC busbar system, rated current <i>I</i> <sub>rated</sub> A	Number	Dimensions mm	Compatible with
M80	1170	1	60 × 10	M83
M81	1500	1	80 × 10	<b>M84</b> and <b>M86</b>
M82	1840	1	100 × 10	<b>M85</b> and <b>M87</b>
M83	2150	2	60 × 10	M80
M84	2730	2	80 × 10	M81 and M86
M85	3320	2	100 × 10	<b>M82</b> and <b>M87</b>
M86	3720	3	80 × 10	M81 and M84
M87	4480	3	100 × 10	M82 and M85

The DC busbars are nickel-plated as standard and are available in different designs for a variety of current-carrying capacities. The scope of delivery also includes the jumpers required to link the busbar systems of individual Cabinet Modules.

#### M88

# DC busbar system for line-side Cabinet Modules (for liquid cooling only)

Option **M88** is required if Motor Modules are to be installed to the left or if up to four Basic Line Connection Modules or Active Line Connection Modules are to be connected for a parallel connection.

For this purpose, DC busbars are built into the upper part on the left hand side in the line-side Cabinet Module of each Active Line Connection Module and Basic Line Connection Module.

The busbars are nickel-plated as standard and are selected for different current carrying capacities as for the selected options **M80 to M87**.

## M90

#### Crane transport assembly (top-mounted)

A top-mounted crane transport assembly can be ordered as an option for Cabinet Modules.

Depending on the width of the module, it consists of either transport eyebolts (width  $\leq$  800 mm) or transport rails (width > 800 mm).

When Cabinet Modules are ordered as factory-assembled transport units (option **Y11**), they are shipped with transport rails, i.e. option **M90** is automatically included in the scope of delivery of option **Y11** and does not need to be ordered separately.

4

# Options (continued)

M91

Marking of all control cable conductor ends (incl. customer-specific wiring)

When this option is selected, all control cables or conductor ends (including all customer-specific options) are labeled throughout the cabinet.

#### N52 DC link fuses

The Basic Line Modules (air-cooled), Active Line Connection Modules and Basic Line Connection Modules (liquid-cooled) come without DC link fuses as standard.

If fuses are required, they can be ordered with option **N52**. The fuses are mounted on the connecting rail to the DC busbar in the cabinet rather than in the power unit.

The use of DC link fuses is recommended when Basic Line Modules, Active Line Connection Modules, and Basic Line Connection Modules are connected in parallel.

The Motor Modules contain DC link fuses as standard.

#### P10

# Measuring instrument for line values, mounted in the cabinet door

A measuring instrument with display, installed in the cabinet door of the Line Connection Module, for acquiring measured values of the power supply. In addition to these measured values, additional plant values (such as power and power factor, etc.) are calculated from the measured values using powerful, stateof-the art microprocessors.

Current transformers (option **L41**) are already included in the scope of delivery.

#### P11

## Measuring instrument for line values with PROFIBUS connection, mounted in the cabinet door

A measuring instrument with display, installed in the cabinet door of the Line Connection Module, for acquiring measured values of the power supply. In addition to these measured values, additional plant values (such as power and power factor, etc.) are calculated from the measured values using powerful, stateof-the art microprocessors. The measuring instrument has a PROFIBUS interface that permits a data transfer rate of up to 12 Mbps.

Current transformers (option L41) are already included in the scope of delivery.

## T58, T60, T80, T83, T85, T91 Rating plate data

The rating plate is provided in English/German as standard. A rating plate in another language combination can be selected by specifying the following option order codes.

Option	Rating plate language	
T58	English/French	
T60	English/Spanish	
Т80	English/Italian	
T83	English/Portuguese (Brazil)	
T85	English/Russian	
T91	English/Chinese	

## W01

#### Heat Exchanger Module, partially redundant with 2 pumps

The Heat Exchanger Module is equipped with a pump and a plate-type heat exchanger as standard. With option **W01**, two redundant pumps with two dirt traps and non-return valves are fitted. The pumps, which operate alternately, pump the hot coolant of the deionized water circuit on the converter side into the plate-type heat exchanger and there it is cooled by the raw water of the plant-side circuit.

System reliability is increased as a result of the alternating operation of the redundant pumps. The time in hours can be parameterized. In addition, the dirt traps can be cleaned independently and during operation, as shutoff valves are installed before and after the individual pumps.

#### Note:

Option **W01** increases the cabinet width by 400 mm and its weight by 110 kg.

## W10

## Pipe insulation in the raw water circuit

With this option, the pipes in the raw water circuit are insulated. This means that if the raw water on the plant side is too cold, condensation does not occur on the pipes and liquid does not collect in the Heat Exchanger Module.

### W20 Raw water connection from the bottom

The raw water from the supply is fed into the Heat Exchanger Module from above as standard. With option **W20**, the plant-side raw water connection in the Heat Exchanger Module is at the bottom.

The piping system is made of W 1.4404 (V4A, AISI 316) stainless steel.

#### W34

## Heat Exchanger Module for installation on the left

With this option, a fixed pipe connection is routed downward on the right-hand side. This option is required to install the Heat Exchanger Module at the left-hand end of the drive line-up and to connect it to the deionized water circuit on the converter side. The connecting parts are enclosed.

#### W36

# Heat Exchanger Module for installation on the right

With this option, a fixed pipe connection is routed downward on the left-hand side. This option is required to install the Heat Exchanger Module at the right-hand end of the drive line-up and to connect it to the deionized water circuit on the converter side. The connecting parts are enclosed.

## W43

## Release valve in the deionized water circuit

A release valve is installed between the intake and return in the converter-side deionized water circuit. The valve limits the discharge pressure of the circulating pumps. As soon as the discharge pressure exceeds the value set at the valve, the valve opens the bypass.

#### W49

# Leakage sensor in the Heat Exchanger Module, at the bottom in the cabinet floor

With this option, a leakage sensor is installed in the cabinet floor of the Heat Exchanger Module. The installed evaluation module is connected to a digital input of the TM31 Terminal Module. When a leak is detected, a corresponding alarm or fault (can be parameterized) is output.

# Options

## Options (continued)

#### W62

#### Sensors in the raw water circuit on the plant/system side

With this option, a flow monitor and a Pt1000 temperature sensor are installed in the intake of the plant-side raw water circuit. The signals are transferred to the TM31 or TM150 Terminal Module. This means that the flow and temperature can be monitored. The temperature alarm limit can be parameterized in the Control Unit. The flow signal is parameterized at the sensor, and is evaluated by the TM31 Terminal Module.

## Y09

## Special cabinet paint finish

The Cabinet Modules are delivered in RAL 7035 as standard. The special paint finish must be specified in plain text when ordering. Any RAL colors that are available as powdered coatings can be selected.

## Notice:

If options such as cable marshaling compartment (option **M07**), top covers or canopies (option **M21**) or roof sections (options **M23/M43/M54**) are ordered for the Cabinet Modules, they will also be supplied in the paint finish specified for the cabinet in the order. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

## Y11

#### Factory assembly into transport units

With this option, Cabinet Modules can be ordered as factoryassembled transport units with a maximum total width of up to 2400 mm. In this case, the relevant modules are shipped as interconnected units (both electrically and mechanically).

When DC busbars (options **M80** to **M87**) are selected, it must be ensured that identical busbars are installed within the transport unit and are compatible with all adjacent Cabinet Modules.

In the case of a transport unit order, all the Cabinet Modules to be included in the unit and their installation sequence from left to right must be specified in plain text according to the syntax below:

Plain text required to order	TE	1	-	1 6
• Transport unit (TU)				
Serial number of transport unit				
• Position of Cabinet Module within transport unit for	rom le	eft to r	ight	

In the case of air-cooled Cabinet Modules, option **Y11** is recommended when creating units comprising Line Connection Modules with Line Modules because the required pre-charging circuits and connection busbars, for example, can be incorporated for certain versions. Please refer to the assignment tables for the Line Connection Modules.

With liquid-cooled Cabinet Modules, option **Y11** is especially recommended to reduce the number of connection elements used in the cooling circuit on the converter side. It results in lower resistance to flow and avoids leaks. Option **Y11** is not admissible in combination with Heat Exchanger Modules.

The transport unit is shipped with a crane transport rail, which means that option  $\mathbf{M90}$  is not required.

#### Y31 One line lab

#### One-line label for system identification, 40 × 80 mm

Resopal labeling plates (white with black lettering) for identifying Cabinet Modules are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  80 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm



#### Y32

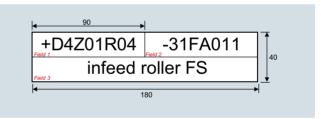
Two-line label for system identification, 40 × 180 mm

Resopal labeling plates (white with black lettering) for identifying Cabinet Modules are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  180 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm Field 2: Max. 9 characters, font size 10 mm Field 3: Max. 20 characters, font size 10 mm



#### Y33

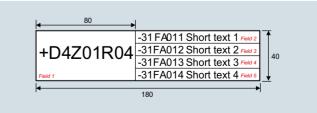
## Four-line label for system identification, 40 × 180 mm

Resopal labeling plates (white with black lettering) for identifying Cabinet Modules are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  180 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm Field 2: Max. 20 characters, font size 6 mm Field 3: Max. 20 characters, font size 6 mm Field 4: Max. 20 characters, font size 6 mm Field 5: Max. 20 characters, font size 6 mm



Supplementary system components

Mounting device for air-cooled power blocks



Power block mounting device for installing and removing the power blocks for the Basic Line Modules, Smart Line Modules, Active Line Modules and Motor Modules in chassis format.

The mounting device is a mounting aid. It is placed in front of the module and attached to the module. The telescopic rails allow the device to be adjusted to the installation height of the power blocks.

Once the mechanical and electrical connections have been released, the power block can be removed from the module.

The power block is guided and supported by the guide rails on the handling device.

# Selection and ordering data

[	Description

Mounting device For installing and removing power blocks Article No.
6SL3766-1FA00-0AA0

# Mounting device for liquid-cooled power units

Overview

Overview



The mounting device is used to install or remove liquid-cooled power units (Line Modules, Motor Modules) in or out of a control cabinet. The mounting device can be used if the power units are mounted on mounting rails, which at the front have two M6 threads at a vertical distance of 20 mm to attach the mounting device. The mounting device is a mounting aid. It is placed in front of the power unit and attached to the mounting rails below the power unit. The telescopic rails allow the mounting device to be adjusted to the installation height and width of the power unit. The power unit can be removed from the control cabinet after releasing the mechanical and electrical connections and the coolant connections. The power unit is guided and supported by the guide rails on the mounting device. To prevent it toppling over, the power unit must be secured to a crane, tripod, or similar assembly using the lifting lugs or the lifting equipment. The unit can then be lowered down from the mounting device.

Selection and	ordering data
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Description	Article No.
Mounting device For installing and removing power units	6SL3766-1CA00-0AA0

#### Order-specific integration engineering

## Overview

Just like the SINAMICS S120 chassis units, SINAMICS S120 Cabinet Modules form a modular drive system that consists of various intelligent Drive Objects such as Line Modules, Motor Modules, Control Units, Sensor Modules, etc.

As a consequence, SINAMICS S120 Cabinet Modules are supplied with documentation that only includes and describes the individual Cabinet Modules (circuit diagram, layout diagram, terminal diagram and additional Operating Instructions).

By selecting option **Y11**, individual Cabinet Modules are assembled at the factory as interconnected units for transport and are then supplied as such.

Detailed documentation showing features such as the signal connections between the individual Cabinet Modules that make up the order, is not included in the normal scope of delivery.

In this case, only a collection of the individual documents are shipped with the converter.

If the documentation is to include a complete representation of the equipment supplied, the equipment and documentation must be additionally processed. This can be ordered with the integration engineering.

Integration engineering includes the following:

- Checking the combinations and options ordered, in relation to the device configurations
- Defining how the individual drive objects are to be connected and coordinated, with the customer if required
- Checking the performance of the ordered CompactFlash card
- Installing the required DRIVE-CLiQ cables within the transport units.

Cables between the transport units are connected at one end

- Higher-level documentation of the scope of delivery (layout diagram, circuit diagram, terminal diagram, dimension drawing, spare parts list)
- Summary of the individual documents included in a shipment, in conjunction with a delivery address separate from the equipment
- Customer-specific system and location designations, coordinated with the customer

#### Note:

The order-specific integration engineering is especially recommended for liquid-cooled Cabinet Modules.

# Selection and ordering data

The following engineering services can be ordered depending on the number of drives/axes included in an order:

Integration engineering	Article No.
For 1 drive (also parallel connection) including the associated Line Modules, Sensor Modules, Terminal Modules, etc.	6SL3780-0AA00-0AA0
For up to 3 drives (also parallel connection) including the associated Line Modules, Sensor Modules, Terminal Modules, etc.	6SL3780-0AC00-0AA0
For up to 5 drives (also parallel connection) including the associated Line Modules, Sensor Modules, Terminal Modules, etc.	6SL3780-0AE00-0AA0
For up to 10 drives (also parallel connection) including the associated Line Modules, Sensor Modules, Terminal Modules, etc.	6SL3780-0AJ00-0AA0

Engineering services for larger drive systems are also available on request.

## Options

The table below lists the options available for order-specific integration engineering (for details, see Description of the options):

Available options	Order code
Customer documentation (circuit diagram, terminal diagram, layout diagram) in DXF format	D02
Preliminary version of customer documentation in PDF format	D14
Documentation in English / French	D58
Documentation in English / Spanish	D60
Documentation in English / Italian	D80
Documentation in English / Chinese	D91
Documentation in English / Russian	D94

When ordering the order-specific integration engineering, the required documentation options must always be ordered together with the order engineering (not to the individual Cabinet Modules).

Ordering the documentation options for the particular Cabinet Modules is only required if equipment is ordered without integration engineering.

# Option selection matrix of the order-specific integration engineering

Certain options are mutually exclusive.

✓	Possible combination
-	Combination not possible

	D02	D14	D58	D60	D80	D91	D94
D02		~	~	~	~	✓	~
D14	~		~	~	✓	~	~
D58	~	~		-	-	-	-
D60	✓	~	-		-	-	-
D80	~	~	-	-		-	-
D91	~	*	-	-	-		-
D94	~	~	-	-	-	-	

Customized solutions

## More information

## **Customized solutions**

In addition to the wide range of possibilities of configuring drives with the available modules and options to address specific plant and system requirements, for special applications we also offer customized applications to fully comply with the actual requirement.

These are based on the standard SINAMICS S120 Cabinet Modules and are supplied as completely wired units that are ready to be connected up.

Examples of applications such as these include:

#### SINAMICS S120 Cabinet Modules Application Marine Drive

The range of requirements that drive systems have to meet aboard a ship is enormous – and highly varied. In addition to maximum efficiency and reliability, compactness is absolutely essential given the confined spaces. The systems used must also be low-maintenance, service-friendly, and in every way suitable for marine applications. Siemens' answer to these requirements is the SINAMICS S120 Cabinet Modules Application Marine Drive.

The innovative liquid-cooled drive system for all marine applications is based on the SINAMICS platform, which is a proven success worldwide. Its footprint has been optimized for use on board and it impresses with its flexibility and economic efficiency.

#### SINAMICS S120 Switch-Over Modules

In order to operate different motors at different times on a common converter, SINAMICS S120 Switch-Over Modules are the ideal solution.

A Switch-Over Module switches the output of the Motor Module over to the motor that is required.

If, for example, processes powered by specific motors run subsequently at different times, or if the individual motor is only briefly used during the day, then costs and space can be saved by using just one converter, supplemented with the corresponding Switch-Over Module.

Such applications include, for instance, pump drives on tankers when various ship compartments have to be emptied one after the other, or container cranes, if in addition to the drive for loading and unloading, the drive for operating the boom also has to be fed from the converter.

## • SINAMICS S120 Motor Multi-Connection Modules

For applications performed in combination with group drives that require a different number of multi-motor outputs, SINAMICS S120 Motor Multi-Connection Modules are a sensible choice.

Motor Modules are supplemented with a corresponding control system, as well as switching and protection devices. This configuration allows the associated motors with small power ratings (motor groups) to be operated from a common converter with a high power rating.

The completely prewired, ready-to-connect cabinet units facilitate and shorten the commissioning procedure. The transparent and flexible design allows changes and additions to be made at any time at low associated costs.

Simply contact us if you are interested or require these or any other applications.

Notes regarding the addresses of contact persons are provided in the appendix under "Contact partners for Industry Automation and Drive Technologies."



Cement mill



Ship docked in port



Oil rig

Notes



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# SINAMICS S150 converter cabinet units

# Overview



SINAMICS S150 converter cabinet units are particularly suitable for all variable-speed single-axis drives with high performance requirements, i.e. drives with:

- · High dynamic requirements
- Frequent braking cycles and high braking energy levels
- · Four-quadrant operation

SINAMICS S150 offers high-performance speed control with excellent accuracy and a high dynamic response.

The following voltages and power ratings are available:

Line voltage	Type rating	
380 480 V 3 AC	110 800 kW	
500 690 V 3 AC	75 1200 kW	

Degrees of protection are IP20 (standard) and optionally IP21, IP23, IP43 and IP54.

Line and motor-side components as well as additional monitoring devices can be installed in the converter cabinet units.

A wide range of electrical and mechanical components enable the drive system to be optimized individually to suit customer requirements.

# Benefits

The self-commutating, pulsed infeed/regenerative unit uses IGBT technology and is equipped with a Clean Power Filter. This combination guarantees extremely line-friendly behavior which is characterized by the following:

- Negligible line harmonics as a result of the Clean Power Filter (<<1 %)</li>
- The stringent limit values of IEEE 519 (2014) are complied with, without any exceptions. The total harmonic distortion factors of current THD(I) and voltage THD(U) are typically in the range of approx. 3 %.
- Regenerative feedback (four-quadrant operation)
- · Tolerant to fluctuations in the line voltage
- Operation on weak line supplies
- Reactive power compensation is possible (inductive or capacitive)
- High drive dynamic performance

In addition, factors have been considered to ensure easy handling of the drive from the planning and design phase through to operation. These factors include:

- Compact, modular design with an optimum degree of service friendliness
- Straightforward configuring and commissioning thanks to assistance provided by the SIZER for Siemens Drives and STARTER tools
- · Simple installation, as it is ready to be connected up
- Fast, menu-prompted commissioning with no complex parameterization
- Clear and convenient drive monitoring/diagnostics, commissioning and operation via a user-friendly graphical operator panel with measured values displayed in plain text or in a quasi-analog bar display.
- SINAMICS as an integral part of Totally Integrated Automation (TIA). The TIA concept offers an optimized range of products for automation and drive technology. This concept is characterized by configuration, communication, and data management that are consistent throughout the product range. SINAMICS is fully integrated in the TIA concept. Separate S7/PCS7 blocks and faceplates for WinCC are available.
- Integration in SIMATIC H systems via Y-Link
- SINAMICS Drive Control Chart (SINAMICS DCC) SINAMICS DCC is an additional tool for the easy configuration of process-oriented functions for SINAMICS. The block library encompasses a large selection of closed-loop, arithmetic and logic blocks, as well as a more comprehensive range of openloop and closed-loop control functions. The user-friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of charts that have already been created. SINAMICS DCC is an add-on to the STARTER commissioning tool.

# Converter cabinet units

# Application

SINAMICS S150 is especially suitable for use in all applications that place the highest demands on process operations with dynamic, reproducible processes. These include, for example:

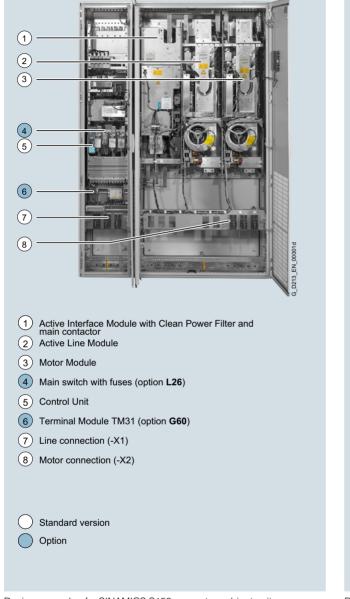
- Test bays
- Centrifuges
- Elevators and cranes
- Cross cutters and shears
- Conveyor belts with a high power demand and energy recovery
- Presses
- Cable winches

Type rating at 400 V or 690 V	Rated output current I <sub>rated</sub>	SINAMICS S150 converter cabinet unit
<w< th=""><th>А</th><th>Article No.</th></w<>	А	Article No.
Line voltage 380	480 V 3 AC	
110	210	6SL3710-7LE32-1AA3
132	260	6SL3710-7LE32-6AA3
160	310	6SL3710-7LE33-1AA3
200	380	6SL3710-7LE33-8AA3
250	490	6SL3710-7LE35-0AA3
315	605	6SL3710-7LE36-1AA3
400	745	6SL3710-7LE37-5AA3
450	840	6SL3710-7LE38-4AA3
560	985	6SL3710-7LE41-0AA3
710	1260	6SL3710-7LE41-2AA3
800	1405	6SL3710-7LE41-4AA3
Line voltage 500	690 V 3 AC	
75	85	6SL3710-7LG28-5AA3
90	100	6SL3710-7LG31-0AA3
110	120	6SL3710-7LG31-2AA3
132	150	6SL3710-7LG31-5AA3
160	175	6SL3710-7LG31-8AA3
200	215	6SL3710-7LG32-2AA3
250	260	6SL3710-7LG32-6AA3
315	330	6SL3710-7LG33-3AA3
400	410	6SL3710-7LG34-1AA3
450	465	6SL3710-7LG34-7AA3
560	575	6SL3710-7LG35-8AA3
710	735	6SL3710-7LG37-4AA3
800	810	6SL3710-7LG38-1AA3
900	910	6SL3710-7LG38-8AA3
1000	1025	6SL3710-7LG41-0AA3
1200	1270	6SL3710-7LG41-3AA3

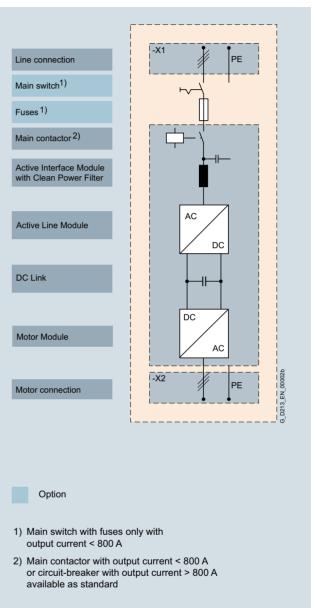
# **Converter cabinet units**

# Design

The SINAMICS S150 converter cabinet units are characterized by their compact, modular and service-friendly design.



Design example of a SINAMICS S150 converter cabinet unit



Basic design of a SINAMICS S150 converter cabinet unit with a number of version-specific options

# Design (continued)

### **Coated modules**

The following devices are equipped as standard with coated modules:

- Chassis format units
- Control Units
- Sensor Modules
- Terminal Modules
- Advanced Operator Panel (AOP30)

The coating on the modules protects the sensitive SMD components against corrosive gases, chemically active dust and moisture.

#### Nickel-plated busbars

All of the copper busbars used in the converter cabinets are nickel-plated in order to achieve the best possible immunity to environmental effects. Further, it is possible to eliminate having to clean the contacts at the customer connections, which is required for bare copper connections.

#### Note:

With some options, parts of the copper busbars cannot be nickel-plated for technical reasons.

### **Degrees of protection**

The EN 60529 standard covers the protection of electrical equipment by means of housings, covers or equivalent, and includes:

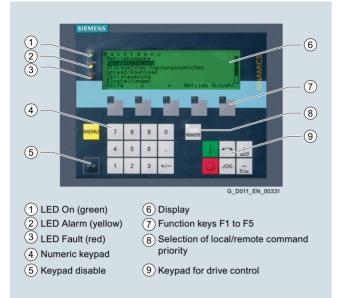
- Protection of persons against accidental contact with live or moving parts within the housing and protection of the equipment against the ingress of solid foreign bodies (touch protection and protection against ingress of solid foreign bodies)
- Protection of the equipment against the ingress of water (water protection)
- Abbreviations for the internationally agreed degrees of protection

The degrees of protection are specified by abbreviations comprising the code letters IP and two digits.

Degree of protection	First digit (Touch protection and protection against foreign bodies)	Second digit (Protection of equipment against the ingress of water)		
IP20 (Standard)	Protected against solid foreign bodies with a diameter ≥ 12.5 mm	No water protection		
IP21 (Option M21)	Protected against solid foreign bodies	Protected against drip water		
	with a diameter $\geq$ 12.5 mm	Vertically falling water drops must not have any harmful effects.		
IP23 (Option M23)	Protected against solid foreign bodies	Protected against spray water		
	with a diameter ≥ 12.5 mm	Water sprayed on both sides of the vertical at an angle of up to 60° shall not have a harmful effect.		
IP43 (Option M43)	Protected against solid foreign bodies	Protected against spray water		
diameter ≥ 1 mm		Water sprayed on both sides of the vertical at an angle of up to 60° shall not have a harmful effect.		
IP54	Dust protected	Protected against splash water		
(Option <b>M54</b> )	Ingress of dust is not totally prevented, but dust must not be allowed to enter in such quantities that the functioning or safety of the equipment is impaired.	Water splashing onto the housing from any direction must not have any harmful effects.		

## Function

### AOP30 Advanced Operator Panel



An Advanced Operator Panel (AOP30) is installed in the cabinet door of the converter for operation, monitoring and commissioning tasks.

The user is guided by interactive menus through the drive commissioning screens. When the drive is commissioned for the first time, only 6 motor parameters (which can be found on the motor rating plate) have to be entered on the AOP30. The closed-loop control is then optimized automatically to adapt the converter to the motor.

The AOP30's two-stage safety concept prevents unintentional or unauthorized changes to settings. Operation of the drive from the operator panel can be disabled by the keyboard lock and so that only parameter values and process variables can be displayed on the operator panel. The OFF key is factory-set to "active", but can be deactivated by the customer. A password can be used to prevent the unauthorized changing of converter parameters.

German, English, French, Italian, Spanish and Chinese are stored on the CU320-2 Control Unit CompactFlash card as operator panel languages. The desired language must be downloaded to the AOP30 prior to commissioning. In addition to these standard operator panel languages, Russian can also be retroinstalled. Further languages are available on request.

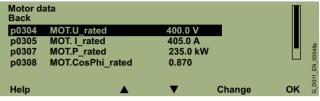
Examples of plain-text displays during various phases of operation are shown below.

The first commissioning is performed via the operator panel.

Service / Commissioning	g			
Drive commissioning				
Device commissioning				
AOP settings				003a
AOP diagnostics				000 N
Help	▼	Back	Select	G_D213_EN_0003a

Only 6 motor parameters have to be entered: Power, speed, current,  $\cos \phi$ , voltage and frequency of the motor.

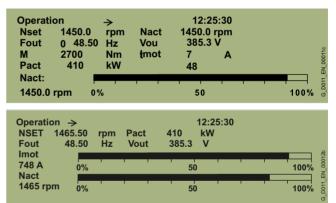
This information can be found on the motor rating plate, and must be entered in the screens on the display by following a short, menu-assisted procedure. The motor cooling method must also be specified.



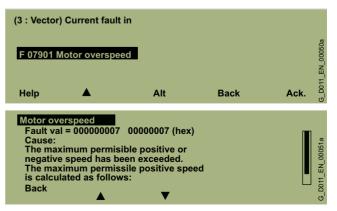
The next screen contains the parameter values that are used to automatically optimize the control.

Basic co Back p0700 p1000 p1080 p1082	mmissioning Default Bl Default Dl n_set Minimum speed Maximum speed	-	S/G150 TM 31 0.000 1500.000	TM 31 AIO rpm rpm	EN_00049a
Help		▼	CI	nange	Further

During operation, the display shows current data, such as setpoints and actual values as absolute values or it is possible to parameterize up to 3 process variables as a quasi-analog bar display.



Any **alarms** that occur are signaled by flashing of the yellow ALARM LED, **faults** by the red FAULT LED, which is then lit. There is also an indication of the cause displayed in plain text on the display's status line (with counter/remedial measures).



# **Converter cabinet units**

# Function (continued)

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Communication with higher-level controller and customer terminal block

A PROFIBUS or PROFINET interface on the Control Unit CU320-2 is provided as standard as the customer control interface.

This interface can be used to connect the system to the higherlevel controller using analog and digital signals, or to connect additional units.

The inputs and outputs available as standard can be optionally expanded by up to two Terminal Modules TM31 (refer to the description of options, option **G60** or **G61**). To simplify configuration and commissioning of the drive, the TM31 Terminal Module can be preset to a variety of factory settings.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

**Open-loop and closed-loop control functions** 

SINAMICS S150 has a high-dynamic vector control with speed and current control – with and without speed actual value feedback.

## Software and protective functions

The software functions available as standard are described below.

Software and protective functions	Description
Setpoint input	The setpoint can be specified both internally and externally; internally as a fixed setpoint, motorized potentiometer setpoint or jog setpoint, externally via the communications interface or an analog input. The internal fixed setpoint and the motorized potentiometer setpoint can be switched or adjusted via control commands from any interface.
Motor identification	The automatic motor identification function makes commissioning faster and easier and optimizes closed-loop control of the drive.
Ramp-function generator	A user-friendly ramp-function generator with separately adjustable ramp-up and ramp-down times, together with adjust- able rounding times in the lower and upper speed ranges, allows the drive to be smoothly accelerated and braked. This results in a good speed control response and plays its role in reducing the stress on the mechanical system. The down ramps can be parameterized separately for quick stop.
V <sub>dc max</sub> controller	The $V_{dc max}$ controller automatically prevents overvoltages in the DC link, if the set down ramp is too short, for example. This may also extend the set ramp-down time.
Kinetic buffering (KIP)	For brief line supply failures, the kinetic energy of the rotating drive is used to buffer the DC link and therefore prevents fault trips. The drive converter remains operational as long as the drive can provide regenerative energy as a result of its motion and the DC link voltage does not drop below the shutdown threshold. When the line supply recovers within this time, the drive is again seamlessly accelerated up to its setpoint speed.
Automatic restart	The automatic restart switches the drive on again when the power is restored after a power failure, and ramps up to the current speed setpoint.
Flying restart	The flying restart function allows the converter to be switched to a motor that is still turning. With the voltage sensing capability provided by the optional VSM10, the flying restart time for large induction motors can be significantly reduced because the motor does not need to be de-magnetized.
Technology controller	The technology controller function module allows simple control functions to be implemented, e.g. level control or volumetric flow control and complex tension controls. The existing D component can act both on the system deviation well as on the actual value (factory setting). The P, I, and D components are set separately.
Free function blocks	Using the freely programmable function blocks, it is easy to implement logic and arithmetic functions for controlling the SINAMICS drive. The blocks can be programmed at the operator panel or the STARTER commissioning tool.
SINAMICS Drive Control Chart (SINAMICS DCC)	SINAMICS DCC is an additional tool for the easy configuration of technological functions for SINAMICS. The block library contains a large selection of control, arithmetic and logic blocks as well as extensive open-loop and closed-loop control functions. The user-friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of charts that have already been created. SINAMICS DCC is an add-on to the STARTER commissioning tool (→ Tools and Engineering).
Pt sensing for motor protection	A motor model stored in the converter software calculates the motor temperature based on the current speed and load. More exact measurement of the temperature, which also takes into account the influence of the ambient temperature, is possible by means of direct temperature measurement using KTY84 sensors in the motor winding.
Motor temperature evaluation	Motor protection by evaluating a KTY84, PTC or Pt100 temperature sensor. When a KTY84 temperature sensor is con- nected, the limit values can be set for alarm or shutdown. When a PTC thermistor is connected, the system reaction to triggering of the thermistor (alarm or trip) can be defined.
Motor blocking protection	A blocked motor is detected and protected against thermal overloading by a fault trip.
Brake control	"Simple brake control" for control of holding brakes: The holding brake is used to secure drives against unwanted motion when deactivated.
	"Extended brake control" function module for complex brake control, e.g. for motor holding brakes and operational brakes: When braking with a feedback signal, the brake control reacts to the feedback signal contacts of the brake.
Essential service mode	Special converter operating mode that increases the availability of the drive system, e.g. in the event of a fire.
Write protection	Write protection to prevent unintentional changing of the setting parameters (without password function).
Know-how protection	Know-how protection for encrypting stored data, e.g. to protect configuration know-how, and to protect against changes and duplication (with password function).
Web server	The integrated web server provides information about the drive unit via its web pages. The web server is accessed using an Internet browser via unsecured (http) or secured transmission (https).

Convert			

# Function (continued)

Power unit protection	
Power unit protection	Description
Ground fault monitoring at the output	A ground fault at the output is detected by a total current monitor and results in shutdown in grounded systems.
Electronic short-circuit protection at the output	A short-circuit at the output (e.g. at the converter output terminals, in the motor cable or in the motor terminal box) is detected and the converter shuts down with a "fault".
Thermal overload protection	An alarm is issued first when the overtemperature threshold responds. If the temperature continues to rise, the unit either shuts down or independently adjusts the pulse frequency or output current so that thermal load is reduced. Once the cause of the fault has been eliminated (e.g. cooling has been improved), the original operating values are automatically resumed.

# Technical specifications

The most important directives and standards are listed below. These are used as basis for the SINAMICS S150 converter cabinet units and they must be carefully observed to achieve an EMC-compliant configuration that is safe both functionally and in operation.

European directives	
2014/30/EU	EMC Directive: Directive of the European Parliament and Council of February 26, 2014, on the harmonization of the laws of the member states relating to electromagnetic compatibility (recast)
2006/42/EC	Machinery Directive: Directive of the European Parliament and Council of May 17, 2006, on machinery and amending Directive 95/16/EC (recast).
European standards	
EN ISO 3744	Acoustics – Determination of the sound power level and sound energy level for noise sources that result from sound pressure measurements – envelope surface procedure of the accuracy class 2 for a largely free sound field over a reflecting plane
EN ISO 13849-1	Safety of machinery – safety-related parts of control systems; Part 1: General principles for design (EN ISO 13849-1: 2006)
EN 60146-1-1	Semiconductor converters – General requirements and line-commutated converters Part 1-1: Specification of basic requirements
EN 60204-1	Safety of machinery – Electrical equipment of machines; Part 1: General requirements
EN 60529	Degrees of protection provided by enclosures (IP Code)
EN 61508-1	Functional safety of electrical/electronic/programmable electronic safety-related systems Part 1: General requirements
EN 61800-2	Adjustable speed electrical power drive systems Part 2: General requirements; rating specifications for low voltage adjustable frequency AC power drive systems
EN 61800-3	Adjustable speed electrical power drive systems Part 3: EMC requirements and specific test methods
EN 61800-5-1	Adjustable speed electrical power drive systems Part 5: Safety requirements Main section 1: Electrical and thermal requirements
EN 61800-5-2	Adjustable speed electrical power drive systems Part 5-2: Safety requirements – Functional safety (IEC 61800-5-2: 2007)

# Technical specifications (continued)

General technical specifications

Electrical specifications									
Line voltages	380 480 V 3 AC, ±10 % (-15 % <	1 min)							
	500 $\dots$ 690 V 3 AC, ±10 % (-15 % $<$	1 min)							
Line supply types	Grounded TN/TT systems and non-g	grounded IT systems							
Line frequency	47 63 Hz								
Output frequency <sup>1)</sup>	0 550 Hz								
Line power factor	Adjustable (factory-set to $\cos \varphi = 1$ )	)							
Efficiency	>96 %								
Overvoltage category	III to EN 61800-5-1	III to EN 61800-5-1							
Control method	Vector control with and without enco	oder or V/f control							
Fixed speeds		eed, parameterizable (in the default set ing terminal block/PROFIBUS/PROFINE							
Skippable speed ranges	4, parameterizable								
Setpoint resolution	0.001 rpm digital (14 bits + sign) 12 bits analog								
Braking operation	Four-quadrant operation is possible (optional via a braking unit if braking								
Mechanical specifications									
Degree of protection	IP20 (higher degrees of protection u	ip to IP54 optional)							
Protection class	I acc. to EN 61800-5-1								
Touch protection	EN 50274/DGUV regulation 3 when	used as intended							
Cabinet system	Rittal TS 8, doors with double-bit key	y, three-section base plates for cable en	htry						
Paint finish	RAL 7035 (indoor requirements)								
Cooling method	Forced air cooling AF according to I	EN 60146							
Ambient conditions	Storage <sup>2)</sup>	Transport <sup>2)</sup>	Operation						
Ambient temperature	-25 +55 °C	-25 +70 °C from <u>-40 °C</u> for 24 hours	<u>0</u> 40 °C to +50 °C, see derating data						
Relative humidity	5 95%	5 95 % at 40 °C	5 <u>95 %</u>						
(condensation not permissible)	Class 1K4 acc. to IEC 60721-3-1	Class 2K3 acc. to IEC 60721-3-2	Class 3K3 acc. to IEC 60721-3-3						
Environmental class/harmful chemical substances	Class 1C2 acc. to IEC 60721-3-1	Class 2C2 acc. to IEC 60721-3-2	Class 3C2 acc. to IEC 60721-3-3						
Organic/biological influences	Class 1B1 acc. to IEC 60721-3-1	Class 2B1 acc. to IEC 60721-3-2	Class 3B1 acc. to IEC 60721-3-3						
Degree of pollution	2 acc. to EN 61800-5-1								
Installation altitude	Up to 2000 m above sea level witho > 2000 m see derating data	ut derating;							
Mechanical stability	Storage <sup>2)</sup>	Transport <sup>2)</sup>	Operation						
Vibratory load	Class 1M2 acc. to IEC 60721-3-1	Class 2M2 acc. to IEC 60721-3-2	-						
Deflection	1.5 mm at <u>5</u> 9 Hz	3.1 mm at <u>5</u> 9 H	0.075 mm at 10 58 Hz						
Acceleration	5 m/s² at >9 200 Hz	10 m/s² at 9 200 Hz	9.8 m/s <sup>2</sup> at 58 200 Hz						
Shock load	Class 1M2 acc. to IEC 60721-3-1	Class 2M2 acc. to IEC 60721-3-2	Class 3M4 acc. to IEC 60721-3-3						
Acceleration	40 m/s <sup>2</sup> at 22 ms	100 m/s <sup>2</sup> at 11 ms	100 m/s <sup>2</sup> at 11 ms						
Compliance with standards									
Certificates of suitability	CE (EMC Directive 2014/30/EU and Machinery Directive 2006/42/EC for functional safety) RCM								
Radio interference suppression	SINAMICS drive converter systems are not designed for connection to the public grid (first environment). Radio inter ference suppression is compliant with the EMC product standard for variable-speed drives EN 61800-3, "Second environment" (industrial networks). EMC disturbances can occur when connected to the public grid. However, if additional measures are taken (e.g. $\rightarrow$ line filter), it can also be operated in the "first environment".								

Deviations from the specified classes are underlined.

1) Please note:

- The correlation between the maximum output frequency, pulse frequency
- The correlation between the maximum output requency, pulse nequency and current derating. Higher output frequencies on request.
   The correlation between the maximum output frequency and permissible output current (current derating).
   Information is provided in the SINAMICS Low Voltage Engineering Manual.
- 2) In transport packaging

## **Converter cabinet units**

# Technical specifications (continued)

Line voltage 380 480 V 3 AC	SINAMICS S150 converter cabinet units						
		6SL3710- 7LE32-1AA3	6SL3710- 7LE32-6AA3	6SL3710- 7LE33-1AA3	6SL3710- 7LE33-8AA3	6SL3710- 7LE35-0AA3	6SL3710- 7LE36-1AA3
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	110	132	160	200	250	315
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	90	110	132	160	200	250
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	250	300	400	500
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	150	200	200	250	350	350
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	210	260	310	380	490	605
<ul> <li>Base-load current I<sub>L</sub><sup>3)</sup></li> </ul>	А	205	250	302	370	477	590
• Base-load current $I_{\rm H}^{4)}$	А	178	233	277	340	438	460
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	307	375	453	555	715	885
nfeed/regenerative feedback current							
<ul> <li>Rated input current I<sub>rated I</sub></li> </ul>	А	197	242	286	349	447	549
Maximum input current I <sub>max I</sub>	А	315	390	570	570	735	907
Current demand, max. <sup>5)</sup>							
<ul> <li>24 V DC aux. power supply</li> </ul>	А	Internal	Internal	Internal	Internal	Internal	Internal
Pulse frequency <sup>6)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	2	2	2	2	2	1.25
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	2	2	2	2	2	1.25
- With current derating	kHz	8	8	8	8	8	7.5
Power loss, max. <sup>7)</sup>							
• At 50 Hz 400 V	kW	6.31	7.55	10.01	10.72	13.13	17.69
• At 60 Hz 460 V	kW	6.49	7.85	10.45	11.15	13.65	18.55
Cooling air requirement	m <sup>3</sup> /s	0.58	0.7	1.19	1.19	1.19	1.96
<b>Sound pressure level L<sub>pA</sub></b> (1 m) at 50/60 Hz	dB	71/73	71/73	72/74	72/74	72/74	77/79
Cable length, max.							
Shielded	m	300	300	300	300	300	300
Unshielded	m	450	450	450	450	450	450
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
Dimensions							
• Width	mm	1400	1400	1600	1800	1800	2200
• Height	mm	2000	2000	2000	2000	2000	2000
Depth	mm	600	600	600	600	600	600
Weight (without options), approx.	kg	708	708	892	980	980	1716
Short-circuit current rating according to IEC <sup>8)</sup>	kA	65	65	65	65	65	65
Minimum short-circuit current <sup>9)</sup>	А	3000	3000	4500	4500	8000	12000
Frame sizes							
Active Interface Module		FI	FI	GI	GI	GI	ні
Active Line Module		FX	FX	GX	GX	GX	НХ
Motor Module		FX	FX	GX	GX	GX	НХ

#### Note:

The power data in hp units is based on the NEC/CEC standards for the North American market. Information about line supply connections, motor connections and cabinet grounding can be found under **Cable cross-sections and connections**.

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- <sup>4)</sup> The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- <sup>5)</sup> If the drive closed-loop control is still to remain active when the line supply fails, the equipment must be provided with an external 24 V DC supply.
- 6) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The specified power losses are the maximum values at 100 % utilization. The values are lower under normal operating conditions.
- <sup>8)</sup> In conjunction with the specified fuses or circuit breakers.
- <sup>9)</sup> Current required for reliably triggering protective devices.

## **Converter cabinet units**

# Technical specifications (continued)

Line voltage 380 480 V 3 AC	SINAMICS S150 converter cabinet units						
		6SL3710- 7LE37-5AA3	6SL3710- 7LE38-4AA3	6SL3710- 7LE41-0AA3	6SL3710- 7LE41-2AA3	6SL3710- 7LE41-4AA3	
Type rating							
• At I <sub>L</sub> (50 Hz 400 V) <sup>1)</sup>	kW	400	450	560	710	800	
• At I <sub>H</sub> (50 Hz 400 V) <sup>1)</sup>	kW	315	400	450	560	710	
• At I <sub>L</sub> (60 Hz 460 V) <sup>2)</sup>	hp	600	700	800	900	1150	
• At I <sub>H</sub> (60 Hz 460 V) <sup>2)</sup>	hp	450	600	700	900	1000	
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	745	840	985	1260	1405	
<ul> <li>Base-load current I<sub>L</sub><sup>3)</sup></li> </ul>	А	725	820	960	1230	1370	
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	570	700	860	1127	1257	
Maximum current Imax O	А	1087	1230	1440	1845	2055	
nfeed/regenerative feedback current							
<ul> <li>Rated input current I<sub>rated I</sub></li> </ul>	А	674	759	888	1133	1262	
<ul> <li>Maximum input current I<sub>max I</sub></li> </ul>	А	1118	1260	1477	1891	2107	
Current demand, max. <sup>5)</sup>							
<ul> <li>24 V DC aux. power supply</li> </ul>	А	Internal	Internal	Internal	Internal	Internal	
Pulse frequency <sup>6)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25	
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	
Power loss, max. <sup>7)</sup>							
• At 50 Hz 400 V	kW	20.63	21.1	27.25	33.05	33.95	
• At 60 Hz 460 V	kW	21.75	22.25	28.65	34.85	35.85	
Cooling air requirement	m <sup>3</sup> /s	1.96	1.96	2.6	2.6	2.6	
<b>Sound pressure level L<sub>pA</sub></b> 1 m) at 50/60 Hz	dB	77/79	77/79	77/79	78/80	78/80	
Cable length, max.							
Shielded	m	300	300	300	300	300	
Unshielded	m	450	450	450	450	450	
Degree of protection		IP20	IP20	IP20	IP20	IP20	
Dimensions							
• Width	mm	2200	2200	2800	2800	2800	
Height	mm	2000	2000	2000	2000	2000	
Depth	mm	600	600	600	600	600	
Weight (without options), approx.	kg	1731	1778	2408	2408	2408	
Short-circuit current rating according o IEC <sup>8)</sup>	kA	65	65	84	100	100	
Minimum short-circuit current <sup>9)</sup>	А	15000	2000	2500	3200	3200	
Frame sizes							
Active Interface Module		ні	н	JI	JI	JI	
Active Line Module		HX	HX	JX	JX	JX	
Motor Module		HX	НХ	JX	JX	JX	

#### Note:

The power data in hp units is based on the NEC/CEC standards for the North American market. Information about line supply connections, motor connections and cabinet grounding can be found under **Cable cross-sections and connections**.

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 400 V 3 AC 50 Hz.
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 460 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- <sup>5)</sup> If the drive closed-loop control is still to remain active when the line supply fails, the equipment must be provided with an external 24 V DC supply.
- 6) Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
- <sup>7)</sup> The specified power losses are the maximum values at 100 % utilization. The values are lower under normal operating conditions.
- <sup>8)</sup> In conjunction with the specified fuses or circuit breakers.
- <sup>9)</sup> Current required for reliably triggering protective devices.

## **Converter cabinet units**

## Technical specifications (continued)

Line voltage 500 690 V 3 AC	SINAMICS S150 converter cabinet units						
		6SL3710- 7LG28-5AA3	6SL3710- 7LG31-0AA3	6SL3710- 7LG31-2AA3	6SL3710- 7LG31-5AA3	6SL3710- 7LG31-8AA3	6SL3710- 7LG32-2AA3
Type rating							
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	75	90	110	132	160	200
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	55	75	90	110	132	160
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	55	55	75	90	110	132
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	45	55	75	90	90	110
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	75	100	150	150	200
• At / <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	75	75	100	125	150	200
Output current							
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	85	100	120	150	175	215
• Base-load current $I_{L}^{(3)}$	А	80	95	115	142	170	208
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	76	89	117	134	157	192
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	120	142	172	213	255	312
Infeed/regenerative feedback current							
Rated current I <sub>rated I</sub>	А	86	99	117	144	166	202
Maximum current I <sub>max I</sub>	А	125	144	170	210	253	308
Current demand, max. <sup>5)</sup>							
<ul> <li>24 V DC aux. power supply</li> </ul>	А	Internal	Internal	Internal	Internal	Internal	Internal
Pulse frequency <sup>6)</sup>							
<ul> <li>Rated frequency</li> </ul>	kHz	1.25	1.25	1.25	1.25	1.25	1.25
<ul> <li>Pulse frequency, max.</li> </ul>							
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	1.25
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	7.5
Power loss, max. <sup>7)</sup>							
• At 50 Hz 690 V	kW	5.12	5.38	5.84	5.75	11.02	11.44
• At 60 Hz 575 V	kW	4.45	4.65	5.12	4.97	11.15	11.56
Cooling air requirement	m <sup>3</sup> /s	0.58	0.58	0.58	0.58	1.19	1.19
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	71/73	71/73	71/73	71/73	75/77	75/77
Cable length, max.							
Shielded	m	300	300	300	300	300	300
Unshielded	m	450	450	450	450	450	450
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20
Dimensions							
• Width	mm	1400	1400	1400	1400	1600	1600
Height	mm	2000	2000	2000	2000	2000	2000
• Depth	mm	600	600	600	600	600	600
Weight (without options), approx.	kg	708	708	708	708	892	892
Short-circuit current rating according to IEC <sup>8)</sup>	kA	65	65	65	65	65	65
Minimum short-circuit current <sup>9)</sup>	А	1000	1000	1300	1800	2500	3000
Frame size							
Active Interface Module		FI	FI	FI	FI	GI	GI
Active Line Module		FX	FX	FX	FX	GX	GX
Motor Module		FX	FX	FX	FX	GX	GX

## Note:

The power data in hp units is based on the NEC/CEC standards for the North American market. Information about line supply connections, motor connections and cabinet grounding can be found under **Cable cross-sections and connections**.

 $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 690 V 3 AC 50 Hz.

- <sup>5)</sup> If the drive closed-loop control is still to remain active when the line supply fails, the equipment must be provided with an external 24 V DC supply.
   (a) Information provided the approximation between the pulse fragmentation of the approximation of t
- <sup>2)</sup> Rated output of a typical 6-pole standard induction motor based on *l*<sub>L</sub> or *l*<sub>H</sub> for 575 V 3 AC 60 Hz.
  <sup>3)</sup> The base-load current *l*<sub>L</sub> is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
  - on *I*<sub>L</sub> or *I*<sub>H</sub>
     <sup>6)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.
     <sup>7)</sup> The specified power losses are the maximum values at 100 % utilization.

 $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

- The values are lower under normal operating conditions.
   <sup>8)</sup> In conjunction with the specified fuses or circuit breakers. Current required for reliably triggering protective devices.
- <sup>9)</sup> Current required for reliably triggering protective devices.

### **Converter cabinet units**

## Technical specifications (continued)

Line voltage 500 … 690 V 3 AC		SINAMICS S150 converter cabinet units								
		6SL3710- 7LG32-6AA3	6SL3710- 7LG33-3AA3	6SL3710- 7LG34-1AA3	6SL3710- 7LG34-7AA3	6SL3710- 7LG35-8AA3	6SL3710- 7LG37-4AA3			
Type rating										
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	250	315	400	450	560	710			
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	200	250	315	400	450	630			
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	160	200	250	315	400	500			
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	132	160	200	250	315	450			
• At I <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	250	300	400	450	600	700			
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	200	250	350	450	500	700			
Output current										
<ul> <li>Rated current I<sub>rated O</sub></li> </ul>	А	260	330	410	465	575	735			
<ul> <li>Base-load current l<sub>1</sub><sup>(3)</sup></li> </ul>	А	250	320	400	452	560	710			
• Base-load current $I_{\rm H}^{2}$	А	233	280	367	416	514	657			
<ul> <li>Maximum current I<sub>max O</sub></li> </ul>	А	375	480	600	678	840	1065			
Infeed/regenerative feedback current										
Rated current I <sub>rated I</sub>	А	242	304	375	424	522	665			
Maximum current I <sub>max I</sub>	А	370	465	619	700	862	1102			
Current demand, max. <sup>5)</sup>										
<ul> <li>24 V DC auxiliary power supply</li> </ul>	А	Internal	Internal	Internal	Internal	Internal	Internal			
Pulse frequency <sup>6)</sup>										
Rated frequency	kHz	1.25	1.25	1.25	1.25	1.25	1.25			
• Pulse frequency, max.										
- Without current derating	kHz	1.25	1.25	1.25	1.25	1.25	1.25			
- With current derating	kHz	7.5	7.5	7.5	7.5	7.5	7.5			
Power loss, max. <sup>7)</sup>										
• At 50 Hz 690 V	kW	11.97	12.69	19.98	20.55	24.05	30.25			
• At 60 Hz 575 V	kW	12.03	12.63	18.86	19.47	22.85	28.75			
Cooling air requirement	m <sup>3</sup> /s	1.19	1.19	1.96	1.96	1.96	2.6			
<b>Sound pressure level L<sub>pA</sub></b> 1 m) at 50/60 Hz	dB	75/77	75/77	77/79	77/79	77/79	77/79			
Cable length, max.										
Shielded	m	300	300	300	300	300	300			
Unshielded	m	450	450	450	450	450	450			
Degree of protection		IP20	IP20	IP20	IP20	IP20	IP20			
Dimensions										
• Width	mm	1600	1600	2200	2200	2200	2800			
Height	mm	2000	2000	2000	2000	2000	2000			
• Depth	mm	600	600	600	600	600	600			
Weight (without options), approx.	kg	892	892	1716	1716	1716	2300			
Short-circuit current rating according o IEC <sup>8)</sup>	-	65	65	65	65	84	85			
Minimum short-circuit current <sup>9)</sup>	A	3000	4500	4500	7000	9000	15000			
Frame size										
<ul> <li>Active Interface Module</li> </ul>		GI	GI	ні	н	ні	JI			
Active Line Module		GX	GX	НХ	НХ	НХ	JX			
Motor Module		GX	GX	НХ	НХ	НХ	JX			

Note:

The power data in hp units is based on the NEC/CEC standards for the North American market. Information about line supply connections, motor connections and cabinet grounding can be found under **Cable cross-sections and connections**.

<sup>1)</sup> Rated output of a typical 6-pole standard induction motor based on  $l_{\rm L}$  or  $l_{\rm H}$  for 690 V 3 AC 50 Hz.

 $^{2)}$  Rate output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 575 V 3 AC 60 Hz.

<sup>3)</sup> The base-load current I<sub>L</sub> is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.

 $^{\rm 4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.

- <sup>5)</sup> If the drive closed-loop control is still to remain active when the line supply fails, the equipment must be provided with an external 24 V DC supply.
- 6) Information regarding the correlation between the pulse frequency and max, output current/output frequency is provided in the SINAMICS Low Voltage Engineering Manual.

<sup>7)</sup> The specified power losses are the maximum values at 100 % utilization. The values are lower under normal operating conditions.

<sup>8)</sup> In conjunction with the specified fuses or circuit breakers.

<sup>9)</sup> Current required for reliably triggering protective devices.

### **Converter cabinet units**

## Technical specifications (continued)

Line voltage 500 690 V 3 AC		SINAMICS S150 converter cabinet units							
		6SL3710- 7LG38-1AA3	6SL3710- 7LG38-8AA3	6SL3710- 7LG41-0AA3	6SL3710- 7LG41-3AA3				
Type rating									
• At I <sub>L</sub> (50 Hz 690 V) <sup>1)</sup>	kW	800	900	1000	1200				
• At I <sub>H</sub> (50 Hz 690 V) <sup>1)</sup>	kW	710	800	900	1000				
• At I <sub>L</sub> (50 Hz 500 V) <sup>1)</sup>	kW	560	630	710	900				
• At I <sub>H</sub> (50 Hz 500 V) <sup>1)</sup>	kW	500	560	630	800				
• At / <sub>L</sub> (60 Hz 575 V) <sup>2)</sup>	hp	800	900	1000	1250				
• At I <sub>H</sub> (60 Hz 575 V) <sup>2)</sup>	hp	700	800	900	1000				
Output current									
Rated current I <sub>rated O</sub>	А	810	910	1025	1270				
<ul> <li>Base-load current I<sub>L</sub><sup>3)</sup></li> </ul>	А	790	880	1000	1230				
<ul> <li>Base-load current I<sub>H</sub><sup>4)</sup></li> </ul>	А	724	814	917	1136				
Maximum current Imax O	А	1185	1320	1500	1845				
Infeed/regenerative feedback current									
Rated current Irated I	А	732	821	923	1142				
Maximum current Imax I	А	1218	1367	1537	1905				
Current demand, max. 5)									
<ul> <li>24 V DC aux. power supply</li> </ul>	А	Internal	Internal	Internal	Internal				
Pulse frequency <sup>6)</sup>									
Rated frequency	kHz	1.25	1.25	1.25	1.25				
Pulse frequency, max.									
- Without current derating	kHz	1.25	1.25	1.25	1.25				
- With current derating	kHz	7.5	7.5	7.5	7.5				
Power loss, max. <sup>7)</sup>									
• At 50 Hz 690 V	kW	34.45	34.65	36.15	42.25				
• At 60 Hz 575 V	kW	32.75	32.85	34.25	39.25				
Cooling air requirement	m <sup>3</sup> /s	2.6	2.6	2.6	2.6				
Sound pressure level L <sub>pA</sub> (1 m) at 50/60 Hz	dB	77/79	77/79	77/79	77/79				
Cable length, max.									
Shielded	m	300	300	300	300				
Unshielded	m	450	450	450	450				
Degree of protection		IP20	IP20	IP20	IP20				
Dimensions									
Width	mm	2800	2800	2800	2800				
Height	mm	2000	2000	2000	2000				
• Depth	mm	600	600	600	600				
Weight (without options), approx.	kg	2408	2408	2408	2408				
Short-circuit current rating according to IEC <sup>8)</sup>	kA	85	85	85	85				
Minimum short-circuit current <sup>9)</sup>	А	2000	2000	2500	3200				
Frame size									
Active Interface Module		JI	JI	JI	JI				
Active Line Module		JX	JX	JX	JX				
Motor Module		JX	JX	JX	JX				

Note:

The power data in hp units is based on the NEC/CEC standards for the North American market. Information about line supply connections, motor connections and cabinet grounding can be found under **Cable cross-sections and connections**.

- $^{1)}$  Rated output of a typical 6-pole standard induction motor based on  $\it I_L$  or  $\it I_H$  for 690 V 3 AC 50 Hz.
- <sup>5)</sup> If the drive closed-loop control is still to remain active when the line supply fails, the equipment must be provided with an external 24 V DC supply.
  <sup>6)</sup> Information regarding the correlation between the pulse frequency and max. output current/output frequency is provided in the SINAMICS Low
- $^{2)}$  Rated output of a typical 6-pole standard induction motor based on  $\it l_L$  or  $\it l_H$  for 575 V 3 AC 60 Hz.
- $^{3)}$  The base-load current  $l_{\rm L}$  is based on a duty cycle of 110 % for 60 s or 150 % for 10 s with a duty cycle duration of 300 s.
- $^{4)}$  The base-load current  $l_{\rm H}$  is based on a duty cycle of 150 % for 60 s or 160 % for 10 s with a duty cycle duration of 300 s.
- <sup>7)</sup> The specified power losses are the maximum values at 100 % utilization. The values are lower under normal operating conditions.
- <sup>8)</sup> In conjunction with the specified fuses or circuit breakers.

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<sup>9)</sup> Current required for reliably triggering protective devices.

## Characteristic curves

### Derating data

SINAMICS S150 converter cabinet units and the associated system components are rated for an ambient temperature of 40 °C and installation altitudes up to 2000 m above sea level.

At ambient temperatures > 40 °C, the output current must be reduced. Ambient temperatures above 50 °C are not permissible.

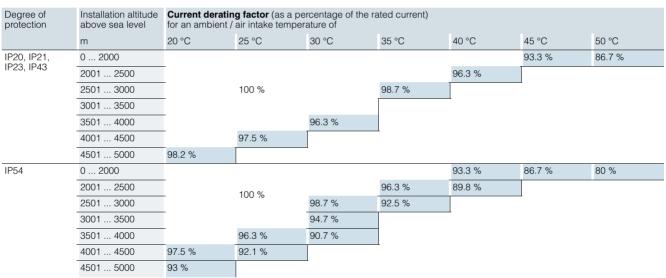
At installation altitudes > 2000 m above sea level, it must be taken into account that the air pressure, and therefore air density, decreases as the height increases. As a consequence, the cooling efficiency and the insulation capacity of the air also decrease.

Due to the reduced cooling efficiency, it is necessary, on the one hand, to reduce the ambient temperature and on the other hand, to lower heat loss in the converter cabinet unit by reducing the output current, whereby ambient temperatures lower than 40 °C may be offset to compensate.

The following table lists the permissible output currents depending on the installation altitude and ambient temperature for the various degrees of protection. The specified values already include a permitted compensation in respect of installation altitude and ambient temperatures < 40 °C (temperature at the air intake of the converter cabinet unit).

The values apply under the precondition that the cooling air flow stated in the technical specifications is ensured by the way the devices are installed in the cabinet.

As additional measure for installation altitudes from 2000 m up to 5000 m, an isolating transformer is required in order to reduce transient overvoltages according to EN 60664-1. For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.



### **Converter cabinet units**

## Characteristic curves (continued)

Current derating as a function of the pulse frequency

To reduce motor noise or to increase output frequency, the pulse frequency can be increased relative to the factory setting (1.25 kHz or 2 kHz). When the pulse frequency is increased, the derating factor of the output current must be taken into account. This derating factor must be applied to the currents specified in the technical specifications.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Derating factor of the output current depending on the pulse frequency for devices with a rated pulse frequency of 2 kHz

SINAMICS S150 converter cabinet unit	Type rating at 400 V	Output current at 2 kHz	Derating factor at pulse frequency						
6SL3710	kW	А	2.5 kHz	4 kHz	5 kHz	7.5 kHz	8 kHz		
380 480 V 3 AC									
7LE32-1AA3	110	210	95 %	82 %	74 %	54 %	50 %		
7LE32-6AA3	132	260	95 %	83 %	74 %	54 %	50 %		
7LE33-1AA3	160	310	97 %	88 %	78 %	54 %	50 %		
7LE33-8AA3	200	380	96 %	87 %	77 %	54 %	50 %		
7LE35-0AA3	250	490	94 %	78 %	71 %	53 %	50 %		

Derating factor of the output current depending on the pulse frequency for devices with a rated pulse frequency of 1.25 kHz

SINAMICS S150 converter cabinet unit	Type rating at 400 V or 690 V	Output current at 1.25 kHz	Derating factor at pulse freque				
6SL3710	kW	А	2 kHz	2.5 kHz	4 kHz	5 kHz	7.5 kHz
380 480 V 3 AC							
7LE36-1AA3	315	605	83 %	72 %	64 %	60 %	40 %
7LE37-5AA3	400	745	83 %	72 %	64 %	60 %	40 %
7LE38-4AA3	450	840	87 %	79 %	64 %	55 %	40 %
7LE41-0AA3	560	985	92 %	87 %	70 %	60 %	50 %
7LE41-2AA3	710	1260	92 %	87 %	70 %	60 %	50 %
7LE41-4AA3	800	1405	97 %	95 %	74 %	60 %	50 %
500 690 V 3 AC							
7LG28-5AA3	75	85	93 %	89 %	71 %	60 %	40 %
7LG31-0AA3	90	100	92 %	88 %	71 %	60 %	40 %
7LG31-2AA3	110	120	92 %	88 %	71 %	60 %	40 %
7LG31-5AA3	132	150	90 %	84 %	66 %	55 %	35 %
7LG31-8AA3	160	175	92 %	87 %	70 %	60 %	40 %
7LG32-2AA3	200	215	92 %	87 %	70 %	60 %	40 %
7LG32-6AA3	250	260	92 %	88 %	71 %	60 %	40 %
7LG33-3AA3	315	330	89 %	82 %	65 %	55 %	40 %
7LG34-1AA3	400	410	89 %	82 %	65 %	55 %	35 %
7LG34-7AA3	450	465	92 %	87 %	67 %	55 %	35 %
7LG35-8AA3	560	575	91 %	85 %	64 %	50 %	35 %
7LG37-4AA3	710	735	87 %	79 %	64 %	55 %	25 %
7LG38-1AA3	800	810	97 %	95 %	71 %	55 %	35 %
7LG38-8AA3	900	910	92 %	87 %	67 %	55 %	33 %
7LG41-0AA3	1000	1025	91 %	86 %	64 %	50 %	30 %
7LG41-3AA3	1200	1270	87 %	79 %	55 %	40 %	25 %

The following table lists the maximum achievable output frequency as a function of the pulse frequency:

Pulse frequency	Max. achievable output frequency
1.25 kHz	100 Hz
2 kHz	160 Hz
2.5 kHz	200 Hz
≥4 kHz	300 Hz

## Characteristic curves (continued)

### **Overload capability**

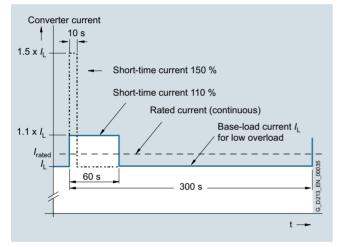
The SINAMICS S150 converter cabinet units are equipped with an overload reserve to deal with breakaway torques, for example. If larger surge loads occur, this must be taken into account in the configuration. For drives with overload requirements, the appropriate base load current must, therefore, be used as a basis for the required load.

The criterion for overload is that the drive is operated with its base load current before and after the overload occurs on the basis of a duty cycle duration of 300 s.

Another precondition is that the frequency converter is operated at its factory-set pulse frequency at output frequencies >10 Hz.

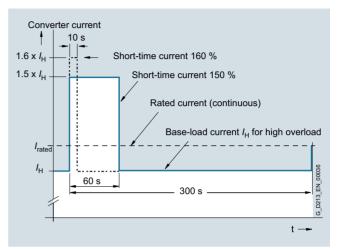
For temporary, periodic duty cycles with high variations of load within the duty cycle, the relevant sections of the SINAMICS Low Voltage Engineering Manual must be observed.

The base-load current for a low overload  $I_{\rm L}$  is the basis for a duty cycle of 110 % for 60 s or 150 % for 10 s.



Low overload

The base-load current  $I_{\rm H}$  for a high overload is based on a duty cycle of 150 % for 60 s or 160 % for 10 s.



High overload

## Converter cabinet units

## Options

When ordering a converter with options, add the suffix "-Z" to the article number and then the order code(s) for the desired option(s).

### Example: 6SL3710-7LE32-1AA3-Z M07+D60+...

### See also ordering examples.

Available options	Order code
Input side	
Use in the first environment according to EN 618003, Category C2 (TN-TT line supplies with grounded neutral point)	L00
Infeed module one level lower	L04
Surge suppression	L21
Main switch incl. fuses or circuit breakers	L26
Line filter monitoring	L40
EMC shielding busbar (cable connection from below) <sup>1)</sup>	M70
Output side	
dv/dt filter compact plus Voltage Peak Limiter	L07
Motor reactor	L08
dv/dt filter plus Voltage Peak Limiter	L10
Sine-wave filter (only for the voltage range 380 to 480 V, up to 200 kW)	L15
EMC shield bus (cable connection from below) 1)	M70
Motor protection and safety functions	
EMERGENCY OFF pushbutton installed in the cabinet door	L45
EMERGENCY OFF Category 0, 230 V AC or 24 V DC	L57
EMERGENCY STOP Category 1, 230 V AC	L59
EMERGENCY STOP Category 1, 24 V DC	L60
Thermistor motor protection device (alarm)	L83
Thermistor motor protection device (trip)	L84
Pt100 evaluation unit	L86
Insulation monitoring	L87
Additional touch protection	M60
Degree of protection increase	
Degree of protection IP21	M21
Degree of protection IP23	M23
Degree of protection IP43	M43
Degree of protection IP54	M54
Mechanical options	
Base 100 mm high, RAL 7022	M06
Cable marshaling compartment 200 mm high, RAL 7035	M07
Line connection from above	M13
Motor connection from above	M78
Crane transport assembly (top-mounted)	M90
Safety Integrated	
Safety license for 1 axis	K01
Second SMC30 Sensor Module Cabinet-Mounted	K52
Terminal module for controlling the Safe Torque Off and Safe Stop 1 safety functions	K82
TM54F Terminal Module	K87
Safe Brake Adapter SBA, 230 V AC	K88

Available options	Order code
Other options	
CBC10 Communication Board	G20
CBE20 Communication Board	G33
TM150 temperature sensor evaluation unit	G51
TM31 Terminal Module	G60
Additional TM31 Terminal Module	G61
TB30 Terminal Board	G62
SMC10 Sensor Module Cabinet-Mounted	K46
SMC20 Sensor Module Cabinet-Mounted	K48
SMC30 Sensor Module Cabinet-Mounted	K50
VSM10 Voltage Sensing Module	K51
CU320-2 PN Control Unit	K95
Connection for external auxiliaries	L19
Cabinet lighting with service socket	L50
Cabinet anti-condensation heating	L55
25/125 kW braking unit for line voltages of 380 480 V (110 132 kW) and 660 690 V (75 132 kW)	L61
50/250 kW braking unit for line voltages of 380 480 V (160 800 kW) and 660 690 V (160 1200 kW)	L62
25/125 kW braking unit for line voltages of 500 600 V (110 132 kW)	L64
50/250 kW braking unit for line voltages of 500 600 V (160 1200 kW)	L65
Marking of all control cable conductor ends	M91
Special cabinet paint finish <sup>2)</sup>	Y09
One-line label for system identification, $40 \times 80$ mm	Y31
Two-line label for system identification, $40 \times 180 \text{ mm}$	Y32
Four-line label for system identification, $40 \times 180 \text{ mm}$	Y33
Production flowcharts	
Documentation, production flowchart: one issue	B43
Documentation, production flowchart: updated every two weeks	B44
Documentation, production flowchart: updated every month	B45
Packaging options	
Generation of a preliminary and a final packing list (shipping)	B55
Packed items labeled with a customized label	B56
Photo documentation of the ordered units	B57

<sup>1)</sup> This option is listed for the input- and output-side options, but is only required once. <sup>2)</sup> The order code **Y..** requires data in plain text.

### Converter cabinet units

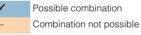
# Options (continued)

Available options	Order code
Documentation (standard: English/German)	
Documentation in German	D00
Customer documentation (circuit diagram, terminal diagram, layout diagram) in DXF format	D02
Customer documentation as hard copy	D04
Preliminary version of customer documentation	D14
Documentation in Russian	D56
Documentation in English / French	D58
Documentation in English / Spanish	D60
Documentation in Italian	D72
Documentation in English	D76
Documentation in French	D77
Documentation in Spanish	D78
Documentation in English / Italian	D80
Documentation in Chinese	D84
Documentation in English / Chinese	D91
Documentation in English / Portuguese (Brazil)	D93
Documentation in English / Russian	D94
Rating plate data (standard: English/German)	
Rating plate data in English/French	T58
Rating plate data in English/Spanish	T60
Rating plate data in English/Italian	T80
Rating plate data in English/Portuguese (Brazil)	T83
Rating plate data in English/Russian	T85
Rating plate data in English/Chinese	T91

Available options	Order code
Options specific to the chemical industry	
NAMUR terminal block	B00
Protective separation for 24 V supply (PELV)	B02
Outgoing feeder for external auxiliaries (uncontrolled)	B03
Options specific to the shipbuilding industry	
Marine version	M66
Individual certificate from Germanische Lloyd (GL)	E11
Individual certificate from Lloyds Register (LR)	E21
Individual certificate from Bureau Veritas (BV)	E31
Individual certificate from Det Norske Veritas (DNV)	E51
Individual certificate from American Bureau of Shipping (ABS)	E61
Individual certificate from Chinese Classification Society (CCS)	E71
Converter acceptance in presence of customer	
Visual acceptance	F03
Function test without motor	F71
Function test with test bay motor under no-load conditions	F75
Insulation test	F77
Customer-specific acceptance inspections (on request)	F97
Converter acceptance without the customer present	
Function test without motor	F72
Function test with test bay motor under no-load conditions	F74
Insulation test	F76

### **Option selection matrix**

Certain options can mutually exclude one another (options that are not involved, are also not shown).



Electrical options

	L07	L08	L10	L15	L57	L59	L60	L61/ L64	L62/ L65	L87	K82	M78
L07		-	-	-	~	~	~	~	~	~	~	-
L08	-		-	-	~	~	~	~	~	~	~	-
L10	-	-		-	~	~	~	~	~	~	~	-
L15	-	-	-		~	~	~	~	~	~	~	-
L57	~	~	~	~		-	-	~	~	~	~	✓
L59	~	~	~	✓	-		-	~	~	~	~	✓
L60	~	~	~	~	-	-		~	~	~	~	✓
L61/L64	~	~	~	✓	~	~	~		-	~	~	✓
L62/L65	~	~	~	~	~	~	~	-		~	~	✓
L87	~	~	~	~	~	~	~	~	~		- <sup>1)</sup>	✓
K82	~	~	~	✓	~	~	~	~	~	_ 1)		✓
M78	I	-	-	I	✓	✓	✓	✓	✓	~	~	

### Converter cabinet units

## Options (continued)

Mechanical/electrical options

	M06	M07	M13	M21	M23	M43	M54	M60	M66	M70	M78
M06		-	✓	~	~	~	~	~	~	~	✓
M07	-		~	~	~	~	~	~	~	~	~
M13	~	~		~	~	✓	~	~	~	_ 1)	~
M21	~	~	✓		-	-	-	_ 2)	-	~	-
M23	~	~	~	-		-	-	-	-	~	~
M43	~	~	~	-	-		-	-	~	~	✓
M54	~	~	✓	-	-	-		-	~	~	~
M60	~	~	-	_ 2)	-	-	-		~	~	-
M66	~	~	~	-	-	~	~	~		~	-
M70	~	✓	_ 1)	✓	✓	✓	✓	✓	✓		- <sup>1)</sup>
M78	✓	~	✓	I	~	~	✓	-	I	_ 1)	

### Other options

	G20	G33	G62	K46	K48	K50	K51	K52
G20		-	-	~	~	~	~	~
G33	-		-	~	~	✓	~	✓
G62	-	-		~	~	~	~	~
K46	~	~	~		-	-	-	-
K48	~	~	~	-		-	-	-
K50	~	✓	~	-	-		-	~
K51	~	~	~	-	-	-		-
K52	~	✓	~	-	-	~	-	

### Documentation

	D00	D02	D14	D56	D58	D60	D72	D76	D77	D78	D80	D84	D91	D93	D94	D99
D00		✓	~	~	~	~	~	~	~	✓	✓	~	✓	✓	~	_
D02	~		~	~	~	~	~	~	✓	~	~	✓	~	~	~	-
D14	✓	✓		~	~	~	~	~	~	✓	~	~	✓	✓	~	_
D56	~	~	~		~	~	~	~	✓	~	~	✓	~	~	-	-
D58	~	~	~	~		-	~	-	-	~	-	✓	-	-	-	-
D60	~	~	~	~	-		~	-	✓	-	-	✓	-	-	-	-
D72	~	~	~	~	~	~		~	✓	~	-	✓	~	~	~	-
D76	~	~	~	~	-	-	~		~	~	-	~	-	-	-	-
D77	~	~	~	~	-	~	~	~		~	~	~	~	~	~	-
D78	~	~	~	~	~	-	~	~	~		~	~	~	~	~	-
D80	~	~	~	~	-	-	-	-	✓	~		✓	-	-	-	-
D84	~	~	~	~	~	✓	~	~	~	~	~		-	~	~	-
D91	~	~	~	~	-	-	~	-	✓	~	-	-		-	-	-
D93	~	~	~	~	-	-	~	-	✓	~	-	✓	-		-	-
D94	✓	✓	~	-	Ι	Ι	✓	-	✓	~	-	✓	-	-		_
D99	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	

## Rating plate data

- –
- –
- –
-
-

<sup>1)</sup> If the line connection (option M13) and the motor connection (option M78) are from above, the EMC shield bus is not required in the lower cabinet area.  $^{2)}$  Can only be selected for converters in the voltage range 400 V to 250 kW and 690 V to 315 kW. The  $\rm M60$  option is fitted as standard for higher outputs.

### Options (continued)

### **Ordering examples**

### Example 1

#### Task:

A drive system is required for a vehicle roller test bench to perform exhaust gas analysis which can simulate driving profiles and cycles as encountered in everyday traffic situations. This means for the drive system that the dynamometer must be operated both in the motoring as well as regenerating modes.

A drive with regenerative feedback into the line supply is required as regenerative operation is the predominant operating mode and dynamic switching operations are required.

The max. regenerative power is 200 kW. The drive converter must have degree of protection IP54 as a result of the environmental conditions. An installation altitude of < 1000 m and 45 °C as the maximum ambient temperature can be assumed. The windings must be equipped with Pt100 resistance thermometers and monitored by the drive converter for alarm and trip. A switch disconnector must be provided to disconnect the converter from the 400 V power supply. In addition, the cabinet is to have a special paint finish in RAL 3002.

#### Solution:

Taking into account the derating factors for degree of protection IP54 and the increased ambient temperature of 45  $^{\circ}$ C, a converter with a minimum power rating of 223 kW should be configured.

A converter with a power rating of at least 250 kW and options **M54** (degree of protection IP54), **L26** (main switch including fuses), **L86** (Pt100 evaluation unit) and **Y09** (special paint finish) is selected.

The ordering data are as follows: 6SL3710-7LE35-0AA3-Z M54+L26+L86+Y09

Cabinet color RAL 3002

### Example 2

#### Task:

A drive system is required for a conveyor belt in a brown-coal open-cast mine that is capable of both motor and generator operation. Since the conveyor belt must be capable of starting after a fault when loaded with bulk material, and it is possible for peak loads to occur where 1.5 times the power is required for up to 60 s, the drive system must be designed according to the overload requirements of such a case. The drive converter is installed in a climate-controlled container as a result of the environmental conditions typical of an open-cast mine. The installation altitude is 320 m above sea level and the maximum ambient temperature in the container is 35 °C. The drive is powered through a converter transformer from the medium-voltage system. The drive is connected to an isolated-neutral system and must have insulation monitoring. A motor with separately-driven fan is selected here as the motor is subject to a high load torque when starting and in the lower range. The fan supply voltage is 690 V and must be drawn from the drive converter. The required motor power is 420 kW.

#### Solution:

Since the converter is installed in an air-conditioned container, it can be designed with degree of protection IP20. The ambient temperature of 35 °C does not necessitate any additional derating. However, due to the specified overload conditions, the base load current  $I_{\rm H}$  (for high overload) must be applied. This results in a power of approx. 520 kW for the drive converter. The converter with article no. 6SL3710-7LG35-8AA3 must be selected.

Option **L87** (insulation monitoring) must be selected for insulation monitoring.

Option **L19** (connection for external auxiliaries) must be selected for the controlled outgoing feeder to power the separately driven fan.

The ordering data are as follows: 6SL3710-7LG35-8AA3-Z L19+L87

### **Description of options**

### Options

#### B00, B02, B03 Options compliant with NAMUR requirements

Exclusion list with other options:

The following restrictions and exclusions applicable to the NAMUR terminal block **B00** with regard to other available options must be taken into account.

Not permis- sible with options	Reason
L45, L57, L59, L60	A Category 0 EMERGENCY OFF is already provided in the NAMUR version. The forced line supply disconnection is connected at terminal -X2: 17, 18.
L83, L84	The <b>B00</b> option already provides a PTC thermistor evaluation unit as standard (trip).
L19	Alternatively, option <b>B03</b> can be selected. This provides a reduced scope for external auxiliaries.
L87	The insulation monitor monitors the complete electrically coupled network. An insulation monitor must therefore be provided on site.
G60	The <b>B00</b> option already provides a Terminal Module TM31 as a standard feature.

With options **L50, L55, L86**, the connection is made as described in the standard. There is no wiring to the NAMUR terminal block.

## B00

## NAMUR terminal block

The terminal block is designed according to the requirements and directives of the standards association for measurement and control in the chemical industry (NAMUR recommendation NE37). I.e. terminals are specifically assigned to particular device functions. The inputs and outputs connected to the terminals fulfill PELV requirements (protective extra-low voltage) with protective separation.

The terminal block and associated functions have been reduced to the necessary minimum. Unlike the NAMUR recommendation, optional terminals are not available.

Terminal -X2:	Meaning	Default	Remarks	
10	DI	ON (dynamic) / ON/OFF (static)	The effective mode can be encoded using a wire jumper at terminal -400: 9; 10 codable	
11	DI	OFF (dynamic)		
12	DI	Faster		
13	DI	Slower		
14	DI	RESET		
15	DI	Interlock		
16	DI	Counter-clockwise	0 signal for CW rotating field 1 signal for CCW rotating field	
17, 18		Supply disconnec- tion	EMERGENCY OFF circuit	
30, 31		Ready	Relay output (NO contact)	
32, 33		Motor is turning	Relay output (NO contact)	
34	DO (NO)	Fault	Relay output	
35	DO (COM)	_	(changeover contact)	
36	DO (NC)	-	,	
50, 51	Al 0/4 20 mA	Speed setpoint		
60, 61	AO 0/4 20 mA	Motor frequency		
62, 63	AO 0/4 20 mA	Motor current	Motor current is default setting; can be reparame- terized for other variables	

The 24 V supply is provided on the plant side via terminals -X2: 1-3 (fused in the converter with 1 A). It must be ensured that the PELV safety requirements are fulfilled (protective extra-low voltage with protective separation).

Terminal -X2:	Meaning	
1	М	Reference conductor
2	P24	24 V DC supply
3	P24	24 V DC outgoing feeder

For temperature monitoring of explosion-proof motors, option **B00** includes a PTC thermistor.

Exceeding the limit value causes a shutdown. The associated PTC sensor is connected to terminal -X3: 90, 91.

Terminal -X3:	Meaning	
90, 91	AI	Connection of PTC sensor

### Options (continued)

**B02** 

### Protective separation for 24 V supply (PELV)

If no protective separation for 24 V supply (PELV) is available at the customer site, this option is used to provide a second power supply to guarantee compliance with PELV. (Terminal assignments as for option **B00**, 24 V supply at terminals -X1:1, 2, 3 is not required)

#### Notice:

The option B02 must always be combined with B00.

#### **B03**

#### Outgoing feeder for external auxiliaries (uncontrolled)

If a motor fan is to be supplied with power from the plant, option **B03** provides an uncontrolled external outgoing feeder with a 10 A fuse. As soon as the supply voltage is present at the converter input, a voltage is also present at these terminals. This corresponds to the converter input voltage ( $U = U_{\text{line}}$ ). You must take this into account when configuring an external fan.

Terminal Meaning -X1:

1, 2, 3, PE Outgoing feeder for exernal auxiliaries

#### Notice:

Option B03 must always be combined with B00.

#### B43, B44, B45 Production flowcharts

Production flowcharts are provided with options **B43** to **B45**. After the order has been clarified, these are emailed as a dual language (English/German) PDF file.

Option	Description
B43	Documentation - Production flowchart: one issue
B44	Documentation - Production flowchart: updated every two weeks
B45	Documentation - Production flowchart: updated every month

### **B55**

# Generation of a preliminary and a final packing list (shipping)

This option provides the electronically editable packing list (possibly predefined from the factory) with the following information in Excel format:

- Number of individual packages
- Type of package (pallet, crate, etc.)
- Weight (unpacked and packed)
- Dimensions (unpacked and packed)
- Delivery location
- Label for package item (when option B56 is ordered)
- · Description of what is in the package

A first packing list is generated after complete technical clarification with preliminary data. When shipped, a final packing list is provided with the actual data.

### **B56**

#### Packed items labeled with a customized label

With this option, customized labels are attached to the unpacked and packed packaged units. Internal customers must provide two labels at least 2 weeks before the shipping date (printout to the factory logistics department, specifying the article number).

### **B**57

#### Photo documentation of the ordered units

This option provides digital photographic documentation with the following content:

- 1 photo diagonally from the front
- 1 photo diagonally from the rear (opposite)
- 1 photo with the packed item on which the label is legible

The listed photos of the packed items are taken in both an unpacked and a packed state in each position (a total of 6 photos per packed item).

### D02

# Customer documentation (circuit diagram, terminal diagram, layout diagram) in DXF format

Option **D02** can be used to order documents such as circuit diagrams, terminal diagrams, layout diagrams, and dimension drawings in DXF format, e.g. for further processing in AutoCAD systems.

## D04

### Customer documentation as hard copy

Device documentation is supplied electronically on a CD-ROM as standard. If the customer also requires a hard copy of the documentation and selects option **D04**, the following documents will be supplied in a folder with the converter:

- Operating instructions
- Circuit diagram
- Terminal diagram
- Layout diagram
- Dimension drawing
- Spare parts list
- Test certificate

Regardless of whether option **D04** is selected, hard copies of the safety and transportation guidelines, a check list and a registration form are always supplied.

### D14

### Preliminary version of customer documentation

If documents such as circuit diagrams, terminal diagrams, layout diagrams and dimension drawings are required in advance for the purpose of system engineering (integration of drive into higher-level systems, interface definition, installation, building planning, etc.), it is possible to order a draft copy of the documentation when ordering the converter cabinet units. These documents are then supplied electronically a few working days following receipt of the order. If the order includes options that fall outside the scope of standard delivery, these will not be covered by the documentation due to the obvious time constraints.

The client is sent the documentation relating to the order by email. The recipient's email address must be specified with the order for this purpose. In the email, the recipient will also receive a link for downloading order-specific documentation.

With the option  $\ensuremath{\text{D02}}$  , the documents are also delivered in DXF format.

### **Description of options**

### Options (continued)

### *D58, D60, D80, D91, D93, D94 Documentation as language package*

If a documentation option is not selected, the relevant documentation is supplied as standard in English/German. When one of the options specified in the table is selected, the standard documentation language will be changed from English/German to the language combination provided by the option.

Language
English/French
English/Spanish
English/Italian
English/Chinese
English/Portuguese (Brazil)
English/Russian

#### D00, D56, D72, D76, D77, D78, D84 Documentation in a single language

The documentation is also available in a single language, for example, to be able to order other language combinations.

If a further language is required for standard documentation in English/German, the option **D74** (documentation in English/German) must also be ordered in addition to that language.

Order code	Language
D00	German
D56	Russian
D72	Italian
D76	English
D77	French
D78	Spanish
D84	Chinese

## 5

#### E11 to E71 Individual certification

The individual certification of the converter by the relevant certification body contains the expansions described in option **M66**.

- E11 Individual certificate from Germanische Lloyd (GL)
- E21 Individual certificate from Lloyds Register (LR)
- **E31** Individual certificate from Bureau Veritas (BV)
- E51 Individual certificate from Det Norske Veritas (DNV)
- **E61** Individual certificate from American Bureau of Shipping (ABS)
- E71 Individual certificate from Chinese Classification Society (CCS)

### Note:

Several individual certificates can be combined.

#### F03, F71, F72, F74, F75, F76, F77, F97 Converter acceptance inspections

Order code	Description				
F03					
FU3	Visual acceptance				
	<ul><li>The inspection includes the following:</li><li>Check of degree of protection</li></ul>				
	<ul> <li>Check of degree of protection</li> <li>Check of equipment (components)</li> <li>Check of equipment identifiers</li> <li>Check of clearance and creepage distances</li> </ul>				
	Check of clearance and creepage distances     Check of cables				
	Check of cables     Check of customer documentation				
	Submission of the acceptance report				
	The tests are carried out with the converter de-energized.				
F71 (witnessed by customer)	Function test without connected motor				
F72 (not witnessed by	After the visual acceptance with the converter switched off, the converter is connected to rated voltage. No current at the converter output end.				
customer)	The inspection includes the following:				
	<ul> <li>Visual acceptance as described for option F03</li> </ul>				
	Check of power supply				
	Check of protective and monitoring devices (simulation)				
	Check of fans				
	Pre-charging test				
	<ul> <li>Function test without connected motor</li> </ul>				
	Submission of the acceptance report				
F74 (not witnessed by	Function test with test bay motor under no-load conditions				
customer) F75 (witnessed by customer)	After the visual acceptance with the converter switched off, the converter is connected to rated voltage. A small current flows at the converter output end in order to operate the test bay motor under no-load conditions. The inspection includes the following:				
	Visual acceptance as described for option F03				
	Check of power supply				
	Check of protective and monitoring devices (simulation)				
	Check of fans				
	Pre-charging test				
	<ul> <li>Function test with test bay motor under no-load conditions</li> </ul>				
	Submission of the acceptance report				
F76 (not	Insulation test				
witnessed by	The inspection includes the following:				
customer) F77 (witnessed	High-voltage test				
by customer)	Measurement of the insulation resistance				
	<ul> <li>Submission of the acceptance report</li> </ul>				
F97	Customer-specific acceptance inspections (on request)				
	If acceptance inspections that are not covered by the options <b>F03</b> , <b>F71</b> , <b>F75</b> , or <b>F77</b> are required, customer-specific acceptance inspections/supplementary tests can be ordered using order code <b>F97</b> on request and following technical clarification.				

#### **Description of options**

### Options (continued)

G20 CBC1

### CBC10 Communication Board

The CBC10 Communication Board is used to connect the CU320-2 Control Unit and thus the SINAMICS S150 to the CAN (Controller Area Network) protocol. The associated driver software fulfills the standards of the following CANopen specification of the CiA organization (CAN in Automation):

- Communication profiles according to DS 301
- Drive profile in accordance with DSP 402 (in this case Profile Velocity Mode)
- EDS (Electronic Data Sheet) in accordance with DSP 306
- Operational state signaling according to DSP 305

The CBC10 Communication Board plugs into the option slot on the CU320-2 Control Unit. The CAN interface on the CBC10 has two SUB-D connections for input and output.

#### It cannot be combined with option G33.

Description of the CBC10 Communication Board  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### G33

#### **CBE20** Communication Board

The CBE20 Communication Board can be used to connect the SINAMICS S150 to a PROFINET IO or Ethernet/IP network via a CU320-2 Control Unit. The CBE Communication Board plugs into the option slot on the CU320-2 Control Unit.

### It cannot be combined with option G20.

#### Note:

Only one communication interface can be used in isochronous operation when the Communication Board CBE20 is used in a Control Unit CU320-2.

- CU320-2 DP: Either the DP interface of the Control Unit or the PN interfaces of the CBE20
- CU320--2 PN: Either the internal PN interfaces or the external PN interfaces of the CBE20

Description of the CBE20 Communication Board  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### G51

#### TM150 temperature sensor evaluation unit

The TM150 Terminal Module is a DRIVE-CLiQ component that is used to acquire and evaluate data from several temperature sensors. The temperature is measured in a temperature range from -99 °C to +250 °C for the following temperature sensors:

- Pt100 (with monitoring for wire breakage and short-circuit)
- Pt1000 (with monitoring for wire breakage and short-circuit)
- KTY84 (with monitoring for wire breakage and short-circuit)
- PTC (with monitoring for short-circuit)
- Bimetallic NC contact (without monitoring)

For the temperature sensor inputs, for each terminal block the evaluation can be parameterized for  $1\times2$ -wire,  $2\times2$ -wire, 3-wire or 4-wire. There is no electrical isolation in the TM150.

A maximum of 12 temperature sensors can be connected to the TM150 Terminal Module.

Description of the TM150 Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

### G60 TM31 Terminal Module

The TM31 Terminal Module is used to expand the customer terminal.

The following additional interfaces are available:

- 8 digital inputs
- 4 bidirectional digital inputs/outputs
- · 2 relay outputs with changeover contact
- 2 analog inputs
- 2 analog outputs
- 1 temperature sensor input (KTY84-130/PTC)
- 2 DRIVE-CLiQ sockets
- 1 connection for the electronics power supply via the 24 V DC supply connector
- 1 PE/protective conductor connection

To simplify configuration and commissioning of the drive, the optional TM31 Terminal Module is already preset with various factory settings, which can then be selected when commissioning the system.

Description of the TM31 Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### G61

#### Additional TM31 Terminal Module

With option **G61**, the number of digital inputs/outputs, as well as the number of analog inputs/outputs in the drive system can be expanded using a second TM31 Terminal Module (in addition to the TM31 Terminal Module that can be selected using option **G60**).

### Note:

Option G61 requires option G60

#### G62

**TB30 Terminal Board** 

The TB30 Terminal Board supports the addition of digital inputs/digital outputs and analog inputs/analog outputs to the Control Unit. The TB30 Terminal Board plugs into the option slot on the Control Unit.

The following are located on the TB30 Terminal Board:

- · Power supply for digital inputs/digital outputs
- 4 digital inputs
- · 4 digital outputs
- 2 analog inputs
- 2 analog outputs

Description of the TB30 Terminal Board  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

### **Description of options**

### Options (continued)

#### K01

#### Safety license for 1 axis

The Safety Integrated Basic Functions do not require a license. However, the Safety Integrated Extended Functions require a license for each axis equipped with safety functions. It is irrelevant which safety functions are used and how many. Option **K01** contains the license for one axis.

Subsequent licensing is possible online via the WEB License Manager by generating a license key:

#### www.siemens.com/automation/license

#### K46

#### SMC10 Sensor Module Cabinet-Mounted

The SMC10 Sensor Module Cabinet-Mounted can be used to simultaneously sense the speed and the rotor position angle. The signals received from the resolver are converted here and made available to the closed-loop controller via the DRIVE-CLiQ interface for evaluation purposes.

The following encoder signals can be evaluated:

- 2-pole resolver
- Multi-pole resolver

The motor temperature can also be measured using KTY84-130 or PTC thermistors.

Description of the SMC10 Sensor Module Cabinet-Mounted  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Encoder system interface.

### K48

#### SMC20 Sensor Module Cabinet-Mounted

The SMC20 Sensor Module Cabinet-Mounted can be used to simultaneously sense the speed and position. The signals received from the incremental encoder are converted here and made available to the closed-loop controller via the DRIVE-CLiQ interface for evaluation purposes.

The following encoder signals can be evaluated:

- Incremental encoder sin/cos 1 V<sub>pp</sub>
- Absolute encoder EnDat 2.1
- SSI encoder with incremental signals sin/cos 1 V<sub>pp</sub>

The motor temperature can also be detected using KTY84-130 or PTC/Pt100 thermistors.

Description of the SMC20 Sensor Module Cabinet-Mounted  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Encoder system interface.

#### K50

### SMC30 Sensor Module Cabinet-Mounted

The SMC30 Sensor Module Cabinet-Mounted can be used to evaluate the encoders of motors without a DRIVE-CLiQ interface. External encoders can also be connected via the SMC30.

The following encoder signals can be evaluated:

- Incremental encoders TTL/HTL with and without open-circuit detection (open-circuit detection is only available with bipolar signals)
- SSI encoders with TTL/HTL incremental signals
- SSI encoders without incremental signals

The motor temperature can also be measured using KTY84-130 or PTC thermistors.

Description of the SMC30 Sensor Module Cabinet-Mounted  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Encoder system interface.

### K51 VSM10 Voltage Sensing Module

The VSM10 Voltage Sensing Module is used to measure the voltage characteristic on the motor side, so that the following function can be implemented:

- Operation of a permanent-magnet synchronous motor without encoder with the requirement to be able to connect to a motor that is already running (flying restart function)
- Quick flying restart of large induction motors: The time for the demagnetization of the motor is eliminated through the measurement of the voltage.

Description of the VSM10 Voltage Sensing Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

### K52

Second SMC30 Sensor Module Cabinet-Mounted

With option **K50**, the cabinet unit contains an SMC30 Sensor Module Cabinet-Mounted. An additional SMC30 (Option **K52**) Sensor Module enables reliable actual-value acquisition when using Safety Integrated Extended Functions (requires a license: Option **K01**).

Detailed and comprehensive instructions and information for the Safety Integrated functions can be found in the associated Function Manual.

#### K82

Terminal Module for controlling the Safe Torque Off and Safe Stop 1 safety functions

The terminal module controls the Safety Integrated Basic Functions Safe Torque Off (STO) and Safe Stop 1 (SS1) (time-controlled) over a wide voltage range from 24 V to 240 V DC/AC (terminology as defined in IEC 61800-5-2).

The integrated safety functions, starting from the Safety Integrated (SI) input terminals of the components (Control Unit and Power Module), satisfy the requirements of EN 61800-5-2, EN 60204-1, EN ISO 13849-1 Category 3 for Performance Level (PL) d and IEC 61508 SIL 2.

With option **K82**, the requirements specified in EN 61800-5-2, EN 60204-1, EN ISO 13849-1 Category 3 for Performance Level (PL) d and IEC 61508 SIL 2 are fulfilled.

The Safety Integrated functions using option  $\mathbf{K82}$  are only available in conjunction with certified components and software versions.

The Safety Integrated functions of SINAMICS are generally certified by independent institutes. An up-to-date list of certified components is available on request from your local Siemens office.

### K87

### TM54F Terminal Module

The Terminal Module TM54F is a terminal expansion module with safe digital inputs and outputs to control the Safety Integrated functions.

The TM54F is directly connected to a Control Unit via DRIVE-CLiQ. Each Control Unit can be assigned precisely to one TM54F.

### **Description of options**

### Options (continued)

Note:

It is not permissible to connect Motor Modules or Line Modules to a TM54F.

The TM54F provides 4 fail-safe digital outputs and 10 fail-safe digital inputs. A fail-safe digital output consists of one 24 V DC switching output, one output switching to ground and one digital input to check the switching state. A fail-safe digital input consists of two digital inputs.

Description of the TM54F Terminal Module  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K88

#### Safe Brake Adapter SBA, 230 V AC

The Safe Brake Control (SBC) is a safety function that is used in safety-relevant applications, for example in presses or rolling mills. In the no-current state, the brake acts on the drive motor using spring force. The brake is released when current flows in it (low active).

The Safe Brake Adapter is already installed in the cabinet unit in the factory. A source of power is connected to terminal -X12 on the Safe Brake Adapter. For control, a connection is established between the Safe Brake Adapter and the Control Interface Module in the factory using a cable harness.

On the plant side, to control the brake, a connection must be established between terminal -X14 on the Safe Brake Adapter and the brake.

Description of the SBA Safe Brake Adapter  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Supplementary system components.

#### K95

### CU320-2 PN Control Unit (PROFINET)

Instead of the CU320-2 DP (PROFIBUS) Control Unit provided as standard, the drive is delivered with a CU320-2 PN Control Unit (PROFINET), including a CompactFlash card.

Description of the CU320-2 Control Unit  $\rightarrow$  SINAMICS S120 chassis format units  $\rightarrow$  System components  $\rightarrow$  Control Units.

#### L00

Use in the first environment according to EN 61800-3, Category C2 (TN/TT supply systems with grounded neutral point)

To limit interference emission, the converter includes as standard a radio interference suppression filter according to the EMC product standard EN 61800-3, Category C3 (use in the industrial environment or in the second environment).

By using the optionally available line filter (option **L00**), up to a motor cable length of 300 m on grounded line supplies, the converters are suitable for use according to Category C2 (residential area or first environment).

However, complying with the limit values in the standard means that all of the relevant installation specifications regarding grounding and shielding must be strictly observed.

Notes on this are provided in the SINAMICS Low Voltage Engineering Manual as well as in the appropriate operating instructions.

### L04

#### Infeed module one level lower

With this option, an infeed (Active Line Module/Active Interface Module) rated one power level lower than the Motor Module (inverter) is used.

For instance, this option is suitable for the following applications:

- When the Motor Module is operated at pulse frequencies greater than the rated pulse frequency, which means that the output power is reduced (current derating as a function of the pulse frequency).
- When the rated power is demanded when generating, and the system losses are covered by the Motor Module.
- When using motors with a higher efficiency and/or a lower power factor when compared to typical standard induction motors.
- The maximum current of the Motor Module is demanded below the maximum power of the unit, e.g. drives with a high breakaway torque.

When using option **L04**, the following restrictions must always be taken into consideration:

- The rated output current of the Motor Module is only available as long as the infeed (Active Line Module) is not loaded with the rated power.
- For line undervoltage conditions, the output power is reduced linearly with the line voltage.
- The unit should be operated with a system power factor  $\cos \varphi = 1$  (this is the factory setting) and should only provide the active power. Additional compensation of reactive power from the power system is not advisable.

Option L04 is available for the following cabinet units:

SINAMICS S150 Type rating converter cabinet at 400 V unit		Permissible currents			
		Output	Input		
			Standard	With option <b>L04</b>	
6SL3710	kW	А	А	А	
Line voltage 380.	480 V 3 AC				
7LE33-1AA3	160	310	310	260	
7LE35-0AA3	250	490	490	380	
7LE36-1AA3	315	605	605	490	
7LE37-5AA3	400	745	745	605	
7LE41-0AA3	560	985	985	840	

#### L07

### dv/dt filter compact plus Voltage Peak Limiter

dv/dt filters compact plus VPL (**V**oltage **P**eak Limiter) limit the voltage rate-of-rise dv/dt to values of < 1600 V/ $\mu$ s and the typical voltage peaks to the following values in accordance with the limit value curve A according to IEC 60034-25: 2007:

- < 1150 V at U<sub>line</sub> < 575 V</li>
- < 1400 V at 660 V <  $U_{\rm line}$  < 690 V

The dv/dt filter compact plus VPL functionally consists of two components that are supplied as a compact mechanical unit, the dv/dt reactor and the voltage limiting network (VPL), which limits voltage peaks and feeds back the energy to the DC link.

### **Description of options**

### Options (continued)

It is so compact that it can be completely integrated into the cabinet, even for high power ratings. An additional cabinet is not reauired.

By using a dv/dt filter compact plus VPL, standard motors with standard insulation and without insulated bearings can be used with supply voltages up to 690 V in converter operation.

The power losses stated in section System components  $\rightarrow$ Motor-side components  $\rightarrow dv/dt$  filter compact plus VPL can be used to determine the total losses for engineering purposes.

dv/dt filters compact plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables 100 m (e.g. Protodur NYCWY)
- Unshielded cables 150 m (e.g. Protodur NYY)

For longer cable lengths (>100 m shielded, >150 m unshielded), the dv/dt filter plus VPL (option L10) should be used.

#### Notice:

- Operation with output frequencies <10 Hz is permissible for</li> max. 5 min.
- The maximum permissible output frequency is 150 Hz.

When using dv/dt filters, restrictions regarding permissible pulse frequencies must be observed.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Note:

L08

- Option L07 cannot be combined with the following options:
- L08 (motor reactor)
- L10 (dv/dt filter plus VPL)
- L15 (sine-wave filter)
- M78 (motor connection from above)

### Motor reactor

Motor reactors reduce the voltage load on the motor windings by reducing the voltage gradients at the motor terminals that occur during converter operation. At the same time, the capacitive charge/discharge currents that place an additional load on the converter output when long motor cables are used, are reduced.

The maximum permissible output frequency when a motor reactor is used is 150 Hz.

The power losses stated in section System components  $\rightarrow$ Motor-side components  $\rightarrow$  Motor reactors can be used to determine the total losses for engineering purposes.

#### Note:

Option L08 cannot be combined with the following options:

- L07 (dv/dt filter compact plus VPL)
- L10 (dv/dt filter plus VPL)
- L15 (sine-wave filter)
- M78 (motor connection from above)

#### L10 dv/dt filter plus Voltage Peak Limiter

A dv/dt filter plus VPL (Voltage Peak Limiter) limits the voltage rate-of-rise dv/dt to values <500 V/µs and the typical voltage peaks to the following values in accordance with the limit value curve according to IEC/TS 60034-17: 2006:

- <1000 V at  $U_{\text{line}}$  < 575 V
- <1250 V at 660 V < U<sub>line</sub> < 690 V

The dv/dt filter plus VPL functionally consists of two components, the dv/dt reactor and the voltage limiting network (VPL), which limits voltage peaks and feeds the energy back to the DC link.

Depending on the converter power, option L10 can be accommodated in the converter cabinet unit or an additional cabinet is required with a width of 400 mm or 600 mm.

Voltage range	Installation of the dv/dt filter plus VPL			
	in the converter	in the additional cabinet		
	(without additional cabinet)	400 mm wide	600 mm wide	
380 480 V	110 250 kW	315 450 kW	560 800 kW	
500 690 V	75 315 kW	400 560 kW	710 1200 kW	

By using a dv/dt filter plus VPL, standard motors with standard insulation and without insulated bearings can be used with supply voltages up to 690 V in converter operation.

dv/dt filters plus VPL are designed for the following maximum motor cable lengths:

- Shielded cables 300 m (e.g. Protodur NYCWY)
- Unshielded cables: 450 m (e.g. Protodur NYY)

For cable lengths <100 m shielded or <150 m unshielded, the dv/dt filter compact plus VPL (option L07) can be used advantageously.

The power losses stated in section System components  $\rightarrow$ Motor-side components  $\rightarrow$  dv/dt filter plus VPL can be used to determine the total losses for engineering purposes.

Notice The maximum permissible output frequency is 150 Hz.

When using dv/dt filters, restrictions regarding permissible pulse frequencies must be observed.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

#### Note:

Parts of option L10 do not have nickel-plated copper busbars.

- Option L10 cannot be combined with the following options:
- L07 (dv/dt filter compact plus VPL)
- L08 (motor reactor)
- L15 (sine-wave filter)
- M78 (motor connection from above)

### Options (continued)

#### L15

### Sine-wave filter

Sine-wave filters are available for converters with a power rating of up to 250 kW (380 V to 480 V). The sine-wave filter at the converter output supplies almost perfect sinusoidal voltages at the motor so that standard motors can be used without special cables or power derating. Standard cables can be used to connect the motor. The max. permissible motor cable length is limited to 300 m.

The power losses stated in section System components  $\rightarrow$ Motor-side components  $\rightarrow$  Sine-wave filter can be used to determine the total losses for engineering purposes.

#### Note:

In conjunction with the option **L15**, the pulse frequency of the converter must be increased. This reduces the power available at the drive converter output (derating factor 0.88). The modulation depth of the output voltage decreases to approx. 85 % (380 V to 480 V). The maximum output frequency is 150 Hz. It should be noted that the reduced voltage at the motor terminals compared with the rated motor voltage means that the motor switches to field weakening mode earlier.

#### Note:

Option L15 cannot be combined with the following options:

- L07 (dv/dt filter compact plus VPL)
- L08 (motor reactor)
- L10 (dv/dt filter plus VPL)
- M78 (motor connection from above)

#### L19

### Connection for external auxiliaries

An outgoing feeder fused with max. 10 A for external auxiliaries (for example, separately driven motor fan).

The voltage is tapped at the converter input upstream of the main contactor / circuit breaker and, therefore, has the same level as the supply voltage.

The outgoing feeder can be switched inside the drive converter or externally.

Terminal -X155:	Meaning	Range
1	L1	380 690 V AC
2	L2	380 690 V AC
3	L3	380 690 V AC
11	Contactor control	230 V AC
12	Contactor control	230 V AC
13	Feedback signal, circuit breaker	230 V AC/0.5 A; 24 V DC/2 A
14	Feedback signal, circuit breaker	230 V AC/0.5 A; 24 V DC/2 A
15	Feedback signal, contactor	230 V AC/6 A
16	Feedback signal, contactor	230 V AC/6 A
PE	PE	-

For more information on engineering, see:

https://support.industry.siemens.com/cs/document/104961375

### L21 Surge suppression

In ungrounded IT systems, the line voltage is not permanently connected to the ground potential because of the missing ground connection of the supply network. Therefore, when a ground fault occurs during operation, a voltage against ground increased by a factor of 2 can occur. For this reason, it is recommended that a surge suppression against ground be installed for operation on IT systems. The surge suppression option includes the installation of line-side surge arresters and upstream fuses for each system phase. The signaling contacts for monitoring the surge arresters are connected in series and connected to a customer interface.

#### Note:

Option L21 does not include the components required to install an insulation monitor for the IT system. An insulation monitor should always be ordered separately as option L87 when the supplying IT system is not monitored at another position (e.g. at the transformer outgoing feeder). Only one insulation monitor can ever be used within the same electrically connected network.

Option **L21** also does not include removal in the factory of the metal bracket that makes the connection to ground of the radio interference suppression filter installed as standard. The metal bracket should therefore be removed during installation or commissioning of the converter if the device is to be operated on an ungrounded IT system.

#### L26 Main switch incl. fuses of

Main switch incl. fuses or circuit breakers

Up to 800 A a switch disconnector with fuses is available as the main switch. For currents greater than 800 A, a circuit breaker provided as standard is used to isolate the drive system from the line supply. The circuit breaker is controlled and supplied within the converter.

Terminal -X50:	Meaning
1	Checkback contact (NO contact) Main switch/circuit breaker closed
2	Checkback contact (NC contact) Main switch/circuit breaker closed
3	Common potential

#### L40

Line filter monitoring

With option **L40**, the filter in the Active Interface Module is monitored for effectiveness against harmonic effects on the system.

The capacitance of the filter capacitors of the integrated filter is continuously calculated and compared with the installed nominal capacitance by measuring the current and voltage in the Active Interface Module. If the calculated capacity deviates by more than the set tolerance, an alarm is triggered.

### **Description of options**

### Options (continued)

#### L45

### EMERGENCY OFF pushbutton installed in the cabinet door

The option **L45** only includes the EMERGENCY OFF pushbutton which is fitted with a protective collar in the cabinet door of the converter. The contacts of the pushbutton are brought out and connected to a terminal block.

The EMERGENCY OFF and/or EMERGENCY STOP functions of Category 0 or 1 can be activated in conjunction with options **L57, L59**, and **L60**.

Terminal -X120:	Meaning
1	Checkback contact of the EMERGENCY OFF pushbutton in the cabinet door
2	Checkback contact of the EMERGENCY OFF pushbutton in the cabinet door
3	Checkback contact of the EMERGENCY OFF pushbutton in the cabinet door $^{1)} \ensuremath{D}$
4	Checkback contact of the EMERGENCY OFF pushbutton in the cabinet door $^{1)} \ensuremath{D}$

#### Notice:

By pressing the EMERGENCY OFF pushbutton, the motor is stopped either uncontrolled or controlled depending on the selected stop Category 0 or 1, and the main voltage disconnected from the motor, in compliance with IEC 60204-1 (VDE 0113). Auxiliary voltages such as the supply for an external fan or anti-condensation heating may still be present. Certain areas within the converter also remain live (under voltage), such as the control or auxiliary equipment. If complete disconnection of all voltages is required, the EMERGENCY OFF pushbutton must be incorporated into a protective system to be implemented by the customer. For this purpose, an NC contact is provided at terminal -X120.

### L50

### Cabinet lighting with service socket

With option **L50**, cabinet lighting is included with an additional service socket for a SCHUKO connector (connector type F) according to CEE 7/4. The power supply for the cabinet lighting and the service socket is external and must be fuse-protected for max. 10 A.

The cabinet lighting consists of an LED hand lamp with On/Off switch and with magnetic fasteners with an approx. 3 m long connecting cable. The lamp is factory-positioned in the cabinet door at a defined marking, and the connecting cable is wound on the associated mount.

#### L55

### Cabinet anti-condensation heating

The anti-condensation heating is recommended at low ambient temperatures and high levels of humidity to prevent condensation. A 100 W cabinet heater is installed in each cabinet section (two heaters are installed per cabinet with cabinet section widths of between 800 mm and 1200 mm).

The power supply for the anti-condensation heating (110 V to 230 V AC, at terminal block -X240) must be provided externally and fused with max. 16 A.

Terminal -X240:	Meaning
1	L1 (110 230 V AC)
2	Ν
3	PE

#### L57 EMERGENCY OFF Category 0, 230 V AC or 24 V DC

EMERGENCY OFF Category 0 for uncontrolled stopping according to EN 60204-1.

The function includes disconnecting the voltage at the converter by means of the line contactor and bypassing the microprocessor controller using a safety combination according to EN 60204-1. The motor then coasts down. When delivered, the pushbutton circuit is preset to 230 V AC. Jumpers must be appropriately set when using 24 V DC.

Terminal -X120:	Meaning
7	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
8	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
15	"ON" for monitored start; remove jumper 15-16!
16	"ON" for monitored start; remove jumper 15-16!
17	Checkback signal, "Safety combination has tripped"
18	Checkback signal, "Safety combination has tripped"

#### L59

### EMERGENCY STOP Category 1, 230 V AC

EMERGENCY STOP Category 1 for controlled stopping according to EN 60204-1.

The function stops the drive using a fast stop along a down ramp that is parameterized by the user. The voltage is then disconnected as described for EMERGENCY OFF Category 0 (option **L57**). The pushbutton circuit is operated at 230 V AC.

In order to maintain the specified stopping times, it may be necessary to use a braking unit.

Terminal -X120:	Meaning
7	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
8	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
15	"ON" for manual start; remove jumper 15-16!
16	"ON" for manual start; remove jumper 15-16!
17	Checkback signal, "Safety combination has tripped"
18	Checkback signal, "Safety combination has tripped"

### Options (continued)

L60

### EMERGENCY STOP Category 1, 24 V DC

EMERGENCY STOP Category 1 for controlled stopping according to EN 60204-1.

The function stops the drive using a fast stop along a down ramp that is parameterized by the user. The voltage is then disconnected as described for EMERGENCY OFF Category 0 (option **L57**). The pushbutton circuit is operated at 24 V DC.

In order to maintain the specified stopping times, it may be necessary to use a braking unit.

Terminal -X120:	Meaning
7	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
8	Loop in the EMERGENCY OFF pushbutton from the plant side; remove jumper 7-8!
15	"ON" for manual start; remove jumper 15-16!
16	"ON" for manual start; remove jumper 15-16!
17	Checkback signal, "Safety combination has tripped"
18	Checkback signal, "Safety combination has tripped"

#### L61, L62, L64, L65 Braking units

Braking units may be required for drives in which motors might operate in generator mode, but have no facility for feeding energy back into the supply system.

The braking unit comprises two components:

- A Braking Module that can be installed in the air discharge of the chassis format power units
- A braking resistor to be mounted externally (degree of protection IP20)

The braking unit functions as an autonomous unit, and does not require an external power supply. During the braking process, the kinetic energy is converted into heat in the externally mounted braking resistor.

A max. cable length of 100 m is permissible between the Braking Module and the braking resistor. This allows the braking resistor to be mounted externally so that heat losses can be dissipated outside the converter enclosure. The braking resistor is connected directly to the terminal -X5 of the converter. The following braking units are available for SINAMICS S150 converter cabinet units:

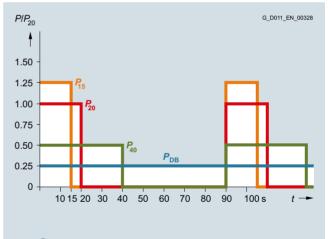
Option	option SINAMICS S150 Braking Module converter							
	Type rating	Rated power P <sub>DB</sub>	Braking power P <sub>20</sub>	Peak power P <sub>15</sub>				
	kW	kW	kW	kW				
380 480	V 3 AC							
L61	110 132	25	100	125				
L62	160 800 50		200	250				
500 600	500 600 V 3 AC							
L64	<b>L64</b> 75 132 25 100 125							
L65	160 1200	50	200	250				
660 690 V 3 AC								
L61	75 132 25 100 125							
L62	160 1200	50	200	250				

P<sub>DB</sub> = Rated power (continuous braking power)

 $P_{20} = 4 \times P_{DB}$ : 20 s power referred to a braking interval of 90 s

 $P_{15} = 5 \times P_{DB}$ : 15 s power referred to a braking interval of 90 s

If more braking power is required than provided by the braking units listed here, then braking units may be connected in parallel for higher converter outputs (on request). In this case, a Braking Module is assigned to each braking resistor.



 $\begin{array}{l} \textbf{P}_{\text{DB}} = \text{Rated power} \\ \textbf{P}_{15} = 5 \text{ x } \textbf{P}_{\text{DB}} = \text{Power which is permissible every 90 s for 15 s} \\ \textbf{P}_{20} = 4 \text{ x } \textbf{P}_{\text{DB}} = \text{Power which is permissible every 90 s for 20 s} \\ \textbf{P}_{40} = 2 \text{ x } \textbf{P}_{\text{DB}} = \text{Power which is permissible every 90 s for 40 s} \end{array}$ 

Load diagram for Braking Modules and braking resistors

Additional notes about possible duty cycles of the braking units and other engineering notes are included in the SINAMICS Low Voltage Engineering Manual.

### **Description of options**

### Options (continued)

#### L83

#### Thermistor motor protection device (alarm)

Thermistor motor protection device for PTC thermistors (PTC resistors, type A) for alarm. The thermistor motor protection device is supplied with power and evaluated internally in the converter.

Terminal -B127:	Meaning
T1	Sensor circuit connection
T2	Sensor circuit connection

**L8**4

### Thermistor motor protection device (trip)

Thermistor motor protection device for PTC thermistors (PTC resistors, type A) for trip. The thermistor motor protection device is supplied with power and evaluated internally in the converter.

Terminal -B125:	Meaning
T1	Sensor circuit connection
T2	Sensor circuit connection

### L86

#### Pt100 evaluation unit

The Pt100 evaluation unit can monitor up to six sensors. The sensors can be connected in a two or three-wire system. The limit values can be freely programmed for each channel.

In the factory setting, the measuring channels are subdivided into two groups, each with 3 channels. With motors, for example, this means that three Pt100s in the stator windings and two Pt100s in the motor bearings can be monitored. Unused channels can be hidden via parameters.

The output relays are integrated into the internal fault and shutdown sequence of the converter.

#### L87

#### Insulation monitoring

An insulation monitor must be used if the converter is connected to an ungrounded line supply. The device monitors the entire galvanically coupled circuit for insulation faults.

An alarm is output in the event of a fault.

#### Notice:

Only **one** insulation monitor can be used in each galvanically coupled network.

As there are different response strategies when a ground fault occurs in an ungrounded system, output relays of the insulation monitor are provided for integration in a plant-side control. The customer can also choose to integrate the outputs into the converter monitoring system.

#### M06 Base 100 mm

### Base 100 mm high, RAL 7022

The additional cabinet base allows larger bending radii for cables (cable inlet from below) and enables them to be routed within the cabinet base.

The cabinet base is supplied in RAL 7022 as standard. A special paint finish is not available for the base. It is delivered completely assembled with the cabinet. The height of the operator panel changes accordingly.

#### M07

#### Cable marshaling compartment 200 mm high, RAL 7035

The cable marshaling compartment is made of strong sheet steel and allows cables to be connected more flexibly (entry from below). It also allows routing of cables within the marshaling compartment. It is delivered completely assembled with the cabinet. The height of the operator panel changes accordingly.

#### Notice:

The cable marshalling compartment is painted as standard with RAL 7035. If a special color is requested for the cabinet (option **Y09**), the cable marshaling compartment is also painted in this color.

#### M13 Line connection from above

The control cabinet is provided with an additional roof section to allow a line connection from above. The connection lugs for the power cables, the clamping bar for mechanically securing the cables, an EMC shield bus, and a PE bar are located within this roof section.

This increases the cabinet height by 405 mm. The busbars for the connection from above are delivered completely preinstalled. For transport reasons, the roof sections are delivered separately and must be fitted on site. Crane transport assemblies (option **M90**) can still be used. However, they must be removed on site before the roof sections can be installed. Use of rope spreaders should be considered in the case of small crane hook heights.

An undrilled aluminum mounting plate (5 mm thick) is provided in the roof section for feeding in the cables. Depending on the number of cables and the cross-sections used, holes for attaching cable glands for feeding in the cables must be drilled in this mounting plate on site.

#### Note:

The control cables are still connected from below. Option **M13** eliminates the lugs, provided as standard, to connect the line supply from below.

The degree of protection of the roof sections is IP21. In combination with options **M23**, **M43** and **M54**, additional plastic ventilation grilles and filter elements are provided.

#### Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. Ventilation grilles used with degrees of protection IP23 and IP54 have color RAL 7035 and cannot be painted.

The covers provided with option **M60** are also included in the scope of supply.

### Options (continued)

M21

### Degree of protection IP21

Cabinet version in IP20, but with additional top covers or canopies. This increases the cabinet height by 250 mm.

For transport reasons, the top covers or canopies are delivered separately and must be fitted on site.

#### Notice:

The top covers or canopies are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the top covers or canopies are also painted in this color.

### M23

### Degree of protection IP23

Converter cabinet units with degree of protection IP23 are supplied with additional roof sections as well as plastic ventilation grilles and a filter medium in the air inlet and outlet. This increases the cabinet height by 400 mm. The covers provided with option **M60** are also included in the scope of supply. The filter medium must be maintained according to the local environmental conditions.

For transport reasons, the roof sections are delivered separately and must be fitted on site.

#### Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

#### M43

#### Degree of protection IP43

Converter cabinet units with IP43 degree of protection are supplied with additional roof sections as well as plastic ventilation grilles and a wire mesh in the air inlet and outlet. This increases the cabinet height by 400 mm. The covers provided with option **M60** are also included in the scope of supply. They are an integral component of the internal cabinet air guidance system and are adapted accordingly.

For transport reasons, the roof sections are delivered separately and must be fitted on site.

#### Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

### M54

#### Degree of protection IP54

Converter cabinet units with IP54 degree of protection are supplied with additional roof sections as well as plastic ventilation grilles and a filter medium in the air inlet and outlet. This increases the cabinet height by 400 mm. The covers provided with option **M60** are also included in the scope of supply. They are an integral component of the internal cabinet air guidance system and are adapted accordingly. The filters must be maintained according to the local environmental conditions.

For transport reasons, the roof sections are delivered separately and must be fitted on site.

#### Notice:

- The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.
- For units with IP54 degree of protection, it is important to observe the derating factor for output currents in relation to ambient temperature and installation altitude.

### M60

#### Additional touch protection

The converter cabinet units are designed as standard according to DGUV regulation 3. Option **M60** provides additional covers (outside arm's reach) in the vicinity of the AC busbars and above the power unit (can only be selected as an option with converters up to 250 kW in the 400 V range and with converters up to 315 kW in the 690 V range with degrees of protection IP20 and IP21; otherwise supplied as standard).

#### M66 Marine version

For compliance with the requirements of the classification institutes:

- Lloyds Register
- American Bureau of Shipping
- Germanischer Lloyd
- Bureau Veritas
- Det Norske Veritas
- China Classification Society

This option includes a strengthened mechanical version of the cabinet, handles (handrail) below the operator panel and mechanical locking of the cabinet doors. The cabinet has degree of protection IP23 (option **M23**) and includes a cabinet anti-condensation heater (option **L55**). To secure the converter to the ship's hull, a welding frame (5 mm high) is supplied separately.

#### Note:

Combination with options **M21**, **M23**, and **L55** is not possible. Individual certification is additionally required if the converter is used for a safety-related drive on the ship (see options **E11** to **E71**).

### **Description of options**

### Options (continued)

#### M70

#### EMC shield bus (cable connection from below)

The EMC shield bus is used to connect shielded line and motor supply cables. With the options **M13** and **M78**, the EMC shield bus is already included as standard for the connection busbars underneath the roof section.

#### M78

#### Motor connection from above

The control cabinet is provided with an additional roof section for a motor connection from above. The connection lugs for the power cables, the clamping bar for mechanically securing the cables, an EMC shield bus, and a PE bar are located within this roof section.

This increases the cabinet height by 405 mm. The busbars for the connection from above are delivered completely preinstalled. For transport reasons, the roof sections are delivered separately and must be fitted on site. Crane transport assemblies (option **M90**) can still be used. However, they must be removed on site before the roof sections can be installed. Use of rope spreaders should be considered in the case of small crane hook heights.

An undrilled aluminum mounting plate (5 mm thick) is provided in the roof section for feeding in the cables. Depending on the number of cables and the cross-sections used, holes for attaching cable glands for feeding in the cables must be drilled in this mounting plate on site.

#### Note:

The control cables are still connected from below. Option **M78** eliminates the lugs, provided as standard, to connect the motor from below.

The degree of protection of the roof sections is IP21. In combination with options **M23**, **M43** and **M54**, additional plastic ventilation grilles and filter elements are provided.

#### Notice:

The roof sections are painted in RAL 7035 as standard. If a special color is requested for the cabinet (option **Y09**), the roof section is also painted in this color. Ventilation grilles used with IP23, IP43 and IP54 degrees of protection are in RAL 7035 and cannot be painted.

The covers provided with option **M60** are also included in the scope of supply.

#### Note:

Option M78 cannot be combined with the following options:

- L07 (dv/dt filter compact plus VPL)
- L08 (motor reactor)
- L10 (dv/dt filter plus VPL)
- L15 (sine-wave filter)

#### M90 Crana transport

### Crane transport assembly (top-mounted)

For single cabinets up to a width of 600 mm, the crane transport assembly consists of transport eyebolts. For cabinet widths of 800 mm and wider, transport rails are used.

#### M91 Marking of all control cable conductor ends

When this option is selected, all control cables or conductor ends (including all customer-specific options) are labeled throughout the cabinet.

#### T58, T60, T80, T83, T85, T91 Rating plate data

The rating plate is provided in English/German as standard. A rating plate in another language combination can be selected by specifying the following option order codes.

Option	Rating plate language
T58	English/French
T60	English/Spanish
T80	English/Italian
T83	English/Portuguese (Brazil)
T85	English/Russian
T91	English/Chinese
Y09	

### Special cabinet paint finish

The converter cabinet units are delivered in RAL 7035 as standard. The special paint finish must be specified in plain text when ordering. All RAL colors which are available as powder coatings can be selected.

#### Notice:

If options such as cable marshaling compartment (option M07), top covers or canopies (option M21), roof sections (options M23/ M43/M54) or cable connection from above (options M13/M78) are ordered for the converter cabinet units, they will also be supplied in the paint finish stated in the order. The molded plastic parts (e.g. ventilation grilles) are in RAL 7035 and cannot be painted.

### **Description of options**

### Options (continued)

Y31

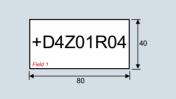
One-line label for system identification, 40 × 80 mm

Resopal labels (white with black lettering) for identifying the control cabinets are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  80 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm



**Y32** 

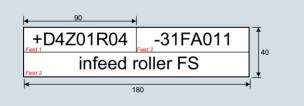
Two-line label for system identification, 40 × 180 mm

Resopal labels (white with black lettering) for identifying the control cabinets are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  180 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm Field 2: Max. 9 characters, font size 10 mm Field 3: Max. 20 characters, font size 10 mm



### Y33

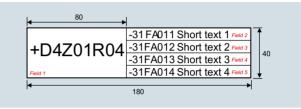
### Four-line label for system identification, 40 × 180 mm

Resopal labels (white with black lettering) for identifying the control cabinets are available. The labels are stuck to the cabinet door.

Dimensions H  $\times$  W: 40  $\times$  180 mm

The text must be specified in plain text when ordering.

Field 1: Max. 9 characters, font size 10 mm Field 2: Max. 20 characters, font size 6 mm Field 3: Max. 20 characters, font size 6 mm Field 4: Max. 20 characters, font size 6 mm Field 5: Max. 20 characters, font size 6 mm



Line-side components - recommended fuses

### Overview

The fuses specified below are the recommended types for protecting the unit on the low-voltage distribution panel. If option **L26** was selected for SINAMICS S150 with rated input currents <800 A, then the semiconductor protection is already integrated in the unit. For units of >800 A, this function is performed by the circuit breaker provided as standard.

In this case, a 3NA fuse can be used in the distribution board. If option **L26** has not been selected for units <800 A, we strongly advise that 3NE fuses are used <sup>1</sup>).

Catalog LV 10 contains additional information on the listed fuses.

Type rating SINAMICS S150 at 400 V or 690 V converter		Cable protection fuse in systems with a fuse switch disconnector			Cable protection fuse (incl. semiconductor protection) in systems <u>without</u> fuse switch disconnector			
At <i>I</i> <sub>L</sub> , 50 Hz 400 V, 500 V or 690 V	At <i>I</i> <sub>L</sub> , 60 Hz 460 V or 575 V			Rated current	Size according to DIN 43620-1		Rated current	Size according to DIN 43620-1
kW	hp	6SL3710	Article No.	А		Article No.	А	
Line voltage	380 480 V 3	AC						
110	150	7LE32-1AA3	3NA3252	315	2	3NE1230-2	315	1
132	200	7LE32-6AA3	3NA3254	355	2	3NE1331-2	350	2
160	250	7LE33-1AA3	3NA3365	500	3	3NE1334-2	500	2
200	300	7LE33-8AA3	3NA3365	500	3	3NE1334-2	500	2
250	400	7LE35-0AA3	3NA3372	630	3	3NE1436-2	630	3
315	500	7LE36-1AA3	3NA3475	800	4	3NE1438-2	800	3
400	600	7LE37-5AA3	3NA3475	800	4	3NE1448-2	850	3
450	700	7LE38-4AA3	-	-	-	Circuit breaker included as standard		
560	800	7LE41-0AA3	-	-	-	Circuit breaker included as standard		
710	1000	7LE41-2AA3	-	-	-	Circuit breaker included as standard		
800	1000	7LE41-4AA3	-	-	-	Circuit breaker included as standard		
Line voltage	500 690 V 3	AC						
75	75	7LG28-5AA3	3NA3132-6	125	1	3NE1022-2	125	00
90	75	7LG31-0AA3	3NA3132-6	125	1	3NE1022-2	125	00
110	100	7LG31-2AA3	3NA3136-6	160	1	3NE1224-2	160	1
132	150	7LG31-5AA3	3NA3240-6	200	2	3NE1225-2	200	1
160	150	7LG31-8AA3	3NA3244-6	250	2	3NE1227-2	250	1
200	200	7LG32-2AA3	3NA3252-6	315	2	3NE1230-2	315	1
250	250	7LG32-6AA3	3NA3354-6	355	3	3NE1331-2	350	2
315	300	7LG33-3AA3	3NA3365-6	500	3	3NE1334-2	500	2
400	400	7LG34-1AA3	3NA3365-6	500	3	3NE1334-2	500	2
450	450	7LG34-7AA3	3NA3352-6	2 × 315	2	3NE1435-2	560	3
560	600	7LG35-8AA3	3NA3354-6	2 × 355	3	3NE1447-2	670	3
710	700	7LG37-4AA3	3NA3365-6	2 × 500	3	3NE1448-2	850	3
800	800	7LG38-1AA3	-	-	-	Circuit breaker in	ncluded as standa	ard
900	900	7LG38-8AA3	-	-	-	Circuit breaker included as standard		
1000	1000	7LG41-0AA3	-	-	-	Circuit breaker included as standard		
1200	1250	7LG41-3AA3	-	-	-	Circuit breaker in	ncluded as standa	ard

Super fast
Lower arc voltage
Improved current limiting (lower let-through values).

### Cable cross-sections and connections

## Overview

The following tables list the recommended and maximum connectable line and motor-side cable cross-sections and connections for a single connection.

The recommended cross-sections are based on the specified fuses. They are valid for a 3-conductor copper cable routed horizontally in air with PVC insulation and a permissible conductor temperature of 70  $^{\circ}$ C (e.g. Protodur NYY or NYCWY) at an ambi-

ent temperature of 40 °C and individual routing. In conditions (cable routing, cable bundling, ambient temperature) that deviate from this the corresponding correction factors according to IEC 60364-5-52 must be considered.

For additional information, please refer to the SINAMICS Low Voltage Engineering Manual.

Type rating at 400 V or 690 V	SINAMICS S150 converter cabinet unit	Line supply o	connection		Motor conne	ection		Cabinet grou	unding
		Recom- mended cross- section <sup>1)</sup>	Maximum conductor cross-section	M12 fixing screw	Recom- mended cross- section <sup>1)</sup>	Maximum conductor cross-section	M12 fixing screw	M12 fixing screw	Remarks
		IEC	IEC	(Number of holes)	IEC	IEC	(Number of holes)	(Number of holes)	
kW	6SL3710	mm <sup>2</sup>	mm <sup>2</sup>		mm <sup>2</sup>	mm <sup>2</sup>			
380 480 V 3	AC								
110	7LE32-1AA3	2 × 70	4 × 240	(2)	2 × 50	2 × 150	(2)	(2)	
132	7LE32-6AA3	2 × 95	4 × 240	(2)	2 × 70	2 × 150	(2)	(2)	
160	7LE33-1AA3	2 × 120	4 × 240	(2)	2 × 95	2 × 150	(2)	(2)	
200	7LE33-8AA3	2 × 120	4 × 240	(2)	2 × 95	2 × 150	(2)	(2)	
250	7LE35-0AA3	2 × 185	4 × 240	(2)	2 × 150	2 × 240	(2)	(2)	
315	7LE36-1AA3	2 × 240	4 × 240	(2)	2 × 185	4 × 240	(2)	(2)	
400	7LE37-5AA3	3 × 185	4 × 240	(2)	2 × 240	4 × 240	(2)	(10)	Cu bar
450	7LE38-4AA3	4 × 150	8 × 240	(4)	3 × 185	4 × 240	(2)	(16)	Cu bar
560	7LE41-0AA3	4 × 185	8 × 240	(4)	4 × 185	6 × 240	(3)	(18)	Cu bar
710	7LE41-2AA3	4 × 240	8 × 240	(4)	4 × 240	6 × 240	(3)	(18)	Cu bar
800	7LE41-4AA3	6 × 185	8 × 240	(4)	6 × 185	6 × 240	(3)	(18)	Cu bar
500 690 V	3 AC								
75	7LG28-5AA3	50	4 × 240	(2)	35	2 × 70	(2)	(2)	
90	7LG31-0AA3	50	4 × 240	(2)	50	2 × 150	(2)	(2)	
110	7LG31-2AA3	70	4 × 240	(2)	70	2 × 150	(2)	(2)	
132	7LG31-5AA3	95	4 × 240	(2)	70	2 × 150	(2)	(2)	
160	7LG31-8AA3	120	4 × 240	(2)	95	2 × 150	(2)	(2)	
200	7LG32-2AA3	2 × 70	4 × 240	(2)	120	2 × 150	(2)	(2)	
250	7LG32-6AA3	2 × 95	4 × 240	(2)	2 × 70	2 × 185	(2)	(2)	
315	7LG33-3AA3	2 × 120	4 × 240	(2)	2 × 95	2 × 240	(2)	(2)	
400	7LG34-1AA3	2 × 185	4 × 240	(2)	2 × 120	4 × 240	(2)	(2)	
450	7LG34-7AA3	2 × 185	4 × 240	(2)	2 × 150	4 × 240	(2)	(2)	
560	7LG35-8AA3	2 × 240	4 × 240	(2)	2 × 185	4 × 240	(2)	(2)	
710	7LG37-4AA3	3 × 185	8 × 240	(4)	3 × 150	6 × 240	(3)	(18)	Cu bar
800	7LG38-1AA3	4 × 150	8 × 240	(4)	3 × 185	6 × 240	(3)	(18)	Cu bar
900	7LG38-8AA3	4 × 150	8 × 240	(4)	4 × 150	6 × 240	(3)	(18)	Cu bar
1000	7LG41-0AA3	4 × 185	8 × 240	(4)	4 × 185	6 × 240	(3)	(18)	Cu bar
1200	7LG41-3AA3	4 × 240	8 × 240	(4)	4 × 240	6 × 240	(3)	(18)	Cu bar

<sup>1)</sup> The recommendations for the North American market in AWG or MCM must be taken from the appropriate NEC (National Electrical Code) and CEC (Canadian Electrical Code) standards.

### Cable cross-sections and connections

### Overview (continued)

### Cable cross-sections for line and motor connection

It is generally recommended to use shielded 3-wire three-phase cables between the converter and motor – and for higher power ratings, symmetrical cables where possible. If required, several of these cables can be connected in parallel. There are two main reasons for this:

- Only then can the high IP55 degree of protection at the motor terminal box be easily achieved. The reason for this is that cables are routed into the terminal box through glands, and the number of possible glands is restricted by the terminal box geometry. Therefore single cables are less suitable.
- With symmetrical 3-wire three-phase cables, the summed ampere-turns over the cable outer diameter are equal to zero. They can easily be routed in conductive, metal cable ducts or racks without any significant currents (ground current or leakage current) being induced in these conductive, metal connections. The danger of induced leakage currents and thus of increased cable sheath losses is significantly higher with single-conductor cables.

The cable cross-section required depends on the current being conducted in the cable. The permissible current load capability of cables is defined, for example in IEC 60364-5-52. It depends partly on the ambient conditions such as temperature, but also on the routing method. It should be taken into account whether cables are individually routed with relatively good cooling, or whether several cables are routed together; in this case, cable ventilation is significantly poorer, which can therefore result in higher cable temperatures. Regarding this topic, reference is made to the corresponding correction factors for these secondary conditions in IEC 60364-5-52.

For 3-wire copper and aluminum cables with PVC insulation and a permissible conductor temperature of 70 °C (e.g. Protodur NYY or NYCWY), as well as an ambient temperature of 40 °C, the cross-sections can be determined from the following table, which is based on IEC 60364-5-52.

Cross-section of 3-wire cable	Copper cable		Aluminum ca	ble
	Individual routing	Several cables next to one another <sup>1)</sup>	Individual routing	Several cables next to one another <sup>1)</sup>
mm <sup>2</sup>	A	А	A	А
3 × 2.5	22	17	17	13
3 × 4.0	30	23	23	18
3 × 6.0	37	29	29	22
3 × 10	52	41	40	31
3 × 16	70	54	53	41
3 × 25	88	69	68	53
3 × 35	110	86	84	65
3 × 50	133	104	102	79
3 × 70	171	133	131	102
3 × 95	207	162	159	124
3 × 120	240	187	184	144
3 × 150	278	216	213	166
3 × 185	317	247	244	190
3 × 240	374	292	287	224

Current-carrying capacity according to IEC 60364-5-52 at 40 °C

Cables must be connected in parallel for higher currents.

#### Note:

The recommendations for the North American market in AWG or MCM must be taken from the appropriate NEC (National Electrical Code) and CEC (Canadian Electrical Code) standards.

#### Grounding and protective conductor cross-section

The protective conductor must be dimensioned taking into account the following data:

- In the case of a ground fault, no impermissibly high contact voltages resulting from voltage drops on the PE conductor caused by the ground fault current may occur (< 50 V AC or < 120 V DC, IEC 61800-5-1, IEC 60364, IEC 60543).</li>
- The protective conductor must not be excessively loaded by any ground fault current it carries.
- If it is possible for continuous currents to flow through the protective conductor when a fault occurs, then the protective conductor cross-section must be dimensioned for this continuous current.
- The protective conductor cross-section must be selected according to EN 60204-1, EN 60439-1, IEC 60364.

Cross-section, line conductor mm <sup>2</sup>	Minimum cross-section, external protective conductor mm <sup>2</sup>
up to 16	Minimum cross-section of line conductor
16 35	16
from 35	Minimum half the cross-section of line conductor

#### Note:

The recommendations for the North American market in AWG or MCM must be taken from the appropriate NEC (National Electrical Code) and CEC (Canadian Electrical Code) standards.

- Switchgear and motors are usually grounded separately via a local grounding electrode. With this constellation, the ground fault current flows via the parallel ground connections and is divided. In spite of the relatively small protective conductor cross-sections used in accordance with the table above, no inadmissible touch voltages occur with this grounding system. However, from experience gained with different grounding constellations, we recommend that the ground cable from the motor return directly to the converter. For EMC reasons and to avoid bearing currents, for large power ratings, it is preferable to use symmetrical 3-wire three-phase cables instead of fourconductor cables. For 3-wire cables, the protective or PE conductor must be routed separately or arranged symmetrically in the motor cable. Symmetry of the PE conductor is achieved using a conductor surrounding all phase conductors or using a cable with a symmetrical arrangement of the three phase conductors and three ground conductors. or additional information, please refer to the SINAMICS Low Voltage Engineering Manual
- Through their high-speed control, the converters limit the load current (motor and ground fault currents) to an rms value corresponding to the rated current. As a result of this fact, we recommend that the cross-section of the protective conductor to ground the cabinets is the same as for the line conductor.

 A maximum of 9 cables may be routed directly next to one another horizontally on a cable tray.

Supplementary system components

Mounting device for power blocks



The mounting device is used for installing and removing the power blocks.

The mounting device is a mounting aid. It is placed in front of the module and attached to the module. The telescopic rails allow the device to be adjusted to the installation height of the power blocks.

Once the mechanical and electrical connections have been released, the power block can be removed from the module.

The power block is guided and supported by the guide rails on the handling device.

## Selection and ordering data

Mounting device for installing and removing power blocks Article No. 6SL3766-1FA00-0AA0

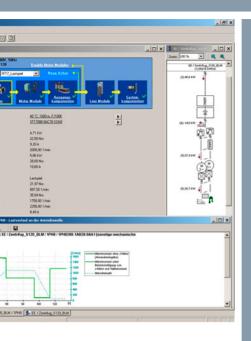
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## **SINAMICS S150 Converter Cabinet Units**

Notes

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## **Tools and Engineering**



### Security information

Siemens provides products and solutions with industrial security functions that support the secure operation of plants, systems, machines and networks.

In order to protect plants, systems, machines and networks against cyber threats, it is necessary to implement – and continuously maintain – a holistic, state-of-the-art industrial security concept. Siemens' products and solutions constitute one element of such a concept.

Customers are responsible for preventing unauthorized access to their plants, systems, machines and networks. Such systems, machines and components should only be connected to an enterprise network or the internet if and to the extent such a connection is necessary and only when appropriate security measures (e.g. firewalls and/or network segmentation) are in place.

For additional information on industrial security measures that may be implemented, please visit

www.siemens.com/industrialsecurity.

Siemens' products and solutions undergo continuous development to make them more secure. Siemens strongly recommends that product updates are applied as soon as they are available and that the latest product versions are used. Use of product versions that are no longer supported, and failure to apply the latest updates may increase customer's exposure to cyber threats.

To stay informed about product updates, subscribe to the Siemens Industrial Security RSS Feed under

www.siemens.com/industrialsecurity.

## Engineering tools

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7 Engineering Manual

Engineering tools

### SinaSave energy efficiency tool

### Overview

The SinaSave energy efficiency tool calculates potential energy savings and amortization times based on your individual conditions of use and therefore offers practical assistance in making decisions about investments in energy-efficient technologies.

From SinaSave Version 6.0 and higher, the drive systems to be compared and the relevant drive component parameters are displayed graphically. An additional expansion are the numerous comparison possibilities for different control types and comprehensive product combinations for drive solutions for pump and fan applications. In addition to SIMOTICS motors and SINAMICS drives, the product portfolio comprises SIRIUS controls, offering a comprehensive range of comparison possibilities – according to your individual requirements.



SinaSave offers numerous comparison scenarios:

- Comparison of drive systems for pump and fan applications in the output range from 0.55 kW (low voltage) to 5.5 MW (medium voltage) for
- Reactor control (fixed speed; motor and switching device)
- Bypass control (fixed speed; motor and switching device)
   Speed control (variable speed; motor and frequency
- speed control (variable speed; motor and frequency converter)
- Comparison and evaluation of standard motors (incl. ignition protection motors) in different energy efficiency classes

SinaSave supports the evaluation of the various comparisons of product and system by

- Displaying the potential savings for energy and energy costs, as well as CO<sub>2</sub> emissions
- Estimation of the amortization time
- · Estimation of the individual total lifecycle costs
- Representation of the system power losses according to EN 50598-2 for full load and partial load
- Direct comparison of Siemens drives with the reference Power Drive System (PDS) described in EN 50598-2



Access to the SinaSave energy efficiency tool

SinaSave can be called up without registration and without a login:

www.automation.siemens.com/sinasave

### More information

For more information about the amortization calculator for energy-efficient drive systems, visit www.siemens.com/sinasave

More information about services for energy saving is available on the Internet at

www.siemens.com/energysaving

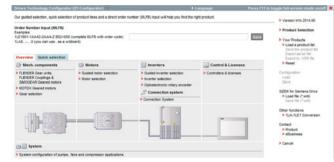
Engineering tools

### **Drive Technology Configurator**

### Overview

The Drive Technology Configurator (DT Configurator) helps you to configure the optimum drive technology products for your appplication – starting with gear units, motors, inverters as well as the associated options and components and ending with controllers, software licenses and connection systems. Whether with little or detailed knowledge of products: preselected product groups, deliberate navigation through selection menus and direct product selection through entry of the product number support quick, efficient and convenient configuration.

In addition, comprehensive documentation comprising technical data sheets, 2D dimensional drawings/3D CAD models, operating instructions, certificates, etc. can be selected in the DT Configurator. Immediate ordering is possible by simply transferring a parts list to the shopping cart of the Industry Mall.



Drive Technology Configurator for efficient drive configuration with the following functions

- Quick and easy configuration of drive products and associated components – gear units, motors, inverters, controllers, connection systems
- Configuration of drive systems for pumps, fans and compressor applications from 1 kW to 2.6 MW
- Retrievable documentation for configured products and components, such as
  - Data sheets in up to 9 languages in PDF or RTF format
  - 2D dimensional drawings/3D CAD models in various formats
  - Terminal box drawing and terminal connection diagram
  - Operating instructions
  - Certificates
  - Start-up calculation for SIMOTICS motors
  - EPLAN macros
- Support with retrofitting in conjunction with Spares On Web (www.siemens.com/sow)
- Ability to order products directly through the Siemens Industry Mall

### Access to the Drive Technology Configurator

The Drive Technology Configurator can be called up without registration and without a login: www.siemens.com/dt-configurator

## Selection and ordering data

Description	Article No.
Interactive catalog CA 01 on DVD-ROM including Drive Technology Configurator, English	E86060-D4001-A510-D8-7600

### More information

Online access to the Drive Technology Configurator

More information about the Drive Technology Configurator is available on the Internet at

www.siemens.com/dtconfigurator

Offline access to the Drive Technology Configurator in the Interactive Catalog CA 01

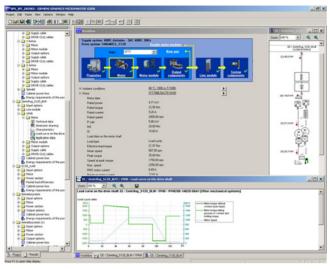
In addition, the Drive Technology Configurator is also included in the Interactive Catalog CA 01 on DVD-ROM – the offline version of the Siemens Industry Mall.

The Interactive Catalog CA 01 can be ordered from the relevant Siemens sales office or via the Internet: www.siemens.com/automation/CA01

Engineering tools

## SIZER for Siemens Drives engineering tool

### Overview



The following drives and controls can be engineered in a userfriendly way using the SIZER for Siemens Drives engineering tool

- SIMOTICS low-voltage motors, including servo geared motors
- SINAMICS low-voltage drive systems
- Motor starters
- SINUMERIK CNC
- SIMOTION Motion Control controller
- SIMATIC controller

It provides support when selecting the technologies involved in the hardware and firmware components required for a drive task. SIZER for Siemens Drives covers the full range of operations required to configure a complete drive system, from basic single-motor drives to complex multi-axis applications.

SIZER for Siemens Drives supports all of the engineering steps in one workflow:

- Configuring the power supply
- Designing the motor and gearbox, including calculation of mechanical transmission elements
- Configuring the drive components
- · Compiling the required accessories
- Selecting the line-side and motor-side power options, e.g. cables, filters, and reactors

When SIZER for Siemens Drives was being designed, particular importance was placed on a high degree of usability and a universal, function-based approach to the drive application. The extensive user guidance makes it easy to use the tool. Status information keeps you continually informed about the progress of the configuration process.

The SIZER for Siemens Drives user interface is available in English, French, German and Italian.

The drive configuration is saved in a project. In the project, the components and functions used are displayed in a hierarchical tree structure.

The project view permits the configuration of drive systems and the copying/inserting/modifying of drives already configured.

The configuration process produces the following results:

- A parts list of the required components (export to Excel, ٠ use of the Excel data sheet for import to SAP)
- Technical specifications of the system
- Characteristic curves
- Comments on system reactions
- Mounting arrangement of drive and control components and dimensional drawings of motors
- Energy requirements of the configured application

These results are displayed in a results tree and can be reused for documentation purposes.

Support is provided by the technological online help menu:

- Detailed technical specifications
- Information about the drive systems and their components
- · Decision-making criteria for the selection of components
- Online help in English, French, German, Italian, Chinese and ٠ Japanese

### System requirements

- PG or PC with Pentium III min. 800 MHz (recommended > 1 GHz)
- 512 MB RAM (1 GB RAM recommended)
- At least 4.1 GB of free hard disk space
- An additional 100 MB of free hard disk space on ٠ Windows system drive
- Screen resolution 1024 × 768 pixels (1280 × 1024 pixels recommended)
- Operating system:
  - Windows 7 Professional (32/64-bit)
    Windows 7 Enterprise (32/64-bit)

  - Windows 7 Ultimate (32/64-bit)
  - Windows 7 Home (32/64-bit)
  - Windows 8.1 Professional (32/64-bit)
  - Windows 8.1 Enterprise (32/64-bit)
- Microsoft Internet Explorer V5.5 SP2

### Selection and ordering data

Description	Article No.
SIZER for Siemens Drives engineering tool on DVD-ROM German, English, French, Italian	6SL3070-0AA00-0AG0

### More information

The SIZER for Siemens Drives engineering tool is available free on the Internet at www.siemens.com/sizer

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Engineering tools

## SIZER WEB ENGINEERING engineering tool

### Overview



The SIZER WEB ENGINEERING tool is used to engineer motors, converters/inverters and drive systems for a broad spectrum of applications within a wide power range starting below 1 kW up to 30 MW and above. To engineer a solution, you need to enter parameters for the motor, converter/inverter or the system – as well as parameters for your own specific application.

When the process is complete, you will receive comprehensive technical documentation (e.g. 3D models) including price information.

An inquiry function integrated in SIZER WEB ENGINEERING allows you to design special solutions for your drive task.

SIZER WEB ENGINEERING fully supports you from the inquiry stage, through the process of engineering products and drive systems, until your own individual quotation is ready. It supplies pricing information and then transfers the engineered products to your shopping cart in the Industry Mall. Seamless support during the engineering process enables you to save time and increase your productivity because you only need to enter the data once. You can use the entered data and the result as a basis for inquiries and orders.

SIZER WEB ENGINEERING is the platform for flexible engineering of your drive tasks and user-friendly management of your projects in conjunction with the engineering tools Drive Technology Configurator and SIZER for Siemens Drives.

### Function



You can quickly find a solution for your drive task with the webbased tool: Menu-prompted workflows navigate you through the technical selection and dimensioning of products and drive systems, including the accessories. Based on an integrated inquiry functionality, SIZER WEB ENGINEERING also offers you special customized solutions for applications which cannot be addressed using "standard products", i.e. the focus is on flexibility and customized solutions.

Furthermore, you can engineer high-voltage motors, mediumvoltage systems and rectifiers for your projects in addition to products from the low-voltage range. Integral tool functions also include comprehensive documentation such as data sheets, start-up calculations for low and high-voltage motors, 2D dimensional drawings and 3D CAD models, and offer documentation to name just a few.

#### Access to the SIZER WEB ENGINEERING engineering tool

SIZER WEB ENGINEERING is available after registration and approval:

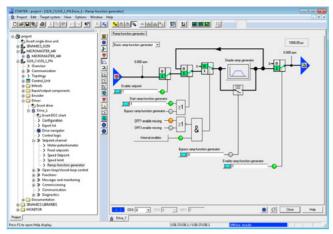
www.siemens.com/sizer-we

#### More information

- More information on the SIZER WEB ENGINEERING engineering tool is available on the Internet at www.siemens.com/sizer-we
- Selection and Engineering Tools: www.siemens.com/engineering-tools

Engineering tools

### Overview



The user-friendly STARTER commissioning tool can be used for:

- Commissioning
- Optimization
- Diagnostics

This software can be operated as a standalone PC application, or integrated as a TIA-compatible program in SIMATIC STEP 7, or highly integrated into the SCOUT Engineering System (for SIMOTION). The basic functions and handling are the same in both cases.

# In addition to the SINAMICS drives, STARTER also supports MICROMASTER 4 devices.

The project wizards can be used to create the drives within the structure of the project tree.

Beginners are supported by solution-based dialog guidance, whereby a standard graphics-based display maximizes clarity when setting the drive parameters.

First commissioning is guided by a wizard which makes all the basic settings in the drive. Therefore, getting a motor up and running is merely a question of setting a few of the drive parameters as part of the drive configuration process.

The individual settings required are made using graphics-based parameterization screens, which also precisely visualize the principle of operation of the drive.

Examples of individual settings that can be made include:

- How terminals are used
- Bus interface
- Setpoint channel (e.g., fixed setpoints)
- Closed-loop speed control (e.g., ramp-function generator, limits)
- BICO interconnections
- Diagnostics

For experts, the expert list can be used to specifically and quickly access individual parameters at any time. An individual compilation of frequently used parameters can be saved in dedicated user lists and watch tables. In addition, the following functions are available for optimization purposes:

- Self-optimization of the controller settings (depending on drive unit)
- Setup and evaluation of trace recordings <sup>1)</sup>
- Tool function for recording  $2 \times 8$  signals with
- Measuring cursor function
- Extensive trigger functions
  Several Y scales
- Sampling times in the current controller cycle clock
- Diagnostics functions provide information about:
- Control/status words
- Parameter status
- Operating conditions
- Communication states

#### Performance features

- User-friendly: Only a small number of settings need to be made for successful first commissioning: The motor starts to rotate
- Solution-oriented dialog-based user guidance simplifies commissioning
- Self-optimization functions reduce manual effort for optimization.

#### Minimum system requirements

The following minimum requirements must be complied with:

- Hardware
  - PG or PC with Pentium III min. 1 GHz
  - (recommended >1 GHz)
  - Work memory 2 GB (4 GB recommended)
  - Screen resolution 1024 × 768 pixels, 16-bit color depth
  - Free hard disk memory: min. 5 GB
- Software
- Microsoft Internet Explorer V6.0 or higher
- 32-bit operating systems: Microsoft Windows 7 Professional incl. SP1 Microsoft Windows 7 Ultimate incl. SP1 Microsoft Windows 7 Enterprise incl. SP1 (standard installation)
   - 64-bit operating systems:
- b4-bit operating systems:
   Microsoft Windows 7 Professional SP1
   Microsoft Windows 7 Ultimate SP1
   Microsoft Windows 7 Enterprise SP1
   (standard installation)
   Microsoft Windows Server 2008 R2 SP1
   Microsoft Windows 10 Pro
   Microsoft Windows 10 Enterprise

### Integration

Data can be exchanged (depending on the version) via PROFIBUS or PROFINET/Ethernet or via a serial interface.

For commissioning and service, a PG/PC can be connected to the CU320-2 Control Unit via PROFIBUS. A PROFIBUS connection must be available with a connecting cable at the PG/PC.

Further, communication between a CU320-2 Control Unit and PG/PC can also be established via Ethernet, either via an (optional) CBE20 Communication Board or the Ethernet interface -X127 on the CU320-2 Control Unit.

### Note:

The terminal strip -X127 is suitable as a communication link to the PG/PC only for the purposes of servicing and commissioning.

<sup>1)</sup> Depending on the drive unit. Not supported for MICROMASTER 4, SINAMICS G110, SINAMICS G120 <firmware V4.4, SINAMICS G110D and SINAMICS G120D <firmware V4.5.</p>

Engineering tools

### **STARTER commissioning tool**

Selection and ordering data	More info

Description

STARTER commissioning tool for SINAMICS and MICROMASTER

Article No. 6SL3072-0AA00-0AG0

English, French, German, Italian, Spanish

Note:

In addition to the STARTER commissioning tool, SINAMICS Drive Control Chart (SINAMICS DCC) can be installed. This allows the device functionality in the SINÁMICS drive system to be expanded with dedicated technology functions as required.

More information about SINAMICS DCC can be found in section "SINAMICS Drive Control Chart (SINAMICS DCC)"

### Accessories

Depending on the version of the Control Unit (CU), the Control Unit of the drive unit can communicate with the programming device (PG) or PC via PROFIBUS or PROFINET/Ethernet or via a serial interface. The following accessories are available for the particular drive system as listed in the following table.

Description		Recommended accessories For communication between the drive unit and the programming device or PC Article No.
SINAMICS S12		
• RS232	SIMATIC S7 connecting cable	6ES7901-1BF00-0XA0
	Null modem cable, 6 m	
PROFIBUS	CP 5711 communication module	6GK1571-1AA00
	USB adapter for connect- ing a PG or notebook to PROFIBUS or MPI	
	USB cable (2 m) included in scope of supply	
	SIMATIC DP plug-in cable	6ES7901-4BD00-0XA0
	12 MBaud, for PG connection, pre-assembled with $2 \times 9$ -pin SUB D connector, 3 m	
PROFINET/ Ethernet	Standard CAT5 Ethernet cable or PROFINET cable	-
SINAMICS S15	0	
PROFIBUS	CP 5711 communication module	6GK1571-1AA00
	USB adapter for connect- ing a PG or notebook to PROFIBUS or MPI	
	USB cable (2 m) included in scope of supply	
	SIMATIC DP plug-in cable	6ES7901-4BD00-0XA0
	12 MBaud, for PG connection, pre-assembled with $2 \times 9$ -pin SUB D connector, 3 m	
PROFINET/ Ethernet	Standard CAT5 Ethernet cable or PROFINET cable	-

<sup>1)</sup> An overview of all the supplementary products (e.g. cables and connectors) that are available for the distributed drives family can be found at the following link: www.siemens.com/distributeddrives-supplementaryproducts

## ormation

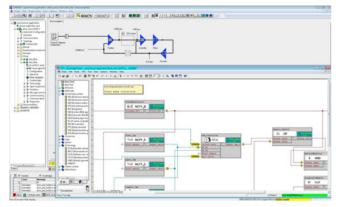
The comissioning tool STARTER is also available on the internet at www.siemens.com/starter

Engineering tools

### SINAMICS Drive Control Chart (SINAMICS DCC)

### Overview

SINAMICS Drive Control Chart (SINAMICS DCC) expands the scope of device functions by means of freely available closed-loop control, arithmetic and logic blocks and offers a means by which proprietary technological functions can be graphically configured in the SINAMICS drive system. In addition, local data processing in the drive supports the implementation of modular machine concepts and results in an increase in the overall machine performance. SINAMICS DCC is a part of the Advanced Technology Function, and is installed as an add-on to the STARTER commissioning tool.



SINAMICS DCC provides users with greater integral scope to adapt systems to the specific functions of their machines. SINAMICS DCC does not limit the number of functions that can be used. The number of functions is limited only by the performance capability of the Control Unit.

SINAMICS DCC is available for the following SINAMICS drive systems:

- SINAMICS G130 and SINAMICS G150
- SINAMICS S120 and SINAMICS S150
- SINAMICS DCM and SINAMICS DCP
- SINAMICS GM150 and SINAMICS SM150
- SINAMICS GL150 and SINAMICS SL150

The user-friendly DCC editor enables easy graphics-based configuration, allows control loop structures to be clearly represented and provides a high degree of reusability of diagrams that have already been created.

The open-loop and closed-loop control functions are defined by using multi-instance-capable blocks (Drive Control Blocks (DCBs)) from a library (DCB library) that are selected and graphically linked with one another by dragging and dropping. Test and diagnostic functions allow the program behavior to be verified and, in the case of a fault, the cause identified.

Two types of DCB library are available, i.e. DCB Standard and DCB Extension. The DCB Standard library supplied with SINAMICS DCC contains a large selection of closed-loop, arithmetic and logic blocks, as well as comprehensive open-loop and closed-loop control functions.

For logically combining, evaluating and acquiring binary signals, all commonly used logic functions are available for selection (AND, XOR, on/off delay, RS flipflop, counter, etc.). A wide range of arithmetic functions, such as absolute value generation, dividers and minimum/maximum evaluation are available to monitor and evaluate numerical quantities.

In addition to the closed-loop drive control, axial winder functions, PI controllers, ramp-function generators or wobble generators are simple to configure.

SINAMICS DCC also offers the DCB Extension library from firmware version V4.6 and higher. This contains an extended range of blocks that is used as an additional, independent library in the DCC Editor. It includes the GMC and Math Extended library.

The GMC contains motion control blocks (GEAR, POSMC, CAMD, etc.).

With Math Extended, supplementary mathematical and logical function blocks (ASIN, ACOS, ATAN, LOG, etc.) are made available.

These libraries are ready for downloading along with application examples from the Siemens Application Support website.

Further information can be found in the Drive Applications section.

As well as the option of using the libraries made available by DCB Extension, DCB Extension proprietary libraries can also be created with custom-programmed blocks. These blocks and libraries are programmed with the separate SINAMICS DCB Studio development tool in the C/C++ high-level language and can be used as your own DCB Extension library in the DCC editor. Use of the DCB Extension blocks requires a runtime license.

The separate SINAMICS DCB Studio development tool is required for programming the blocks and generating the library as a DCB Extension.

Minimum hardware and software requirements

See STARTER commissioning tool.

#### Selection and ordering data

SINAMICS DCC comprises the graphical configuring tool (DCC Editor) and the DCB Standard library. SINAMICS DCC is installed as an add-on to the STARTER commissioning tool.

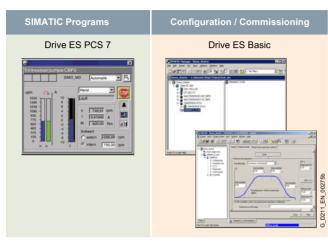
The necessary engineering license for each PC (floating) for SINAMICS DCC is acquired at the same time the order is placed. No runtime license is required for the DCB Standard library included in the scope of supply.

Existing licenses for SINAMICS DCC V2.1, V2.2 SP1 and V2.3 SPx are also valid for SINAMICS DCC V2.4 SP1. An upgrade version including an engineering license for applications with STARTER V4.5 SP1 is available for existing SINAMICS DCC V2.0 SPx.

Description	Article No.
SINAMICS DCC V2.4 SP1 for STARTER V4.5 SP1	
Graphic configuring with SINAMICS DCC DCC Editor + DCB Standard library	
<ul> <li>Single-user engineering license, with data carrier</li> </ul>	6AU1810-1HA24-1XA0
<ul> <li>Upgrade engineering license, with data carrier</li> </ul>	6AU1810-1HA24-1XE0
DCB Extension license Runtime license for license upgrading with firmware version V4.6 or later (can also be ordered in conjunction with the CompactFlash card, see CompactFlash card for CU310-2 and CU320-2 Control Units)	6SL3077-0AA00-0AB0

Engineering tools

## Overview



Drive ES is the engineering system used to integrate the communication, configuration and data management functions of Siemens drive technology into the SIMATIC automation world easily, efficiently and cost-effectively.

The following software packages are available for selection:

- Drive ES Basic (discontinued product)
- Drive ES Basic Maintenance (in preparation)
- Drive ES PCS 7

Drive ES (**D**rive **E**ngineering **S**oftware) fully integrates drives from Siemens into the world of Totally Integrated Automation.

## Design

The following software packages are available for selection:

- Drive ES Basic (discontinued product)
- Drive ES Basic Maintenance (in preparation)
- Drive ES PCS 7 (APL Style or Classic Style)

#### Drive ES Basic (discontinued product)

Drive ES Basic is for first-time users of the world of Totally Integrated Automation and the basic software for setting the parameters of all drives online and offline in this environment. Drive ES Basic enables both the automation system and the drives to be handled using the SIMATIC Manager software. Drive ES Basic is the starting point for common data archiving for complete projects and for extending the use of the SIMATIC teleservice to drives. Drive ES Basic provides the configuration tools for the new motion control functions – slave-to-slave communication, equidistance and isochronous operation with PROFIBUS DP and ensures that drives with PROFINET IO are simply integrated into the SIMATIC environment.

### Note:

For SINAMICS and MICROMASTER 4 drives, this TIA functionality is provided with the STARTER commissioning tool (V4.3.2 and higher).

#### Drive ES Basic Maintenance (in preparation)

This software product will ensure TIA functionality for the previous drive systems not supported by STARTE. Drive ES Basic Maintenance will thus replace the current product Drive ES Basic.

### Drive ES PCS 7 (APL Style or Classic Style)

Drive ES PCS 7 links the drives with a PROFIBUS DP interface into the SIMATIC PCS 7 process control system, and it requires that SIMATIC PCS 7, V6.1 and higher has first been installed. Drive ES PCS 7 provides a block library with blocks for the drives and the corresponding faceplates for the operator station, which enables the drives to be operated from the PCS 7 process control system. From V6.1 and higher, drives will also be able to be represented in the PCS 7 Maintenance Station.

From Drive ES PCS 7 V8.0 and higher, two versions of the library are available: The APL (Advanced Process Library) variant and the previous version in the so-called Classic Style.

Detailed contents of the Drive ES PCS 7 (APL Style or Classic Style)

- Block library for SIMATIC PCS 7 Faceplates and control blocks for SIMOVERT MASTERDRIVES VC and MC, as well as MICROMASTER/MIDIMASTER of the third and fourth generation and SIMOREG DC MASTER and SINAMICS
- STEP 7 slave object manager for convenient configuration of drives and non-cyclic PROFIBUS DP communication with the drives
- STEP 7 device object manager for easy configuration of drives with PROFINET-IO interfaces (V8.0 SP1 and higher)
- SETUP program for installing the software in the PCS 7 environment

Engineering tools

## Drive ES engineering software

## Selection and ordering data

Description	Article No.
Description	Article No.
Drive ES PCS 7 V8.0 SPx *) Block library for PCS 7 for the integration of drives in Classic Style (as predecessor)	
Requirement: PCS 7 V8.0 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
Single-user license incl. 1 runtime license	6SW1700-8JD00-0AA0
Runtime license (without data carrier)	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD00-0AB2
<ul> <li>Upgrade from V6.x to V8.0 SPx *)</li> </ul>	6SW1700-8JD00-0AA4
Drive ES PCS 7 APL V8.0 SPx *)	
Block library for PCS 7 for the integration of drives in APL Style (Advanced Process Library)	
Requirement: PCS 7 V8.0 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
Single-user license incl. 1 runtime license	6SW1700-8JD01-0AA0
<ul> <li>Runtime license (without data carrier)</li> </ul>	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD01-0AB2
<ul> <li>Upgrade of APL V8.0 to V8.0 SP1 or Drive ES PCS7 V6.x, V7.x, V8.x classic to Drive ES PCS7 APL V8.0 SPx *)</li> </ul>	6SW1700-8JD01-0AA4
Drive ES PCS 7 V8.1 SPx *)	
Block library for PCS 7 for the integration of drives in Classic Style (as predecessor)	
Requirement: PCS 7 V8.1 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
• Single-user license incl. 1 runtime license	6SW1700-8JD00-1AA0
Runtime license (without data carrier)	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD00-0AB2
• Upgrade from V6.x/V7.x/V8.x to V8.1 SPx *)	6SW1700-8JD00-1AA4
Drive ES PCS 7 APL V8.1 SPx *)	
Block library for PCS 7 for the integration of drives in APL Style (Advanced Process Library)	
Requirement: PCS 7 V8.1 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
• Single-user license incl. 1 runtime license	6SW1700-8JD01-1AA0
Runtime license (without data carrier)	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD01-0AB2
Upgrade of APL V8.x to V8.1 SPx *) or Drive ES PCS 7 V6.x, V7.x, V8.x classic to Drive ES PCS 7 APL V8.1 SPx *)	6SW1700-8JD01-1AA4

Description	Article No.
Drive ES PCS 7 V8.2 SPx *)	
Block library for PCS 7 for the integration of drives in Classic Style (as predecessor)	
Requirement: PCS 7 V8.2 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
• Single-user license incl. 1 runtime license	6SW1700-8JD00-2AA0
Runtime license (without data carrier)	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD00-0AB2
• Upgrade from V6.x/V7.x/V8.x to V8.2 SPx *)	6SW1700-8JD00-2AA4
Drive ES PCS 7 V8.2 SPx *)	
Block library for PCS 7 for the integration of drives in APL Style (Advanced Process Library)	
Requirement: PCS 7 V8.2 and higher	
Type of delivery: CD-ROM Languages: de, en, fr, it, es with electronic documentation	
• Single-user license incl. 1 runtime license	6SW1700-8JD01-2AA0
Runtime license (without data carrier)	6SW1700-5JD00-1AC0
Update service for single-user license	6SW1700-0JD01-0AB2
• Upgrade of APL V8.x to V8.2 SPx or Drive ES PCS 7 V6.x, V7.x, V8.x classic to Drive ES PCS 7 APL V8.2 SPx ')	6SW1700-8JD01-2AA4
Options	
Drive ES software update service	
A software update service can also be Drive ES software. The user will auton software, service packs and full versio ing.	natically receive the latest
<ul><li>The update service can only be ordere (i.e. previously ordered) full version.</li><li>Period of update service: 1 year</li></ul>	d in addition to an existing

The update service is automatically extended by 1 further year unless canceled up to 6 weeks prior to expiration.

Description	Article No.
Drive ES PCS 7	
<ul> <li>Update service for single-user license</li> </ul>	6SW1700-0JD00-0AB2
Drive ES PCS 7 APL	
Update service for single-user license	6SW1700-0JD01-0AB2

## More information

More information is available on the Internet at www.siemens.com/drive-es

 $^{*)}$  Orders are automatically supplied with the latest Service Pack (SP).

6

Engineering tools

### Overview

Configuring with EPLAN

EPLAN is an engineering software for configuring electrical installations. The EPLAN platform combines expert systems for various disciplines, such as electrical, fluid and EMC engineering (EMC = electrical, measuring and control engineering) as well as control cabinet and plant engineering. It provides the wiring information required to determine the optimal laying routes, connection lengths, bundle diameters, and design of the cable tree.

EPLAN Electric P8 - an EPLAN module - is CAE software specifically for configuring documentation and managing electrical automation projects for machines and systems. EPLAN Electric P8 offers the following functions:

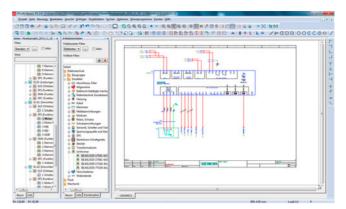
- · Creating circuit diagrams for control cabinets
- · Managing article master data
- Automatic generation of bills of materials, terminal plans, PLC diagrams and overviews
- · Preparation of the documentation for the configured system
- · Design of the mechanical control cabinet configuration

### **EPLAN macros for SINAMICS components**

EPLAN Electric P8 macros are available as downloads without charge, so that SINAMICS components can be easily and cost-effectively integrated into an EPLAN project. Macros are available for the following components:

- SINAMICS G120P, PM330 Power Modules
- SINAMICS G130 built-in units
- SINAMICS S120 chassis units
- SINAMICS DCM DC converters
- Line and motor-side components
- DC link components
- Control Units
- Supplementary system components

Using EPLAN Electric P8 macros substantially shortens the configuration time. All the necessary information about a component is supplied at the press of a button. This ensures that the data is up-to-date and correct - and mistakes/errors can be avoided.



EPLAN user interface

The macros are provided in the file format EDZ (EPLAN Data Archived Zipped). An EDZ file is an archive for article master data, CAx data and macros. A macro in EDZ format contains the following data:

- Internal circuit diagrams
- Wiring diagrams
- Product master data
- Product images
- · Data sheets

EPLAN Electric P8 macros for SINAMICS components are available in the following tools:

- Drive Technology Configurator (www.siemens.com/dt-configurator)
- CAx Onlinemanager
- Image database (download)

### EPLAN projects for SINAMICS converter cabinet units

EPLAN projects are available for SINAMICS converter cabinet units, that simplify the configuration, and save time throughout the entire engineering process. EPLAN projects are available for the following converter cabinet units:

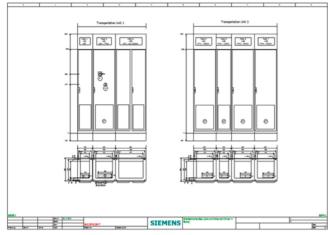
- SINAMICS G120P Cabinet
- SINAMICS G150
- SINAMICS G180
- SINAMICS S120 Cabinet Modules
- SINAMICS S150
- SINAMICS DCM Cabinet

The complete EPLAN project is supplied on a separate DVD-ROM together with the converter. The order is made by stating an additional Article No.

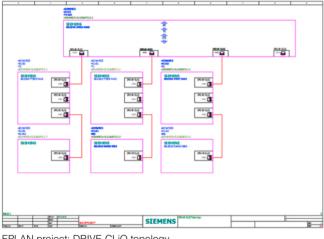
**Engineering tools** 

## **Configuration with EPLAN**

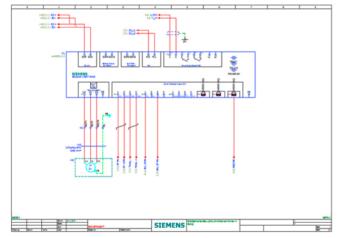
### **Overview** (continued)



EPLAN project: Control cabinet layout



EPLAN project: DRIVE-CLiQ topology



EPLAN project: Circuit diagram

The following data are available when you purchase the DVD-ROM:

- EPLAN project as a ZW1 file
- Updated, customer-specific, project article master database
- List of the Article Nos. created in the project
- A PDF version of the project

The EPLAN project includes the following documentation components:

- Title sheet
- Table of contents
- List of the structure identifiers used
- Single-line diagram
- General layout, external view
- · General layout, internal view
- Circuit diagram
- Terminal diagram
- Connector diagram
- Parts list
- Order list/complete parts list

## Selection and ordering data

### Description

•	
EPLAN Electric P8	6SL3780-0AK00-0AA0
Project documentation on DVD-ROM for:	
<ul> <li>SINAMICS G120 P Cabinet</li> </ul>	
<ul> <li>SINAMICS S120 Cabinet Modules</li> </ul>	
SINAMICS S150	
SINAMICS G150	

Article No.

Planning

### Overview

### General procedure when engineering

The function description of the machine provides the basis for the configuration. The definition of the components is based on physical interdependencies and is usually carried out as follows:

Step	Description of configuration activity
1	Clarification of type of drive
2	Specification of the supplementary conditions and integration in the automation system
3	Definition of the load, calculation of the max. load torque, selection of the motor
4	Definition of the Motor Module
5	Repetition of steps 3 and 4 for additional axes
6	Calculation of the required DC link power and definition of the Line Module
7	Specification of the required control performance and selection of the Control Unit, definition of component cabling
8	Specification of the line-side power options (main switch, fuses, line filters, etc.) and cable cross-sections for system connection and motor connection
9	Definition of additional system components
10	Calculation of the current requirement for the 24 V DC supply for the components and specification of power supplies (SITOP devices, Control Supply Modules)
11	Specification of components for connection system
12	Configuration of drive line-up components
13	Thermal design of the control cabinet

Configuration begins with the mechanical interface to the machine. A suitable motor is selected according to the specified torques and speeds. A matching power unit is then also chosen. Depending on the requirements of the machine, the motor is supplied as a single-motor drive via a Power Module or within a multi-motor drive group via a Motor Module. Once the basic components have been defined, the system components for matching to the electrical and mechanical interfaces are selected.

The SIZER for Siemens Drives engineering tool allows the correct components to be selected quickly and easily. Based on the torque and speed characteristics entered, SIZER for Siemens Drives guides the user through the configuring process, identifying suitable motors and matching SINAMICS power units and other system components.

Important information about SINAMICS S120 components that are needed to create a drive system subject to certain supplementary conditions can be found in the SINAMICS Low Voltage Engineering Manual, and in the online help for the SIZER for Siemens Drives engineering tool.

Engineering information

### EMC notes for applying product standard EN 61800-3

## Overview

The electromagnetic compatibility describes - according to the definition of the EMC Directive - the "capability of a device to work satisfactorily in the electromagnetic environment without itself causing electromagnetic interference which is unacceptable for other devices present in this environment". To guarantee that the appropriate EMC Directives are observed, the devices must demonstrate a sufficiently high noise immunity, and also the emitted interference must be limited to acceptable values.

The product standard EN 61800-3 describes the EMC requirements placed on "Variable-speed drive systems".

A variable-speed drive system (or Power Drive System PDS) consists of the Control Unit and Power Module or Control Unit, Line Module, and Motor Module plus the relevant electric motors and encoders including connecting cables. The driven machine is not part of the drive system.

### Environments

EN 61800-3 defines different limit values depending on the site of installation of the drive system, referred to as the first and second environments.

Residential buildings or locations at which the drive system is directly connected to a public low-voltage supply without intermediate transformer are defined as the **first environment**.

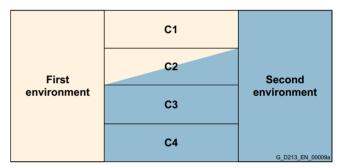
A **second environment** refers to all locations outside residential areas, or industrial sites which are supplied from the medium-voltage network via a separate transformer.

### Categories

Four different categories are defined in EN 61800-3 Ed.2 depending on the installation site and the output power of the drive:

- Category C1: Drive systems for rated voltages <1000 V for unlimited use in the first environment.
- Category C2: Stationary drive systems for rated voltages <1000 V for use in the second environment. Use in the first environment is possible if the drive system is operated and installed by qualified personnel. The warning information and installation instructions supplied by the manufacturer must be observed.
- Category C3: Drive systems for rated voltages <1000 V for exclusive use in the second environment.
- Category C4: Drive systems for rated voltages ≥1000 V or for rated currents ≥400 A for use in complex systems in the second environment. An EMC plan must be drawn up.

The following diagram shows how the four categories are assigned to the first and second environments:



## EMC notes for applying product standard EN 61800-3

## Configuration

The SINAMICS S120 and SINAMICS S150 drive systems are basically suitable for operation in the second environment (Categories C3 and C4). The measures necessary for operation in the first and second environment (Category C2) are listed below.

Measures for complying with product standard EN 61800-3 second environment

### Interference immunity

All SINAMICS S120 drive systems, SINAMICS S120 Cabinet Modules, and SINAMICS S150 are suitable for use in the second environment.

Regarding interference immunity, they can be used in both the **first** and **second environments**.

Interference emission – complying with Category C2 second environment

Regarding interference emission, to comply with the limit values according to EN 61800-3 second environment, Category C2, the following measures must be applied:

- The drive system must be installed in compliance with EMC regulations by appropriately trained professionals.
- The drive system requires a radio interference suppression filter, Category C2 (as optional external line filter with/without line reactor)
- The pulse frequency is less than or equal to the rated pulse frequency
- The maximum motor cable length is complied with (shielded)
- Line supply with grounded neutral point (TN/TT supply system)

Device-specific assignment of the measures to comply with product standard EN 61800-3 second environment, Category C2

SINAMICS S120 chassis			Measures for		
			Radio interference suppression filter, Category C2	Maximum pulse frequency fp	Maximum motor cable length (shielded)
Devices	Line voltage	Frame size		kHz	m
Active Line Modules	380 480 V 3 AC	FX JX GXL JXL <sup>1)</sup>	External line filter required	4 <sup>3)</sup>	300
	500 690 V 3 AC	FX JX HXL and JXL <sup>1)</sup>	External line filter required	4 <sup>3)</sup>	300
Smart Line Modules	380 480 V 3 AC	GX JX	External line filter required	4 <sup>3)</sup>	300
	500 690 V 3 AC	GX JX	External line filter required	4 <sup>3)</sup>	300
Basic Line Modules	380 480 V 3 AC	FB GD FBL and GBL <sup>1)</sup>	External line filter plus line reactor required <sup>2)</sup>	4 <sup>3)</sup>	100
	500 690 V 3 AC	FB GD FBL and GBL <sup>1)</sup>	External line filter plus line reactor required <sup>2)</sup>	4 <sup>3)</sup>	100
Power Modules	380 480 V 3 AC	FX and GX FL and GL <sup>1)</sup>	External line filter plus line reactor required <sup>2)</sup>	2	100

<sup>1)</sup> For liquid-cooled and water-cooled devices on request.

<sup>2)</sup> Selection and ordering data for line filters an line reactors see sections Line-side power components. <sup>3)</sup> Refers to the pulse frequency of the Motor Modules.

Engineering information

### EMC notes for applying product standard EN 61800-3

## Configuration (continued)

SINAMICS S120 Cabinet Mod	lules, air-cooled <sup>1)</sup>		Measures for		
			Radio interference suppression filter, Category C2	Maximum pulse frequency f <sub>p</sub>	Maximum motor cable length (shielded)
Cabinet Modules	Line voltage	Frame size		kHz	m
Line Connection Modules for	380 480 V 3 AC	FX JX	Option L00	4 <sup>3)</sup>	300
Active Line Modules (L42)	500 690 V 3 AC	FX JX	Option L00	4 <sup>3)</sup>	300
Line Connection Modules for	380 480 V 3 AC	GX JX	Option L00	4 <sup>3)</sup>	300
Smart Line Modules ( <b>L44</b> )	500 690 V 3 AC	GX JX	Option L00	4 <sup>3)</sup>	300
Line Connection Modules for	380 480 V 3 AC	FB GD	Option L00 <sup>2)</sup>	4 <sup>3)</sup>	100
Basic Line Modules ( <b>L43</b> )	500 690 V 3 AC	FB GD	Option L00 <sup>2)</sup>	4 <sup>3)</sup>	100

#### SINAMICS S150

			Radio interference suppression filter, Category C2	Maximum pulse frequency f <sub>p</sub>	Maximum motor cable length (shielded)
Converter cabinet units	Line voltage	Frame size		kHz	m
S150	380 480 V 3 AC	FI+FX JI+JX	Option L00	4 <sup>3)</sup>	300
	500 690 V 3 AC	FI+FX JI+JX	Option L00	4 <sup>3)</sup>	300

Measures for

# Interference emission – complying with Category C3 second environment

Covered by Active Interface Modules in chassis format in the standard version of all SINAMICS S120 Cabinet Modules, SINAMICS S150 converter cabinet units, and SINAMICS S120 Line Modules. A line reactor is required for Power Modules in chassis format.

The maximum cable lengths and pulse frequencies (see previous tables) must be taken into consideration.

Interference emission – complying with Category C4 second environment

When connected to IT line supplies, only devices without integrated filter are permissible. To limit symmetrical interference emission, suitable external filters without capacitors connected to ground must be used.

Further selected accessories are available from the "Siemens Product Partner for Drives Options" www.siemens.com/drives-options-partner

### Measures for complying with product standard EN 61800-3 first environment

The SINAMICS S120 drive systems, SINAMICS S120 Cabinet Modules air-cooled, and SINAMICS S150 are basically suitable for use in the second environment.

Regarding interference immunity, they can be used in both the **first and second environments**.

Interference emission - complying with Category C2 first environment

For use in the first environment, **in addition** to the requirements for use in the second environment, device-specific notes to maintain the **harmonic current** limits must be **taken into consideration**.

### More information

Converters are equipment used on a professional basis, deployed in certain areas of business and industry – and are not operated in the general public domain.

Further information on SINAMICS S120 components, SINAMICS S120 Cabinet Modules, and SINAMICS S150, which are needed to create a drive system subject to certain supplementary conditions can be found in the SINAMICS Low Voltage Engineering Manual:

https://support.industry.siemens.com/cs/document/83180185

Here, EMC product standard EN 61800-3 makes reference to the standards pertaining to harmonic currents: EN 61000-3-2 and EN 61000-3-12.

<sup>2)</sup> Option L22 (scope of supply without line reactor) not permissible for use in Category C2 second environment. <sup>3)</sup> Refers to the pulse frequency of the Motor Modules

### Overview



To correctly select and configure the devices listed in this catalog, we would like to refer to the SINAMICS Low Voltage Engineering Manual. This supplements the Catalogs D 11 and D 21.3, and is intended to simplify the handling of SINAMICS series devices.

This manual is only available in electronic form and only in German and English. It is available as a PDF in the Information and Download Center:

https://support.industry.siemens.com/cs/document/83180185

The Engineering Manual contains general information on the basics of variable-speed electric AC drives, as well as detailed system descriptions and direct specifications for the following SINAMICS series devices:

- SINAMICS G130 Drive Converter Chassis Units (Catalog D 11)
- SINAMICS G150 Drive Converter Cabinet Units (Catalog D 11)
- SINAMICS S120 Modular Chassis Units (Catalogs D 21.3 and D 21.4)
- SINAMICS S120 Cabinet Modules (Catalog D 21.3)
- SINAMICS S150 Converter Cabinet Units (Catalog D 21.3)

The Engineering Manual is divided into several sections with different layouts.

The first chapter – Basics and system description – essentially explains the physical basics of variable-speed electric AC drives and provides a generally valid system description of the SINAMICS series devices.

The second chapter – EMC design guideline – discusses the topic of **E**lectromagnetic **C**ompatibility (EMC) and provides all the information required to configure and install drives with the specified SINAMICS devices in compliance with EMC guidelines.

The following chapters – Configuration of the SINAMICS G130, G150, S120 chassis units, S120 Cabinet Modules and S150 devices – discuss device-specific topics, which go beyond the contents of the generally valid system descriptions.

The information provided addresses technically qualified and trained personnel. It is the responsibility of the configuration engineer to evaluate the completeness of the information provided for the respective application. This person also has the final system responsibility for the entire drive or the plant.

Notes

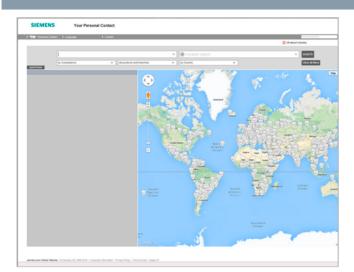
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## **Services and Documentation**



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Partner at Siemens



At Siemens we are resolutely pursuing the same goal: long-term improvement of your competitive ability. We are committed to this goal. Thanks to our commitment, we continue to set new standards in automation and drive technology. In all industries – worldwide.

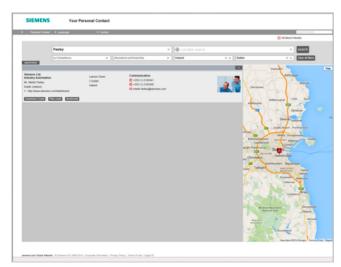
At your service locally, around the globe for consulting, sales, training, service, support, spare parts on the entire portfolio of Digital Factory and Process Industries and Drives.

Your partner can be found in our Personal Contacts Database at: www.siemens.com/automation-contact

### You start by selecting

- the required competence,
- products and branches,
- a country,
- a city
- or by a
- location search or
- person search.





7

Information and Ordering Options on the Internet and DVD

### The Future of Manufacturing on the Internet



Detailed knowledge of the range of products and services available is essential when planning and engineering automation systems. It goes without saying that this information must always be as up-to-date as possible.

Industry is on the threshold of the fourth industrial revolution as digitization now follows after the automation of production. The goals are to increase productivity and efficiency, speed, and quality. In this way, companies can remain competitive on the path to the future of industry.

You will find everything you need to know about products, systems and services on the internet at:

www.siemens.com/industry

### Product Selection Using the Interactive CA 01 Automation and Drives Catalog



#### Easy Shopping with the Industry Mall



Detailed information together with user-friendly interactive functions:

The CA 01 interactive catalog covers more than 100,000 products, thus providing a comprehensive overview of the product range provided by Siemens.

You will find everything you need here for solving tasks in the fields of automation, switching, installation and drives. All information is provided over a user interface that is both user-friendly and intuitive.

You can order the CA 01 product catalog from your Siemens sales contact or in the Information and Download Center:

www.siemens.com/industry/infocenter

Information about the CA 01 interactive catalog can be found on the Internet at:

www.siemens.com/automation/ca01

or on DVD.

The Industry Mall is the electronic ordering platform of Siemens AG on the Internet. Here you have online access to a huge range of products presented in an informative and attractive way.

Data transfer via EDIFACT allows the whole procedure, from selection through ordering to tracking and tracing, to be carried out online. Availability checks, customer-specific discounts and bid creation are also possible.

Numerous additional functions are provided for your support. For example, powerful search functions make it easy to select the required products. Configurators enable you to configure complex product and system components quickly and easily. CAx data types are also provided here.

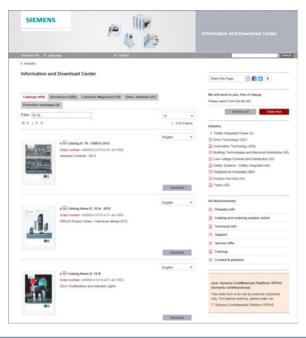
You can find the Industry Mall on the Internet at:

www.siemens.com/industrymall

Online Services

### Information and Download Center, Social Media, Mobile Media

## Downloading Catalogs



In addition to numerous other useful documents, you can also find the catalogs listed on the back inside cover of this catalog in the Information and Download Center. You can download these catalogs in PDF format without having to register.

The filter dialog above the first catalog displayed makes it possible to carry out targeted searches. If you enter "MD 3" for example, you will find both the MD 30.1 and MD 31.1 catalogs. If you enter "IC 10", both the IC 10 catalog and the associated news or add-ons are displayed.

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### Social and Mobile Media



Connect with Siemens through social media: visit our social networking sites for a wealth of useful information, demos on products and services, the opportunity to provide feedback, to exchange information and ideas with customers and other Siemens employees, and much, much more. Stay in the know and follow us on the ever-expanding global network of social media.

To find out more about Siemens' current social media activities, visit us at:

#### www.siemens.com/socialmedia

Or via our product pages at:

www.siemens.com/automation or www.siemens.com/drives

Here you can read all the news on the future of the industry, watch current videos and obtain information about all the latest industry developments.

www.siemens.com/future-of-manufacturing

#### Discover the world of Siemens.

We are also constantly expanding our offering of cross-platform apps for smartphones and tablets. You will find the current Siemens apps at the App Store (iOS) or at Google Play (Android):

https://itunes.apple.com/en/app/siemens/id452698392?mt=8

#### https://play.google.com/store/search?q=siemens

The Siemens app, for example, tells you all about the history, latest developments and future plans of the company – with informative pictures, fascinating reports and the most recent press releases.



### Keep your business running and shaping your digital future - with Industry Services

Optimizing the productivity of your equipment and operations can be a challenge, especially with constantly changing market conditions. Working with our service experts makes it easier. We understand your industry's unique processes and provide the services needed so that you can better achieve your business goals.

You can count on us to maximize your uptime and minimize your downtime, increasing your operations' productivity and reliability. When your operations have to be changed quickly to meet a new demand or business opportunity, our services give you the flexibility to adapt. Of course, we take care that your production is protected against cyber threats. We assist in keeping your operations as energy and resource efficient as possible and reducing your total cost of ownership. As a trendsetter, we ensure that you can capitalize on the opportunities of digitalization and by applying data analytics to enhance decision making: You can be sure that your plant reaches its full potential and retains this over the longer lifespan. You can rely on our highly dedicated team of engineers, technicians and specialists to deliver the services you need – safely, professionally and in compliance with all regulations. We are there for you, where you need us, when you need us.

https://www.siemens.com/global/en/home/products/services/ industry.html

Industry Services

### Industry Services – Portfolio overview

### Overview



Digital Services make your industrial processes transparent to gain improvements in productivity, asset availability, and energy efficiency.

Production data is generated, filtered and translated with intelligent analytics to enhance decision-making.

This is done whilst taking data security into consideration and with continuous protection against cyber-attack threats.

ttps://www.siemens.com/global/en/home/products/services/ industry/digital-services.html



**Industry Online Support** site for comprehensive information, application examples, FAQs and support requests.

**Technical and Engineering Support** for advice and answers for all inquiries about functionality, handling, and fault clearance. The Service Card as prepaid support for value added services such as Priority Call Back or Extended Support offers the clear advantage of quick and easy purchasing.

**Information & Consulting Services**, e.g. SIMATIC System Audit; clarity about the state and service capability of your automation system or Lifecycle Information Services; transparency on the lifecycle of the products in your plants.

https://support.industry.siemens.com/cs/ww/en/sc/2235



From the basics and advanced to specialist skills, SITRAIN courses provide expertise right from the manufacturer – and encompass the entire spectrum of Siemens products and systems for the industry.

Worldwide, SITRAIN courses are available wherever you need a training course in more than 170 locations in over 60 countries.

https://support.industry.siemens.com/cs/ww/en/sc/2226



Spare Parts Services are available worldwide for smooth and fast supply of spare parts – and thus optimal plant availability. Genuine spare parts are available for up to ten years. Logistic experts take care of procurement, transport, custom clearance, storage and order management. Reliable logistics processes ensure that components reach their destination as needed.

Since not all spare parts can be kept in stock at all times, Siemens offers a preventive measure for spare parts provisioning on the customer's premises with optimized **Spare Parts Packages** for individual products, custom-assembled drive components and entire integrated drive trains – including risk consulting.

**Asset Optimization Services** help you design a strategy for parts supply where your investment and carrying costs are reduced and the risk of obsolescence is avoided.

https://support.industry.siemens.com/cs/ww/en/sc/2110

Industry Services - Portfolio overview

### **Overview** (continued)



Repair Services are offered on-site and in regional repair centers for fast restoration of faulty devices' functionality.

Also available are extended repair services, which include additional diagnostic and repair measures, as well as emergency services.

https://support.industry.siemens.com/cs/ww/en/sc/2154



Provide a cost-effective solution for the expansion of entire plants, optimization of systems or upgrading existing products to the latest technology and software, e.g. migration services for automation systems.

Service experts support projects from planning through commissioning and, if desired over the entire extended lifespan, e.g. Retrofit for Integrated Drive Systems for an extended lifetime of your machines and plants.

https://support.industry.siemens.com/cs/ww/de/sc/2286



Siemens specialists are available globally to provide expert field and maintenance services, including commissioning, functional testing, preventive maintenance and fault clearance. All services can be included in customized service agreements with defined reaction times or fixed maintenance intervals.

https://support.industry.siemens.com/cs/ww/en/sc/2265



A technical Service Program or Agreement enables you to easily bundle a wide range of services into a single annual or multiyear agreement.

You pick the services you need to match your unique requirements or fill gaps in your organization's maintenance capabilities.

Programs and agreements can be customized as KPI-based and/or performance-based contracts.

https://support.industry.siemens.com/cs/ww/de/sc/2275

Industry Services

### **Online Support**

## Overview



Siemens Industry and Online Support with some 1.7 million visitors per month is one of the most popular web services provided by Siemens. It is the central access point for comprehensive technical know-how about products, systems and services for automation and drives applications as well as for process industries. In connection with the challenges and opportunities related to digitalization you can look forward to continued support with innovative offerings.

Extension of the liability for defects

## Extension of the liability for defects

We provide the option of extending the liability for defects period beyond the normal period for our SINAMICS S120 Cabinet Modules and SINAMICS S150 cabinet units. The standard liability for defects period, as listed in our standard conditions for the supply of services and products, is 12 months.

### 1. Extended liability for defects when ordering new products

When ordering new products, it is possible to extend the standard liability for defects period for an additional price. Various extension periods can be selected.

Extended liabilit	Extended liability for defects for converters		
Additional ordering data -Z with order code	Additional text		
Q80	Extension of the liability for defects period by 12 months to a total of 24 months (2 years) after being delivered		
Q81	Extension of the liability for defects period by 18 months to a total of 30 months ( $2\frac{1}{2}$ years) after being delivered		
Q82	Extension of the liability for defects period by 24 months to a total of 36 months (3 years) after being delivered		
Q83	Extension of the liability for defects period by 30 months to a total of 42 months ( $3\frac{1}{2}$ years) after being delivered		
Q84	Extension of the liability for defects period by 36 months to a total of 48 months (4 years) after being delivered		
Q85	Extension of the liability for defects period by 48 months to a total of 60 months (5 years) after being delivered		

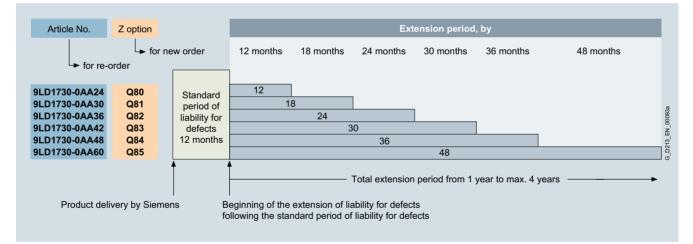
### Overview of the extended liability for defects period

2. Extended liability for defects period after the product has already been delivered

If a product has already been delivered, an extended liability for defects period can be ordered if the original liability for defects period has still not expired. In addition to the article number specified on the rating plate, the serial number must also be stated in the order.

The following article numbers are used:

Extended liability for defects for converters			
Article No.	Text		
<b>9LD1730-0AA24</b> Extension of the liability for defects period by 12 months to a total of 24 months (2 years) after being delivered			
9LD1730-0AA30	Extension of the liability for defects period by 18 months to a total of 30 months (2½ years) after being delivered		
9LD1730-0AA36	Extension of the liability for defects period by 24 months to a total of 36 months (3 years) after being delivered		
9LD1730-0AA42	Extension of the liability for defects period by 30 months to a total of 42 months (3½ years) after being delivered		
9LD1730-0AA48	Extension of the liability for defects period by 36 months to a total of 48 months (4 years) after being delivered		
9LD1730-0AA60	Extension of the liability for defects period by 48 months to a total of 60 months (5 years) after being delivered		



Service & Support

### Extension of the liability for defects

Conditions for an extension of the liability for defects:

- 1. The liability for defects period can be extended only once, i.e. it is not possible to extend an extension. If a product has already been delivered, an extended liability for defects period can only be ordered if the original liability for defects period has still not expired.
- The scope of services provided by an extended liability of defects period includes all material and work expenditure by Siemens for rectification of the damage and, where applicable, all travel costs and expenses.
- 3. For all extension periods of liability for defects, when ordering a new product and when reordering, the final destination of the product must be known (region in which the equipment will be finally installed). Please contact your Siemens representative for the purpose of providing this information.
- 4. The general storage conditions described in the operating instructions must be adhered to, especially the specifications for long-term storage. These specifications must be requested separately from Siemens if necessary.
- 5. Commissioning must be performed by appropriately qualified personnel. When making liability for defect claims, under certain circumstances, it may be necessary to submit the commissioning report to the department making the decision.

- 6. For all liability of defect extensions, all of the regular maintenance intervals must be complied with according to what is specified in the operating instructions. When ordering the appropriate maintenance, this must be carried out by Siemens or by personnel authorized by Siemens. The corresponding maintenance documentation and history must be submitted when making liability for defect claims.
- 7. The operating conditions correspond to the specifications and data provided in the operating instructions, in the engineering manual or special conditions specified in the specific contract.
- 8. The extended liability for defects excludes wearing parts such as fans or filters. This does not apply if it can be clearly proven that the failure is a premature one.
- 9. Otherwise, the general conditions regarding liability for defects applies as agreed in the delivery contract.

## Services and Documentation Training



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#### Contact

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Training

### Range of training courses

## Overview

Range of training courses for the SINAMICS S120 and SINAMICS S150 drive systems

Here you will find an overview of the training courses available for SINAMICS S120 and SINAMICS S150.

The courses are modular in design and are directed at a variety of target groups as well as individual customer requirements.

The system overview will acquaint decision-makers and sales personnel with the system very quickly.

The basic and follow-up courses are guaranteed to provide all of the technical knowledge that service personnel will need for commissioning and service.

All courses contain as many practical exercises as possible in order to enable intensive and direct training on the drive system and with the tools in small groups.

You will find further information about course contents and dates in Catalog ITC and on the Internet.

Title	Target group			Duration	Course code
(all courses are available in English and/or German)	Sales personnel, planners, decision makers	Commissioning engineers, programmers	Service personnel, maintenance technicians		
SINAMICS System Overview	✓	-	-	3 days	DR-SYS
Integrated Drive Systems Introduction and Fundamentals	√	-	-	3 days	DR-IDS
SIMOTICS induction motors Planning and Configuration	√	-	-	3 days	DR-ASM-PL
SINAMICS S120 Designing and Engineering	√	-	-	5 days	DR-S12-PL
SINAMICS S120 Parameterizing and Commissioning	-	✓	-	5 days	DR-S12-PM
SINAMICS S120 Parameterizing Advanced	-	✓	-	5 days	DR-S12-PA
SINAMICS S120 Parameterizing Safety Integrated	-	✓	-	4 days	DR-S12-SAF
SINAMICS S120 Parameterizing and Optimization	-	√	-	3 days	DR-S12-OPT
SINAMICS S120 Diagnostics and Service	-	-	√	5 days	DR-S12-DG
SINAMICS S120 Diagnostics on Chassis and Cabinet Units	-	√	√	3 days	DR-S12-CHA
SINAMICS S120 Diagnostics PROFINET and PROFIBUS	-	√	√	3 days	DR-S12-NET

## Overview

Spares on Web – online identification of spare parts



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Spares on Web is a web-based tool for identifying spare parts. After you have entered the Article No. and serial number, the spare parts available for the relevant unit are displayed.

www.siemens.com/sow

mySupport documentation

### Overview

mySupport documentation – Compiling personal documents



mySupport documentation is a web-based system for generating personalized documentation based on standard documents and is part of the Siemens Industry Online Support portal.

In mySupport, a personal document library can be created in the "Documentation" category. This library can be accessed online in mySupport or also be generated in various formats for offline use.

Previously, this functionality was available in the

My Documentation Manager for configurable manuals. Due to the integration in mySupport, all entries of the Industry Online Support can now be imported into the personal document library, including FAQs or product notifications.

If you have already worked with the My Documentation Manager, all of the previously created libraries will continue to be available without restrictions in mySupport.

In addition, the personal library in mySupport can be shared with other mySupport users. In this way, a collection of relevant documents can be created very effectively and used together with other mySupport users all over the world.

You must register/log in for configuring and generating/ managing.

## Benefits

Display

- View, print or download standard documents or personalized documents
- Configure

Transfer standard documents or parts of them to personalized documents

 Generate/Manage Generate and manage personalized documents in the formats PDF, RTF or XML in all available languages

### Function

Opening mySupport documentation in the Industry Online Support portal

- Via the product support, entry type "Manual": https://support.industry.siemens.com/cs/ww/en/ps/man By clicking on the required version of the manual and then "Show and configure", the manual opens in a modular view, where you can navigate from topic to topic. Here the direct link to a topic can be used and made available to other users. The selected document can be added to the personal library via "mySupport Cockpit" > "Add to mySupport documentation".
- Via the direct link https://support.industry.siemens.com/my/ww/en/ documentation/advanced After registration/logon, the online help is displayed as the current document.

## More information

You can find more information on the Internet at

- https://support.industry.siemens.com/my/ww/en/ documentation
- https://support.industry.siemens.com/cs/helpcenter/en/ index.htm?#persoenliche\_bibliothek\_aufbauen.htm

### Overview

### SINAMICS S120 Cabinet Modules and SINAMICS S150 Converter Cabinet Units

The documentation is provided as standard in PDF format on CD-ROM, and comprises the following sections:

- Description
- · Installation instructions
- Commissioning guide
- Function description
- Maintenance information
- Engineering manual
- · Lists of spare parts
- Equipment-specific documents such as circuit diagrams, dimensional drawings, layout diagrams, and terminal diagrams

Documentation in English/German is supplied as standard with the device.

The scope of delivery also includes a DVD-ROM with the STARTER commissioning tool.

If one of the languages subsequently listed is required, when ordering this should be specified using the corresponding option order code (see Description of options):

Language	Order code
English/French	D58
English/Spanish	D60
English/Italian	D80
English/Chinese	D91
English/Portuguese (Brazil)	D93
English/Russian	D94

Configuring documents/documentation available for downloading at:

For SINAMICS S120 Cabinet Modules https://support.industry.siemens.com/cs/ww/en/ps/13233/man

## For SINAMICS S150

https://support.industry.siemens.com/cs/ww/en/ps/13234/man

SINAMICS S120 Chassis Format Converter Units

Comprehensive documentation is available for the SINAMICS S120 Chassis Format Converter Units including Operating Instructions, List Manuals and the Engineering Manual.

Information is available in the following formats:

- PDF file
- Configuring documents/documentation available for • downloading at: https://support.industry.siemens.com/cs/ww/en/ps/13231/man

## Application

### Explanations for the manuals:

#### **Operating Instructions**

contain all the information needed to install the device and make electrical connections, information about commissioning and a description of the converter functions. Phases of use: Control cabinet construction, commissioning, operation, maintenance and servicing.

#### Manuals •

contain all the necessary information about the intended use of the components of a system, e.g. technical data, interfaces, dimension drawings, characteristic curves and possible applications.

Phases of use: Cabinet configuration/setup, circuit diagram configuration/drawing

### • Engineering Manuals

contain all the information needed for EMC-compliant installation and for the configuration of control cabinets and drive systems.

Phases of use: Control cabinet configuration/construction.

#### List Manuals

describe all parameters, function diagrams and faults/alarms for the product/system as well as their meaning and setting options. It contains parameter data and fault/warning descriptions with functional correlations.

Phases of use: Commissioning of components that have already been connected, configuration of system functions, fault cause/diagnostics.

### **Function Manuals**

contain all the relevant information about individual drive functions.

Phases of use: Commissioning of components that have already been connected, configuration of system functions.

Notes

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## Appendix



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## Certificates of suitability (approvals)

### Overview

Many of the products in this Catalog fulfill requirements, e.g. for UL, CSA or FM and are labeled with the corresponding approval designation.

All of the certificates of suitability, approvals, certificates, declarations of conformity, test certificates, e.g. CE, UL, Safety Integrated etc. have been performed with the associated system components as they are described in the Catalogs and Configuration Manuals.

The certificates are only valid if the products are used with the described system components, are installed according to the Installation Guidelines and used for their intended purpose.

In other cases, the vendor of these products is responsible for arranging for the issue of new certificates.

Test code	Tested by	Device series/ component	Test standard	Product category/ File-No.
	iters Laboratories public testing body in North Americ	a		
	UL according to UL standard	SINUMERIK	Standard UL 508, CSA C22.2 No. 142	NRAQ/7.E164110 NRAQ/7.E217227
0		SIMOTION	Standard UL 508, CSA C22.2 No. 142	NRAQ/7.E164110
c (UL)	UL according to CSA standard	SINAMICS	Standard UL 508, 508C, 61800-5-1 CSA C22.2 No. 142, 274	NRAQ/7.E164110, NMMS/2/7/8.E192450, NMMS/2/7/8.E203250, NMMS/7.E214113, NMMS/7.E253831
	UL according to UL and CSA standards			NMMS/2/7/8.E121068
				NMMS/7.E355661
				NMMS/7.E323473
ЯĽ	UL according to UL standard	SIMODRIVE	Standard UL 508C, CSA C22.2 No. 274	NMMS/2/7/8.E192450 NMMS/7.E214113
د <i>91</i> °،	UL according to CSA standard UL according to UL and CSA standards	Motors	Standard UL 1004-1, 1004-6, 1004-8, CSA C22.2 No. 100	PRGY2/8.E227215 PRHZ2/8.E93429 PRHJ2/8.E342747 PRGY2/8.E253922
	OL and CSA standards			PRHZ2/8.E342746
		Line/motor reactors	Standard UL 508, 506, 5085-1, 5085-2, 1561, CSA C22.2 No. 14, 47, 66.1-06, 66.2-06	XQNX2/8.E257859 NMTR2/8.E219022 NMMS2/8.E333628 XPTQ2/8.E257852 XPTQ2/8.E103521 NMMS2/8.E224872 XPTQ2/8.E354316 XPTQ2/8.E198309 XQNX2/8.E475972
		Line filters, dv/dt filters, sine-wave filters	UL 1283, CSA C22.2 No. 8	FOKY2/8.E70122
		Resistors	UL 508, 508C, CSA C22.2 No. 14, 274	NMTR2/8.E224314 NMMS2/8.E192450 NMTR2/8.E221095 NMTR2/8.E226619
Independent TÜV: TÜV SÜ	einland of North America Inc. public testing body in North Americ D Product Service public testing body in Germany, Nat		- Testing Laboratory (NRTL) ng Laboratory (NRTL) for North America	
	TUV according to UL and CSA standards	SINAMICS	NRTL listing according to standard UL 508C	U7V 12 06 20078 013 U7 11 04 20078 009 U7 11 04 20078 010 U7 11 04 20078 011
		SIMOTION	NRTL listing according to standard UL 508	U7V 13 03 20078 01
		SIMODRIVE	NRTL listing according to standard UL 508C, CSA C22.2. No. 14	CU 72090702
		Motion Control Encoder	NRTL listing according to UL 61010-1 CSA C22.2 No. 61010-1	U8V 10 06 20196 024

Certificates of suitability (approvals)

Test code	Tested by	Device series/ component	Test standard	Product category/ File-No.
	dian Standards Association ht public testing body in Canada			
SP°	CSA according to CSA standard	SINUMERIK	Standard CSA C22.2 No. 142	2252-01 : LR 10252
	tory Mutual Research Corporation ht public testing body in North Ameri	ca		
FM	FM according to FM standard	SINUMERIK	Standard FMRC 3600, FMRC 3611, FMRC 3810, ANSI/ISA S82.02.1	-
	vo-Certificate nt public testing body in the Russian	Federation		
EAC	EAC in accordance with the EAC Directive	SINAMICS SINUMERIK SIMOTION	Standard IEC 61800-5-1/-2, IEC 61800-3	_
	ralian Communications and Media Au nt public testing body in Australia	thority		
$\bigcirc$	RCM according to EMC standard	SINAMICS SINUMERIK SIMOTION	Standard IEC AS 61800-3, EN 61800-3	_
	al Radio Research Agency nt public testing body in South Korea			
C	KC according to EMC standard	SINAMICS SINUMERIK SIMOTION	Standard KN 11	_
BIA Federal Ins	titute for Occupational Safety			
-	Functional safety	SINAMICS SINUMERIK SIMOTION	Standard EN 61800-5-2	-
TÜV SÜD R	ail			
-	Functional safety	SINAMICS SINUMERIK SIMOTION	Standard EN 61800-5-2	-

More information about certificates can be found online at: https://support.industry.siemens.com/cs/ww/en/ps/cert

### Software licenses

## Overview

### Software types

Software requiring a license is categorized into types. The following software types have been defined:

- Engineering software
- Runtime software

#### Engineering software

This includes all software products for creating (engineering) user software, e.g. for configuring, programming, parameterizing, testing, commissioning or servicing.

Data generated with engineering software and executable programs can be duplicated for your own use or for use by thirdparties free-of-charge.

### Runtime software

This includes all software products required for plant/machine operation, e.g. operating system, basic system, system expansions, drivers, etc.

The duplication of the runtime software and executable programs created with the runtime software for your own use or for use by third-parties is subject to a charge.

You can find information about license fees according to use in the ordering data (e.g. in the catalog). Examples of categories of use include per CPU, per installation, per channel, per instance, per axis, per control loop, per variable, etc.

Information about extended rights of use for parameterization/configuration tools supplied as integral components of the scope of delivery can be found in the readme file supplied with the relevant product(s).

#### License types

Siemens Industry Automation & Drive Technologies offers various types of software license:

- · Floating license
- Single license
- Rental license
- · Rental floating license
- Trial license
- Demo license
- Demo floating license

#### Floating license

The software may be installed for internal use on any number of devices by the licensee. Only the concurrent user is licensed. The concurrent user is the person using the program. Use begins when the software is started. A license is required for each concurrent user.

#### Single license

Unlike the floating license, a single license permits only one installation of the software per license.

The type of use licensed is specified in the ordering data and in the Certificate of License (CoL). Types of use include for example per instance, per axis, per channel, etc.

One single license is required for each type of use defined.

#### **Rental license**

A rental license supports the "sporadic use" of engineering software. Once the license key has been installed, the software can be used for a specific period of time (the operating hours do not have to be consecutive).

One license is required for each installation of the software.

#### Rental floating license

The rental floating license corresponds to the rental license, except that a license is not required for each installation of the software. Rather, one license is required per object (for example, user or device).

#### Trial license

A trial license supports "short-term use" of the software in a nonproductive context, e.g. for testing and evaluation purposes. It can be transferred to another license.

#### Demo license

The demo license support the "sporadic use" of engineering software in a non-productive context, for example, use for testing and evaluation purposes. It can be transferred to another license. After the installation of the license key, the software can be operated for a specific period of time, whereby usage can be interrupted as often as required.

One license is required per installation of the software.

#### Demo floating license

The demo floating license corresponds to the demo license, except that a license is not required for each installation of the software. Rather, one license is required per object (for example, user or device).

### Certificate of License (CoL)

The CoL is the licensee's proof that the use of the software has been licensed by Siemens. A CoL is required for every type of use and must be kept in a safe place.

### Downgrading

The licensee is permitted to use the software or an earlier version/release of the software, provided that the licensee owns such a version/release and its use is technically feasible.

### **Delivery versions**

Software is constantly being updated. The following delivery versions

- PowerPack
- Upgrade

can be used to access updates.

Existing bug fixes are supplied with the ServicePack version.

#### **PowerPack**

PowerPacks can be used to upgrade to more powerful software. The licensee receives a new license agreement and CoL (Certificate of License) with the PowerPack. This CoL, together with the CoL for the original product, proves that the new software is licensed.

A separate PowerPack must be purchased for each original license of the software to be replaced.

#### Upgrade

An upgrade permits the use of a new version of the software on the condition that a license for a previous version of the product is already held.

The licensee receives a new license agreement and CoL with the upgrade. This CoL, together with the CoL for the previous product, proves that the new version is licensed.

A separate upgrade must be purchased for each original license of the software to be upgraded.

## Overview

### ServicePack

ServicePacks are used to debug existing products. ServicePacks may be duplicated for use as prescribed according to the number of existing original licenses.

#### License key

Siemens Industry Automation & Drive Technologies supplies software products with and without license keys.

The license key serves as an electronic license stamp and is also the "switch" for activating the software (floating license, rental license, etc.).

The complete installation of software products requiring license keys includes the program to be licensed (the software) and the license key (which represents the license).

### Software Update Service (SUS)

As part of the SUS contract, all software updates for the respective product are made available to you free of charge for a period of one year from the invoice date. The contract will automatically be extended for one year if it is not canceled three months before it expires.

The possession of the current version of the respective software is a basic condition for entering into an SUS contract.

You can download explanations concerning license conditions from www.siemens.com/automation/salesmaterial-as/catalog/en/terms\_of\_trade\_en.pdf

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## Conversion tables

Rotary iner	r <b>tia</b> (to convert	from A to B	, multiply by	/ entry in tat	ole)					
A	B lb-in <sup>2</sup>	lb-ft <sup>2</sup>	lb-in-s <sup>2</sup>	lb-ft-s <sup>2</sup> slug-ft <sup>2</sup>	kg-cm <sup>2</sup>	kg-cm-s <sup>2</sup>	gm-cm <sup>2</sup>	gm-cm-s <sup>2</sup>	oz-in <sup>2</sup>	oz-in-s <sup>2</sup>
lb-in <sup>2</sup>	1	$6.94 \times 10^{-3}$	$2.59 \times 10^{-3}$	$2.15 \times 10^{-4}$	2.926	$2.98 \times 10^{-3}$	$2.92 \times 10^{3}$	2.984	16	4.14×10
b-ft <sup>2</sup>	144	1	0.3729	3.10 × 10 <sup>-2</sup>	421.40	0.4297	$4.21 \times 10^{5}$	429.71	2304	5.967
b-in-s <sup>2</sup>	386.08	2.681	1	$8.33 \times 10^{-2}$	1.129×10 <sup>3</sup>	1.152	1.129×10 <sup>6</sup>	1.152×10 <sup>3</sup>	$6.177 \times 10^{3}$	16
b-ft-s <sup>2</sup> slug-ft <sup>2</sup>	4.63 × 10 <sup>3</sup>	32.17	12	1	1.35×10 <sup>4</sup>	13.825	1.355 × 10 <sup>7</sup>	1.38 × 10 <sup>4</sup>	7.41 × 10 <sup>4</sup>	192
kg-cm <sup>2</sup>	0.3417	$2.37 \times 10^{-3}$	$8.85 \times 10^{-4}$	$7.37 \times 10^{-5}$	1	$1.019 \times 10^{-3}$	1000	1.019	5.46	$1.41 \times 10^{-1}$
kg-cm-s <sup>2</sup>	335.1	2.327	0.8679	7.23×10 <sup>-2</sup>	980.66	1	$9.8 \times 10^{5}$	1000	5.36×10 <sup>3</sup>	13.887
gm-cm <sup>2</sup>	3.417 × 10 <sup>-4</sup>	2.37 × 10 <sup>-6</sup>	$8.85 \times 10^{-7}$	$7.37 \times 10^{-8}$	1 × 10 <sup>-3</sup>	1.01 × 10 <sup>-6</sup>	1	1.01 × 10 <sup>-3</sup>	$5.46 \times 10^{-3}$	$1.41 \times 10^{-1}$
gm-cm-s <sup>2</sup>	0.335	2.32×10 <sup>-3</sup>	$8.67 \times 10^{-4}$	7.23 × 10 <sup>-5</sup>	0.9806	1 × 10 <sup>-3</sup>	980.6	1	5.36	1.38×10
oz-in <sup>2</sup>	0.0625	$4.34 \times 10^{-4}$	$1.61 \times 10^{-4}$	$1.34 \times 10^{-5}$	0.182	$1.86 \times 10^{-4}$	182.9	0.186	1	$2.59 \times 10^{-10}$
oz-in-s <sup>2</sup>	24.13	0.1675	$6.25 \times 10^{-2}$	$5.20 \times 10^{-3}$	70.615	$7.20 \times 10^{-2}$	$7.09 \times 10^{4}$	72.0	386.08	1

## **Torque** (to convert from A to B, multiply by entry in table)

А	B lb-in	lb-ft	oz-in	N-m	kg-cm	kg-m	gm-cm	dyne-cm
lb-in	1	8.333 × 10 <sup>-2</sup>	16	0.113	1.152	1.152 × 10 <sup>-2</sup>	1.152×10 <sup>3</sup>	1.129×10 <sup>6</sup>
lb-ft	12	1	192	1.355	13.825	0.138	$1.382 \times 10^{4}$	1.355 × 10 <sup>7</sup>
oz-in	6.25 × 10 <sup>-2</sup>	$5.208 \times 10^{-3}$	1	$7.061 \times 10^{-3}$	$7.200 \times 10^{-2}$	$7.200 \times 10^{-4}$	72.007	$7.061 \times 10^{4}$
N-m	8.850	0.737	141.612	1	10.197	0.102	$1.019 \times 10^{4}$	1 × 10 <sup>7</sup>
kg-cm	0.8679	7.233×10 <sup>-2</sup>	13.877	9.806 × 10 <sup>-2</sup>	1	10 <sup>-2</sup>	1000	9.806 × 10 <sup>5</sup>
kg-m	86.796	7.233	1.388×10 <sup>3</sup>	9.806	100	1	1 × 10 <sup>5</sup>	$9.806 \times 10^{7}$
gm-cm	$8.679 \times 10^{-4}$	7.233×10 <sup>-5</sup>	1.388×10 <sup>-2</sup>	$9.806 \times 10^{-5}$	1 × 10 <sup>-3</sup>	1 × 10 <sup>-5</sup>	1	980.665
dyne-cm	$8.850 \times 10^{-7}$	7.375 × 10 <sup>-8</sup>	1.416×10 <sup>-5</sup>	10 <sup>-7</sup>	1.0197 × 10 <sup>-6</sup>	1.019×10 <sup>−8</sup>	1.019×10 <sup>-3</sup>	1

Length (to c	con	vert from	n A to B,	multip	ly by entry	in table	e)
А	В	inches	feet	cm	yd	mm	m
inches		1	0.0833	2.54	0.028	25.4	0.0254
feet		12	1	30.48	0.333	304.8	0.3048
cm		0.3937	0.03281	1	1.09 × 10 <sup>-2</sup>	10	0.01
yd		36	3	91.44	1	914.4	0.914
mm		0.03937	0.00328	0.1	1.09 × 10 <sup>-3</sup>	1	0.001
m		39.37	3.281	100	1.09	1000	1

Force	(to con	vert from	A to B, mul	tiply by	entry in tabl	e)
A	B lb		OZ	gm	dyne	Ν
lb	1		16	453.6	$4.448 \times 10^{5}$	4.4482
OZ	0.0	)625	1	28.35	$2.780 \times 10^{4}$	0.2780
gm	2.2	$205 \times 10^{-3}$	0.03527	1	1.02 × 10 <sup>-3</sup>	N.A.
dyne	2.2	248×10 <sup>-6</sup>	3.59 × 10 <sup>−5</sup>	980.7	1	0.0000
N	0.2	22481	3.5967	N.A.	100000	1

Power (to con	<b>Power</b> (to convert from A to B, multiply by entry in table)				
A	hp	Watts			
hp (English)	1	745.7			
(lb-in) (deg./s)	2.645 × 10 <sup>-6</sup>	1.972×10 <sup>-3</sup>			
(lb-in) (rpm)	1.587 × 10 <sup>-5</sup>	1.183 × 10 <sup>−2</sup>			
(lb-ft) (deg./s)	3.173×10 <sup>-5</sup>	2.366 × 10 <sup>-2</sup>			
(lb-ft) (rpm)	$1.904 \times 10^{-4}$	0.1420			
Watts	1.341 × 10 <sup>-3</sup>	1			

A	В	lb	OZ	gm	kg	slug
lb		1	16	453.6	0.4536	0.0311
oz		6.25 × 10 <sup>-2</sup>	1	28.35	0.02835	1.93 × 10 <sup>-3</sup>
gm		$2.205 \times 10^{-3}$	3.527 × 10 <sup>-2</sup>	1	10 <sup>-3</sup>	$6.852 \times 10^{-5}$
kg		2.205	35.27	10 <sup>3</sup>	1	$6.852 \times 10^{-2}$
slug		32.17	514.8	$1.459 \times 10^{4}$	14.59	1

Mass (to convert from A to B, multiply by entry in table)

- Rotation (to convert from A to B, multiply b	y entry in table)
--	-------------------

A	3 rpm	rad/s	degrees/s
rpm	1	0.105	6.0
rad/s	9.55	1	57.30
degrees/s	0.167	1.745 × 10 <sup>-2</sup>	1

## **Conversion tables**

## Temperature Conversion

°F	°C	°C	°F
0	-17.8	-10	14
32	0	0	32
50	10	10	50
70	21.1	20	68
90	32.2	30	86
98.4	37	37	98.4
212	100	100	212
subtract 32 and multiply by $^{5}/_{9}$		multiply	by $^{9}/_{5}$ and add 32

## Mechanism Efficiencies

Acme-screw with brass nut	~0.35–0.65	
Acme-screw with plastic nut	~0.50-0.85	
Ball-screw	~0.85–0.95	
Chain and sprocket	~0.95–0.98	
Preloaded ball-screw	~0.75–0.85	
Spur or bevel-gears	~0.90	
Timing belts	~0.96–0.98	
Worm gears	~0.45–0.85	
Helical gear (1 reduction)	~0.92	

## Friction Coefficients

Materials	μ
Steel on steel (greased)	~0.15
Plastic on steel	~0.15–0.25
Copper on steel	~0.30
Brass on steel	~0.35
Aluminum on steel	~0.45
Steel on steel	~0.58
Mechanism	μ
Ball bushings	<0.001
Linear bearings	<0.001
Dove-tail slides	~0.2++
Gibb ways	~0.5++

Material Densities		
Material	lb-in <sup>3</sup>	gm-cm <sup>3</sup>
Aluminum	0.096	2.66
Brass	0.299	8.30
Bronze	0.295	8.17
Copper	0.322	8.91
Hard wood	0.029	0.80
Soft wood	0.018	0.48
Plastic	0.040	1.11
Glass	0.079–0.090	2.2–2.5
Titanium	0.163	4.51
Paper	0.025-0.043	0.7–1.2
Polyvinyl chloride	0.047-0.050	1.3–1.4
Rubber	0.033–0.036	0.92-0.99
Silicone rubber, without filler	0.043	1.2
Cast iron, gray	0.274	7.6
Steel	0.280	7.75

## Wire Gauges<sup>1)</sup>

Cross-section mm <sup>2</sup>	Standard Wire Gauge (SWG)	American Wire Gauge (AWG)
0.2	25	24
0.3	23	22
0.5	21	20
0.75	20	19
1.0	19	18
1.5	17	16
2.5	15	13
4	13	11
6	12	9
10	9	7
16	7	6
25	5	3
35	3	2
50	0	1/0
70	000	2/0
95	00000	3/0
120	0000000	4/0
150	-	6/0
185	_	7/0

<sup>1)</sup> The table shows approximate SWG/AWG sizes nearest to standard metric sizes; the cross-sections do not match exactly.

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## Appendix

Notes

## Catalogs

## Digital Factory, Process Industries and Drives and Energy Management

Further information can be obtained from our branch offices listed at www.siemens.com/automation-contact

Interactive Catalog on DVD Products for Automation and Drives	Catalog CA 01
Building Control GAMMA Building Control	ET G1
Drive Systems	
SINAMICS G130 Drive Converter Chassis Units	D 11
SINAMICS G150 Drive Converter Cabinet Units SINAMICS GM150, SINAMICS SM150	D 12
Medium-Voltage Converters	DIE
SINAMICS PERFECT HARMONY GH180 Medium-Voltage Air-Cooled Drives (Germany Edition)	D 15.1
SINAMICS G180	D 18.1
Converters – Compact Units, Cabinet Systems,	
Cabinet Units Air-Cooled and Liquid-Cooled SINAMICS S120 Chassis Format Units and	D 21.3
Cabinet Modules	D 21.0
SINAMICS S150 Converter Cabinet Units	
SINAMICS S120 and SIMOTICS SINAMICS DCM DC Converter, Control Module	D 21.4 D 23.1
SINAMICS DOW DO COnventer, Control Module SINAMICS Inverters for	D 23.1 D 31.1
Single-Axis Drives · Built-In Units	
SINAMICS Inverters for Single-Axis Drives · Distributed Inverters	D 31.2
Digital: SINAMICS G120P and SINAMICS G120P	D 35
Cabinet pump, fan, compressor converters	2 00
LOHER VARIO High Voltage Motors Flameproof, Type Series 1PS4, 1PS5, 1MV4 and 1MV5 Frame Size 355 to 1000, Power Range 80 to 7100 kW	D 83.2
Three-Phase Induction Motors SIMOTICS HV, SIMOTICS TN	D 84.1
High Voltage Three-phase Induction Motors SIMOTICS HV Series A-compact PLUS	D 84.9
Digital: Modular Industrial Generators SIGENTICS M	D 85.1
Three-Phase Induction Motors SIMOTICS HV, Series H-compact	D 86.1
Synchronous Motors with Permanent-Magnet Technology, HT-direct	D 86.2
DC Motors	DA 12
SIMOREG DC MASTER 6RA70 Digital Chassis Converters	DA 21.1
SIMOREG K 6RA22 Analog Chassis Converters Digital: SIMOREG DC MASTER 6RM70 Digital Converter Cabinet Units	DA 21.2 <i>DA 22</i>
SIMOVERT PM Modular Converter Systems	DA 45
MICROMASTER 420/430/440 Inverters	DA 51.2
MICROMASTER 411/COMBIMASTER 411	DA 51.3
Low-Voltage Three-Phase-Motors	D 44
SIMOTOCS S-1FG1 Servo geared motors SIMOTICS Low-Voltage Motors	D 41 D 81.1
SIMOTICS FD Low-Voltage Motors	D 81.8
LOHER Low-Voltage Motors	D 83.1
Digital: MOTOX Geared Motors	D 87.1
SIMOGEAR Geared Motors	MD 50.1
SIMOGEAR Electric-monorail geared motors Light-load and heavy-load applications	MD 50.8
SIMOGEAR Gearboxes with adapter	MD 50.11
Mechanical Driving Machines	
FLENDER Standard Couplings	MD 10.1
FLENDER High Performance Couplings	MD 10.2
FLENDER Backlash-free Couplings	MD 10.3
FLENDER SIP Standard industrial planetary gear units	MD 31.1

ch	offices listed at www.siemens.com/automat	ion-contact
	Process Instrumentation and Analytics	Catalog
	Digital: Field Instruments for Process Automation	FI 01
	0	
	Digital: Display Recorders SIREC D	MP 20
	Digital: SIPART Controllers and Software	MP 31
	Products for Weighing Technology	WT 10
	Digital: Process Analytical Instruments	AP 01
	Digital: Process Analytics, Components for Continu-	AP 11
	ous Emission Monitoring	
	Low-Voltage Power Distribution and	
	Electrical Installation Technology	
	SENTRON · SIVACON · ALPHA	LV 10
	Protection, Switching, Measuring and Monitoring	
	Devices, Switchboards and Distribution Systems	
	Standards-Compliant Components for	LV 11
	Photovoltaic Plants	
	Electrical Components for the Railway Industry	LV 12
	Power Monitoring Made Simple	LV 14
	Components for Industrial Control Panels according	LV 16
	to UL Standards	
	3WT Air Circuit Breakers up to 4000 A	LV 35
	3VT Molded Case Circuit Breakers up to 1600 A	LV 36
	Digital: SIVACON System Cubicles, System Lighting	LV 50
	and System Air-Conditioning	
	Digital: ALPHA Distribution Systems	LV 51
	ALPHA FIX Terminal Blocks	LV 52
	SIVACON S4 Power Distribution Boards	LV 56
	SIVACON 8PS Busbar Trunking Systems	LV 70
	Digital: DELTA Switches and Socket Outlets	ET D1
	Vacuum Switching Technology and Components for	HG 11.01
	Medium Voltage	
	Motion Control	
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	SINUMERIK 808 Equipment for Machine Tools	NC 81.1
	SINUMERIK 828 Equipment for Machine Tools	NC 82
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_	Digital: Drive and Control Components for Cranes	
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	Safety Integrated	
	Safety Technology for Factory Automation	SI 10
	Salety recimology for ractory Automation	51 10
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	Human Machine Interface Systems/	ST 80/
	PC-based Automation	ST PC
	SIMATIC Ident	
	Industrial Identification Systems	ID 10
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